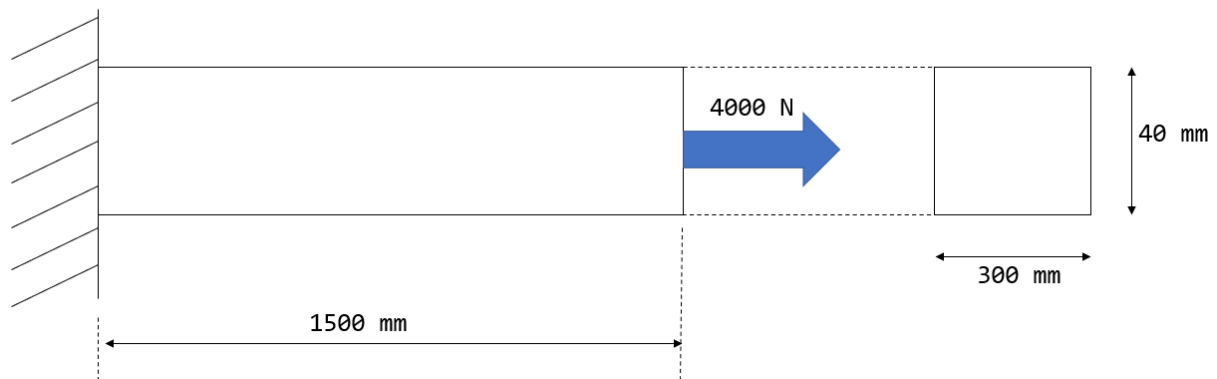


## 1D Bar Finite Element Method (FEM) Analysis

- This project contains Python code for performing Finite Element Method (FEM) analysis on 1D bar elements with Non-Linear Constitutive Behaviour.
- The code includes implementations for Static Non-Linear for problems with Linear and Non-Linear Constitutive Behaviour.
- When Non-Linear FEM code is used to solve Linear Problem, the solution is obtained in 2 iterations only.
- For a regular Non-Linear Problem, the solution is obtained in multiple steps.
- The Non-Linearity effect can be observed only if, the  $E_0$  is small or  $F$  is large.

### 1D Bar Static Analysis Problem



The Non-Linearity considered,

$$\sigma(\varepsilon) = E_0 \varepsilon + E_1 \varepsilon^3$$

The strong form equation of 1D bar can be written as,

$$A \frac{d}{dx}(\hat{\sigma}(\varepsilon)) + b = 0, [0, l_e]$$

Where,

$$\varepsilon = \frac{du}{dx}$$

If no body forces are considered,  $b = 0$

$$A \frac{d}{dx}(\hat{\sigma}(\varepsilon)) = 0, [0, l_e]$$

The boundary conditions are as described below:

$$u = 0, \quad x = 0$$

$$A \hat{\sigma} \left( \frac{du}{dx} \right) = F, \quad x = l_e$$

The equation can be converted into weak form by multiplying with a weight function and integrating over the entire domain as,

$$A \int_0^l \frac{d}{dx} (\hat{\sigma}(\varepsilon)) w dx = 0$$

Integrating by parts,

$$A \int_0^l \frac{d}{dx} (\hat{\sigma}(\varepsilon)) \frac{dw}{dx} dx = Pw(l)$$

Now, given  $\hat{\sigma}(\varepsilon)$  is a non-linear function in  $\varepsilon$ , it should be linearized to obtain the solution. To linearize, Newton Raphson method is used where  $u^{k+1} = u^k + \Delta u^k$  is considered and using Taylor series expansion

$$\hat{\sigma} \left( \frac{du^{k+1}}{dx} \right) = \hat{\sigma} \left( \frac{d(u^k + \Delta u^k)}{dx} \right) = \hat{\sigma} \left( \frac{du^k}{dx} \right) + \hat{\sigma}' \left( \frac{du^k}{dx} \right) \frac{d\Delta u^k}{dx}$$

Now,

$$A \int_0^l \left( \hat{\sigma} \left( \frac{du^k}{dx} \right) + \hat{\sigma}' \left( \frac{du^k}{dx} \right) \frac{d\Delta u^k}{dx} \right) \frac{dw}{dx} dx = Pw(l)$$

$$A \int_0^l \hat{\sigma}' \left( \frac{du^k}{dx} \right) \frac{d\Delta u^k}{dx} \frac{dw}{dx} dx = Pw(l) - A \int_0^l \hat{\sigma} \left( \frac{du^k}{dx} \right) \frac{dw}{dx} dx$$

The above equation is used to obtain  $\Delta u^k$  which is the in kth step and is added to  $u^k$  to get the displacement for the  $(k + 1)^{th}$  iteration. This equation is solved till the residue which is the RHS of equation becomes less than a tolerance value. The value of  $\hat{\sigma}'$  and  $\hat{\sigma}$  are obtained based on the assumed Constitutive mode (in this case  $\sigma(\varepsilon) = E_0 \varepsilon + E_1 \varepsilon^3$ ) for each iteration.

