Species persistence under climate and fishing

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3 1 Abstract

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- When the climate changes, the habitat in which organisms can survive and reproduce
- 5 moves through space. This change does not occur in isolation but rather appears on a
- background of other disturbances. We used an integrodifference model explicitly
- ⁷ accounting for dispersal, reproduction, to examine how two disturbances, range shift and
- 8 harvesting, interact and govern population persistence. We found threshold rates of
- harvesting and of environmental shift such that more increasing either disturbance will
- drive the population extinct and studied how these critical parameters depend on the
- 11 growth rate and dispersal behavior of the population. We then measured the interaction
- between the stressors and we found low but positive synergy between the two stressors:
- harvesting aggravates the population's sensitivity to a shifting range. Finally, we
- 14 introduced two conservation techniques into simulations of the population model –
- threshold harvest rules and marine protected areas (MPAs) and found that these
- approaches could mitigate, under some circumstances, the negative interaction of the two
- 17 stressors.
- 18 **Keywords:** Climate change, fishing, integrodifference model, synergy, multiple
- 19 disturbances

20 2 Introduction

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There are many stressors that can disturb an ecosystem. Ecologists have quantified the
effects of a number of stressors individually [Wilcove et al., 1998, Crain et al., 2008,
Darling and Côté, 2008], but less work has been done to measure the effects of multiple
stressors and the interactions between them. If disturbances interact synergistically, a
perturbation that has little effect when it occurs individually may amplify the disturbance
caused by a coincident perturbation [Crain et al., 2008, Darling and Côté, 2008, Nye et al.,
2013, Gurevitch et al., 2000. In the most extreme (and worrying) cases, synergistic
interactions between multiple stressors will drive a population extinct even though it could
persist in the face of any single stressor (i.e. Pelletier et al. [2006]). If disturbances interact
antagonistically, on the other hand, the effects of multiple stressors may be less than that
predicted by any stressor individually. Since disturbances rarely occur in isolation, it is
important to measure the synergy between disturbances in order to understand how a
system will be affected by their presence and to understand when multiple disturbances will
drive a population extinct [Doak and Morris, 2010, Fordham et al., 2013, Folt et al., 1999].
Climate change and fishing have been identified as the two largest human impacts on the
ocean [Halpern et al., 2008]. They therefore present an important case study of how
disturbances interact in their effects on biological populations. Further, understanding
these interactions will be crucial to managing populations subjected to both of these
disturbances. Marine fish are already moving in response to climate change [Perry et al.,
2005, Hiddink and ter Hofstede, 2008, Rijnsdorp et al., 2009, Dulvy et al., 2008, Simpson
et al., 2011 and they are projected to continue moving in the future [Kell et al., 2005,
Mackenzie et al., 2007]. Species that are likely to undergo or already undergoing shifts in
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- range are also subject to harvesting, in addition to many other disturbances including
- pollution, ocean acidification, habitat fragmentation, and invasive species [Wilcove et al.,
- ⁴⁵ 1998, Sala, 2000, Assessment, 2005, Pinsky et al., 2013, Barry et al., 1995, Nye et al.,
- ⁴⁶ 2009]. Empirical case studies have identified interactions between overfishing and
- temperature-driven range shifts that suggest synergy in the magnitude of the disturbance
- [Ling et al., 2009] and have demonstrated synergistic effects in microcosm experiments
- between warming temperatures, harvesting and connectivity [Mora et al., 2007]. This
- 50 empirical work underscores the importance of understanding how range shifts and
- 51 harvesting interact.
- 52 A common approach to predicting future population distributions under climate change
- has been to use bioclimatic-envelope models (also known as species distribution models –
- 54 SDMs). These statistical models typically correlate presence-absence data with biophysical
- 55 characteristics such as mean or maximum temperatures, rainfall, or salinity, to explain and
- predict how species ranges' will differ under climate change [Elith et al., 2006, Guisan and
- 57 Thuiller, 2005, Guisan and Zimmermann, 2000]. Despite these models' widespread
- ⁵⁸ adoption, SDMs have frequently been criticized as oversimplified as they lack species
- interactions, dispersal and reproductive processes [Kearney and Porter, 2009, Zarnetske
- et al., 2012, Robinson et al., 2011. Recent work on range shifts has addressed some of
- these gaps by explicitly including dispersal and reproduction [Berestycki et al., 2009, Zhou
- and Kot, 2011]. However these models only address one disturbance: that of climate-driven
- 63 range shifts.
- 64 Work considering the joint impacts of climate and fishing often consider climate
- 65 fluctuations (large anomalies around the mean) rather than directional changes in climate
- ⁶⁶ [Walters and Parma, 1996, King and McFarlane, 2006]. When the effects of climate-driven

