FAST AND ACCURATE TEMPLATE FITTING WITH TEMPLATE PERIODOGRAMS

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ABSTRACT

Astrophysical time series often contain periodic signals. In the near future, the sheer volume of astrophysical time series data (e.g. from LSST) will demand computationally efficient methods for detecting and characterizing such signals. The most efficient algorithms that exist to date are those that exploit the $\mathcal{O}(N\log N)$ nature of the Fast Fourier Transform. However, these methods are not optimal for non-sinusoidal signal shapes. Template fitting optimizes sensitivity for a priori known signal shapes but at enormous computational cost that scales as $\mathcal{O}(N^2)$, and without the garauntee that the fitting procedure obtains the best fit at each trial frequency. In this work, we present a non-linear extension of the Lomb-Scargle periodogram as a template-fitting algorithm that is both accurate (the exact optimal solutions are obtained except in rare cases) and computationally efficient (scaling as $\mathcal{O}(N\log N)$). We show that our method is twice as fast as existing algorithms for small problems ($N \lesssim 10$ observations) and up to 3 orders of magnitude faster for long base-line time series with $N \sim 10^4$ observations. Additional speedups are likely with improvements to the existing implementation.

1. INTRODUCTION

Astrophysical time series are challenging to analyze. Unlike time series in other domains like economics and finance, astrophysical observations are often irregularly sampled in time with heteroskedastic, non-Gaussian, and time-correlated measurement uncertainties.

Irregular sampling thwarts the straightforward application of many well-known time series tools like the discrete Fourier transform (DFT) and the auto-regressive moving average (ARMA) models. The DFT is a particularly unfortunate loss, since the Fast Fourier Transform (Cooley and Tukey 1965) reduces the $\mathcal{O}(N^2)$ DFT to $\mathcal{O}(N\log N)$, and is a powerful tool for finding periodic signals.

Fortunately, the DFT can be extended to irregularly sampled data via what is sometimes referred to as the classical periodogram (Stoica *et al.* 2009)

$$P_x(\omega) = \frac{1}{N^2} \left| \sum_{n=0}^{N-1} y_n e^{-i\omega t_n} \right|^2.$$
 (1)

However, as Stoica *et al.* (2009) point out, this is not an optimal measure of periodicity. A more robust estimate of the power spectrum is given by the Lomb-Scargle periodogram (Lomb 1976; Scargle 1982; Barning 1963; Vaníček 1971).

ARMA models can also be extended to unevenly sampled data with the CARMA model (Kelly *et al.* 2014; Zinn *et al.* 2016), but for the purposes of this paper, we focus solely on tools applicable to the detection of periodic signals in astrophysical data.

The Lomb-Scargle periodogram and its extensions can

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$$\hat{y}_{LS}(t|\theta,\omega) = \theta_0 \cos \omega t + \theta_1 \sin \omega t. \tag{2}$$

This is equivalent to performing a DFT if the data is regularly sampled. The Lomb-Scargle periodogram can be obtained from solving the linear system of equations that arise from the condition that the summed squares of residuals between the data and the optimal model,

$$\chi^2(\theta, S) \equiv \sum_{i} (y_i - \hat{y}(t_i|\theta))^2, \tag{3}$$

must be a local minimum. This means that

$$\left. \frac{\partial \chi^2}{\partial \theta_i} \right|_{\theta = \theta_{\text{best}}} = 0 \quad \forall \theta_i \in \theta. \tag{4}$$

The resulting periodogram can be expressed as

$$P_{\rm LS} = \frac{1}{2\sigma^2} \left(\frac{\left[\sum_{n=1}^N (y_n - \bar{y})\cos\omega t_n\right]^2}{\sum_{n=1}^N \cos^2\omega t_i} + \frac{\left[\sum_{n=1}^N (y_n - \bar{y})\sin\omega t_n\right]^2}{\sum_{n=1}^N \sin^2\omega t_i} \right),$$
(5)

where $\bar{y} = \mathbb{E}[y_n]$, the mean of the data, and $\sigma = \text{Var}(y_n)$, the variance of the data.

