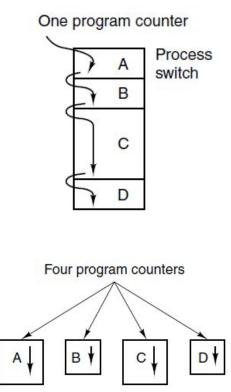
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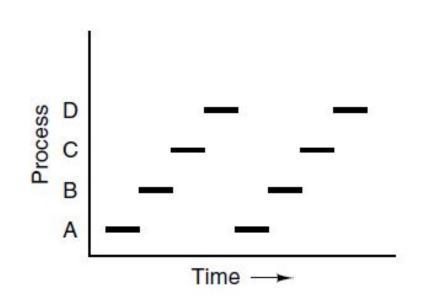
Processes - part 2

Outline

- CPU utilization
- processes creation, termination
- process scheduling
- process states
- context switching

Multiprogramming on a single CPU





CPU utilization

- example:
 - OS is running 4 processes, P1, P2, P3 and P4
 - P1 spends 40% of the time waiting on I/O
 - P2 spends 20% of the time waiting on I/O
 - P3 spends 50% of the time waiting on I/O
 - P4 spends 90% of the time waiting on I/O
 - if there is only one CPU, what will be the CPU's utilization?
 - i.e. what percentage of the time is the CPU going to be running 'something'?
- Answer:
 - CPU utilization = probability that at least one of the processes is not waiting on I/O

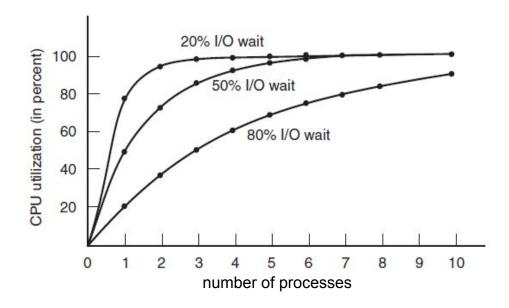
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 - i.e. what percentage of the time is the CPU going to be running 'something'?
- Answer:
 - \Box CPU utilization = probability that at least one of the processes is not waiting on I/O
 - = 1 (probability that all processes are waiting on I/O)
 - = 1 (0.4 * 0.2 * 0.5 * 0.9) = 0.964 = 96.4%

CPU utilization - under simplistic multiprogramming model

- assume N similar processes
- each process spends the same
 fraction P of its time waiting on I/O
- then:

CPU utilization = $1 - P^N$



CPU utilization as a function of the number of processes in memory.

CPU utilization example

- example:
 - computer has 8GB of RAM
 - let's say 2GB are taken up by OS, leaving 6GB available to user programs
 - user wants to run multiple copies of a program that needs 2GB RAM, with average 80% I/O
 - with 6GB remaining, user could run 3 copies of the program
 - \Box CPU utilization would be = 1 0.8³ ~= 49%
- is it a good idea to buy 8GB more of RAM?

CPU utilization example

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 - □ with 6GB remaining, user could run 3 copies of the program
 - \Box CPU utilization would be = 1 0.8³ ~= 49%
- is it a good idea to buy 8GB more of RAM?
 - with 14GB remaining, user could run 7 copies of the program
 - \Box CPU utilization would be = 1 0.8⁷ ~= 79%
 - \Box throughput increased by 79% 49% = **30%**
- is it a good idea to buy 8GB more?
 - CPU utilization = 1 0.8¹¹ ~= 91%
 - \Box throughput increased only by 91% 79% = 12% (diminishing returns)

Process creation

- in UNIX
 - init process is created at boot time by kernel (special case)
 - afterwards, only an existing process can create a new processes, via fork()
 - therefore all processes are descendants of init
 - in many modern Linux distributions init is replaced by systemd
 - fork() often followed by exec*() to spawn a different program,
 or you could use a the system() convenience function
- in Windows: CreateProcess() is used to create processes,but the behavior is quite different from fork()

Process creation

- a process can create new processes for a variety of reasons
 - system initialization (boot)
 - background processes daemons, services
 - application decides to spawn additional processes
 - eg. to execute external programs or to do parallel work
 - a user requests to create a new process
 - eg. launching an application from desktop
 - starting a batch job
 - mainframes

Address space

each process has its own address space, created during process creation

Parent		Parent	Child
Stack	fork()	Stack	Stack
Неар	 duplicate address space (almost identical) next instruction is the same but code flow may differ 	Неар	Неар
Data		Data	Data
Text		Text	Text
Code: fork()		Code: wait()	Code: execlp()
РСВ		РСВ	РСВ

Resource allocation

- several options for allocating resources for a new process, for example:
 - child obtains resources directly from the OS
 - most common, easiest to implement
 - child obtains subset of parent's resources
 - o eg. parent decides to give up some if its resources so that a child can use them
 - parent shares some/all resources with the child
 - hybrids
- cons/pros...
 - should a process be allowed to exhaust resources of the entire OS?

