Persistence of marine populations under climate and fishing

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1 Abstract

When the climate changes, so does the location of habitats suitable for an organism's survival and reproduction. This change does not occur in isolation but appears on a background of other disturbances, making the study of interactions between stressors important. In order to understand how two disturbances, range shift and harvesting, interact and affect population persistence, we analyzed an integrodifference model that explicitly includes the mechanisms of dispersal and reproduction. We have shown how the critical 16 rates of harvesting and climate velocity that suffice to drive the population extinct depend 17 on the growth rate and dispersal kernel of the population. We measured the interaction between the stressors and find the disturbances interact nearly additively in the parameter 19 space that results in a stable population, with low positive synergy present only at the 20 greatest harvest rates and climate velocity. Using simulations, we introduced two 21 conservation techniques, threshold harvest rules and marine protected areas (MPAs), and have shown that these approaches can be effective management tools as they can mitigate the interaction between the two stressors.

Keywords: Climate change, fishing, integrodifference model, synergy, multiple disturbances

₇ 2 Introduction

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A number of stressors can disturb an ecosystem, and ecologists have quantified the
consequences of many of these of perturbations [Wilcove et al., 1998, Crain et al., 2008,
Darling and Côté, 2008]. Less work, however, has been done to measure the effects of
multiple stressors and the interactions between them. If disturbances interact synergistically,

- $_{32}$ a perturbation that has little effect when occurring individually may amplify the disturbance
- caused by a coincident perturbation [Crain et al., 2008, Darling and Côté, 2008, Nye et al.,
- ³⁴ 2013, Gurevitch et al., 2000]. In the most extreme (and worrying) cases, synergistic
- interactions between multiple stressors could drive a population extinct even though
- assessments of impacts individually predict the population to be robust (e.g. Pelletier et al.
- [2006]). If disturbances interact antagonistically, on the other hand, the effects of multiple
- stressors may be less than that predicted by the individual effects of the stressors. Since
- disturbances rarely occur in isolation, measuring the effects of multiple disturbances gives a
- better understanding of the likely impacts to the system [Doak and Morris, 2010, Fordham
- et al., 2013, Folt et al., 1999].
- ⁴² Climate change and fishing, two of the largest human impacts on the ocean [Halpern et al.,
- 2008, provide an important example of ecological disturbances occurring in unison. Marine
- 44 fish are already moving in response to climate change [Perry et al., 2005, Hiddink and ter
- 45 Hofstede, 2008, Rijnsdorp et al., 2009, Dulvy et al., 2008, Simpson et al., 2011, Pinsky et al.,
- 46 2013] and are projected to continue in the future [Kell et al., 2005, Mackenzie et al., 2007].
- 47 These shifting species are also subject to harvesting, among other disturbances including
- pollution, ocean acidification, habitat fragmentation, and invasive species [Wilcove et al.,
- ⁴⁹ 1998, Sala, 2000, Assessment, 2005, Pinsky et al., 2013, Barry et al., 1995, Nye et al., 2009].
- 50 Previous empirical work has found synergistic interactions between overfishing and
- temperature-driven range shifts [Ling et al., 2009] and synergistic interactions between
- ₅₂ warming temperatures, harvesting and connectivity have been identified in microcosm
- experiments [Mora et al., 2007]. This empirical work underscores the importance of
- understanding how range shifts and harvesting interact.
- 55 A common approach to predicting future population distributions has been to use