Heteroskedasticity can be handled by using weighted least squares,

$$\chi^{2}(\theta, S) \equiv \sum_{i} \frac{(y_{i} - \hat{y}(t_{i}|\theta))^{2}}{\sigma_{i}}^{2}, \qquad (6)$$

with weights $w_i = \frac{W}{\sigma_i^2}$, $W \equiv \sum \sigma_i^{-2}$ being a normalization factor to ensure $\sum w_i = 1$, and correlated uncertainties can be accounted for by using the full covariance matrix, $\Sigma_{ij} = \text{Cov}((y_i - \bar{y})(y_j - \bar{y}))$.

$$\chi^{2}(\theta, S) \equiv (y_{i} - \hat{y}(t_{i}|\theta))^{\mathrm{T}} \Sigma (y_{i} - \hat{y}(t_{i}|\theta)). \tag{7}$$

If we assume the covariance matrix is diagonal, the Lomb-Scargle periodogram can be evaluated quickly in one of two popular ways. The first, by Press and Rybicki (1989) involves "extirpolating" irregularly sampled data onto a regularly sampled mesh, and then performing FFTs to evaluate the necessary sums. The second, as pointed out in Leroy (2012), is to use the non-equispaced FFT (NFFT) Keiner et al. (2009) to evaluate the sums; this provides an order of magnitude speedup over the Press and Rybicki (1989) algorithm, and both algorithms scale as $\mathcal{O}(N\log N)$.

There also exists a continually growing number of alternative methods for detecting periodic signals in astrophysical data. Some of these methods can reliably outperform the Lomb-Scargle periodogram, especially for non-sinusoidal signal shapes (see Graham et al. (2013) for a recent empirical review). However, a key advantage that the LS periodogram and its extensions have over many alternatives is speed. Virtually all other methods scale as $N \times N_f \sim N^2 \sim N_f^2$, where N is the number of observations and N_f is the number of trial frequencies, while the Lomb-Scargle periodogram scales as $N_f \log N_f \sim N \log N$.

The importance of efficient algorithms will only become more important as the volume of data produced by astronomical observatories continues to grow. The HAT-Net telescope, for example, has already made $\mathcal{O}(10^4)$ observations of $\mathcal{O}(10^6-10^7)$ stars. The Gaia telescope (Gaia Collaboration et al. 2016) is set to produce $\mathcal{O}(10-100)$ observations of $\mathcal{O}(10^9)$ stars. The Large Synoptic Survey Telescope (LSST; LSST Science Collaboration et al. (2009)) will produce 15 Terabytes of data per night once operation begins in 2023.

This paper develops new extensions to least-squares spectral analysis for arbitrary signal shapes. For non-periodic signals this method is known as matched filter analysis, and can be extended to search for periodic signals by phase folding the data at different trial periods. We refer to latter technique, the subject of this paper, as template fitting.

Recently, Sesar et al. (2016) found that template fitting significantly improved period and amplitude estimation for RR Lyrae in Pan-STARRS DR1 (Chambers et al. 2016). Since the signal shapes for RR Lyrae in various bandpasses are known a priori (see Sesar et al. (2010)), template fitting provides an optimal estimate of amplitude and period, given that the object is indeed an RR Lyrae star well modeled by at least one of the templates. Templates were especially crucial for Pan-STARRS data, since there are typically only 35 observations per source over 5 bands (Hernitschek et al. 2016), not enough to obtain accurate amplitudes empirically by phase-folding.

By including domain knowledge (i.e. knowledge of what RR Lyrae lightcurves look like), template fitting allows for accurate inferences of amplitude even for undersampled lightcurves.

However, the improved accuracy comes at substantial computational cost: the template fitting procedure took 30 minutes per CPU per object, and Sesar et al. (2016) were forced to limit the number of fitted lightcurves $(\lesssim 1000)$ in order to keep the computational costs to a reasonable level. Several cuts were made before the template fitting step to reduce the more than 1 million Pan-STARRS DR1 objects to a small enough number, and each of these steps removes a small portion of RR Lyrae from the sample. Though this number was reported by Sesar et al. (2016) to be small ($\lesssim 10\%$), it may be possible to further improve the completeness of the final sample by applying template fits to a larger number of objects, which would require either more computational resources, more time, or, ideally, a more efficient template fitting procedure.

The paper is organized as follows. Section 2 poses the problem of template fitting in the language of least squares spectral analysis and derives the fast template periodogram. Section 3 describes a freely available implementation of the new template periodogram. Section 4 summarizes our results, addresses caveats, and discusses possible avenues for improving the efficiency of the current algorithm.

