

Species persistence under climate and fishing

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1 Abstract

When the climate changes, the habitat in which organisms can survive and reproduce moves through space. This change does not occur in isolation but rather appears on a background of other disturbances. We used an integrodifference model explicitly accounting for dispersal, reproduction, to examine how two disturbances, range shift and harvesting, interact and govern population persistence. We found threshold rates of harvesting and of environmental shift such that more increasing either disturbance will drive the population extinct and studied how these critical parameters depend on the growth rate and dispersal behavior of the population. We then measured the interaction between the stressors and we found low but positive synergy between the two stressors: harvesting aggravates the population's sensitivity to a shifting range. Finally, we introduced two conservation techniques into simulations of the population model – threshold harvest rules and marine protected areas (MPAs) – and found that these approaches could mitigate, under some circumstances, the negative interaction of the two stressors.

Keywords: Climate change, fishing, integrodifference model, synergy, multiple disturbances

2 Introduction

There are many stressors that can disturb an ecosystem. Ecologists have quantified the effects of a number of stressors individually [Wilcove et al., 1998, Crain et al., 2008, Darling and Côté, 2008], but less work has been done to measure the effects of multiple stressors and the interactions between them. If disturbances interact synergistically, a perturbation that has little effect when it occurs individually may amplify the disturbance caused by a coincident perturbation [Crain et al., 2008, Darling and Côté, 2008, Nye et al., 2013, Gurevitch et al., 2000]. In the most extreme (and worrying) cases, synergistic interactions between multiple stressors will drive a population extinct even though it could persist in the face of any single stressor (i.e. Pelletier et al. [2006]). If disturbances interact antagonistically, on the other hand, the effects of multiple stressors may be less than that predicted by any stressor individually. Since disturbances rarely occur in isolation, it is important to measure the synergy between disturbances in order to understand how a system will be affected by their presence and to understand when multiple disturbances will drive a population extinct [Doak and Morris, 2010, Fordham et al., 2013, Folt et al., 1999]. Climate change and fishing have been identified as the two largest human impacts on the ocean [Halpern et al., 2008]. They therefore present an important case study of how disturbances interact in their effects on biological populations. Further, understanding these interactions will be crucial to managing populations subjected to both of these disturbances. Marine fish are already moving in response to climate change [Perry et al., 2005, Hiddink and ter Hofstede, 2008, Rijnsdorp et al., 2009, Dulvy et al., 2008, Simpson et al., 2011] and they are projected to continue moving in the future [Kell et al., 2005, Mackenzie et al., 2007]. Species that are likely to undergo or already undergoing shifts in

range are also subject to harvesting, in addition to many other disturbances including pollution, ocean acidification, habitat fragmentation, and invasive species [Wilcove et al., 1998, Sala, 2000, Assessment, 2005, Pinsky et al., 2013, Barry et al., 1995, Nye et al., 2009]. Empirical case studies have identified interactions between overfishing and temperature-driven range shifts that suggest synergy in the magnitude of the disturbance [Ling et al., 2009] and have demonstrated synergistic effects in microcosm experiments between warming temperatures, harvesting and connectivity [Mora et al., 2007]. This empirical work underscores the importance of understanding how range shifts and harvesting interact.

A common approach to predicting future population distributions under climate change has been to use bioclimatic-envelope models (also known as species distribution models – SDMs). These statistical models typically correlate presence-absence data with biophysical characteristics such as mean or maximum temperatures, rainfall, or salinity, to explain and predict how species ranges’ will differ under climate change [Elith et al., 2006, Guisan and Thuiller, 2005, Guisan and Zimmermann, 2000]. Despite these models’ widespread adoption, SDMs have frequently been criticized as oversimplified as they lack species interactions, dispersal and reproductive processes [Kearney and Porter, 2009, Zarnetske et al., 2012, Robinson et al., 2011]. Recent work on range shifts has addressed some of these gaps by explicitly including dispersal and reproduction [Berestycki et al., 2009, Zhou and Kot, 2011]. However these models only address one disturbance: that of climate-driven range shifts.

Work considering the joint impacts of climate and fishing often consider climate fluctuations (large anomalies around the mean) rather than directional changes in climate [Walters and Parma, 1996, King and McFarlane, 2006]. When the effects of climate-driven

range shifts on fishing are considered, the models are typically case-specific and detailed, integrating multiple drivers and disturbances [Cheung et al., 2010, Lindegren et al., 2010, Brown et al., 2010, Merino et al., 2010a,b, Plaganyi et al., 2011, Ainsworth et al., 2011, Zhang et al., 2011, Barange et al., 2011, Howard et al., 2013]. These predicted impacts are important for management and conservation planning [Allison et al., 2009], however these models are so complex that understanding the relative importance of particular drivers, disturbances, and interactions is difficult (but see Nye et al. [2013] for an approach using ecosystem-level models to discern relative importance of disturbances). Here we develop models of intermediate complexity [sensu Gaylord et al., 2005] that can help clarify the importance of two interacting disturbances: temperature-driven range shifts and harvest. Here we constructed an analytical model of a fish population subject to both harvesting and climate change-induced range-shift. We explicitly included two mechanistic processes central to species' responses to climate and fishing: reproduction and dispersal. Previous work has highlighted the importance of these two processes and their vulnerability to climate change [Fordham et al., 2013, Hastings et al., 2005]. We found that climate-driven range shifts and fishing interact synergistically, when their effects are measured by absolute drop in biomass. We also found how the threshold level of harvesting that suffices to drive the population extinct depends on how quickly the range is shifting. We also examined the effect of threshold harvesting rules and marine protected areas (MPAs) on species persistence. Protected areas have been suggested as a key form of climate insurance and stepping stones to help species keep up with a changing environment [Thomas et al., 2012, Hannah et al., 2007]. MPAs are frequently recommended for conservation of biodiversity and improved fisheries yield [Gaines et al., 2010a], and we evaluate whether MPAs established for those purposes could improve species persistence

when habitat is shifting rapidly. We found that MPAs can help a species persist with higher harvesting pressure, but does not change the maximum climate velocity with which a species can keep up.