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range shifts on fishing are considered, the models are typically case-specific and detailed,
integrating multiple drivers and disturbances [Cheung et al., 2010, Lindegren et al., 2010,
Brown et al., 2010, Merino et al., 2010a,b, Plaganyi et al., 2011, Ainsworth et al., 2011,
Zhang et al., 2011, Barange et al., 2011, Howard et al., 2013. These predicted impacts are
important for management and conservation planning [Allison et al., 2009], however these
models are so complex that understanding the relative importance of particular drivers,
disturbances, and interactions is difficult (but see Nye et al. [2013] for an approach using
ecosystem-level models to discern relative importance of disturbances). Here we develop
models of intermediate complexity [sensu Gaylord et al., 2005] that can help clarify the
importance of two interacting disturbances: temperature-driven range shifts and harvest.
Here we constructed an analytical model of a fish population subject to both harvesting
and climate change-induced range-shift. We explicitly included two mechanistic processes
central to species' responses to climate and fishing: reproduction and dispersal. Previous
work has highlighted the importance of these two processes and their vulnerability to
climate change [Fordham et al., 2013, Hastings et al., 2005]. We found that climate-driven
range shifts and fishing interact synergistically, when their effects are measured by absolute
drop in biomass. We also found how the threshold level of harvesting that suffices to drive
the population extinct depends on how quickly the range is shifting.
We also examined the effect of threshold harvesting rules and marine protected areas
(MPAs) on species persistence. Protected areas have been suggested as a key form of
climate insurance and stepping stones to help species keep up with a changing environment
[Thomas et al., 2012, Hannah et al., 2007]. MPAs are frequently recommended for
conservation of biodiversity and improved fisheries yield [Gaines et al., 2010a], and we
evaluate whether MPAs established for those purposes could improve species persistence
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when habitat is shifting rapidly. We found that MPAs can help a species persist with
higher harvesting pressure, but does not change the maximum climate velocity with which
a species can keep up.

94 3 Methods

- We studied the dynamics of a fish population constrained to a single, one-dimensional habitat patch by their inability to reproduce outside of the patch. This viable habitat patch (here after 'patch') is shifting at a fixed velocity and fish at each point in space can be harvested. We first measured the drop in biomass caused by range shifts, harvesting, and both stressors together in order to determine whether they interact synergistically. We then determined the climate velocity and harvesting rate that would drive the population extinct. We finally implemented marine protected areas (MPAs) and threshold harvesting rules in numerical simulations of the model to determine how these management strategies affect population persistence.
- The Model In the model of Zhou and Kot [2011], the adults from the current year 104 produce offspring according to a recruitment function, and these offspring disperse across 105 the one-dimensional world according to a dispersal kernel to become the next generation's 106 adults. We extend this model by additionally subjecting the adults to harvesting before they produce offspring so that only a proportion of the fish survive to reproduce. These 108 processes—recruitment, harvesting, and dispersal—are incorporated into an 109 integrodifference model to describe how the population changes over time. If $n_t(x)$ is the 110 density of fish at position x at time t, then the density of fish at the next generation is 111 given by

$$n_{t+1}(x) = \int_{-\frac{L}{2} + ct}^{\frac{L}{2} + ct} k(x - y) f((1 - h)n_t(y)) dy, \tag{1}$$

where h is the proportion of adults harvested, f(n) is the recruitment function giving the number of offspring produced by a population of size n (accounting for density dependence), k(x-y) is the dispersal kernel giving the probability of a larva traveling from position y to position x, L is the length of the patch, and c is the rate at which it shifts across space. We chose to use a Beverton-Holt recruitment function,

$$f(n_t) = \frac{R_0 n_t}{1 + \left(\frac{R_0 - 1}{K}\right) n_t}.$$

Regardless of the exact functional form of the recruitment function, a critical parameter of the recruitment function in determining population persistence is how quickly recruitment 119 increases when the population size is near (but above) 0, which is equivalent to the intrinsic growth rate, $R_0 = f'(0)$. Analyzing this kind of model becomes easier if the 121 dispersal kernel is separable into its dependence on the source of larvae and its dependence 122 on the destination of the larvae, i.e. if there are functions a_i, b_i such that $k(x-y) = \sum_{i=1}^{\infty} a_i(x)b_i(y)$ and we use such a kernel in our analytical expressions. We 124 provide a list of variables and functions in Table 1. At equilibrium, the population will be described by a traveling wave, where the density of fish at a given point in space will change but the density of fish at a location relative to the 127 shifting patch will not. We sought to describe how the population is distributed over the viable patch as it shifts through the world in order to study the size of the population at 129 equilibrium and whether or not the population could persist. The traveling wave n^* must satisfy 131

$$n^*(\bar{x}) = \int_{-\frac{L}{2}}^{\frac{L}{2}} k(\bar{x} + c - \bar{y}) f((1-h)) n^*(\bar{y})) d\bar{y}, \tag{2}$$

where $\bar{x} \in \left[-\frac{L}{2}, \frac{L}{2}\right]$ describes the position within the patch [Zhou and Kot, 2011]. Zhou and Kot [2011] only considered whether a shifting environment will drive a population extinct, however to quantify the effects of both a shifting environment and harvesting pressure we must also find the total biomass in the equilibrium traveling wave. For a separable kernel, the equilibrium traveling pulse $n^*(x)$ must satisfy

$$n^*(x) = \sum_{i=1}^{\infty} a_i(x) \int_{-\frac{L}{2}}^{\frac{L}{2}} b_i(y-c) f((1-H(n^*(y)))n^*(y)) dy = \sum_{i=1}^{\infty} m_i a_i(x),$$
 (3)

where the m_i satisfy the recursive equations

$$m_i = \int_{-\frac{L}{2}}^{\frac{L}{2}} b_i(y - c) f\left((1 - h) \sum_{j=1}^{\infty} m_j a_j(x)\right) dy.$$
 (4)

[Latore et al., 1998]. Equation 4 allowed us to find the values of m_i numerically. We then found the total biomass in the equilibrium traveling pulse by using these m_i and integrating Equation 3.

3.2 Calculating Synergy In order to quantify whether the two stressors are interacting additively, synergistically, or antagonistically, we found the total biomass of the population when it reached an equilibrium traveling pulse and compared this equilibrium biomass in the presence and absence of each stressor individually or the two stressors together.