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bioclimatic-envelope models (also known as species distribution models – SDMs). These
   statistical models typically correlate presence-absence data with biophysical characteristics
   such as mean or maximum temperature, rainfall, or salinity, to predict how species ranges'
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   will differ under climate change [Elith et al., 2006, Guisan and Thuiller, 2005, Guisan and
   Zimmermann, 2000. Despite these models' widespread adoption, many authors have
   criticized SDMs as oversimplified as they lack species interactions, dispersal and
   reproductive processes [Kearney and Porter, 2009, Zarnetske et al., 2012, Robinson et al.,
   2011. Recent work on range shifts has addressed some of these gaps by explicitly including
   dispersal and reproduction [Berestycki et al., 2009, Zhou and Kot, 2011]. However these
   models only address one disturbance, climate-driven range shifts.
   Previous work has considered the joint impacts of climate and fishing, however these studies
   consider climate fluctuations (large anomalies around the mean) rather than directional
   shifts in temperature [Walters and Parma, 1996, King and McFarlane, 2006]. When studies
   consider the effects of climate-driven range shifts on fishing, the models are typically
   case-specific and detailed, integrating multiple drivers and disturbances [Cheung et al., 2010,
   Lindegren et al., 2010, Brown et al., 2010, Merino et al., 2010a, Plaganyi et al., 2011,
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   Ainsworth et al., 2011, Zhang et al., 2011, Barange et al., 2011, Howard et al., 2013. These
   predicted impacts are important for management and conservation planning [Allison et al.,
   2009, but the complexity of these models makes it difficult to understand the relative
   importance of particular drivers, disturbances, and interactions (but see Nye et al. [2013] for
   an approach using ecosystem-level models to discern relative importance of disturbances).
   Here we extend a previously studied model [Zhou and Kot, 2011] to a fish population subject
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   to climate-driven range shift and harvesting pressure. The model explicitly included
   reproduction and dispersal, two mechanistic processes central to species' responses to
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climate and fishing. Previous work has highlighted the importance of these two processes and their vulnerability to climate change [Fordham et al., 2013, Hastings et al., 2005]. We find the critical harvesting rate and climate velocity that drive the population extinct and how these critical rates depend on one another. We also show that climate-driven range shifts and fishing interact nearly additively, with low positive synergy at more extreme levels of the stressors. We also examine the efficacy of two different types of management strategies: threshold harvesting rules and marine protected areas (MPAs). MPAs are frequently recommended for conservation of biodiversity and improved fisheries yield [Gaines et al., 2010a], and we evaluate whether MPAs established for those purposes could improve species persistence when habitat shifts rapidly. Previous work has suggested protected areas can be a key form of climate insurance and can provide stepping stones to help species keep up with a changing environment [Thomas et al., 2012, Hannah et al., 2007]. We find that threshold harvesting rules remove the interaction between harvesting rates and climate velocity and that MPAs can help a species persist with higher harvesting pressure and slightly increase the maximum climate velocity with which a species can keep up.

96 3 Methods

We studied a model of the dynamics of a fish population constrained to a single,
one-dimensional habitat patch by their inability to reproduce outside of that area, as
introduced by Zhou and Kot [2011]. This viable habitat patch (hereafter 'patch') shifts at a
fixed velocity and harvest occurs at each point in space along the entire one-dimensional
world. We first analytically determined the harvesting rate climate velocity that would drive

the population extinct (hereafter the critical harvesting rate and critical climate velocity),
and then measured synergy by calculating the drop in biomass caused by each stressor both
individually and together. We then added threshold harvesting rules and marine protected
areas (MPAs) in numerical simulations of the model to determine how these management
strategies affect population persistence.

The Model In the model of Zhou and Kot [2011], the adults from the current year 3.1 107 produce offspring according to a recruitment function and these offspring disperse across the 108 one-dimensional world according to a dispersal kernel to become the next generation's 109 adults. We extend this model by additionally subjecting the adults to harvesting before they 110 produce offspring so that only a proportion of the fish survive to reproduce. These processes 111 recruitment, harvesting, and dispersal – are incorporated into an integrodifference model 112 to describe how the population changes over time. If $n_t(x)$ is the density of fish at position x 113 at time t, then the density of fish at the next generation is given by

$$n_{t+1}(x) = \int_{-\frac{L}{2}+ct}^{\frac{L}{2}+ct} k(x-y) f((1-h)n_t(y)) dy,$$

where h is the proportion of adults harvested, k(x-y) is the dispersal kernel giving the probability of a larva traveling from position y to position x, L is the length of the patch, and c is the rate at which it shifts across space. We used a Beverton-Holt stock-recruitment function for f(n),

$$f(n_t) = \frac{R_0 n_t}{1 + \left(\frac{R_0 - 1}{K}\right) n_t}$$

which gives the number of offspring produced by a population of size n (accounting for

density dependence). Here R_0 is the intrinsic growth rate and K is carrying capacity (see table 1 for a full description of parameters and functions).