3 Methods

We studied the dynamics of a fish population constrained to a single, one-dimensional habitat patch by their inability to reproduce outside of the patch. This viable habitat patch (here after ‘patch’) is shifting at a fixed velocity and fish at each point in space can be harvested. We first measured the drop in biomass caused by range shifts, harvesting, and both stressors together in order to determine whether they interact synergistically. We then determined the climate velocity and harvesting rate that would drive the population extinct. We finally implemented marine protected areas (MPAs) and threshold harvesting rules in numerical simulations of the model to determine how these management strategies affect population persistence.

3.1 The Model In the model of Zhou and Kot [2011], the adults from the current year produce offspring according to a recruitment function, and these offspring disperse across the one-dimensional world according to a dispersal kernel to become the next generation’s adults. We extend this model by additionally subjecting the adults to harvesting before they produce offspring so that only a proportion of the fish survive to reproduce. These processes— recruitment, harvesting, and dispersal— are incorporated into an integrodifference model to describe how the population changes over time. If $n_t(x)$ is the density of fish at position x at time t , then the density of fish at the next generation is given by

$$n_{t+1}(x) = \int_{-\frac{L}{2}+ct}^{\frac{L}{2}+ct} k(x-y)f((1-h)n_t(y))dy, \quad (1)$$

where h is the proportion of adults harvested, $f(n)$ is the recruitment function giving the number of offspring produced by a population of size n (accounting for density dependence), $k(x-y)$ is the dispersal kernel giving the probability of a larva traveling from position y to position x , L is the length of the patch, and c is the rate at which it shifts across space. We chose to use a Beverton-Holt recruitment function,

$$f(n_t) = \frac{R_0 n_t}{1 + \left(\frac{R_0-1}{K}\right) n_t}.$$

Regardless of the exact functional form of the recruitment function, a critical parameter of the recruitment function in determining population persistence is how quickly recruitment increases when the population size is near (but above) 0, which is equivalent to the intrinsic growth rate, $R_0 = f'(0)$. Analyzing this kind of model becomes easier if the dispersal kernel is separable into its dependence on the source of larvae and its dependence on the destination of the larvae, i.e. if there are functions a_i, b_i such that $k(x-y) = \sum_{i=1}^{\infty} a_i(x)b_i(y)$ and we use such a kernel in our analytical expressions. We provide a list of variables and functions in Table 1.

At equilibrium, the population will be described by a traveling wave, where the density of fish at a given point in space will change but the density of fish at a location relative to the shifting patch will not. We sought to describe how the population is distributed over the viable patch as it shifts through the world in order to study the size of the population at equilibrium and whether or not the population could persist. The traveling wave n^* must satisfy

$$n^*(\bar{x}) = \int_{-\frac{L}{2}}^{\frac{L}{2}} k(\bar{x} + c - \bar{y}) f((1 - h)) n^*(\bar{y}) d\bar{y}, \quad (2)$$

where $\bar{x} \in \left[-\frac{L}{2}, \frac{L}{2}\right]$ describes the position within the patch [Zhou and Kot, 2011]. Zhou and Kot [2011] only considered whether a shifting environment will drive a population extinct, however to quantify the effects of both a shifting environment and harvesting pressure we must also find the total biomass in the equilibrium traveling wave. For a separable kernel, the equilibrium traveling pulse $n^*(x)$ must satisfy

$$n^*(x) = \sum_{i=1}^{\infty} a_i(x) \int_{-\frac{L}{2}}^{\frac{L}{2}} b_i(y - c) f((1 - H(n^*(y))) n^*(y)) dy = \sum_{i=1}^{\infty} m_i a_i(x), \quad (3)$$

where the m_i satisfy the recursive equations

$$m_i = \int_{-\frac{L}{2}}^{\frac{L}{2}} b_i(y - c) f\left((1 - h) \sum_{j=1}^{\infty} m_j a_j(x)\right) dy. \quad (4)$$

[Latore et al., 1998]. Equation 4 allowed us to find the values of m_i numerically. We then found the total biomass in the equilibrium traveling pulse by using these m_i and integrating Equation 3.

3.2 Calculating Synergy In order to quantify whether the two stressors are interacting additively, synergistically, or antagonistically, we found the total biomass of the population when it reached an equilibrium traveling pulse and compared this equilibrium biomass in the presence and absence of each stressor individually or the two stressors together. We used B_0 to denote the equilibrium biomass without either stressor, B_h the equilibrium biomass with harvesting but a constant environment, B_c the equilibrium biomass with a shifting environment but no harvesting, and B_{hc} the equilibrium biomass with both

148 stressors. For each stressor or combination of stressors, we found the drop in biomass
 149 caused by stressor s ,

$$E_s = B_0 - B_s.$$

150 If the stressors do not interact, the drop caused by both stressors would be the sum of the
 151 drops caused by either individually. The synergy is therefore defined as

$$S = E_{hc} - (E_h + E_c).$$

152 If the stressors aggravate each other, the effect of both stressors is worse than would be
 153 expected from considering either stressor individually, and synergy is positive. If the
 154 stressors alleviate each other, the effect of both stressors is better than would be expected
 155 from considering either stressor individually, and synergy is negative. If the effect of both
 156 stressors is exactly as expected from considering either stressor individually, there is no
 157 interaction and no synergy.