We used B_0 to denote the equilibrium biomass without either stressor, B_h the equilibrium biomass with a shifting environment but no harvesting, and B_{hc} the equilibrium biomass with both

stressors. For each stressor or combination of stressors, we found the drop in biomass caused by stressor s,

$$E_{\rm s} = B_0 - B_{\rm s}.$$

150 If the stressors do not interact, the drop caused by both stressors would be the sum of the
151 drops caused by either individually. The synergy is therefore defined as

$$S = E_{\rm hc} - (E_{\rm h} + E_{\rm c}).$$

If the stressors aggravate each other, the effect of both stressors is worse than would be
expected from considering either stressor individually, and synergy is positive. If the
stressors alleviate each other, the effect of both stressors is better than would be expected
from considering either stressor individually, and synergy is negative. If the effect of both
stressors is exactly as expected from considering either stressor individually, there is no
interaction and no synergy.

158 **3.3 Persistence** One possible equilibrium traveling wave that solves Equation 2 is the 159 'trivial' traveling pulse, $n^*(\bar{x}) = 0$ for all $x \in \left[-\frac{L}{2}, \frac{L}{2}\right]$, i.e. a patch with no fish in it. If a 160 population becomes very small (or if we introduce a small population), one of two things 161 can happen. First, the population may crash and the trivial traveling pulse without any 162 fish may appear again. Second, those small numbers may increase and form a stable 163 population. In this sense, a small population can be thought of as a perturbation to the 164 trivial traveling pulse. If the trivial pulse is stable, the system will return to the trivial 165 pulse even after a perturbation in the form of the introduction of a small population. If a population is to persist, even when it is small it must be able to avoid extinction and grow.

For this to be the case, the trivial pulse must be unstable to small perturbations.

We would like to know the rate of environmental shift and the harvesting rate such that as long as the environment moves more slowly or we harvest less severely than those parameters, then the population will be able to persist. We call these, respectively, the critical rate of environmental shift, c^* , and the critical harvesting rate, h^* . We found these rates by finding the parameters that make the trivial pulse unstable. In our analyses, as in [Latore et al., 1998], we used the separable Gaussian kernel given by

$$k(x-y) = \frac{1}{2\sqrt{D\pi}}e^{\frac{-(x-y)^2}{4D}}.$$

To find analytical results about the Gaussian kernel, we approximated the kernel, as described in the Appendix. Analytical results for a separable sinusoidal kernel are also 175 described in the Appendix. We used simulations to analyze a Laplace dispersal kernel that 176 is not amenable to this method, as described below. 177 For each kernel, the population's ability to persist depends on properties of the population 178 itself- the expected distance a larva disperses ($\langle d \rangle$) and the intrinsic growth rate (R_0) ; 179 properties of the environment- the length of the viable patch (L) and how quickly the 180 environment is shifting (c); and the harvesting rate (h). Whereas equilibrium biomass 181 depends on the function form of recruitment, population persistence only depends on the 182 intrinsic growth rate R_0 . If the environment shifts more quickly than the critical rate c^* or 183 the population is harvested at more than the critical rate h^* then the population will not 184 be able to persist, as described in the Appendix. For a Gaussian kernel, the critical rates c^* 185 and h^* are those values of c and h such that

$$R_0(1-h)2\sqrt{2}\exp\left(\frac{-c^2}{8D}\right)\left[\operatorname{erf}\left(\frac{L-c}{2\sqrt{2D}}\right)-\operatorname{erf}\left(\frac{-L-c}{2\sqrt{2D}}\right)\right]=1.$$

A similar expression for a sinusoidal kernel is derived in the appendix. For both kernels, the critical harvesting proportion can be approximated by a function that looks like

$$h^* \sim 1 - \frac{1}{R_0} \cdot C(L, R_0) f(\langle d \rangle, c^2, L^2 + 3c^2),$$
 (5)

where $C(L, R_0)$ is a decreasing function of the length of the viable patch and the intrinsic growth rate.

3.4 Simulations We used simulations to extend the basic integrodifference model in two ways that make it analytically intractable. First, we examined the sensitivity of the model to choice of dispersal kernel by using the Laplace dispersal kernel,

$$k(x - y) = \frac{1}{2}be^{-b|x-y|},$$

a commonly used model of larval dispersal [Pinsky, 2011]. Second, we examined harvesting 194 rules more complex than harvesting a constant proportion of the population. Whereas 195 population persistence in the analytical model does not depend on the functional form of 196 recruitment f, to perform simulations we must specify a recruitment function. Again, we chose to use a Beverton-Holt function. In the first generation, we seeded the world with 50 198 individuals at a single point, as in [Zhou and Kot, 2011]. We first ran through 150 199 generations in order for the population to reach equilibrium without harvesting or climate 200 shift. We then added harvesting pressure, allowed the population to again reach 201 equilibrium, and finally added climate change by moving the viable patch. Equilibrium

