#### pp00aa

Constructs Poincaré plot and "approximate" rotational-transform (driver).

[called by: xspech.] [calls: pp00ab.]

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# 1.1 relevant input variables

- 1. The resolution of Poincaré plot is controlled by
  - i. nPtraj trajectories will be located in each volume;
  - ii. nPpts iterations per trajectory;
  - iii. odetol o.d.e. integration tolerance;
- 2. The magnetic field is given by bfield.
- 3. The approximate rotational transform is determined, in pp00ab, by fieldline integration.

### 1.2 format of output: Poincaré

1. The Poincaré data is written to .ext.poincare:xxxx, where xxxx is an integer indicating the volume. The format of this file is as follows:

where

- i.  $\theta \equiv \text{data(1,k,j)}$  is the poloidal angle,
- ii.  $s \equiv \text{data(2,k,j)}$  is the radial coordinate,
- iii.  $R \equiv \text{data(3,k,j)}$  is the cylindrical R,
- iv.  $Z \equiv \text{data(4,k,j)}$  is the cylindrical Z,
- 2. The integer k=0,Nz-1 labels toroidal planes, so that  $\phi = (2\pi/\text{Nfp})(k/\text{Nz})$ ,
- 3. The integer j=1,nPpts labels toroidal iterations.
- 4. Usually (if no fieldline integration errors are encountered) the number of fieldlines followed in volume lvol is given by N + 1, where the radial resolution,  $N \equiv Ni(lvol)$ , is given on input. This will be over-ruled by if nPtrj(lvol), given on input, is non-negative.
- 5. The starting location for the fieldline integrations are equally spaced in the radial coordinate  $s_i = s_{l-1} + i(s_l s_{l-1})/N$  for i = 0, N, along the line  $\theta = 0, \zeta = 0$ .

# 1.3 format of output: rotational-transform

1. The rotational-transform data is written to .exttransform:xxxx, where xxxx is an integer indicating the volume. The format of this file is as follows:

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SPEC subroutines;