2. DERIVATIONS

We define a template M

$$\mathbf{M}: [0,1) \to \mathbb{R}, \tag{8}$$

as a mapping between the unit interval and the set of real numbers. We restrict our discussion to sufficiently smooth templates such that M can be adequately described by a truncated Fourier series

$$\hat{\mathbf{M}}(\omega t|H) = \sum_{n=1}^{H} \left[c_n \cos n\omega t + s_n \sin n\omega t \right]$$
 (9)

for some H > 0. Specifically, we require that

$$(\forall \epsilon > 0)(\exists H \in \mathbb{N}) \text{ s.t.}$$

$$\left| \mathbf{M}(t) - \hat{\mathbf{M}}(t|H) \right| < \epsilon \ \forall t \in [0, 1).$$
(10)

We now construct a periodogram for this template. The periodogram assumes that an observed time series $S = \{(t_i, y_i, \sigma_i)\}_{i=1}^N$ can be modeled by a scaled, transposed template that repeats with period $2\pi/\omega$, i.e.

$$y_i \approx \hat{y}(\omega t_i | \theta, \mathbf{M}) = \theta_1 \mathbf{M}(\omega t_i - \theta_2) + \theta_3,$$
 (11)

where $\theta \in \mathbb{R}^3$ is a set of model parameters.

The optimal parameters are the location of a local minimum of the (weighted) sum of squared residuals,

$$\chi^{2}(\theta, S) \equiv \sum_{i} w_{i} (y_{i} - \hat{y}(\omega t_{i}|\theta))^{2}, \qquad (12)$$

and thus the following condition must hold for all three model parameters at the optimal solution $\theta = \theta_{\text{opt}}$:

$$\left. \frac{\partial \chi^2}{\partial \theta_i} \right|_{\theta = \theta_{\text{opt}}} = 0 \quad \forall \theta_i \in \theta. \tag{13}$$

Note that we have implicitly assumed $\chi^2(\theta, S)$ is a C^1 differentiable function of θ , which requires that both \mathbf{M} and \mathbf{M}^2 are C^1 differentiable functions. Though this assumption could be violated if we considered a more complete set of templates, (e.g. a box function), our restriction to truncated Fourier series guarantees that both \mathbf{M} and \mathbf{M}^2 are C^1 differentiable and thus that $\chi^2(\theta, S)$ is C^1 differentiable.

We can derive a system of equations for $\theta_{\rm opt}$ from the condition given in Equation 13. The explicit condition that must be met for each parameter θ_i is simplified below

$$0 = \frac{\partial \chi^2}{\partial \theta_i} \bigg|_{\theta = \theta_{\text{opt}}}$$
$$= -2 \sum_n w_n (y_n - \hat{y}) \frac{\partial \hat{y}}{\partial \theta_i}$$
(14)

$$\sum_{n} w_{n} y_{n} \left(\frac{\partial \hat{y}}{\partial \theta_{i}} \right)_{n} = \sum_{n} w_{n} \hat{y}_{n} \left(\frac{\partial \hat{y}}{\partial \theta_{i}} \right)_{n}.$$

The above is a general result that extends to all least squares periodograms. To hopefully make our derivations more intuitive, we adopt the following notation:

$$\langle X \rangle \equiv \sum_{n} w_n X_n \tag{15}$$

$$\langle XY \rangle \equiv \sum_{n} w_n X_n Y_n \tag{16}$$

$$Var(X) \equiv \langle X^2 \rangle - \langle X \rangle^2 \tag{17}$$

$$Cov(X, Y) \equiv \langle XY \rangle - \langle X \rangle \langle Y \rangle \tag{18}$$

In addition, we denote shifted template $\mathbf{M}(x - \theta_2)$ by $\mathbf{M}_{\theta_2}(x)$.