Common parent-child execution scenarios

- when child process is created, parent process usually does one of three things:
 - 1. the parent waits until the child process is finished
 - often used when child executes another program, eg. fork/exec(), or system()
 - the parent continues to execute concurrently and independently of the child process
 - o eg. autosave feature
 - 3. the parent continues to execute concurrently, but synchronizes with the child
 - can be quite complicated to synchronize

```
pid = fork()
if pid > 0 :
    wait()
```

```
pid = fork()
if pid > 0 :
    do_whatever()
    exit()
```

```
pid = fork()
if pid > 0 :
    do_something_1()
    synchronize()
    do_something_2()
    synchronize()
    ...
```

Process termination

- typical conditions which terminate a process:
 - voluntary:
 - o normal exit eg. application decides it's done, or user instructs an app to 'close'
 - application calls exit() or ExitProcess()
 - error exit application detects an error, optionally notifies user
 - application calls exit() or ExitProcess()
 - □ involuntary:
 - fatal error
 - usually due to a bug in the program, detected by OS
 - eg. accessing invalid memory, division by zero
 - involuntary killed by another process
 - parent, or another process calls kill() or TerminateProcess()
 - eg. during shutdown, pressing <ctrl-c> in terminal, closing GUI window

Process termination

- parent may terminate its children for different reasons, for example:
 - the child has exceeded its usage of some of the resources
 - the task assigned to the child is no longer required
 - the parent needs/wants to exit and wants to clean up first
- in Unix, when a parent process is terminated:
 - the child processes may be terminated, or assigned to the grandparent process,
 or to the init process
 - process hierarchy is always maintained
- default behavior on Linux is to reparent the child process to the init process
 - this can be changed (eg. to kill children, reparent to some other process)
 - see prctl() for more details

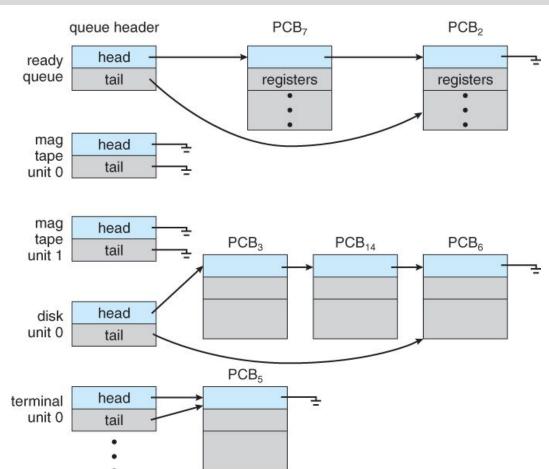
Process termination

- when terminating a process, what happens to resources owned by the process?
 - OS must free all related resources, eg.
 - free memory used by the process
 - delete PCB
 - delete process from process table
 - □ kill children or assign them a new parent
 - close files
 - close network connections
 - □ ..