Analyzing this kind of model becomes easier if the dispersal kernel is separable into its dependence on the source of larvae and its dependence on the destination of the larvae, i.e. if there are functions a_i, b_i such that $k(x - y) = \sum_{i=1}^{\infty} a_i(x)b_i(y)$. In our analyses, as in Latore et al. [1998], we used the separable Gaussian kernel given by

$$k(x-y) = \frac{1}{2\sqrt{D\pi}}e^{\frac{-(x-y)^2}{4D}}.$$

To derive analytical expressions, we approximated the kernel, as described Appendix A.3,
and analytical results for a separable sinusoidal kernel are also described in Appendix A.4.
We used simulations to analyze a Laplace dispersal kernel that is not amenable to this
method, as described below.

At equilibrium, the population will move in a traveling wave, where the density of fish at a
given point in space will change but the density of fish at a location relative to the shifting
patch will not. The traveling wave n^* must satisfy

$$n^*(\bar{x}) = \int_{-\frac{L}{2}}^{\frac{L}{2}} k(\bar{x} + c - \bar{y}) f((1-h)) n^*(\bar{y}) d\bar{y}, \tag{1}$$

where $\bar{x} \in \left[-\frac{L}{2}, \frac{L}{2}\right]$ describes the position within the patch [Zhou and Kot, 2011]. For a separable kernel, the equilibrium traveling pulse $n^*(x)$ must satisfy

$$n^*(x) = \sum_{i=1}^{\infty} a_i(x) \int_{-\frac{L}{2}}^{\frac{L}{2}} b_i(y - c) f((1 - h)n^*(y)) dy = \sum_{i=1}^{\infty} m_i a_i(x),$$
 (2)

where the m_i satisfy the recursive equations

$$m_i = \int_{-\frac{L}{2}}^{\frac{L}{2}} b_i(y - c) f\left((1 - h) \sum_{j=1}^{\infty} m_j a_j(x)\right) dy.$$
 (3)

136 [Latore et al., 1998].

Persistence If the population is harvested at low enough levels and the climate 137 velocity is slow enough, the population will be able to persist. There are threshold values of 138 the harvesting rate h and the climate velocity c such that if we increase the parameters 139 beyond these values, the population will be driven extinct. When the population is extinct, 140 the system is in equilibrium, i.e. there is a 'trivial' traveling pulse, $n^*(\bar{x}) = 0$ for all 141 $x \in \left[-\frac{L}{2}, \frac{L}{2}\right]$, which satisfies Equation (1). If a population persists, it must be able to avoid 142 extinction and grow even when small. If the trivial pulse is stable, the system will return to 143 extinction even after the introduction of a small population. If the trivial pulse is unstable, a 144 small population may increase and form a persistent population. Population persistence is 145 therefore equivalent to the trivial traveling pulse being an unstable equilibrium. We found 146 the critical parameters, h^* and c^* , by finding the parameters that make the trivial pulse 147 unstable. See Appendix A.1 for details. 148 Regardless of its exact functional form, the only property of the recruitment function that 149 determines whether or not a population can persist is how quickly recruitment increases 150 when the population size is near (but above) 0, which is equivalent to the intrinsic growth 151 rate $R_0 = f'(0)$. For each kernel, therefore, the population's ability to persist depends on 152 properties of the population itself – the expected distance a larva disperses $\langle d \rangle$ and the 153 intrinsic growth rate R_0 ; properties of the environment – the length of the viable patch L 154 and how quickly the environment shifts c; and the harvesting rate h. For a Gaussian kernel, 155 the critical rates c^* and h^* are those values of c and h such that

$$R_0(1-h)2\sqrt{2}\exp\left(\frac{-c^2}{8D}\right)\left[\operatorname{erf}\left(\frac{L-c}{2\sqrt{2D}}\right)-\operatorname{erf}\left(\frac{-L-c}{2\sqrt{2D}}\right)\right]=1.$$

We derive a similar expression for a sinusoidal kernel in the Appendix A.4. For both kernels, we can approximate the critical harvesting proportion by a function that looks like

$$h^* \sim 1 - \frac{1}{R_0} \cdot C(L, R_0) f(\langle d \rangle, c^2, L^2 + 3c^2),$$

where $C(L, R_0)$ is a decreasing function of the length of the viable patch and the intrinsic growth rate.