158 **3.3 Persistence** One possible equilibrium traveling wave that solves Equation 2 is the
 159 ‘trivial’ traveling pulse, $n^*(\bar{x}) = 0$ for all $x \in \left[-\frac{L}{2}, \frac{L}{2}\right]$, i.e. a patch with no fish in it. If a
 160 population becomes very small (or if we introduce a small population), one of two things
 161 can happen. First, the population may crash and the trivial traveling pulse without any
 162 fish may appear again. Second, those small numbers may increase and form a stable
 163 population. In this sense, a small population can be thought of as a perturbation to the
 164 trivial traveling pulse. If the trivial pulse is stable, the system will return to the trivial
 165 pulse even after a perturbation in the form of the introduction of a small population. If a

population is to persist, even when it is small it must be able to avoid extinction and grow. For this to be the case, the trivial pulse must be unstable to small perturbations. We would like to know the rate of environmental shift and the harvesting rate such that as long as the environment moves more slowly or we harvest less severely than those parameters, then the population will be able to persist. We call these, respectively, the critical rate of environmental shift, c^* , and the critical harvesting rate, h^* . We found these rates by finding the parameters that make the trivial pulse unstable. In our analyses, as in [Latore et al., 1998], we used the separable Gaussian kernel given by

$$k(x - y) = \frac{1}{2\sqrt{D\pi}} e^{\frac{-(x-y)^2}{4D}}.$$

To find analytical results about the Gaussian kernel, we approximated the kernel, as described in the Appendix. Analytical results for a separable sinusoidal kernel are also described in the Appendix. We used simulations to analyze a Laplace dispersal kernel that is not amenable to this method, as described below. For each kernel, the population's ability to persist depends on properties of the population itself— the expected distance a larva disperses ($\langle d \rangle$) and the intrinsic growth rate (R_0); properties of the environment— the length of the viable patch (L) and how quickly the environment is shifting (c); and the harvesting rate (h). Whereas equilibrium biomass depends on the function form of recruitment, population persistence only depends on the intrinsic growth rate R_0 . If the environment shifts more quickly than the critical rate c^* or the population is harvested at more than the critical rate h^* then the population will not be able to persist, as described in the Appendix. For a Gaussian kernel, the critical rates c^* and h^* are those values of c and h such that

$$R_0(1-h)2\sqrt{2}\exp\left(\frac{-c^2}{8D}\right)\left[\operatorname{erf}\left(\frac{L-c}{2\sqrt{2D}}\right)-\operatorname{erf}\left(\frac{-L-c}{2\sqrt{2D}}\right)\right]=1.$$

187 A similar expression for a sinusoidal kernel is derived in the appendix. For both kernels,
188 the critical harvesting proportion can be approximated by a function that looks like

$$h^* \sim 1 - \frac{1}{R_0} \cdot C(L, R_0) f(\langle d \rangle, c^2, L^2 + 3c^2), \quad (5)$$

189 where $C(L, R_0)$ is a decreasing function of the length of the viable patch and the intrinsic
190 growth rate.

191 **3.4 Simulations** We used simulations to extend the basic integrodifference model in two
192 ways that make it analytically intractable. First, we examined the sensitivity of the model
193 to choice of dispersal kernel by using the Laplace dispersal kernel,

$$k(x-y) = \frac{1}{2} b e^{-b|x-y|},$$

194 a commonly used model of larval dispersal [Pinsky, 2011]. Second, we examined harvesting
195 rules more complex than harvesting a constant proportion of the population. Whereas
196 population persistence in the analytical model does not depend on the functional form of
197 recruitment f , to perform simulations we must specify a recruitment function. Again, we
198 chose to use a Beverton-Holt function. In the first generation, we seeded the world with 50
199 individuals at a single point, as in [Zhou and Kot, 2011]. We first ran through 150
200 generations in order for the population to reach equilibrium without harvesting or climate
201 shift. We then added harvesting pressure, allowed the population to again reach
202 equilibrium, and finally added climate change by moving the viable patch. Equilibrium

203 biomass is calculated as the mean biomass of 300 time steps once the difference in biomass
 204 between time step t and $t + 1$ was no greater than 0.1.

205 We added harvesting pressure by harvesting a constant proportion of the population, in
 206 order to confirm our analytical results. We then evaluated the effect of a threshold harvest
 207 rule and marine protected areas (MPAs). With a threshold rule, we evaluated the
 208 population at each point in space to determine how much harvesting should occur. If the
 209 population abundance was below the designated threshold, no harvesting occurred. If the
 210 population exceeded the threshold, then a proportion of the ‘surplus’ individuals were
 211 harvested.

212 MPAs are a form of management designed to check the impact of fishing on targeted
 213 populations and are typically designed to meet either conservation or fishery management
 214 goals [Agardy, 1994, Holland and Brazee, 1996, Gaines et al., 2010b]. To implement an
 215 MPA management strategy in our model, we examine the effect of both of these commonly
 216 advocated approaches. While both conservation and fisheries oriented MPA schemes align
 217 in their goal of maintaining a sustainable fished population, they differ in desired level of
 218 adult spillover. Fisheries-oriented MPAs are often designed such that they maximize adult
 219 spillover into fishable areas by creating many small reserves closely spaced [Hastings and
 220 Botsford, 2003]. The converse of this is the goal of conservation-oriented MPAs which seek
 221 to reduce adult spillover by minimizing the ratio between the reserve edge length relative to
 222 area protected [Gaines et al., 2010b].

223 Networks of MPAs were introduced into our simulations by designating segments of space
 224 in which harvesting was forbidden (i.e. harvesting rates were equal to 0).

225 Conservation-oriented MPAs, are frequently large and rarely part of a larger network of
 226 reserves [Hastings and Botsford, 2003]. For solitary reserves to be successful at protecting

target species, they must encompass self-sustaining fish populations [Hastings and Botsford, 2006, Gaines et al., 2010b]. As such modeling studies estimate that isolated reserves must be at least as large as the average dispersal distance for the targeted fish species [Lockwood et al., 2002, Hastings and Botsford, 2003, Botsford et al., 2001, Gaines et al., 2010a]. To implement conservation MPAs we created reserves with a length of 4 times the average dispersal distance and had a distance of 8 times the average dispersal distance between them to ensure that populations would be self sustaining and not dependent on other dispersal for other reserves [Lockwood et al., 2002].