For the amplitude and offset model parameters (θ_1 and θ_3 , respectively), we obtain the following relations from Equation 14

$$\langle y\mathbf{M}_{\theta_2}(\omega t)\rangle = \theta_1 \langle \mathbf{M}_{\theta_2}^2(\omega t)\rangle + \theta_3 \langle \mathbf{M}_{\theta_2}(\omega t)\rangle$$
 (19)

$$\theta_3 = \bar{y} - \theta_1 \langle \mathbf{M}_{\theta_2}(\omega t) \rangle. \tag{20}$$

Combining these expressions yields

$$\theta_1 = \frac{\langle (y - \bar{y}) \mathbf{M}_{\theta_2}(\omega t) \rangle}{\operatorname{Var}(\mathbf{M}_{\theta_2}(\omega t))}.$$
 (21)

For the offset parameter θ_2 ,

$$\frac{\partial \hat{y}}{\partial \theta_2} = \theta_1 \frac{\partial \mathbf{M}_{\theta_2}}{\partial \theta_2}
= -\theta_1 \partial \mathbf{M}_{\theta_2},$$
(22)

where

$$\partial \mathbf{M}_{\theta_2}(x) = \sum_n \left[s_n \cos n(x - \theta_2) - c_n \sin n(x - \theta_2) \right]. \tag{23}$$

From this we obtain

$$\theta_1 = \frac{\langle (y - \bar{y})\partial \mathbf{M}_{\theta_2}(\omega t) \rangle}{\operatorname{Cov}(\mathbf{M}_{\theta_2}(\omega t), \partial \mathbf{M}_{\theta_2}(\omega t))}, \tag{24}$$

which, combined with Equation 21, provides a non-linear expression for θ_2 :

$$\langle (y - \bar{y}) \partial \mathbf{M}_{\theta_2}(\omega t) \rangle \operatorname{Var}(\mathbf{M}_{\theta_2}(\omega t)) = \langle (y - \bar{y}) \mathbf{M}_{\theta_2}(\omega t) \rangle \operatorname{Cov}(\mathbf{M}_{\theta_2}(\omega t), \partial \mathbf{M}_{\theta_2}(\omega t)).$$
 (25)

To obtain an explicit expression for Equation 25, we define several quantities,

$$CC_{nm} \equiv \text{Cov}(\cos n\omega t, \cos m\omega t)$$
 (26)

$$CS_{nm} \equiv \text{Cov}(\cos n\omega t, \sin m\omega t)$$
 (27)

$$SS_{nm} \equiv \text{Cov}(\sin n\omega t, \sin m\omega t)$$
 (28)

$$YC_n \equiv \langle (y - \bar{y}) \cos n\omega t \rangle$$
 (29)

$$YS_n \equiv \langle (y - \bar{y}) \sin n\omega t \rangle, \qquad (30)$$

all of which can be evaluated efficiently with NFFTs. We also obtain an expression for the shifted template:

$$\mathbf{M}_{\theta_2}(x) = \sum_n \left[c_n \cos n(x - \theta_2) + s_n \sin n(x - \theta_2) \right]$$

$$\mathbf{M}_{\theta_2}(x) = \sum_n \left[(c_n \cos n\theta_2 - s_n \sin n\theta_2) \cos nx \right]$$

$$+ (s_n \cos n\theta_2 + c_n \sin n\theta_2) \sin nx]$$

$$\mathbf{M}_{\theta_2}(x) = \sum_n \left[\left(c_n T_n(u) \mp s_n \sqrt{1 - u^2} U_{n-1}(u) \right) \cos nx \right]$$

$$+\left(s_nT_n(u)\pm c_n\sqrt{1-u^2}U_{n-1}(u)\right)\sin nx$$

$$\mathbf{M}_{\theta_2}(x) = \sum_n \left[A_n(u) \cos nx + B_n(u) \sin nx \right]$$
(31)

where $u \equiv \cos \theta_2$, T_n and U_n are the Chebyshev polynomials of the first and second kind, respectively, and the \pm ambiguity arises out of the two possible signs for $\sin \theta_2$.