Calculating synergy Zhou and Kot [2011] only considered whether a shifting 159 environment will drive a population extinct. In order to quantify whether the two stressors 160 interact additively, synergistically, or antagonistically, we found the total biomass of the 161 population when it reached an equilibrium traveling pulse and compared this equilibrium 162 biomass in the presence and absence of each stressor individually or the two stressors 163 together. Equations (3) and (2) allowed us to numerically find the total biomass in the 164 equilibrium traveling pulse. 165 We used B_0 to denote the equilibrium biomass without either stressor, B_h the equilibrium 166 biomass with harvesting but a constant environment, B_c the equilibrium biomass with a 167 shifting environment but no harvesting, and B_{hc} the equilibrium biomass with both 168 stressors. For each stressor or combination of stressors, we found the drop in biomass caused 169 by stressor s, 170

$$E_{\rm s} = B_0 - B_{\rm s}$$
.

171 If the stressors do not interact, the drop caused by both stressors would be the sum of the
172 drops caused by either individually. The synergy is therefore defined as

$$S = E_{\rm hc} - (E_{\rm h} + E_{\rm c}).$$

173 If the stressors aggravate each other, the effect of both stressors is greater than we would
174 expect from considering either stressor individually and synergy is positive. If the stressors
175 alleviate each other, the effect of both stressors is less than we would expect from considering
176 either stressor individually and synergy is negative. If the effect of both stressors is exactly as
177 expected from considering either stressor individually, there is no interaction and no synergy.

3.4 Simulations We used simulations to extend the basic integrodifference model in two ways that make it analytically intractable. First, we examined the sensitivity of the model to choice of dispersal kernel by using the Laplace dispersal kernel,

$$k(x - y) = \frac{1}{2}be^{-b|x-y|},$$

a commonly used model of larval dispersal [Pinsky, 2011]. Second, we implemented two 181 management strategies, threshold rules and MPAs, to examine their effect on population 182 persistence and on the interactions between stressors. For every simulation we seeded the 183 world with 50 individuals at a single point, as in Zhou and Kot [2011]. We first ran through 184 150 generations in order for the population to reach equilibrium without harvesting or 185 climate shift. We then added harvesting pressure, allowed the population to again reach 186 equilibrium (150 generations), and finally added climate change by moving the viable patch. 187 We calculated equilibrium biomass as the mean biomass of 300 time steps once the difference 188

in biomass between successive generations was no greater than 0.1. Under the two management strategies, harvesting pressure was implemented differently. 190 With a threshold rule, we evaluated the population at each point in space to determine how 191 much harvesting should occur. If the population abundance was below the designated 192 threshold, no harvesting occurred. If the population exceeded the threshold, then we 193 harvested all the 'surplus' individuals. We introduce networks of MPAs into our simulations 194 by designating segments of space where the harvesting rate was equal to 0. MPAs are 195 typically designed to meet either fishery management or conservation goals [Agardy, 1994, 196 Holland and Brazee, 1996, Gaines et al., 2010b, thus their spacing and size differ. 197 Fisheries-oriented MPAs are often designed such that they maximize adult spillover into 198 fishable areas by creating many small reserves closely spaced [Hastings and Botsford, 2003, 199 Gaylord et al., 2005, Gaines et al., 2010b. To mimic this management scheme, we 200 implemented MPAs with a length of $\frac{1}{3}$ of the average dispersal distance and a distance of $\frac{2}{3}$ 201 of the average dispersal distance between them. Conservation-oriented MPAs seek to reduce 202 adult spillover by creating fewer larger protected areas [Hastings and Botsford, 2006, Gaines 203 et al., 2010b. To mimic this scheme we implemented MPAs with a length of 4 times the 204 average dispersal distance and a distance of 8 times the average dispersal distance between 205 them [Lockwood et al., 2002]. 206

207 4 Results

4.1 Interactions Between Stressors The critical climate velocity and harvest rate are inversely related. As the climate velocity shift c increases, the critical harvesting rate h^* decreases (Figure 1). This means that a harvesting rate that is sustainable in the absence of

