$$P(||\mathcal{H}(x_1-x_2)||_p < \epsilon|y_1,y_2)$$
 as a metric

Tejal Bhamre

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1 Definitions

$$Y_1 = H_1 X_1 + N_1$$

$$Y_2 = H_2 X_2 + N_2$$

$$X_1, X_2 \sim N(\mu, \Sigma)$$

$$N_1, N_2 \sim N(0, \sigma^2 I_n)$$

 Y_1, Y_2 are independent Gaussian random vectors. \mathcal{H} : Filter function

$$E(Y_1) = H_1 \mu$$

$$Cov(Y_1) = H_1 \Sigma H_1^T + \sigma^2 I_n = K_1$$

$$E(Y_2) = H_2 \mu$$

$$Cov(Y_2) = H_2 \Sigma H_2^T + \sigma^2 I_n = K_2$$

The pdf's are thus

$$f_{X_1}(x_1) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\{-\frac{1}{2}(x_1 - \mu)^T \Sigma^{-1}(x_1 - \mu)\}$$
 (1)

$$f_{X_2}(x_2) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\{-\frac{1}{2}(x_2 - \mu)^T \Sigma^{-1}(x_2 - \mu)\}$$
 (2)

$$f_N(y_1 - H_1 x_1) = \frac{1}{(2\pi)^{\frac{n}{2}} \sigma^n} \exp\{-\frac{1}{2} (y_1 - H_1 x_1)^T \frac{1}{\sigma^2} (y_1 - H_1 x_1)\}$$
(3)

$$f_N(y_2 - H_2 x_2) = \frac{1}{(2\pi)^{\frac{n}{2}} \sigma^n} \exp\{-\frac{1}{2} (y_2 - H_2 x_2)^T \frac{1}{\sigma^2} (y_2 - H_2 x_2)\}$$
(4)

$$f_{Y_1}(y_1) = \frac{1}{(2\pi)^{\frac{n}{2}}|K_1|^{\frac{1}{2}}} \exp\{-\frac{1}{2}(y_1 - H_1\mu)^T K_1^{-1}(y_1 - H_1\mu)\}$$
 (5)

$$f_{Y_2}(y_2) = \frac{1}{(2\pi)^{\frac{n}{2}} |K_2|^{\frac{1}{2}}} \exp\{-\frac{1}{2} (y_2 - H_2\mu)^T K_2^{-1} (y_2 - H_2\mu)\}$$
 (6)

2 Calculation

Suppose we apply some filter \mathcal{H} to the clean signal, this would mean that we now have

$$\mathcal{H}Y_1 = \mathcal{H}H_1X_1 + \mathcal{H}N_1 \tag{7}$$

$$\begin{bmatrix} \mathcal{H} & 0 \\ 0 & \mathcal{H} \end{bmatrix} \begin{bmatrix} X_1 \\ Y_1 \end{bmatrix} = \begin{bmatrix} I & 0 \\ H_1 & I \end{bmatrix} \begin{bmatrix} X_1 \\ N_1 \end{bmatrix}$$
 (8)

$$\sim N \left[\begin{bmatrix} \mathcal{H}\mu \\ \mathcal{H}H_1\mu \end{bmatrix}, \begin{bmatrix} \mathcal{H}\Sigma\mathcal{H}^T & \mathcal{H}\Sigma H_1^T \mathcal{H}^T \\ \mathcal{H}H_1\Sigma\mathcal{H}^T & \mathcal{H}H_1\Sigma H_1^T \mathcal{H}^T + \mathcal{H}\sigma^2 \mathcal{H}^T \end{bmatrix} \right]$$
(9)

Using conditional distributions (Wiki MND)

$$f_{X_1|Y_1}(x_1|y_1) \sim N(\alpha, L)$$
 (10)

$$f_{X_2|Y_2}(x_2|y_2) \sim N(\beta, M)$$
 (11)

where

where
$$\alpha = \mathcal{H}\mu + \mathcal{H}\Sigma H_1^T \mathcal{H}^T (\mathcal{H}H_1\Sigma H_1^T \mathcal{H}^T + \mathcal{H}\sigma^2 \mathcal{H}^T)^{-1} (\mathcal{H}y_1 - \mathcal{H}H_1\mu)$$

$$L = \mathcal{H}\Sigma \mathcal{H}^T - \mathcal{H}\Sigma H_1^T \mathcal{H}^T (\mathcal{H}H_1\Sigma H_1^T \mathcal{H}^T + \mathcal{H}\sigma^2 \mathcal{H}^T)^{-1} (\mathcal{H}H_1\Sigma \mathcal{H}^T)$$

$$\beta = \mathcal{H}\mu + \mathcal{H}\Sigma H_2^T \mathcal{H}^T (\mathcal{H}^T H_2\Sigma H_2^T \mathcal{H}^T + \mathcal{H}\sigma^2 \mathcal{H}^T)^{-1} (\mathcal{H}y_2 - \mathcal{H}H_2\mu)$$

$$M = \mathcal{H}\Sigma \mathcal{H}^T - \mathcal{H}\Sigma H_2^T \mathcal{H}^T (\mathcal{H}H_2\Sigma H_2^T \mathcal{H}^T + \mathcal{H}\sigma^2 \mathcal{H}^T)^{-1} (\mathcal{H}H_2\Sigma \mathcal{H}^T)$$
So

$$P(x_1 - x_2 | y_1, y_2) \sim N(\alpha - \beta, L + M)$$
 (12)

$$P(\mathcal{H}(x_1 - x_2)|y_1, y_2) \sim N(\mathcal{H}(\alpha - \beta), \mathcal{H}(L + M)\mathcal{H}^T)$$
(13)

Let $X_1 - X_2 = X_3$. Then

$$P(||\mathcal{H}x_3||_{\infty} < \epsilon |y_1, y_2) =$$

$$\int_{-\epsilon}^{\epsilon} \frac{1}{(2\pi)^{\frac{n}{2}} |\mathcal{H}(L+M)\mathcal{H}^T|^{\frac{1}{2}}} \exp\{-\frac{1}{2} (x_3 - \mathcal{H}(\alpha - \beta))^T (\mathcal{H}(L+M)\mathcal{H}^T)^{-1} (x_3 - (\mathcal{H}(\alpha - \beta))) \} dx_3$$

$$(14)$$

For small ϵ this is

$$=\frac{(2\epsilon)^n}{(2\pi)^{\frac{n}{2}}|\mathcal{H}(L+M)\mathcal{H}^T|^{\frac{1}{2}}}\exp\{-\frac{1}{2}(\mathcal{H}(\alpha-\beta))^T(\mathcal{H}(L+M)\mathcal{H}^T)^{-1}(\mathcal{H}(\alpha-\beta))\}$$
(15)

So we can define our metric after taking log and dropping out the constant term

$$-\frac{1}{2}\log(|\mathcal{H}(L+M)\mathcal{H}^T|) - \frac{1}{2}(\mathcal{H}(\alpha-\beta))^T(\mathcal{H}(L+M)\mathcal{H}^T)^{-1}(\mathcal{H}(\alpha-\beta))$$
 (16)