Previous work has shown that if MPAs are to benefit fisheries, the reserves should be broken into a network, closely spaced to maximize adult spillover into fishable areas and export of larvae from reserve to reserve [Hastings and Botsford, 2003, Gaylord et al., 2005, Gaines et al., 2010b]. To mimic this management scheme, MPAs had a length of $\frac{1}{3}$ of the average dispersal distance and had a distance of $\frac{2}{3}$ of the average dispersal distance between them.

4 Results

4.1 Interactions Between Stressors We found positive synergy between the two stressors in our analysis of the Gaussian kernel (Figure 2). In other words, a doubly stressed population loses more biomass than would be predicted from either stressor individually. The stressors interact most strongly when they are both high, shortly before they drive the population extinct. We found similar analytical results for a sinusoidal dispersal kernel and our simulations with a Laplace kernel produce similar results which indicates that this result is robust to changes in the dispersal kernel. We chose to measure the effect of each

249 stressor by the absolute drop in biomass caused by the stressor, and we used the sum of the
 250 individual effects for our null prediction of the effect of both stressors, as in [Crain et al.,
 251 2008, Darling and Côté, 2008, Nye et al., 2013]. We could also have measured the effect by
 252 the percentage drop caused by the stressor(s) and used a multiplicative null prediction for
 253 the effect of both stressors. In general, measuring synergy against an additive null
 254 prediction is more conservative than measuring synergy multiplicatively: the presence of
 255 additive synergy implies multiplicative synergy, but not vice versa [Crain et al., 2008, Folt
 256 et al., 1999]. Since we found small levels of positive additive synergy between the two
 257 stressors, other measures of synergy might show even higher levels of interaction.

258 As the harvesting rate h increases, the critical rate of environmental shift c^* decreases: the
 259 environment must move more slowly to accommodate the population growing more slowly
 260 (Figure 1). Conversely, as the rate of environmental shift c increases, the critical harvesting
 261 rate h^* decreases (Figure 1). This means that a harvesting rate that is sustainable in the
 262 absence of environmental shift may no longer be sustainable if the environment starts
 263 shifting. When the harvesting pressure has exceeded the critical harvesting rate h^* or the
 264 environmental is shifting more quickly than the critical rate of environmental shift c^* , the
 265 biomass of the population at equilibrium will be equal to 0. Before those thresholds are
 266 reached, the equilibrium biomass of the population decreases as either the harvesting
 267 pressure increases or the environmental shifts more quickly (Figure 1). The simulations
 268 replicate the analytical results with the critical speed c^* declining as the critical harvest
 269 rate h^* increases and vice versa (Figure 3a).

270 It is always the case that increasing the intrinsic growth rate, R_0 , of the population
 271 increases the critical speed c^* and the critical harvesting rate h^* , since a population that
 272 grows more quickly can recover more quickly from losses caused by these disturbances.

However, whether or not dispersing farther is better depends on how quickly the environment is shifting (Figure 1). When the environment is shifting slowly, dispersing farther is detrimental since many larvae will disperse too far away from the viable patch. When the environment is shifting quickly, on the other hand, dispersing farther can help the population persist because some larvae will disperse into the space that will become viable shortly in the future. This affects the critical harvesting rate: at a low rate of environmental shift, populations that disperse less can be harvested more severely than those that disperse further, whereas at a high rate of environmental shift, populations that disperse further can be harvested more severely.

4.2 Management Strategies We found that when thresholds are in place, the harvesting rate no longer determines the critical rate of environmental shift c^* (Figure 3). We also examined the effect of marine protected areas (MPAs) on the population's persistence to see whether it might extend the range of harvesting and climate change parameters where the fish population could survive. With MPAs in place, the population had a slightly higher abundance along the edges of the patch where the population is limited by harvesting, which translated into a slightly increased critical harvest rate (Figure 3).

5 Discussion

Knowing whether two disturbances are synergistic in their impacts for a given population is important for management. The co-occurrence of climate change-driven range shifts and fishing mean that there is the potential for synergistic interactions, which have been largely unexamined. Previous work examining how harvest and range shift interact has lacked the

generality to examine how these two disturbances are likely to jointly affect population persistence. Many modeling studies have focused on how fish populations are likely to change in the future under a variety of fishing and climate scenarios, but the degree of detail and case-specificity makes it difficult to draw general conclusions. Here we have built a general model to examine how climate and harvesting interact to affect species persistence by incorporating dispersal and reproduction.

To quantify the interaction between the stressors, we measured the synergy between their effects on population biomass. We found positive synergy between the stressors and that the synergy is greatest in the region of parameter space where the equilibrium biomass is smallest. We found similar results from the analytically derived biomass and the simulation derived biomass. This indicates that this result is robust to changes in the dispersal kernel. We chose to measure the effect of each stressor by the absolute drop in biomass caused by the stressor, and we used the sum of the individual effects for our null prediction of the effect of both stressors, as in [Crain et al., 2008, Darling and Côté, 2008, Nye et al., 2013]. We could also have measured the effect by the percentage drop caused by the stressor(s) and used a multiplicative null prediction for the effect of both stressors. In general, measuring synergy against an additive null prediction is more conservative than measuring synergy multiplicatively: the presence of additive synergy implies multiplicative synergy, but not vice versa [Crain et al., 2008, Folt et al., 1999]. Since we found small levels of positive additive synergy between the two stressors, other measures of synergy might show even higher levels of interaction.