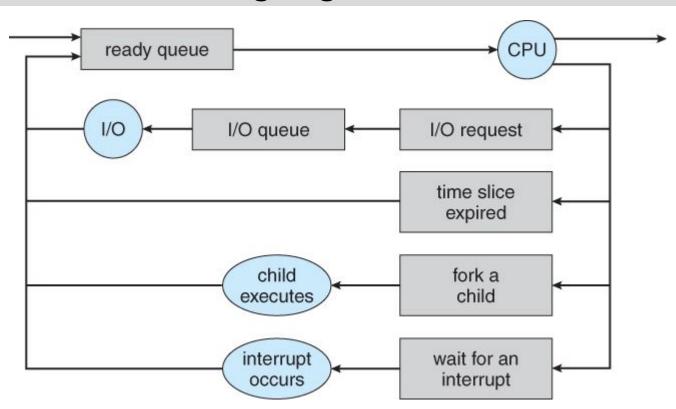
Process scheduling

- part of multitasking is deciding which process gets the CPU next
- typical objective is to maximize CPU utilization
- process scheduler:
 - kernel routine/algorithm that selects an available process to execute on the CPU
 - selected from processes in a ready queue
- OS maintains many different scheduling queues:
 - job queue: all programs waiting to run, usually found in batch systems
 - eg. priority queue
 - ready queue: all processes that are ready to execute their next instruction
 - eg. linked list, implemented via a pointers in PCBs
 - device queues: processes waiting for a particular device
 - each device has its own queue

Queues



Process scheduling diagram



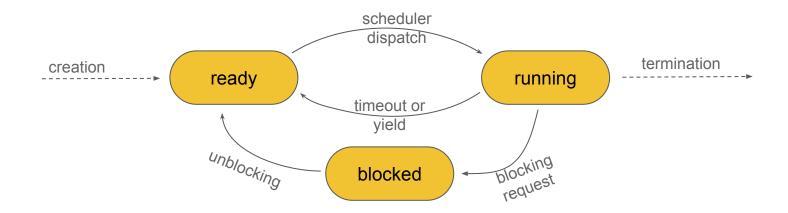
Process states

3 process states:

- running actually running on the CPU
- **blocked** waiting for some event to occur, eg. I/O
- ready the process is ready to execute on CPU

only 4 transitions are possible:

- ready \rightarrow running
- running \rightarrow ready
- running → blocked
- blocked \rightarrow ready



Exercise – simulating round-robin scheduling

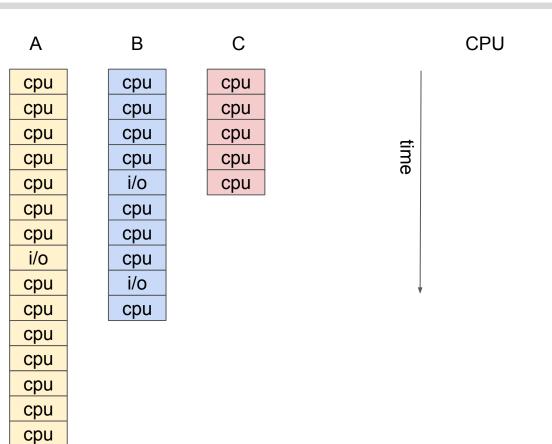
- simulate 3 processes A, B, C
 - A: cpu x 7, i/o, cpu x 7
 - B: cpu x 4, i/o, cpu x 3, i/o, cpu x 1
 - C: cpu x 5
- time slice = 3 cycles
 - give the CPU to a process for at most 3 cycles
 - after 3 cycles switch to the next process
 - if process is doing I/O switch to the next process
- assume I/O is very short, only 1 CPU cycle

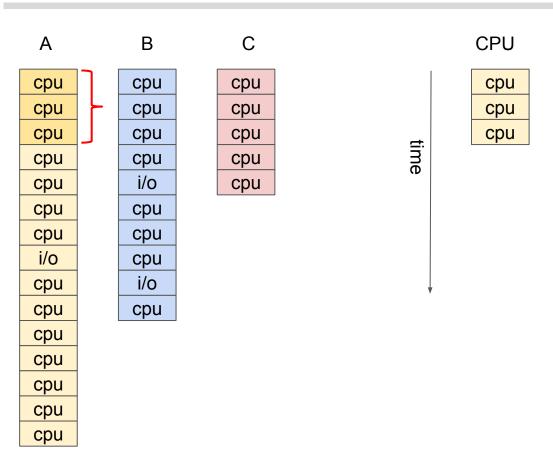
cpu cpu cpu cpu cpu cpu cpu cpu i/o cpu cpu cpu cpu cpu i/o cpu i/o cpu cpu cpu cpu cpu cpu cpu