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environmental shift may no longer be sustainable if the environment starts changing.
    Conversely, as the harvesting rate h increases, the critical climate velocity c^* decreases
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    (Figure 1). Thus as harvesting pressure increases, it becomes increasingly easy for a shifting
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   environment to drive the population extinct.
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   When the climate velocity or harvesting pressure exceed their critical rates (c^*, h^*)
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   respectively), the biomass of the population at equilibrium will be equal to 0. Before the
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   stressors reaches those thresholds, the equilibrium biomass of the population decreases as
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   either the harvesting pressure increases or the environmental shifts more quickly (Figure 1).
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   Our simulations confirm the analytical results with the critical speed c^* declining as the
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   critical harvest rate h^* increases and vice versa (Figure 3a).
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   It is always the case that increasing the intrinsic growth rate, R_0, increases the critical
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   climate velocity c^* and the critical harvesting rate h^*, since a population that grows more
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   quickly can recover more quickly from losses caused by these disturbances. However,
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    whether or not dispersing farther is better depends on how quickly the environment is
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   shifting (Figure 1). When the environment is shifting slowly, dispersing farther is
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   detrimental since many larvae will disperse too far away from the viable patch. When the
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   environment is shifting quickly, on the other hand, dispersing farther can help the
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   population persist because some larvae will disperse into the space that will become viable
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   shortly in the future. This affects the critical harvesting rate: at a low climate velocity, we
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   can more severely harvest populations that have a shorter dispersal distance than those that
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   disperse farther, whereas at a high climate velocity, we can more aggressively harvest
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   populations that disperse farther.
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   We found low levels of positive synergy between the two stressors in our analysis of the
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   Gaussian kernel (Figure 2). Where positive synergy exists, a doubly stressed population loses
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more biomass than we would predict from either stressor individually. The stressors interact
most strongly at high harvest and climate velocity rates, shortly before they drive the
population extinct. However, the synergistic loss in biomass is very low, meaning that these
stressors interact more or less additively. We found similar analytical results for a sinusoidal
dispersal kernel, which indicates that this result is robust to changes in the dispersal kernel.

Management strategies Without any management strategies, we found that the 240 more severely we harvest the population, a slower climate velocity will suffice to drive the 241 population extinct. However, when we put thresholds in place, a small population can 242 always escape harvesting pressure and the critical climate velocity c^* no longer depends on 243 the harvesting rate (Figure 3). In other words, as long as there is some threshold below 244 which harvesting is not allowed, there is a constant critical climate velocity that only 245 depends on the growth rate, length of the viable patch, and average dispersal distance. 246 With either type of MPA strategies examined (many small versus few large), the population 247 withstood combinations of higher climate velocities and harvesting rates (Figure 3). At 248 lower climate velocities, MPAs spaced more than one average dispersal distance apart 240 resulted in larger fluctuations of population biomass relative to small, closely spaced, MPAs. 250 As climate velocities increase, for both MPA strategies, the mean population abundance 251 declines but the population experiences less extreme oscillations in abundance. Since 252 minimum population biomass is increased, the population is a larger buffer to possible 253 extinction in a stochastic environment.

5 Discussion

Understanding interactions among disturbances will help to design management for populations subjected to these stressors. The co-occurrence of climate change-driven range 257 shifts and fishing mean that there is the potential for synergistic interactions, which have 258 been largely unexamined. Here we have analyzed a general model that incorporates dispersal 250 and reproduction to examine how climate and harvesting interact in their effects on species 260 persistence and biomass. 261 For each dispersal kernel we studied, we found that the higher the growth rate and the more 262 the mean dispersal distance matches the climate velocity, the better a population can persist 263 under harvesting and climate change. Further, we found a negative relationship between the 264 critical harvesting rate and the climate velocity. That is, the more quickly the environment 265 shifts the less harvesting it takes to drive the population extinct. This is evidence that the 266 stressors interact since each stressor's ability to drive the population extinct depends on the 267 severity of the other stressor. 268 To quantify the interaction between the stressors, we measured the synergy between their 260 effects on population biomass. We found positive synergy between the stressors and that the synergy is greatest in the region of parameter space where the equilibrium biomass is 271 smallest. We chose to measure the effect of each stressor by the absolute drop in biomass 272 caused by the stressor, and we used the sum of the individual effects for our null prediction 273 of the effect of both stressors, as in Crain et al. [2008], Darling and Côté [2008], Nye et al. 274 [2013]. In general, measuring synergy against an additive null prediction is more 275 conservative than measuring synergy multiplicatively: the presence of additive synergy 276 implies multiplicative synergy, but not vice versa [Crain et al., 2008, Folt et al., 1999]. Since 277 we found small levels of positive additive synergy between the two stressors, other measures