While we did find synergy between the stressors, the drop in biomass caused by both stressors was never very much higher than the null prediction, i.e. synergistic effects were quite small. However, the fact that synergy is highest in those populations whose

persistence is most tenuous is worrisome from a conservation perspective. Additionally, the fact that we found additive synergy means that harvesting levels or rate of environment shift that are sustainable individually together can drive a population to extinction. Synergy between harvesting and climate changes has been identified in experimental populations [Mora et al., 2007], in specific populations [Planque et al., 2010], and at the ecosystem level [Kirby et al., 2009, Planque et al., 2010]. However, these results are not directly comparable to ours because they focus on different aspects of climate change, e.g. warming temperature [Mora et al., 2007, Kirby et al., 2009] or a more variable climate [Planque et al., 2010]. Additionally, in the experimental populations, synergy was identified between warming and harvesting but not between habitat fragmentation [Mora et al., 2007]. Nevertheless, our results generally agree with these empirical findings and it is therefore important to take the effects of both stressors into consideration when designing conservation and management strategies.

We also derived expressions for critical harvesting rates and critical rates of environmental shift for a separable Gaussian kernel and found these critical rates using numerical simulations of a Laplace kernel. For each kernel we studied, we found that the higher the growth rate and the better the mean dispersal distance matches the rate of environmental shift, the better a population can adjust to harvest and climate change. More interestingly, we found a negative relationship between the critical harvesting rate and the rate of environmental shift. That is, the more quickly the environment shifts the less harvesting it takes to drive the population extinct. The curved line separating parameters that will allow the population to persist from those that won't is another indication of an interaction between the stressors.

Our results suggest that particular combinations of harvesting and rate of environmental

shift will affect some species more than others. As shown in Figure 1, species with a shorter generation time and a longer average dispersal distance will better track a high rate of environmental shift relative to a species that has a long generation time and short dispersal distance. This is in agreement with empirical work which has found that fish which shifted in response to warming in North Sea had faster life histories than non shifting species (smaller body sizes, faster maturation, smaller sizes at maturity) [Perry et al., 2005]. We also examined frequently recommended management approaches: ~~harvest thresholds and MPAs and whether these strategies would work to ensure species persistence.~~ We found ~~these two management strategies to both~~ increase the population's biomass at equilibrium and improved its ability to persist. Protected areas have been advanced as a way to help organisms keep pace with range shifts, as well as to ameliorate anthropogenic disturbances like harvesting and habitat fragmentation [Lawler et al., 2010, Hannah et al., 2007, Botsford et al., 2001, Gaylord et al., 2005, Hastings and Botsford, 2003, Thomas et al., 2012]. Our results, that spatial management increased the maximum harvesting rate at which the population could survive, support the idea that MPAs could be used to reduce the impact of harvesting. However we did not find any evidence that MPAs increased the climate velocity under which the population could persist. The second management approach we investigated, harvesting thresholds, are already widely implemented in fisheries management, and we found that this management tactic alleviates interactions between the two stressors. While the management strategies only change harvesting practices and do not directly address the effects of climate change, understanding how they ameliorate synergistic affects between harvesting and range shifts will help to better implement harvesting rules and place protected areas. The advantage of a simple model like ours is that it is general enough to be ~~applied~~ to a

number of systems. However, it ignores many of the complexities present in marine fisheries. We do not include Allee effects, so that even if the population shrank to very low levels it was possible for it to persist over time. However, we found that qualitatively similar results about the interaction between climate and harvesting would hold for a model with a recruitment function with Allee effect. We also did not include age structure in our model. The effects of both harvesting and climate change may be different across different age classes; including this level of complexity is left for future work. Additionally, we did not include any mechanisms aside from larval dispersal by which the population could keep up with a shifting climate. In addition to these species-specific extensions, this modeling framework could be extended to consider species interactions, especially predator-prey pairs. By introducing a predatory species, we would be imposing yet another stressor on the focus species [Ling et al., 2009, Gurevitch et al., 2000] and we are interested in measuring the interaction between the effects of this stressor and the two we consider here. Using a simple mechanistic model like the one we present here provides a useful framework for incorporating additional ecological complexities which can mediate species persistence under multiple disturbances. Exploring how species interactions, age structure, and additional disturbances (i.e. pollution, disease, physiological response to temperature) affect population viability will improve our predictions and help us to understand whether species will persist under predicted climate and harvesting regimes. Finally, this work can help make general predictions as to whether specific life histories are likely to be selected over others as harvesting and/or range shifts increase.

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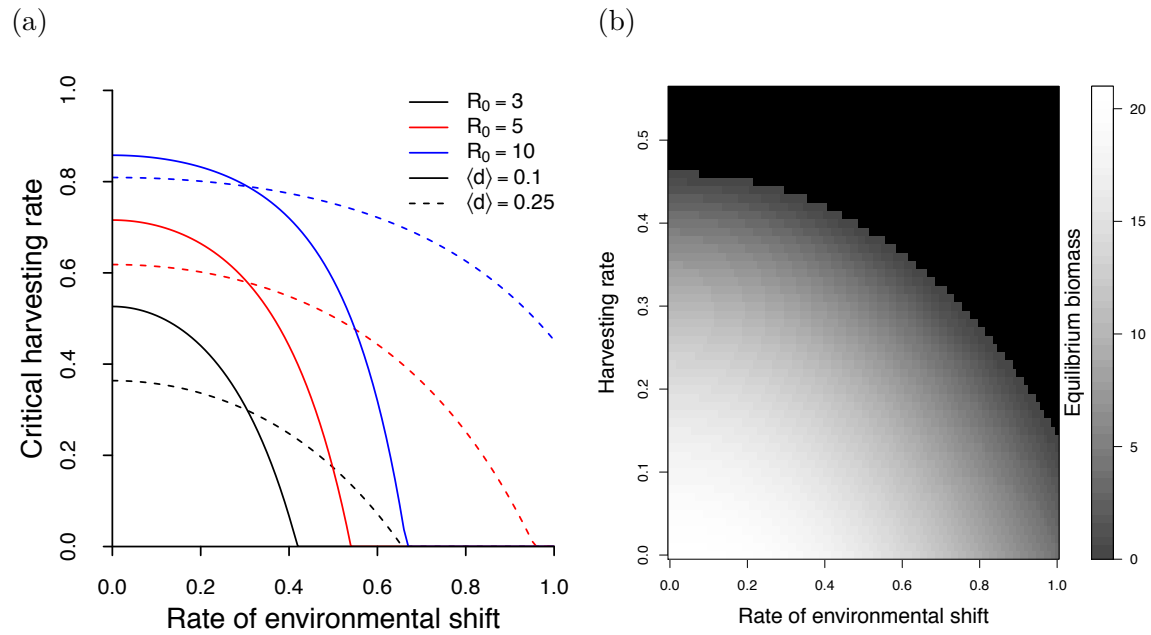