The derivatives of first and second order Chebyshev polynomials are known to be

$$\frac{dT_n}{dx} = nU_{n-1}(x) \tag{32}$$

$$\frac{dU_n}{dx} = \frac{(n+1)T_{n+1}(x) - xU_n(x)}{x^2 - 1},$$
(33)

and this implies that the first derivative of the shifted template is

$$\partial \mathbf{M}_{\theta_2}(x) = \sum_{n} \left[n \left(c_n U_{n-1}(u) \pm s_n \frac{T_n(u)}{\sqrt{1 - u^2}} \right) \cos nx + n \left(s_n U_{n-1}(u) \mp c_n \frac{T_n(u)}{\sqrt{1 - u^2}} \right) \sin nx \right]$$
$$\partial \mathbf{M}_{\theta_2}(x) = \sum_{n} \left[\partial A_n(u) \cos nx + \partial B_n(u) \sin nx \right]$$
(34)

Using the sums provided in Equations 26-30, writing A_n and B_n as as shorthand for $A_n(u)$ and $B_n(u)$, and employing Einstein summation notation, we have that

$$\langle (y - \bar{y})\mathbf{M}_{\theta_2} \rangle = A_n Y C^n + B_n Y S^n$$

$$\langle (y - \bar{y})\partial \mathbf{M}_{\theta_2} \rangle = \partial A_n Y C^n + \partial B_n Y S^n$$

$$\operatorname{Var}(\mathbf{M}_{\theta_2}^2) = A_n A_m C C^{nm}$$

$$+ 2A_n B_m C S^{nm} + B_n B_m S S^{nm}$$

$$(37)$$

$$Cov(\mathbf{M}_{\theta_2}, \partial \mathbf{M}_{\theta_2}) = A_n \partial A_m C C^{nm} + (A_n \partial B_m + B_n \partial A_m) C S^{nm} + B_n \partial B_m S S^{nm}$$
(38)

Equation 25 now becomes

$$0 = A_i A_j \partial A_k \left(Y C^i C C^{jk} - Y C^k C C^{ji} \right)$$

$$+ A_i A_j \partial B_k \left(Y C^i C S^{jk} - Y S^k C C^{ji} \right)$$

$$+ A_i B_j \partial A_k \left(Y C^i C S^{kj} + Y S^j C C^{ki} \right)$$

$$+ A_i B_j \partial B_k \left(Y C^i S S^{jk} + Y S^j C S^{ik} \right)$$

$$+ B_i B_j \partial A_k \left(Y S^i C S^{kj} - Y C^k S S^{ij} \right)$$

$$+ B_i B_j \partial B_k \left(Y S^i S S^{jk} - Y S^k S S^{ji} \right) .$$

$$(39)$$

Each $AA\partial A$, $AA\partial B$, ..., $BB\partial B$ can be expressed as

$$AA\partial A, \ AA\partial B, \ \dots = p(u) \pm (1 - u^2)^{-1/2} q(u), \quad (40)$$

where both p(u) and q(u) are polynomials in u. Therefore, Equation 39 can be expressed as

$$0 = (1 - u^2)\hat{p}^2(u) - \hat{q}^2(u) = \hat{P}(u)$$
 (41)

for some polynomials \hat{p}, \hat{q} , and \hat{P} .

We have derived an explicit, non-linear system of equations to solve for the parameters θ_1 , θ_2 , and θ_3 . Solving this system of equations requires finding the zeros of a polynomial $\hat{P}(u)$ at the given trial frequency.

2.1. Extending to multi-band observations

As shown in VanderPlas and Ivezić (2015), the multiphase periodogram (their $(N_{\text{base}}, N_{\text{band}}) = (0, 1)$ periodogram), for any model can be expressed as a linear combination of single-phase periodograms:

$$P^{(0,1)} = \frac{\sum_{k=1}^{K} \chi_{0,k}^2 P_k}{\sum_{k=1}^{K} \chi_{0,k}^2}$$
(42)

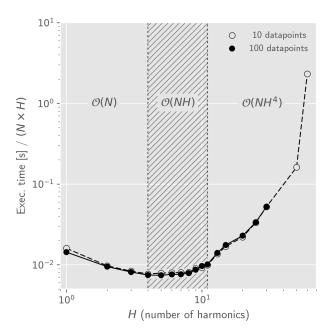


Figure 1. Computation time of FTP scaled by NH for different numbers of harmonics. For $H \lesssim 3$, FTP scales sublinearly in H (possibly due to a constant overhead per trial frequency, independent of H). When $3 \lesssim H \lesssim 11$, FTP scales approximately linearly in H, and when $H \gtrsim 11$ FTP approaches the $\mathcal{O}(H^4)$ scaling limit. where K denotes the number of bands. This means that the template periodogram can be applied to multi-band time series, which is crucial for experiments like LSST, SDSS, Pan-STARRS, and other current and future surveys.