- $_{203}$ biomass is calculated as the mean biomass of 300 time steps once the difference in biomass
- between time step t and t+1 was no greater than 0.1.
- We added harvesting pressure by harvesting a constant proportion of the population, in
- order to confirm our analytical results. We then evaluated the effect of a threshold harvest
- ²⁰⁷ rule and marine protected areas (MPAs). With a threshold rule, we evaluated the
- 208 population at each point in space to determine how much harvesting should occur. If the
- population abundance was below the designated threshold, no harvesting occurred. If the
- 210 population exceeded the threshold, then a proportion of the 'surplus' individuals were
- 211 harvested.
- MPAs are a form of management designed to check the impact of fishing on targeted
- 213 populations and are typically designed to meet either conservation of fishery management
- goals [Agardy, 1994, Holland and Brazee, 1996, Gaines et al., 2010b]. To implement an
- MPA management strategy in our model, we examine the effect of both of these commonly
- advocated approaches. While both conservation and fisheries oriented MPA schemes align
- in their goal of maintaining a sustainable fished population, they differ in desired level of
- adult spillover. Fisheries-oriented MPAs are often designed such that they maximize adult
- spillover into fishable areas by creating many small reserves closely spaced [Hastings and
- Botsford, 2003. The converse of this is the goal of conservation-oriented MPAs which seek
- to reduce adult spillover by minizing the ratio between the reserve edge length relative to
- area protected [Gaines et al., 2010b].
- Networks of MPAs were introduced into our simulations by designating segments of space
- in which harvesting was forbidden (i.e. harvesting rates were equal to 0).
- 225 Conservation-oriented MPAs, are frequently large and rarely part of a larger network of
- reserves [Hastings and Botsford, 2003]. For solitary reserves to be successful at protecting

target species, they must encompass self-sustaining fish populations [Hastings and Botsford, 2006, Gaines et al., 2010b]. As such modeling studies estimate that isolated 228 reserves must be at least as large as the average dispersal distance for the targeted fish species [Lockwood et al., 2002, Hastings and Botsford, 2003, Botsford et al., 2001, Gaines 230 et al., 2010a. To implement conservation MPAs we created reserves with a length of 4 231 times the average dispersal distance and had a distance of 8 times the average dispersal distance between them to ensure that populations would be self sustiaining and not 233 dependent on other dispersal for other reserves [Lockwood et al., 2002]. 234 Previous work has shown that if MPAs are to benefit fisheries, the reserves should be 235 broken into a network, closely spaced to maximize adult spillover into fishable areas and 236 export of larvae from reserve to reserve [Hastings and Botsford, 2003, Gaylord et al., 2005, Gaines et al., 2010b]. To mimic this management scheme, MPAs had a length of $\frac{1}{3}$ of the 238 average dispersal distance and had a distance of $\frac{2}{3}$ of the average dispersal distance between them. 240

4 Results

242 4.1 Interactions Between Stressors We found positive synergy between the two
243 stressors in our analysis of the Gaussian kernel (Figure 2). In other words, a doubly stressed
244 population loses more biomass than would be predicted from either stressor individually.
245 The stressors interact most strongly when they are both high, shortly before they drive the
246 population extinct. We found similar analytical results for a sinusoidal dispersal kernel and
247 our simulations with a Laplace kernel produce similar results which indicates that this
248 result is robust to changes in the dispersal kernel. We chose to measure the effect of each

stressor by the absolute drop in biomass caused by the stressor, and we used the sum of the individual effects for our null prediction of the effect of both stressors, as in [Crain et al., 250 2008, Darling and Côté, 2008, Nye et al., 2013. We could also have measured the effect by 251 the percentage drop caused by the stressor(s) and used a multiplicative null prediction for 252 the effect of both stressors. In general, measuring synergy against an additive null 253 prediction is more conservative than measuring synergy multiplicatively: the presence of additive synergy implies multiplicative synergy, but not vice versa [Crain et al., 2008, Folt 255 et al., 1999. Since we found small levels of positive additive synergy between the two 256 stressors, other measures of synergy might show even higher levels of interaction. 257 As the harvesting rate h increases, the critical rate of environmental shift c^* decreases: the 258 environment must move more slowly to accommodate the population growing more slowly (Figure 1). Conversely, as the rate of environmental shift c increases, the critical harvesting 260 rate h^* decreases (Figure 1). This means that a harvesting rate that is sustainable in the 261 absence of environmental shift may no longer be sustainable if the environment starts 262 shifting. When the harvesting pressure has exceeded the critical harvesting rate h^* or the 263 environmental is shifting more quickly than the critical rate of environmental shift c^* , the biomass of the population at equilibrium will be equal to 0. Before those thresholds are 265 reached, the equilibrium biomass of the population decreases as either the harvesting 266 pressure increases or the environmental shifts more quickly (Figure 1). The simulations 267 replicate the analytical results with the critical speed c^* declining as the critical harvest 268 rate h^* increases and vice versa (Figure 3a). It is always the case that increasing the intrinsic growth rate, R_0 , of the population 270 increases the critical speed c^* and the critical harvesting rate h^* , since a population that 271 grows more quickly can recover more quickly from losses caused by these disturbances.

However, whether or not dispersing farther is better depends on how quickly the
environment is shifting (Figure 1). When the environment is shifting slowly, dispersing
farther is detrimental since many larvae will disperse too far away from the viable patch.
When the environment is shifting quickly, on the other hand, dispersing farther can help
the population persist because some larvae will disperse into the space that will become
viable shortly in the future. This affects the critical harvesting rate: at a low rate of
environmental shift, populations that disperse less can be harvested more severely than
those that disperse further, whereas at a high rate of environmental shift, populations that
disperse further can be harvested more severely.

4.2 Management Strategies We found that when thresholds are in place, the
harvesting rate no longer determines the critical rate of environmental shift c^* (Figure 3).

We also examined the effect of marine protected areas (MPAs) on the population's
persistence to see whether it might extend the range of harvesting and climate change
parameters where the fish population could survive. With MPAs in place, the population
had a slightly higher abundance along the edges of the patch where the population is
limited by harvesting, which translated into a slightly increased critical harvest rate
(Figure 3).