of synergy might show even higher levels of interaction. Worryingly, we find the highest synergy in those populations whose persistence is most tenuous. This means that harvesting 280 levels or climate velocity that are sustainable individually together can drive a population to 281 extinction. However the drop in biomass caused by both stressors was never much higher 282 than the null prediction, i.e. synergistic effects were quite small. 283 Despite the absence of synergy in our analysis, whether or not we should assume that synergy 284 is unlikely to exist between climate velocity and harvesting remains to be seen. Synergy 285 between harvesting and the effects of climate change has been identified in experimental 286 populations [Mora et al., 2007], and observationally at both the population [Planque et al., 287 2010a], and ecosystem level [Kirby et al., 2009, Planque et al., 2010a]. Some of the 288 discrepancies may be due to the ways in which climate was measured. In the experimental 289 populations, effects of climate were mimicked by increased temperatures, and organisms were 290 unable to relocate to thermal optima. Synergy was identified between warming and 291 harvesting but not between habitat fragmentation [Mora et al., 2007], which may be more 292 similar to the range shift we analyzed in our theoretical model. While we did find (very) low 293 levels of positive synergy, we did not find as much as predicted from these empirical studies. 294 However, these previous results are not directly comparable to ours because they focus on 295 different aspects of climate change, e.g. warming temperature [Mora et al., 2007, Kirby 296 et al., 2009] or a more variable climate [Planque et al., 2010a]. Additionally, while we can 297 isolate the affects of climate shift and harvesting in our simple analytical model, there are 298 other forces acting on real populations that may produce the observed synergistic effects. 290 Absence of synergy does not mean absence of effect, and our results suggest that particular 300 combinations of harvesting and climate velocity will affect some species more than others. 301 Species with a higher reproductive rate and a longer average dispersal distance will better 302

track a high climate velocity relative to a species that has a low reproductive rate and short 303 dispersal distance (Figure 1). The finding that a higher reproductive rate can sustain higher 304 climate velocities and harvesting rates is intuitive, especially because harvesting rate and 305 reproductive rate cancel each other out. However it is worth pointing out that a higher 306 reproductive rate can be generated either by shorter generation times or higher fecundity. 307 Finding that species with shorter generation times can better keep up with shifts in climate 308 is in agreement with empirical work which has found that fish which shifted in response to 309 warming in North Sea had faster life histories than non shifting species [Perry et al., 2005]. 310 While higher reproductive rates improved a population's ability to persist, increasing 311 dispersal distances did not necessarily. At low speeds, we found that a short dispersal 312 dispersal distance improved the maximum harvesting rate a population could sustain while 313 at higher speeds a longer dispersal distance improved the maximum climate velocity in 314 which the population could persist (Figure 1). This is because when climate is shifting 315 slowly, a large dispersal distance sends most offspring ahead of the patch, while with faster 316 climate velocities a long dispersal distance allows the population to make it to the new patch 317 (Figure 1). Thus climate velocity will selectively favor species with dispersal distances best 318 matched to the rate of shift. 319 We also examined whether frequently recommended management approaches, MPAs and 320 harvest control rules, ensure species persistence. With these management strategies we 321 found increases in the population's biomass at equilibrium and an improved ability to 322 persist. We found that a threshold harvesting rule alleviates interactions between the two 323 stressors. Thresholds have this effect as the management approach effectively prevents 324 harvesting of the leading edge, which allows colonization to occur as if these individuals were 325 moving into un-fished areas. It's interesting to note that novel, low abundance species are 326