2.2. Computational requirements

For a given number of harmonics H, the task of deriving \hat{P} requires a triple sum over H terms, with each sum requiring $\mathcal{O}(n_{\hat{P}})$ operations, where $n_{\hat{P}}$ is the order of \hat{P} . The order of \hat{P} can be shown to be

$$6H - \gcd((1 - u^2) \star \hat{p}^2, \hat{q}^2) \propto H,$$
 (43)

where $gcf(p_1, p_2)$ denotes the greatest common polynomial factor between polynomials p_1 and p_2 . Computing the coefficients of \hat{P} therefore scales as $\mathcal{O}(H^4)$ at each trial frequency.

The computational complexity of polynomial root finding is algorithm dependent. If we choose to perform singular value decomposition of the polynomial companion matrix¹, the root finding step scales as $\mathcal{O}(n_{\hat{P}}^3) = \mathcal{O}(H^3)$. The polynomial root-finding step should be asymptotically faster (for large H) than the computation of the polynomial coefficients.

When considering N_f trial frequencies, the polynomial computation and root-finding step scales as $\mathcal{O}(H^4N_f)$. The computation of the sums (Equations 26-30) scales as $\mathcal{O}(HN_f\log HN_f)$. Therefore, the entire template periodogram scales as

$$\mathcal{O}(HN_f \log HN_f + H^4N_f). \tag{44}$$

¹ The numpy.polynomial.polyroots function uses this method.

For a fixed number of harmonics H, the template periodogram scales as $\mathcal{O}(N_f \log N_f)$. However, for a constant number of trial frequencies N_f , the template algorithm scales as $\mathcal{O}(H^4)$, and computational resources alone limit H to reasonably small numbers $H \lesssim 15$ (see Figure 1).

3. IMPLEMENTATION

An open-source implementation of the template periodogram in Python is available.² Computing $\hat{P}(u)$ is done using the numpy.polynomial module (Jones et al. 01). The pynfft Python module, ³ which provides a Python wrapper for the NFFT library (Keiner et al. 2009), is used to compute the necessary sums for a particular time series.

No explicit parallelism is used anywhere in the current implementation, however the NFFT library optionally exploits OpenMP if compiled to do so (requires specifying the --enable-openmp flag when running configure) and certain linear algebra operations in Scipy may use OpenMP via calls to BLAS libraries that have OpenMP enabled.

All timing tests were run on a quad-core 2.6 GHz Intel Core i7 MacBook Pro laptop (mid-2012 model) with 8GB of 1600 MHz DDR3 memory. The NFFT library (version 3.2.4) was compiled with --enable-openmp, and the Scipy stack (version 0.18.1) was compiled with multithreaded MKL libraries. However, the slowest portion of the algorithm, computing the polynomial coefficients, uses the numpy.einsum function which is not multithreaded.

3.1. Comparison with gatspy

The gatspy (General tools for Astronomical Time Series in Python; VanderPlas (2016); VanderPlas and Ivezić (2015)) library provides template fitting routines, which rely on non-linear optimization at each trial frequency to pick the optimal parameters θ . We compare the accuracy and speed of the fast template periodogram with the template fitting procedure provided by the gatspy library.

Periodograms computed in Figures 2, 3, and 4 used simulated data. The simulated data has uniformly random observation times, with gaussian-random, homoskedastic, uncorrelated uncertainties. An eclipsing binary template, generated by fitting an eclipsing binary in the HATNet dataset (put in HATID for template) with a 10-harmonic truncated Fourier series.

3.1.1. Accuracy

Gatspy uses non-linear optimization at each trial frequency to solve for the best-fit amplitude, phase, and offset of the template. For weak signals or signals folded at the incorrect trial period, there may be a large number of local χ^2 minima in parameter space, and thus the optimization algorithm may have trouble finding the global minimum. The FTP, on the other hand, solves for the optimal parameters directly, and thus is able to recover optimal solutions even when the signal is weak or not present.

Figure 3 illustrates the accuracy improvement with FTP. For large $P_{\text{FTP}}(\omega)$, Gatspy and FTP agree well,

² https://github.com/PrincetonUniversity/FastTemplatePeriodogram

³ https://pypi.python.org/pypi/pyNFFT

while for $P_{\rm FTP} \lesssim 0.25$, FTP consistently finds better template fits than Gatspy. For many trial frequencies, Gatspy returns a periodogram value of $P_{\rm gatspy} = 0$, indicating no improvement over a constant fit, while FTP is able to find superior solutions at many of these frequencies.