5 Discussion

Knowing whether two disturbances are synergistic in their impacts for a given population
is important for management. The co-occurrence of climate change-driven range shifts and
fishing mean that there is the potential for synergistic interactions, which have been largely
unexamined. Previous work examining how harvest and range shift interact has lacked the

generality to examine how these two disturbances are likely to jointly affect population persistence. Many modeling studies have focused on how fish populations are likely to 296 change in the future under a variety of fishing and climate scenarios, but the degree of 297 detail and case-specificity makes it difficult to draw general conclusions. Here we have built 298 a general model to examine how climate and harvesting interact to affect species 290 persistence by incorporating dispersal and reproduction. To quantify the interaction between the stressors, we measured the synergy between their 301 effects on population biomass. We found positive synergy between the stressors and that 302 the synergy is greatest in the region of parameter space where the equilibrium biomass is 303 smallest. We found similar results from the analytically derived biomass and the simulation 304 derived biomass. This indicates that this result is robust to changes in the dispersal kernel. We chose to measure the effect of each stressor by the absolute drop in biomass caused by 306 the stressor, and we used the sum of the individual effects for our null prediction of the effect of both stressors, as in [Crain et al., 2008, Darling and Côté, 2008, Nye et al., 2013]. 308 We could also have measured the effect by the percentage drop caused by the stressor(s) 300 and used a multiplicative null prediction for the effect of both stressors. In general, measuring synergy against an additive null prediction is more conservative than measuring 311 synergy multiplicatively: the presence of additive synergy implies multiplicative synergy, 312 but not vice versa [Crain et al., 2008, Folt et al., 1999]. Since we found small levels of 313 positive additive synergy between the two stressors, other measures of synergy might show 314 even higher levels of interaction. While we did find synergy between the stressors, the drop in biomass caused by both 316 stressors was never very much higher than the null prediction, i.e. synergistic effects were 317 quite small. However, the fact that synergy is highest in those populations whose

persistence is most tenuous is worrisome from a conservation perspective. Additionally, the fact that we found additive synergy means that harvesting levels or rate of environment 320 shift that are sustainable individually together can drive a population to extinction. Synergy between harvesting and climate changes has been identified in experimental 322 populations [Mora et al., 2007], in specific populations [Planque et al., 2010], and at the 323 ecosystem level [Kirby et al., 2009, Planque et al., 2010]. However, these results are not directly comparable to ours because they focus on different aspects of climate change, e.g. 325 warming temperature [Mora et al., 2007, Kirby et al., 2009] or a more variable climate 326 [Planque et al., 2010]. Additionally, in the experimental populations, synergy was identified 327 between warming and harvesting but not between habitat fragmentation [Mora et al., 328 2007. Nevertheless, our results generally agree with these empirical findings and it is therefore important to take the effects of both stressors into consideration when designing 330 conservation and management strategies. 331 We also derived expressions for critical harvesting rates and critical rates of environmental 332 shift for a separable Gaussian kernel and found these critical rates using numerical 333 simulations of a Laplace kernel. For each kernel we studied, we found that the higher the growth rate and the better the mean dispersal distance matches the rate of environmental 335 shift, the better a population can adjust to harvest and climate change. More interestingly, 336 we found a negative relationship between the critical harvesting rate and the rate of 337 environmental shift. That is, the more quickly the environment shifts the less harvesting it 338 takes to drive the population extinct. The curved line separating parameters that will allow the population to persist from those that won't is another indication of an interaction 340 between the stressors.

Our results suggest that particular combinations of harvesting and rate of environmental

shift will affect some species more than others. As shown in Figure 1, species with a shorter generation time and a longer average dispersal distance will better track a high rate of 344 environmental shift relative to a species that has a long generation time and short dispersal 345 distance. This is in agreement with empirical work which has found that fish which shifted in response to warming in North Sea had faster life histories than non shifting species 347 (smaller body sizes, faster maturation, smaller sizes at maturity) [Perry et al., 2005]. We also examined frequently recommended management approaches: harvest thresholds 340 and MPAs and whether these strategies would work to ensure species persistence. We found these two management strategies to both increase the population's biomass at 351 equilibrium and improved its ability to persist. Protected areas have been advanced as a 352 way to help organisms keep pace with range shifts, as well as to ameliorate anthropogenic disturbances like harvesting and habitat fragmentation [Lawler et al., 2010, Hannah et al., 354 2007, Botsford et al., 2001, Gaylord et al., 2005, Hastings and Botsford, 2003, Thomas 355 et al., 2012. Our results, that spatial management increased the maximum harvesting rate 356 at which the population could survive, support the idea that MPAs could be used to reduce 357 the impact of harvesting. However we did not find any evidence that MPAs increased the climate velocity under which the population could persist. The second management 350 approach we investigated, harvesting thresholds, are already widely implemented in fisheries management, and we found that this management tactic alleviates interactions 361 between the two stressors. While the management strategies only change harvesting practices and do not directly address the effects of climate change, understanding how they ameliorate synergistic affects between harvesting and range shifts will help to better 364 implement harvesting rules and place protected areas.