Figure 1

609 **Figure 1:** (a) The equilibrium biomass of the population as a function of the rate of envi-
 610 ronmental shift on the x-axis and the harvesting rate on the y-axis. These results are from
 611 a Gaussian dispersal kernel with parameters $L = 1$, $R_0 = 5$, $\langle d \rangle = 0.399$. (b) The critical
 612 harvesting rate on the y-axis as a function of the rate of environmental shift on the x-axis.
 613 Black lines correspond to a growth rate of $R_0 = 3$, red to $R_0 = 7$, and blue to $R_0 = 10$. Solid
 614 lines correspond to an average dispersal distance $\langle d \rangle = 0.1$ and dashed lines correspond to
 615 an average dispersal distance $\langle d \rangle = 0.25$. These results are from an approximated Gaussian
 616 dispersal kernel with $L = 1$.

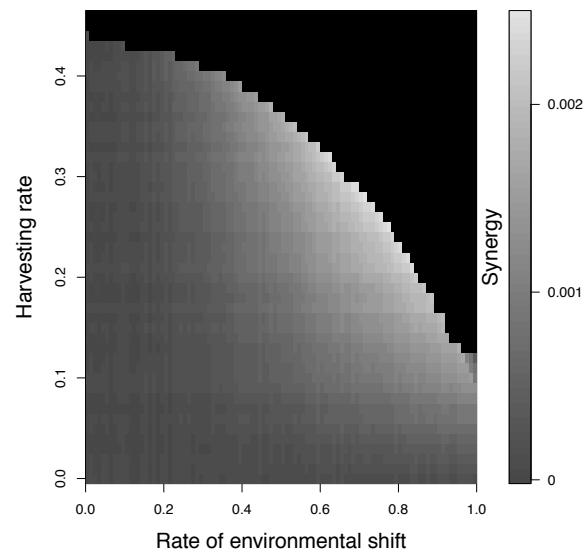
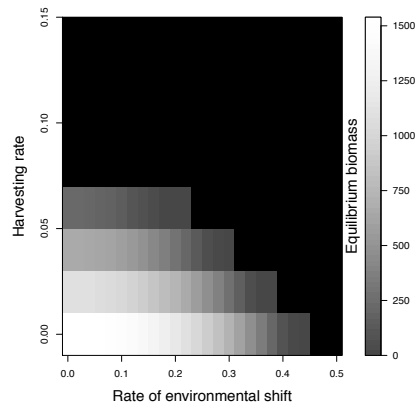


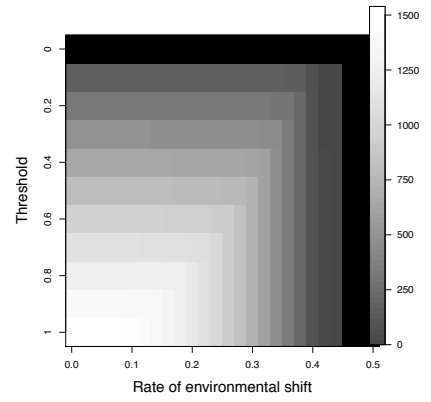
Figure 2

617 **Figure 2:** Positive synergy between the two stressors. The x-axis shows the rate of environ-
618 mental shift, the y-axis shows the harvesting rate, and the color indicates the loss in biomass
619 in the doubly stressed population in excess of the sum of the losses caused by each stressor
620 individually, $E_{hc} - E_h - E_c$. These results are from an approximated Gaussian dispersal
621 kernel with parameters $L = 1$, $R_0 = 5$, $\langle d \rangle = 0.399$.

(a)



(b)



(c)

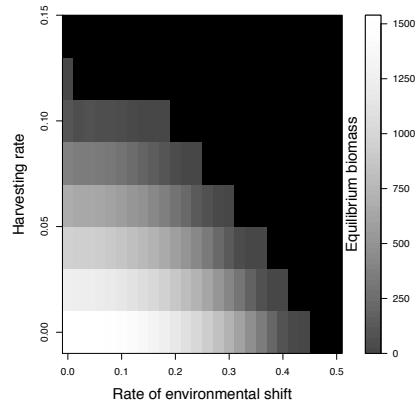


Figure 3

Figure 3: The equilibrium biomass of the population as a function of the rate of environmental shift on the x-axis and the harvesting rate on the y-axis with and without management strategies. (a) No management. (b) Threshold harvesting levels. (c) MPAs. These results are from a simulation with a Laplacian dispersal kernel with parameters $L = 1$, $R_0 = 5$, $K = 100$, and $\langle d \rangle = 2$.