commonly unregulated in fisheries systems; so in order to decouple the additive effects of harvest and climate change, management would have to reverse this paradigm by allowing 328 no harvest of shifting species until they had become established in new areas. 329 Unlike thresholds, MPAs are explicitly spatial. Previous work has advanced protected areas 330 as a way to help organisms keep pace with range shifts, as well as to ameliorate 331 anthropogenic disturbances like harvesting and habitat fragmentation [Lawler et al., 2010, 332 Hannah et al., 2007, Botsford et al., 2001, Gaylord et al., 2005, Hastings and Botsford, 2003, 333 Thomas et al., 2012. Our results show that both threshold and MPAs increase the 334 equilibrium biomass at a given climate velocity, which support their use as a tool to 335 ameliorate the effect of climate velocity. However for MPAs the details mater: few, large 336 MPAs caused increased variability at low climate velocities while many smaller MPAs 337 maintained a population bounded farther from extinction (see Figure 1, Appendix A.6). 338 Finally, with sufficiently high harvesting pressure, few, large MPAs rescued populations at 339 intermediate speeds. With intermediate speeds, the population was able to reach a protected 340 area fast enough to avoid extinction, and the protected area was large enough to allow a 341 partial rebuilding of the population before it moved out the other side. However this effect 342 disappears as speed continues to increase, suggesting that understanding the relationship 343 between climate velocity, dispersal distance and reproductive rate are important parameters 344 in designing management strategies effective under both climate change and harvesting 345 pressure. 346 The advantage of a simple model like ours is that it is general enough to be applied to a 347 number of systems. However, this simplistic approach requires that we ignore complexities 348 known to be present in marine fisheries. For example, we do not include Allee effects, so that 349 even if the population shrank to low levels it was possible for it to persist over time. 350

However, with Alee effects we expect qualitatively similar results. An Allee effect would make it harder for populations to colonize new areas and add a threshold below which 352 fishing drives the population to extinction. Thus an Allee effect would change lower the 353 critical harvest rates and climate velocity, but we do not expect the additive nature of the 354 interaction between climate and harvesting to change. We also did not include age structure 355 in our model. The effects of both harvesting and climate change may be different across 356 different age classes and may destabilize the system in complicated ways, including 357 resonance [Botsford et al., 2011, Planque et al., 2010b]; and we leave this additional 358 complexity for future work. Similarly, we did not include any mechanisms aside from larval 359 dispersal by which the population could keep up with a shifting climate. Besides these 360 species-specific extensions, this modeling framework could be extended to consider species 361 interactions, especially predator-prey pairs. By introducing a predatory species, we would be 362 imposing yet another stressor on the focus species [Ling et al., 2009, Gurevitch et al., 2000] 363 and we are interested in measuring the interaction between the effects of this stressor and 364 the two we consider here. 365 Using a simple mechanistic model like the one we present here provides a useful framework 366 for incorporating additional ecological complexities which can mediate species persistence 367 under multiple disturbances. Using this modeling framework as a starting point, we believe 368 exploring how species interactions, age structure, and additional disturbances (e.g. 369 physiological response to temperature) affect population viability will improve our 370 predictions and help us to understand whether species will persist under predicted climate 371 and harvesting regimes. Finally, this work can help make general predictions as to whether 372 specific life histories offer selective advantages over others as harvesting and range shifts 373 increase and highlights the importance of considering stressors in combination as outcomes 374

can deviate from what we would predict in isolation. This is especially true for management strategies which may result in unanticipated effects such as large fluctuations associated with big, distant MPAs shown here. While the management strategies only change harvesting practices and do not directly address the effects of climate change, understanding how they ameliorate synergistic affects between harvesting and range shifts will help to better implement harvesting rules and place protected areas. This is encouraging evidence that a single set of of management practices may help to protect marine populations from both harvesting and climate change.