The advantage of a simple model like ours is that it is general enough to be applied to a

number of systems. However, it ignores many of the complexities present in marine fisheries. We do not include Allee effects, so that even if the population shrank to very low 368 levels it was possible for it to persist over time. However, we found that qualitatively similar results about the interaction between climate and harvesting would hold for a model with a recruitment function with Allee effect. We also did not include age structure in our model. The effects of both harvesting and climate change may be different across different age classes; including this level of complexity is left for future work. Additionally, we did 373 not include any mechanisms aside from larval dispersal by which the population could keep 374 up with a shifting climate. In addition to these species-specific extensions, this modeling 375 framework could be extended to consider species interactions, especially predator-prey 376 pairs. By introducing a predatory species, we would be imposing yet another stressor on the focus species [Ling et al., 2009, Gurevitch et al., 2000] and we are interested in 378 measuring the interaction between the effects of this stressor and the two we consider here. Using a simple mechanistic model like the one we present here provides a useful framework 380 for incorporating additional ecological complexities which can mediate species persistence 381 under multiple disturbances. Exploring how species interactions, age structure, and additional disturbances (i.e. pollution, disease, physiological response to temperature) 383 affect population viability will improve our predictions and help us to understand whether species will persist under predicted climate and harvesting regimes. Finally, this work can 385 help make general predictions as to whether specific life histories are likely to be selected over others as harvesting and for range shifts increase.

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608 6 Figures

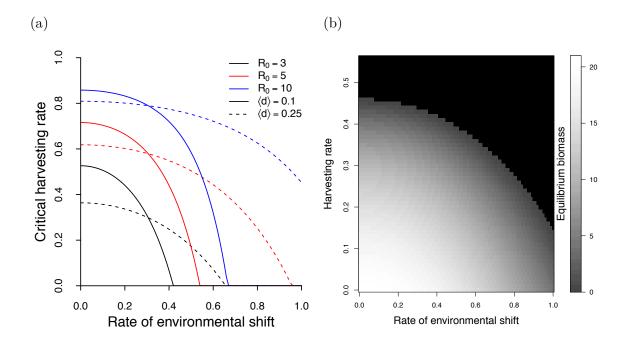


Figure 1

Figure 1: (a) The equilibrium biomass of the population as a function of the rate of environmental shift on the x-axis and the harvesting rate on the y-axis. These results are from a Gaussian dispersal kernel with parameters L=1, $R_0=5$, $\langle d \rangle=0.399$. (b) The critical harvesting rate on the y-axis as a function of the rate of environmental shift on the x-axis. Black lines correspond to a growth rate of $R_0=3$, red to $R_0=7$, and blue to $R_0=10$. Solid lines correspond to an average dispersal distance $\langle d \rangle=0.1$ and dashed lines correspond to an average dispersal distance $\langle d \rangle=0.25$. These results are from an approximated Gaussian dispersal kernel with L=1.

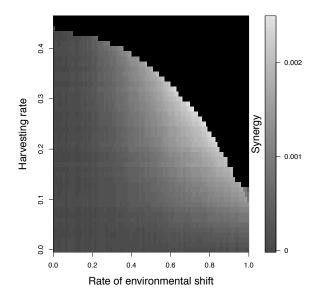
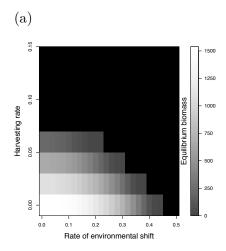


Figure 2

Figure 2: Positive synergy between the two stressors. The x-axis shows the rate of environmental shift, the y-axis shows the harvesting rate, and the color indicates the loss in biomass in the doubly stressed population in excess of the sum of the losses caused by each stressor individually, $E_{\rm hc} - E_{\rm h} - E_{\rm c}$. These results are from an approximated Gaussian dispersal kernel with parameters L = 1, $R_0 = 5$, $\langle d \rangle = 0.399$.



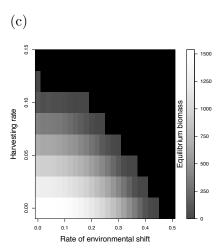


Figure 3

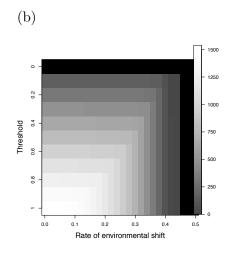


Figure 3: The equilibrium biomass of the population as a function of the rate of environmental shift on the x-axis and the harvesting rate on the y-axis with and without management strategies. (a) No management. (b) Threshold harvesting levels. (c) MPAs. These results are from a simulation with a Laplacian dispersal kernel with parameters $L=1, R_0=5, K=100, \text{ and } \langle d \rangle = 2.$

7 Tables

Table 1: Table of variables used in the text

Variable	Definition
$\overline{n_t(x)}$	density of fish at position x at time t
$n^*(\overline{x})$	density of fish at equilibrium at position \overline{x} relative to the patch
k(x-y)	dispersal kernel, probability of larva traveling from position y to position x
$\langle d \rangle$	expected distance traveled by larva
f(n)	recruitment function, number of offspring produced by a population of size n
R_0	intrinsic growth rate, $R_0 = f'(0)$
h	proportion of adults harvested
L	patch length
c	rate of environmental shift

8 Appendix

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As in Zhou et al. [Zhou and Kot, 2011], let k(x-y) be a dispersal kernel and let f(y) be a recruitment function. The integrodifference model describing the population over time is given by

$$n_{t+1}(x) = \int_{-L/2+ct}^{L/2+ct} k(x-y) f(n_t(y)) dy.$$
 (6)

To find a traveling pulse, we are only interested in the population density as a function of the location within the patch rather than absolute position, $\overline{x} \equiv x - ct$.