Figure 4 compares FTP results obtained using the full template (H=10) with those obtained using smaller numbers of harmonics. The left-most plot compares the H=1 case (weighted Lomb-Scargle), which, as also demonstrated in Figure 2, illustrates the advantage of the template periodogram for known, non-sinusoidal signal shapes.

3.1.2. Computation time

FTP scales asymptotically as $\mathcal{O}(N_f H \log N_f H)$, however the computational time is usually dominated by computing polynomial coefficients and zero-finding, which scales as $\mathcal{O}(N_f H^4)$, even for very large numbers of frequencies $(N_f > 10^7)$.

of frequencies $(N_f > 10^7)$. Figure 5 shows that FTP achieves a factor of 3 speedup for even the smallest test case (15 datapoints), while for larger cases $(N \sim 10^4)$ FTP offers 2-3 orders of magnitude speed improvement over Gatspy.

4. DISCUSSION

Template fitting is a powerful technique for accurately recovering the period and amplitude of objects with a priori known lightcurve shapes. It has been used in the literature by, e.g. Sesar et al. (2016, 2010), to analyze RR Lyrae in the SDSS and PS1 datasets, where it has been shown to produce purer samples of RR Lyrae at a given completeness. The computational cost of current template fitting algorithms, however, limits their application to larger datasets or with a larger number of templates.

We have presented a novel template fitting algorithm that extends the Lomb-Scargle periodogram (Lomb 1976; Scargle 1982; Barning 1963; Vaníček 1971) to handle nonsinusoidal signals that can be expressed in terms of a truncated Fourier series with a reasonably small number of harmonics ($H \lesssim 10$).

The fast template periodogram (FTP) asymptotically scales as $\mathcal{O}(N_f H \log N_f H)$, while previous template fitting algorithms such as the one used in the gatspy library (VanderPlas 2016), scale as $\mathcal{O}(N_{\rm obs}N_f \sim N_f^2)$. However, the FTP effectively scales as $\mathcal{O}(N_f H^4)$, since the time needed to compute polynomial coefficients and perform zero-finding dominates the computational time for most practical cases $(N_{\rm obs} \sim N_f \lesssim 10^7)$. This effectively restricts the space of templates to those that are sufficiently smooth to be explained by a small number of Fourier terms.

FTP also improves the accuracy of previous template fitting algorithms, which rely on non-linear optimization at each trial frequency to minimize the χ^2 of the template fit. The FTP routinely finds superior fits, especially when the signal is weak.

An open-source Python implementation of the FTP is available at GitHub.⁴ The current implementation can be improved in several ways:

 $^{^4\} https://github.com/PrincetonUniversity/FastTemplatePeriodogram$

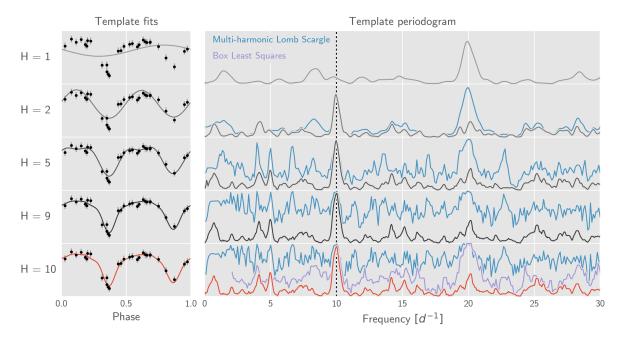


Figure 2. Template periodograms performed on a simulated eclipsing binary lightcurve (shown phase-folded in the left-hand plots). The top-most plot uses only one harmonic, equivalent to a Lomb-Scargle periodogram. Subsequent plots use an increasing number of harmonics, which produces a narrower and higher peak height around the correct frequency. For comparison, the multi-harmonic extension to Lomb-Scargle is plotted in blue, using the same number of harmonics as the FTP. The Box Least-Squares (Kovács et al. 2002) periodogram is shown in the final plot.