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606 6 Tables

Table 1: Table of variables used in the text

Variable	Definition
$\overline{n_t(x)}$	density of fish at position x at time t
$n^*(\overline{x})$	density of fish at equilibrium at position \overline{x} relative to the patch
k(x-y)	dispersal kernel, the probability of larva traveling from position y to position x
$\langle d \rangle$	expected distance traveled by larva
f(n)	recruitment function, the number of offspring produced by a population of size n
R_0	intrinsic growth rate, $R_0 = f'(0)$
h	proportion of adults harvested
L	patch length
c	climate velocity

607 Figure Legends

Figure 1: (a) The critical harvesting rate on the y-axis as a function of the climate velocity 608 on the x-axis. Black lines correspond to a growth rate of $R_0 = 3$, red to $R_0 = 7$, and blue to 609 $R_0 = 10$. Solid lines correspond to an average dispersal distance $\langle d \rangle = 0.1$ and dashed lines 610 correspond to an average dispersal distance $\langle d \rangle = 0.25$. These results are from an approxi-611 mated Gaussian dispersal kernel with L=1. (b) The equilibrium biomass of the population 612 as a function of the climate velocity on the x-axis and the harvesting rate on the y-axis. 613 These results are from a Gaussian dispersal kernel with parameters $L=1, R_0=5, \langle d \rangle=0.5$. 614 615 **Figure 2**: Positive synergy between the two stressors. The x-axis shows the climate velocity, 616 the y-axis shows the harvesting rate, and the color indicates the loss in biomass in the doubly 617 stressed population in excess of the sum of the losses caused by each stressor individually, $E_{\rm hc}$ 618 $E_{\rm h}-E_{\rm c}$. This excess loss, on the order of .05, is small in comparison to the total biomass, which 619 can be greater than 40. These results are from an approximated Gaussian dispersal kernel with 620 parameters L = 1, $R_0 = 5$, $\langle d \rangle = 0.5$. 621 622 Figure 3: The equilibrium biomass of the population as a function of the climate velocity on 623

figure 3: The equilibrium blomass of the population as a function of the climate velocity on the x-axis and the harvesting rate on the y-axis with and without management strategies. (a) MPAs (b) Threshold harvesting levels. These results are from a simulation with a Laplacian dispersal kernel with parameters L = 1, $R_0 = 5$, K = 100, and $\langle d \rangle = 2$.

7 Figures

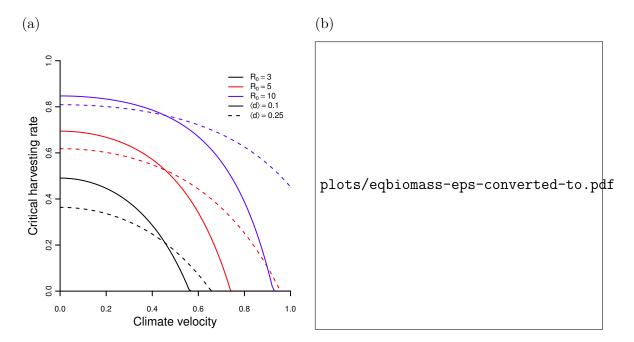


Figure 1

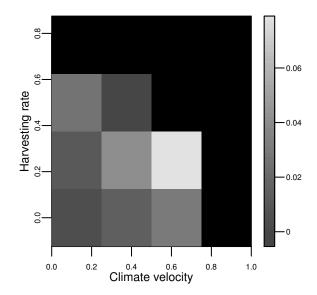


Figure 2

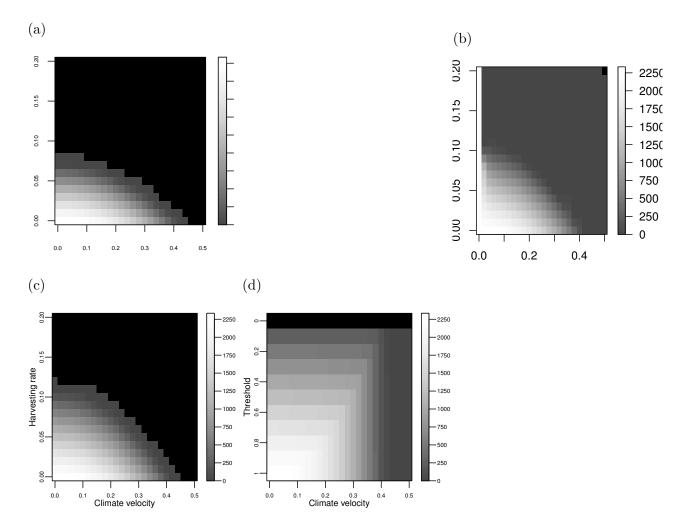


Figure 3