7 Tables

Table 1: Table of variables used in the text

Variable	Definition
$n_t(x)$	density of fish at position x at time t
$n^*(\bar{x})$	density of fish at equilibrium at position \bar{x} relative to the patch
$k(x - y)$	dispersal kernel, probability of larva traveling from position y to position x
$\langle d \rangle$	expected distance traveled by larva
$f(n)$	recruitment function, number of offspring produced by a population of size n
R_0	intrinsic growth rate, $R_0 = f'(0)$
h	proportion of adults harvested
L	patch length
c	rate of environmental shift

8 Appendix

As in Zhou et al. [Zhou and Kot, 2011], let $k(x - y)$ be a dispersal kernel and let $f(y)$ be a recruitment function. The integrodifference model describing the population over time is given by

$$n_{t+1}(x) = \int_{-L/2+ct}^{L/2+ct} k(x - y)f(n_t(y))dy. \quad (6)$$

To find a traveling pulse, we are only interested in the population density as a function of the location within the patch rather than absolute position, $\bar{x} \equiv x - ct$.

$$n^*(\bar{x}) \equiv n^*(x - ct) = n_t(x). \quad (7)$$

Then (6) gives us an expression for n^* :

$$\begin{aligned} n^*(\bar{x} - c) &= \int_{-L/2}^{L/2} k(\bar{x} - \bar{y})f(n^*(\bar{y}))d\bar{y} \\ \Rightarrow n^*(\bar{x}) &= \int_{-L/2}^{L/2} k(\bar{x} + c - \bar{y})f(n^*(\bar{y}))d\bar{y} \end{aligned} \quad (*)$$

If $f(0) = 0$, $n^*(\bar{x}) \equiv 0$ for all $\bar{x} \in [-L/2, L/2]$ is a trivial solution to this problem, i.e. if there are no fish anywhere there won't be at any time in the future. The population can be said to be persistent if the trivial traveling pulse is unstable since even when there are very small population levels, the population won't crash to 0. To evaluate stability (i.e. persistence), we will introduce a small perturbation to the traveling pulse $n^*(\bar{x})$,

$$\begin{aligned} n_t(x) &= n^*(\bar{x}) + \xi_t(x) \\ \Rightarrow \xi_{t+1}(x) &= \int_{-L/2+ct}^{L/2+ct} k(x - y)f'(n^*(\bar{y}))\xi_t(y)dy \text{ by linearizing around the traveling pulse and using } (*) \\ \Rightarrow \xi_{t+1}(x) &= \int_{-L/2+ct}^{L/2+ct} k(x - y)f'(0)\xi_t(y)dy \text{ if we're interested in the stability of the trivial traveling pulse} \end{aligned}$$

If we assume $\xi_t(x) = \lambda^t u(x - ct)$ for some $\lambda \in \mathbb{R}$ and $u : [-L/2, L/2] \rightarrow \mathbb{R}$, then

$$\begin{aligned} \lambda u(x - ct - c) &= f'(0) \int_{-L/2+ct}^{L/2+ct} k(x - y)u(y - ct)dy \\ \lambda u(\bar{x}) &= f'(0) \int_{-L/2}^{L/2} k(\bar{x} + c - \bar{y})u(\bar{y})d\bar{y} \end{aligned}$$

Define the integral operator

$$\psi_f(g)(x) = \int_{-L/2}^{L/2} f'(0)k(x + c - y)g(y)dy.$$

so that the perturbation to the traveling pulse will satisfy

$$\psi_f(u)(x) = \lambda u(x) \quad (8)$$

Then the trivial traveling pulse is unstable when the dominant eigenvalue of ψ_f is greater than 1.

Let f denote the recruitment function, let h denote a harvesting function and let $m(y) = f(y - h(y))$, i.e. m denotes the number of offspring after the adults have been harvested. Note that $m'(0) = f'(0)(1 - h'(0))$, assuming $h(0) = 0$ (which must be the case).

Suppose u is an eigenfunction of ψ_f with eigenvalue λ . Then

$$\begin{aligned}\psi_m(u)(x) &= \int_{-L/2}^{L/2} m'(0)k(x + c - y)u(y)dy \\ &= (1 - h'(0)) \int_{-L/2}^{L/2} f'(0)k(x + c - y)u(y)dy \\ &= (1 - h'(0))\psi_f(u)(x) \\ &= (1 - h'(0))\lambda u(x)\end{aligned}$$

so that u is also an eigenfunction of ψ_m , now with eigenvalue $(1 - h'(0))\lambda$.

8.1 Separable dispersal kernels Jentzsch's theorem shows that there is an eigenfunction u , provided that the kernel k satisfy some properties. Finding the eigenfunction is in general a hard problem to solve. It becomes easier if the kernel k is separable, i.e. there are functions a_n, b_n such that $k(x - y) = \sum_{n=1}^{\infty} a_n(x)b_n(y)$. In that case, (8) becomes

$$\begin{aligned}\lambda u(x) &= f'(0) \sum_{n=1}^{\infty} \left(a_n(x) \int_{-L/2}^{L/2} b_n(y - c)u(y)dy \right) \\ \Rightarrow \lambda \int_{-L/2}^{L/2} b_k(x - c)u(x)dx &= f'(0) \sum_{n=1}^{\infty} \left(\int_{-L/2}^{L/2} b_n(x - c)u(x)dx \right) \left(\int_{-L/2}^{L/2} a_n(y)b_k(y - c)dy \right) \\ \Rightarrow \lambda d_k &= f'(0) \sum_{n=1}^{\infty} A_{nk}d_n\end{aligned}\tag{**}$$

where

$$A_{nk} = \int_{-L/2}^{L/2} a_n(x)b_k(x - c)dx \text{ and } d_k = \int_{-L/2}^{L/2} b_k(x - c)u(x)dx$$

8.2 Gaussian dispersal kernel The Gaussian dispersal kernel is given by

$$k(|x - y|) = \frac{1}{2\sqrt{D\pi}} e^{-\frac{(x-y)^2}{4D}}.$$

As in [Latore et al., 1998], this separable kernel can be written as

$$k(|x - y|) = \sum_{n=0}^{\infty} a_n(x)b_n(y)$$

where

$$a_n(x) = b_n(x) = \frac{1}{\sqrt{2n!}\sqrt{D\pi}} e^{-x^2/4D} \left(\frac{x}{\sqrt{2D}} \right)^n.$$

As a first approximation to k we ignore all but the 0^{th} terms for a_n and b_n so that Equation ** becomes

$$\begin{aligned}\lambda d_0(c) &= f'(0)A_{00}(c)d_0(c) \\ \Rightarrow \lambda &= R_0(1-h)A_{00}(c) \\ \text{where } A_{00}(c) &= 2\sqrt{2} \exp\left(\frac{-c^2}{8D}\right) \left[\operatorname{erf}\left(\frac{L-c}{2\sqrt{2D}}\right) - \operatorname{erf}\left(\frac{-L-c}{2\sqrt{2D}}\right) \right]\end{aligned}$$

647 where erf is the error function. The critical rate of environmental shift c^* and the critical
648 harvesting rate h^* are those values of c and h , respectively, that make $\lambda = 1$.