According to FEA approximation, the values of displacements can be considered as sum of displacements at nodes multiplied by weight functions as shown below,

$$u^k(x) = \sum_{i=1}^N u_i^k \varphi_i(x) = \sum_i u_i^k \varphi_i(x)$$

$$w^k(x) = \sum_{j=1}^N \varphi_j(x) = \sum_j \varphi_j(x)$$

$$\Delta u^k(x) = \sum_{m=1}^N \Delta u_m^k \varphi_m(x) = \sum_m \Delta u_m^k \varphi_m(x)$$

Now the equation becomes,

$$A \int_0^l \hat{\sigma}' \left( \frac{d(\sum_i u_i^k \phi_i(x))}{dx} \right) \frac{d(\sum_m \Delta u_m^k \phi_m(x))}{dx} \frac{d(\sum_j \phi_j(x))}{dx} dx = P - A \int_0^l \hat{\sigma} \left( \frac{d(\sum_i u_i^k \phi_i(x))}{dx} \right) \frac{d(\sum_j \phi_j(x))}{dx} dx$$

$$\left[ \sum_m \sum_j A \int_0^l \hat{\sigma}' \left( \sum_i \frac{d\phi_i}{dx} u_i^k \right) \frac{d\phi_m}{dx} \frac{d\phi_j}{dx} dx \right] \{ \Delta u_m^k \} = \{ P \} - \left\{ \sum_j A \int_0^l \hat{\sigma} \left( \sum_i \frac{d\phi_i}{dx} u_i^k \right) \frac{d\phi_j}{dx} dx \right\}$$

Substituting the values of shape functions for each node, the equation simplifies to,

If  $i < N$ :

$$\begin{aligned} & A \left( \int_{X_{i-1}}^{X_i} \sigma' \left( \frac{u_i - u_{i-1}}{X_i - X_{i-1}} \right) \phi_i' \phi_{i-1}' dx \right) \Delta u_{i-1} + A \left( \int_{X_i}^{X_{i+1}} \sigma' \left( \frac{u_{i+1} - u_i}{X_{i+1} - X_i} \right) \phi_i' \phi_{i+1}' dx \right) \Delta u_{i+1} \\ & + \left( A \int_{X_{i-1}}^{X_i} \sigma' \left( \frac{u_i - u_{i-1}}{X_i - X_{i-1}} \right) \phi_i'^2 dx + A \int_{X_i}^{X_{i+1}} \sigma' \left( \frac{u_{i+1} - u_i}{X_{i+1} - X_i} \right) \phi_i'^2 dx \right) \Delta u_i \\ & = -A \int_{X_{i-1}}^{X_i} \sigma \left( \frac{u_i - u_{i-1}}{X_i - X_{i-1}} \right) \phi_i' dx - A \int_{X_i}^{X_{i+1}} \sigma \left( \frac{u_{i+1} - u_i}{X_{i+1} - X_i} \right) \phi_i' dx + F v_i \end{aligned}$$

If  $i=1$  or  $i=N$ , i.e at the end points of the bar

These equations can be analytically solved, as  $\phi$  is a linear function of  $X$ . Solving it accordingly the equation simplifies to, where  $h_i = X_{i+1} - X_i$

$$\begin{aligned} & A \sigma' \left( \frac{u_i - u_{i-1}}{h_{i-1}} \right) \left( \frac{-1}{h_{i-1}} \right) \Delta u_{i-1} + A \sigma' \left( \frac{u_{i+1} - u_i}{h_i} \right) \left( \frac{-1}{h_i} \right) \Delta u_{i+1} \\ & + A \sigma' \left( \frac{u_i - u_{i-1}}{h_{i-1}} \right) \left( \frac{1}{h_{i-1}} \right) \Delta u_i + A \sigma' \left( \frac{u_{i+1} - u_i}{h_i} \right) \left( \frac{1}{h_i} \right) \Delta u_i \\ & = A \sigma \left( \frac{u_i - u_{i-1}}{h_{i-1}} \right) + A \sigma \left( \frac{u_{i+1} - u_i}{h_i} \right) + F v_i \end{aligned}$$