$$n^*(\overline{x}) \equiv n^*(x - ct) = n_t(x). \tag{7}$$

Then (6) give s us an expression for n^* :

$$n^*(\overline{x} - c) = \int_{-L/2}^{L/2} k(\overline{x} - \overline{y}) f(n^*(\overline{y})) d\overline{y}$$

$$\Rightarrow n^*(\overline{x}) = \int_{-L/2}^{L/2} k(\overline{x} + c - \overline{y}) f(n^*(\overline{y})) d\overline{y}$$
(*)

If f(0) = 0, $n^*(\overline{x}) \equiv 0$ for all $\overline{x} \in [-L/2, L/2]$ is a trivial solution to this problem, i.e. if there are no fish anywhere there won't be at any time in the future. The population can be said to be persistent if the trivial traveling pulse is unstable since even when there are very small population levels, the population won't crash to 0. To evaluate stability (i.e. persistence), we will introduce a small perturbation to the traveling pulse $n^*(\overline{x})$,

$$n_t(x) = n^*(\overline{x}) + \xi_t(x)$$

$$\Rightarrow \xi_{t+1}(x) = \int_{-L/2+ct}^{L/2+ct} k(x-y) f'(n^*(\overline{y})) \xi_t(y) dy \text{ by linearizing around the traveling pulse and using (*)}$$

$$\Rightarrow \xi_{t+1}(x) = \int_{-L/2+ct}^{L/2+ct} k(x-y) f'(0) \xi_t(y) dy \text{ if we're interested in the stability of the trivial traveling pulse}$$

If we assume $\xi_t(x) = \lambda^t u(x - ct)$ for some $\lambda \in \mathbb{R}$ and $u: [-L/2, L/2] \to \mathbb{R}$, then

$$\lambda u(x - ct - c) = f'(0) \int_{-L/2 + ct}^{L/2 + ct} k(x - y)u(y - ct)dy$$
$$\lambda u(\overline{x}) = f'(0) \int_{-L/2}^{L/2} k(\overline{x} + c - \overline{y})u(\overline{y})dy$$

Define the integral operator

$$\psi_f(g)(x) = \int_{-L/2}^{L/2} f'(0)k(x+c-y)g(y)dy.$$

 $_{540}$ so that the perturbation to the traveling pulse will satisfy

$$\psi_f(u)(x) = \lambda u(x) \tag{8}$$

Then the trivial traveling pulse is unstable when the dominant eigenvalue of ψ_f is greater than 1.

Let f denote the recruitment function, let h denote a harvesting function and let m(y) = f(y - h(y)), i.e. m denotes the number of offspring after the adults have been harvested. Note that m'(0) = f'(0)(1 - h'(0)), assuming h(0) = 0 (which must be the case).

Suppose u is an eigenfunction of ψ_f with eigenvalue λ . Then

$$\psi_m(u)(x) = \int_{-L/2}^{L/2} m'(0)k(x+c-y)u(y)dy$$

$$= (1-h'(0)) \int_{-L/2}^{L/2} f'(0)k(x+c-y)u(y)dy$$

$$= (1-h'(0))\psi_f(u)(x)$$

$$= (1-h'(0))\lambda u(x)$$

so that u is also an eigenfuction of ψ_m , now with eigenvalue $(1 - h'(0))\lambda$.

8.1 Separable dispersal kernels Jentzsch's theorem shows that there is an eigenfunction u, provided that the kernel k satisfy some properties. Finding the eigenfunction is in general a hard problem to solve. It becomes easier if the kernel k is separable, i.e. there are functions a_n, b_n such that $k(x - y) = \sum_{n=1}^{\infty} a_n(x)b_n(y)$. In that case, (8) becomes

$$\lambda u(x) = f'(0) \sum_{n=1}^{\infty} \left(a_n(x) \int_{-L/2}^{L/2} b_n(y - c) u(y) dy \right)$$

$$\Rightarrow \lambda \int_{-L/2}^{L/2} b_k(x - c) u(x) dx = f'(0) \sum_{n=1}^{\infty} \left(\int_{-L/2}^{L/2} b_n(x - c) u(x) dx \right) \left(\int_{-L/2}^{L/2} a_n(y) b_k(y - c) dy \right)$$

$$\Rightarrow \lambda d_k = f'(0) \sum_{n=1}^{\infty} A_{nk} d_n$$
(**)

where

$$A_{nk} = \int_{-L/2}^{L/2} a_n(x)b_k(x-c)dx$$
 and $d_k = \int_{-L/2}^{L/2} b_k(x-c)u(x)dx$

8.2 Gaussian dispersal kernel The Gaussian dispersal kernel is given by

$$k(|x-y|) = \frac{1}{2\sqrt{D\pi}}e^{\frac{-(x-y)^2}{4D}}.$$

As in [Latore et al., 1998], this separable kernel can be written as

$$k(|x - y|) = \sum_{n=0}^{\infty} a_n(x)b_n(y)$$

where

$$a_n(x) = b_n(x) = \frac{1}{\sqrt{2n!\sqrt{D\pi}}} e^{-x^2/4D} \left(\frac{x}{\sqrt{2D}}\right)^n.$$

As a first approximation to k we ignore all but the 0^{th} terms for a_n and b_n so that Equation ** becomes

$$\lambda d_0(c) = f'(0)A_{00}(c)d_0(c)$$

$$\Rightarrow \lambda = R_0(1-h)A_{00}(c)$$
where $A_{00}(c) = 2\sqrt{2}\exp\left(\frac{-c^2}{8D}\right)\left[\operatorname{erf}\left(\frac{L-c}{2\sqrt{2D}}\right) - \operatorname{erf}\left(\frac{-L-c}{2\sqrt{2D}}\right)\right]$

where erf is the error function. The critical rate of environmental shift c^* and the critical harvesting rate h^* are those values of c and h, respectively, that make $\lambda = 1$.