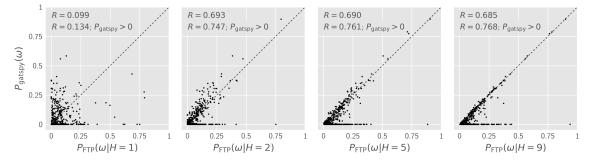


Figure 3. Comparing the gatspy template periodogram with the FTP using the same simulated data as shown in Figure 2. When H is sufficiently large, FTP consistently finds more optimal template fits than Gatspy. Gatspy numerically minimizes the χ^2 at each frequency, and sometimes gets caught in a local minimum. The FTP solves for the optimal fit parameters directly, and therefore is able to achieve greater accuracy than Gatspy.

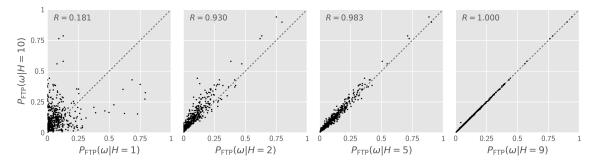


Figure 4. Comparing the template periodogram calculated with H=10 harmonics to the template periodogram using a smaller number of harmonics H<10. The template and data used to perform the periodogram calculations are the same as those shown in Figure 2.

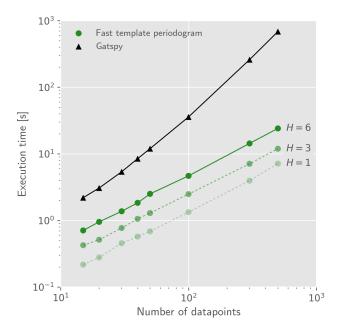


Figure 5. Computation time of FTP compared with Gatspy. For a 6-harmonic template and 15 observations, the FTP is three times faster than Gatspy. FTP scales roughly as $\mathcal{O}(N)$ (or, for large enough values of N, $\mathcal{O}(N\log N)$), while Gatspy scales as N^2 , thus the speedup of FTP over Gatspy scales linearly in N. For large time series of $N\approx 10,000$, FTP offers over three orders of magnitude speedup over Gatspy.

Survey	$N_{ m LC}$	$N_{ m obs}$	Refs.
CoRoT	1.5×10^{5}	53,000	
ASAS-3	2×10^{7}	500	
HATNet	5.6×10^{6}	10,000	
Gaia	10 ⁹	70	
SuperWASP	3.2×10^{7}	13,870	
OGLE-IV	10^{9}	5000	
LSST	$3.7 \times 10^{1}0$	825	

Table 1
Survey parameters used for Figure 6. Add references (if we decide to keep this figure)

- 1. Improving the speed of the polynomial coefficient calculations and the zero-finding steps.
- 2. Porting FTP to C/C++ and using CUDA to exploit GPU parallelism.
- 3. Extending the FTP to a multi-band periodogram to improve performance on sparsely sampled multi-band data (e.g. SDSS, LSST, Pan-STARRS).

As pointed out in VanderPlas and Ivezić (2015), current template fitting procedures are too slow to be practical for LSST-sized time-domain surveys. We attempt to quantify the improvement in computational efficiency for several important time-domain surveys, using estimated survey values for $N_{\rm obs}$, the number of observations per object, and $N_{\rm LC}$, the number of objects with lightcurves in the survey.

Figure 6 shows estimated computation time for a single template periodogram performed on the entirety of a given survey. For all surveys, the FTP improves compu-

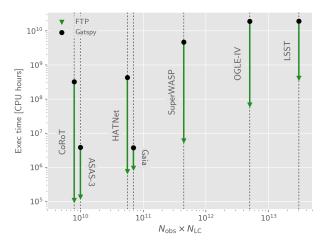


Figure 6. Computational resources needed for performing a single template periodogram (H=6) on an entire survey dataset. Our python implementation of FTP improves computational efficiency of template searches by orders of magnitude in most cases, and in one case by over three orders of magnitude (CoRoT). Parameters for $N_{\rm obs}$ and $N_{\rm LC}$ were estimated from publicly available information (see text).

tational efficiency in one case over three orders of magnitude, but typically between 2-3 orders of magnitude. Improving the existing implementation, and porting to C/C++ and CUDA, should further improve these numbers.

Template fitting remains prohibitively slow for practical applications to large time-domain surveys, but this work presents a possible shortcut that potentially could make template fitting a fast and valuable tool.

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