8.3 Sinusoidal dispersal kernel A sinusoidal dispersal kernel is given by

$$k(x-y) = \begin{cases} \frac{w}{2} \cos(w(x-y)) & , \quad |x-y| \leq \frac{\pi}{2w} \\ 0 & , \quad |x-y| > \frac{\pi}{2w} \end{cases}$$

649 where L is the length of the patch and we assume $\frac{\pi}{2w} > L, c < \frac{\pi}{2w} - L$.

In this case, $k(x-y) = \frac{w}{2} \cos(wx) \cos(w(y-c)) + \frac{w}{2} \sin(wx) \sin(w(y-c))$ so that A_{ij} and d_i can be found for $i, j = 1, 2$ and $(**)$ reduces to

$$\lambda^2 - \left(\frac{R_0(1-h)wL}{2} \cos(wc) \right) \lambda + \frac{R_0^2(1-h)^2}{16} (w^2L^2 - \sin^2(wL)) = 0.$$

650 If we solve for λ , we find

$$\lambda = R_0(1-h) \left[\frac{wL \cos(wc)}{4} + \frac{1}{4} \sqrt{\sin^2(wL) - w^2L^2 \sin^2(wc)} \right]. \quad (9)$$

Zhou et al. [Zhou and Kot, 2011] solve for the critical speed, c^* , at the population will be driven extinct:

$$c^* = c^*(R_0) = \frac{1}{w} \cos^{-1} \left[\frac{16 + R_0^2(1-h)^2(w^2L^2 - \sin^2(wL))}{8R_0(1-h)wL} \right].$$

Similarly, we can solve for the critical harvesting rate, h^* , at which the population will be driven extinct:

$$h^* = 1 - \frac{1}{R_0} \cdot \frac{4wL}{w^2L^2 - \sin^2(wL)} \left[\cos(wc) - \sqrt{\cos^2(wc) - 1 + \frac{\sin^2(wL)}{w^2L^2}} \right]$$

8.4 Approximate Critical Harvesting Proportions

We will use the following Taylor series to make approximations of the critical harvesting

proportions under the two dispersal kernels:

$$\begin{aligned}\cos(x) &= 1 - \frac{x^2}{2} \\ \cos^2(x) &= 1 - x^2 \\ \sin^2(x) &= x^2 - \frac{x^4}{3} \\ erf(x) &= \frac{2}{\sqrt{\pi}}(x - \frac{x^3}{3}) \\ \exp(x) &= 1 + x + \frac{x^2}{2}\end{aligned}$$

651 For the sinusoidal kernel we found

$$h^* = 1 - \frac{1}{R_0} \cdot \frac{4wL}{w^2L^2 - \sin^2(wL)} \left[\cos(wc) - \sqrt{\cos^2(wc) - 1 + \frac{\sin^2(wL)}{w^2L^2}} \right] \quad (10)$$

Using the Taylor series and the fact that $w = \frac{\sqrt{\frac{\pi^2}{4} - 2}}{\sigma}$ where σ^2 is the variance of the sinusoidal kernel,

$$\begin{aligned}h^* &\sim 1 - \frac{1}{R_0} \cdot \frac{12wL}{w^4L^4} \left[1 - \frac{w^2c^2}{2} - \sqrt{1 - w^2c^2 - \frac{w^2L^2}{3}} \right] \\ &= 1 - \frac{1}{R_0} \cdot \frac{4\sqrt{3}}{L^3(\pi^2 - 8)^{3/2}} \cdot \sigma \left[8\sqrt{3}\sigma^2 - (\pi^2 - 8)\sqrt{3}c^2 - 4\sigma\sqrt{12\sigma^2 - (\pi^2 - 8)(3c^2 + L^2)} \right]\end{aligned}$$

652 For the Gaussian kernel we found

$$h^* = 1 - \frac{2\sqrt{2}\exp\left(\frac{c^2}{8D}\right)}{R_0 \left[erf\left(\frac{L-c}{2\sqrt{2D}}\right) - erf\left(\frac{-L-c}{2\sqrt{2D}}\right) \right]} \quad (11)$$

Using the Taylor series and the fact that $D = \frac{\sigma^2}{2}$ where σ^2 is the variance of the exponential kernel,

$$\begin{aligned}h^* &\sim 1 - \frac{\sqrt{2\pi}(1 + \frac{c^2}{8D} + \frac{c^4}{128D^2})}{R_0\sqrt{\pi} \left[\frac{L-c}{2\sqrt{2D}} - \frac{(L-c)^3}{3(2\sqrt{2D})^3} - \frac{-L-c}{2\sqrt{2D}} + \frac{(-L-c)^3}{3(2\sqrt{2D})^3} \right]} \\ &= 1 - \frac{1}{R_0} \cdot \frac{3\sqrt{2\pi}}{8L} \cdot \frac{(32\sigma^4 + 8c^2\sigma^2 + c^4)}{\sigma(12\sigma^2 - (L^2 + 3c^2))}\end{aligned}$$

653 In the case of both kernels, the critical harvesting proportion can be approximated by a
654 function that looks like

$$h^* \sim 1 - \frac{1}{R_0} \cdot C(L)f(\sigma^2, c^2, L^2 + 3c^2) \quad (12)$$

655 where $C(L, R_0)$ is a decreasing function of the length of the viable patch and the intrinsic
656 growth rate.