8.3 Sinusoidal dispersal kernel A sinusoidal dispersal kernel is given by

$$k(x-y) = \begin{cases} \frac{w}{2}\cos(w(x-y)) &, |x-y| \le \frac{\pi}{2w} \\ 0 &, |x-y| > \frac{\pi}{2w} \end{cases}$$

where L is the length of the patch and we assume $\frac{\pi}{2w} > L, c < \frac{\pi}{2w} - L$. In this case, $k(x-y) = \frac{w}{2}\cos(wx)\cos(w(y-c)) + \frac{w}{2}\sin(wx)\sin(w(y-c))$ so that A_{ij} and d_i can be found for i,j=1,2 and (**) reduces to

$$\lambda^2 - \left(\frac{R_0(1-h)wL}{2}\cos(wc)\right)\lambda + \frac{R_0^2(1-h)^2}{16}\left(w^2L^2 - \sin^2(wL)\right) = 0.$$

If we solve for λ , we find

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$$\lambda = R_0(1 - h) \left[\frac{wL\cos(wc)}{4} + \frac{1}{4} \sqrt{\sin^2(wL) - w^2L^2\sin^2(wc)} \right]. \tag{9}$$

Zhou et al. [Zhou and Kot, 2011] solve for the critical speed, c^* , at the population will be driven extinct:

$$c^* = c^*(R_0) = \frac{1}{w} \cos^{-1} \left[\frac{16 + R_0^2 (1 - h)^2 (w^2 L^2 - \sin^2(wL))}{8R_0 (1 - h)wL} \right].$$

Similarly, we can solve for the critical harvesting rate, h^* , at which the population will be driven extinct:

$$h^* = 1 - \frac{1}{R_0} \cdot \frac{4wL}{w^2L^2 - \sin^2(wL)} \left[\cos(wc) - \sqrt{\cos^2(wc) - 1 + \frac{\sin^2(wL)}{w^2L^2}} \right]$$

Approximate Critical Harvesting Proportions

We will use the following Taylor series to make approximations of the critical harvesting

proportions under the two dispersal kernels:

$$\cos(x) = 1 - \frac{x^2}{2}$$

$$\cos^2(x) = 1 - x^2$$

$$\sin^2(x) = x^2 - \frac{x^4}{3}$$

$$erf(x) = \frac{2}{\sqrt{\pi}}(x - \frac{x^3}{3})$$

$$\exp(x) = 1 + x + \frac{x^2}{2}$$

For the sinusoidal kernel we found

$$h^* = 1 - \frac{1}{R_0} \cdot \frac{4wL}{w^2L^2 - \sin^2(wL)} \left[\cos(wc) - \sqrt{\cos^2(wc) - 1 + \frac{\sin^2(wL)}{w^2L^2}} \right]$$
(10)

Using the Taylor series and the fact that $w = \frac{\sqrt{\frac{\pi^2}{4} - 2}}{\sigma}$ where σ^2 is the variance of the sinusoidal kernel,

$$h^* \sim 1 - \frac{1}{R_0} \cdot \frac{12wL}{w^4L^4} \left[1 - \frac{w^2c^2}{2} - \sqrt{1 - w^2c^2 - \frac{w^2L^2}{3}} \right]$$

$$= 1 - \frac{1}{R_0} \cdot \frac{4\sqrt{3}}{L^3(\pi^2 - 8)^{3/2}} \cdot \sigma \left[8\sqrt{3}\sigma^2 - (\pi^2 - 8)\sqrt{3}c^2 - 4\sigma\sqrt{12\sigma^2 - (\pi^2 - 8)(3c^2 + L^2)} \right]$$

For the Gaussian kernel we found

$$h^* = 1 - \frac{2\sqrt{2}\exp\left(\frac{c^2}{8D}\right)}{R_0\left[erf\left(\frac{L-c}{2\sqrt{2D}}\right) - erf\left(\frac{-L-c}{2\sqrt{2D}}\right)\right]}$$
(11)

Using the Taylor series and the fact that $D = \frac{\sigma^2}{2}$ where σ^2 is the variance of the exponential kernel,

$$h^* \sim 1 - \frac{\sqrt{2\pi} \left(1 + \frac{c^2}{8D} + \frac{c^4}{128D^2}\right)}{R_0 \sqrt{\pi} \left[\frac{L-c}{2\sqrt{2D}} - \frac{(L-c)^3}{3(2\sqrt{2D})^3} - \frac{-L-c}{2\sqrt{2D}} + \frac{(-L-c)^3}{3(2\sqrt{2D})^3}\right]}$$
$$= 1 - \frac{1}{R_0} \cdot \frac{3\sqrt{2\pi}}{8L} \frac{\left(32\sigma^4 + 8c^2\sigma^2 + c^4\right)}{\sigma\left(12\sigma^2 - (L^2 + 3c^2)\right)}$$

In the case of both kernels, the critical harvesting proportion can be approximated by a function that looks like

$$h^* \sim 1 - \frac{1}{R_0} \cdot C(L) f(\sigma^2, c^2, L^2 + 3c^2)$$
 (12)

where $C(L, R_0)$ is a decreasing function of the length of the viable patch and the intrinsic growth rate.