### dforce

Calculates  $\mathbf{F}(\mathbf{x})$ , where  $\mathbf{x} \equiv \{\text{geometry}\} \equiv \{R_{i,v}, Z_{i,v}\}$  and  $\mathbf{F} \equiv [[p + B^2/2]] + \{\text{spectral constraints}\}\$ , and  $\nabla \mathbf{F}$ .

[called by: hesian, newton, pc00aa, pc00ab and xspech.]

[calls: packxi, ma00aa, matrix, ma02aa, lforce, volume, packab, tr00ab, coords and brcast.]

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## 1.1 unpacking

1. The geometrical degrees of freedom are represented as a vector,  $\mathbf{x} \equiv \{R_{i,v}, Z_{i,v}\}$ , where i = 1, mn labels the Fourier harmonic and v = 1, Mvol-1 is the interface label. This vector is "unpacked" using packxi. (Note that packxi also sets the coordinate axis, i.e. the  $R_{i,0}$  and  $Z_{i,0}$ .)

## 1.2 parallelization over volumes

- 1. In each volume, vvol = 1, Mvol,
  - (a) the logical array ImagneticOK(vvol) is set to .false.
  - (b) the energy and helicity matrices, dMA(0:NN,0:NN), dMB(0:NN,0:2), etc. are allocated;
  - (c) the volume-integrated metric arrays, DToocc, etc. are allocated;
  - (d) calls ma00aa to compute the volume-integrated metric arrays;
  - (e) calls matrix to construct the energy and helicity matrices;
  - (f) calls ma02aa to solve for the magnetic fields consistent with the appropriate constraints, perhaps by iterating on mp00ac;
  - (g) calls volume to compute the volume of the v-th region;
  - (h) calls lforce to compute  $p + B^2/2$  (and the spectral constraints if required) on the inner and outer interfaces;
  - (i) the derivatives of the force-balance will also be computed if LComputeDerivatives = 1;
- 2. After the parallelization loop over the volumes, breast is called to broadcast the required information.

## 1.3 broadcasting

1. The required quantities are broadcast by breast.

## 1.4 construction of force

1. The force vector,  $\mathbf{F}(\mathbf{x})$ , is a combination of the pressure-imbalance Fourier harmonics,  $[[p+B^2/2]]_{i,v}$ , where i labels Fourier harmonic and v is the interface label:

$$F_{i,v} \equiv \left[ (p_{v+1} + B_{i,v+1}^2/2) - (p_v + B_{i,v}^2/2) \right] \times \text{BBweight}_i, \tag{1}$$

where BBweight(i) is defined in preset; and the spectral condensation constraints,

$$F_{i,v} \equiv I_{i,v} \times \operatorname{epsilon} + S_{i,v,1} \times \operatorname{sweight}_{v} - S_{i,v+1,0} \times \operatorname{sweight}_{v+1}, \tag{2}$$

where the spectral condensation constraints,  $I_{i,v}$ , and the "star-like" poloidal angle constraints,  $S_{i,v,\pm 1}$ , are calculated and defined in lforce; and the sweight<sub>v</sub> are defined in preset.

# 1.5 construct derivatives of matrix equation

1. Matrix perturbation theory is used to compute the derivatives of the solution, i.e. the Beltrami fields, as the geometry of the interfaces changes:

# 1.6 extrapolation: planned redundant

1. The extrapolation constraint is  $R_{j,1}=R_{j,2}\,\psi_1^{m/2}/\psi_2^{m/2}$ . Combining this with the regularization factor for the geometry, i.e.  $R_{j,i}=\psi_i^{m/2}\xi_{j,i}$ , we obtain

$$\xi_{j,1} = R_{j,2}/\psi_2^{m/2}.\tag{3}$$

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 ${\bf SPEC\ subroutines};$