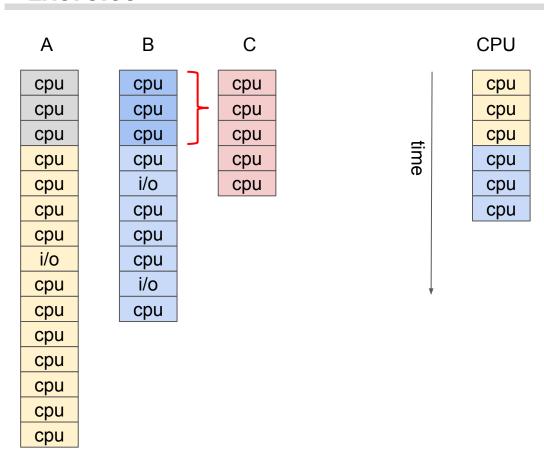
Α

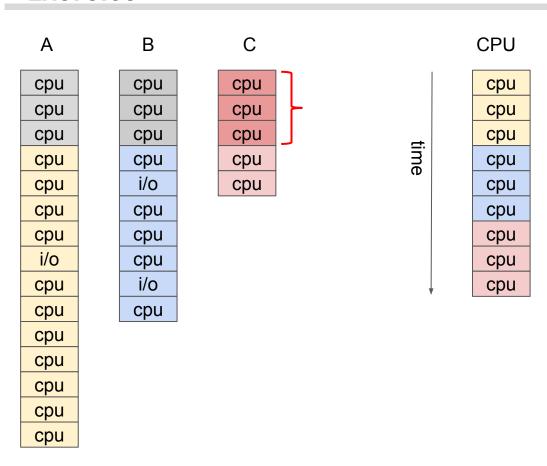
cpu

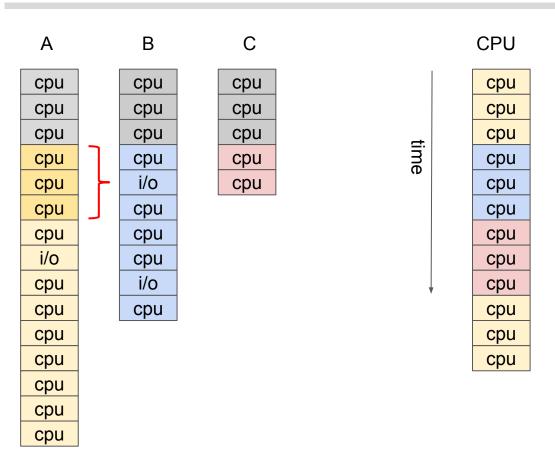
В C cpu cpu cpu cpu cpu

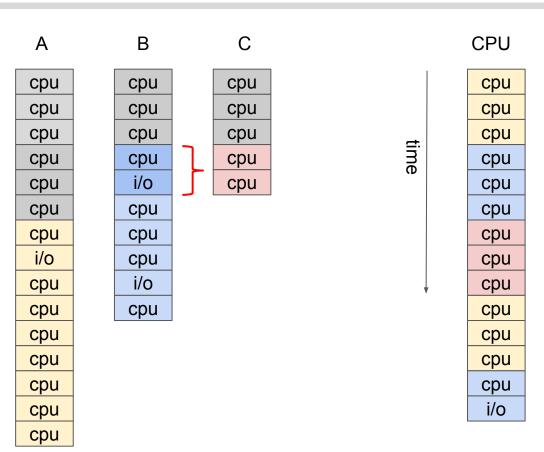


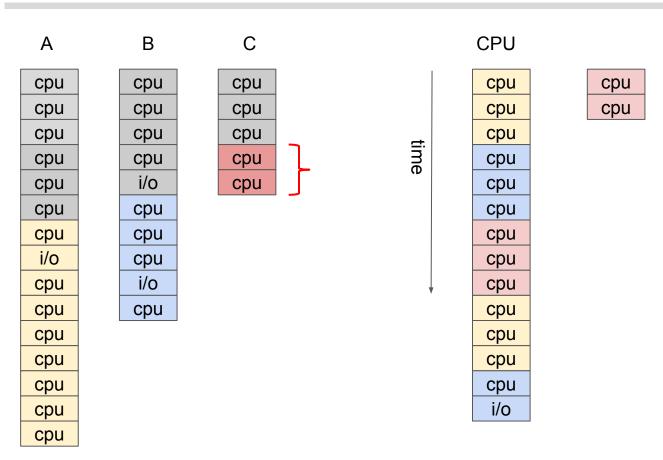


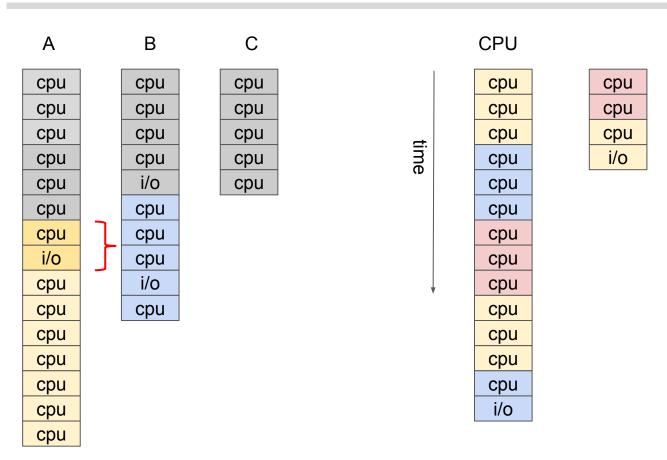


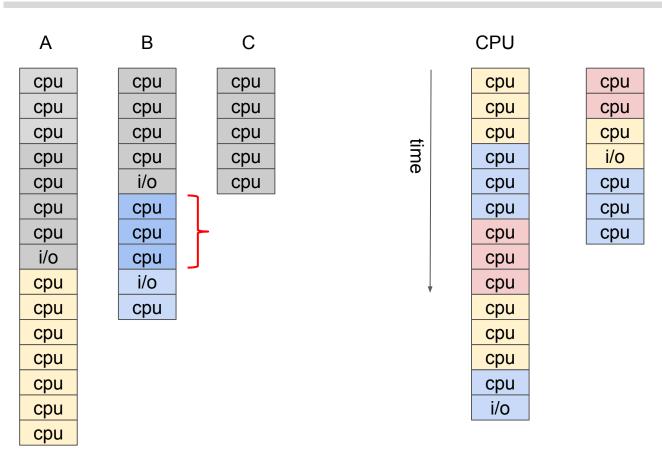


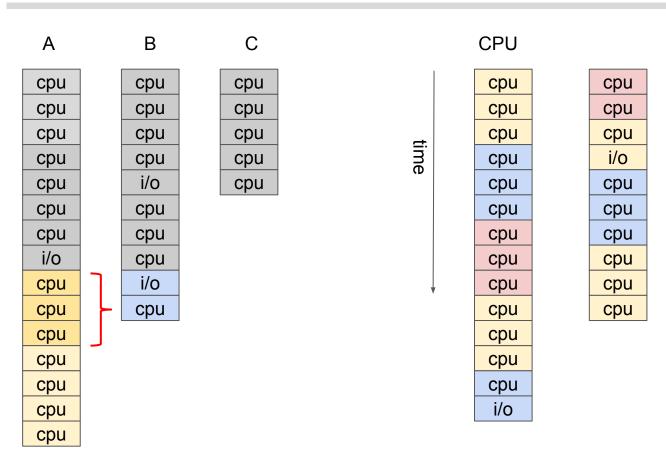


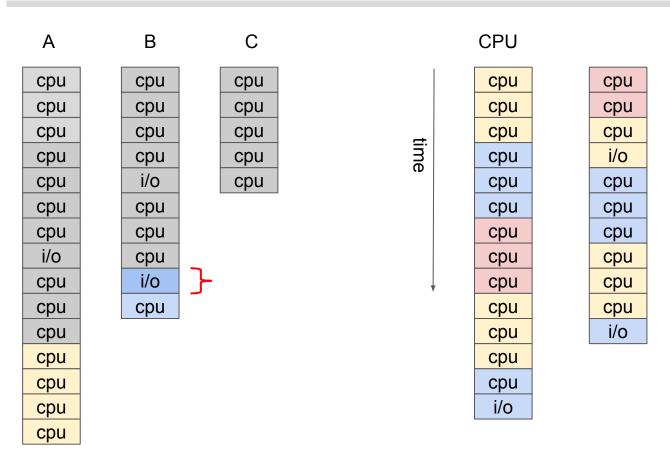


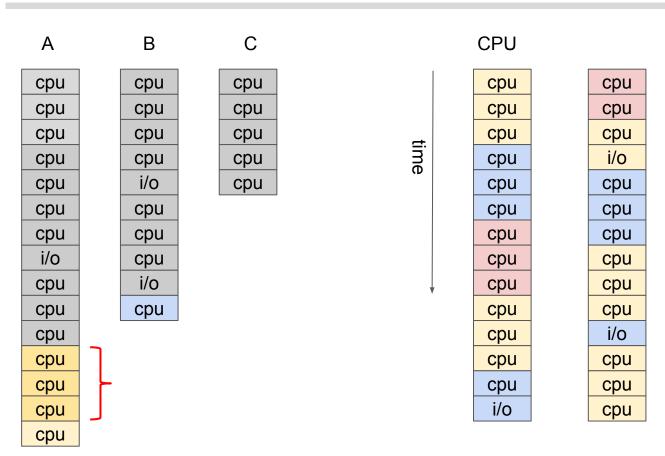


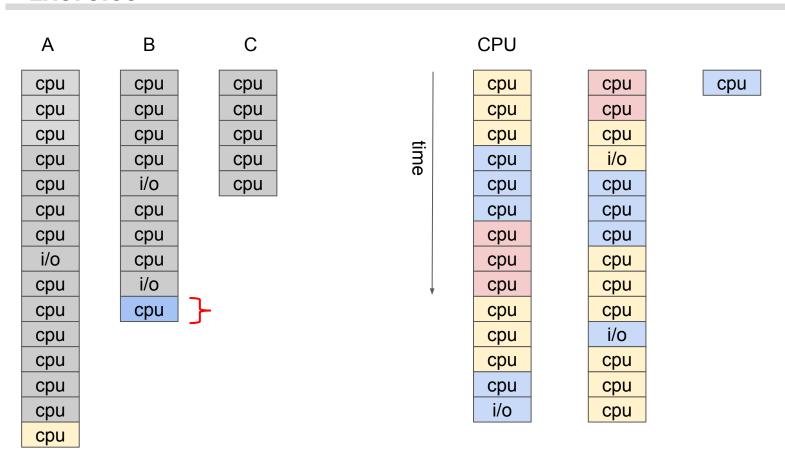


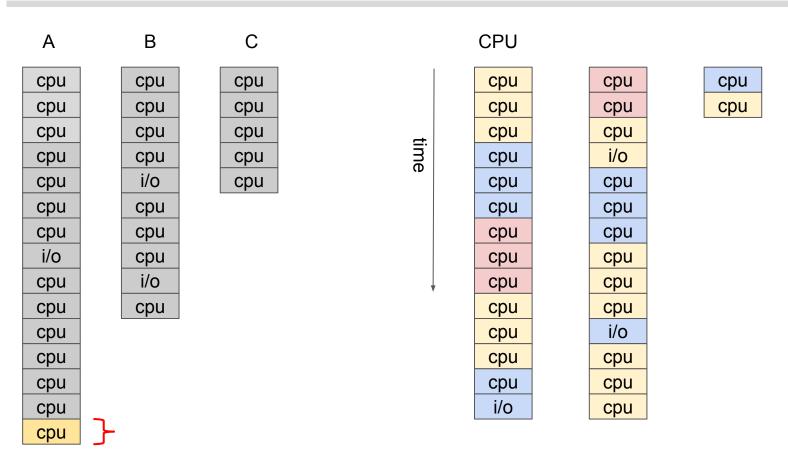












Context switching

- essential feature of any multitasking OS
- allows the illusion of sharing of a single CPU (or limited number of CPUs) among many processes
- we need context switching to implement multitasking when # CPUs < # processes</p>
- OS maintains a context (state) for each process
 - usually part of PCB
- when OS switches between processes A and B:
 - OS first saves A's state in A's PCB
 - eg. save current CPU registers into PCB_A
 - OS then restores B's state from B's PCB
 - eg. load CPU registers from PCB_B

Context switching

- context switch occurs in kernel mode:
 - for example when process exceeds its time slice
 - enforcing time slice policy usually implemented via timer interrupt
 - or when current process voluntarily relinquishes (yields) CPU, eg. by sleeping
 - or when current process requests a blocking I/O operation, or any blocking system call
 - or due to other events, such as keyboard, mouse, network interrupts
- context switch introduces time overhead
 - CPU spends cycles on no "useful" work, eg. saving/restoring CPU registers
 - context switch routine is one of the most optimized parts of kernels
- context switch performance could be improved by hardware support:
 - eg. CPU supporting saving/restoring registers in a single instruction
 - or CPU could support multiple sets of registers
 - software based context switch is slower, but more customizable, and often more efficient

Questions?