

Homework 2  
Due Date: October 17, 2017

**Problem 1:** (20 points)

Consider an array  $x[0..n-1]$  of ascii characters. The Burrows-Wheeler Transform (BWT) of  $x$  works as follows:

1. It forms a matrix  $A$  of all the  $n$  rotations of  $x$ ;
  2. It sorts the rows of  $A$  lexicographically where every row is treated as a word; the outcome is a matrix  $B$ ;
  3. It returns  $(y, L)$  where  $y$  is the last column of  $B$ , and  $L$  is the location of the original  $x$  in  $B$ ;
- a. Apply BWT on the string *babacaab*, and also on the string ``The hat on that cat'', where the blank character ' ' is less than any alphabetic character. Note that you can use Matlab ``sortrows'' command to sort the rows of  $A$ .
  - b. Give a general algorithm that constructs  $B$  from  $(y, L)$ .
  - c. Give an algorithm to reconstruct  $x$  from  $(y, L)$  using the algorithm in (b).
  - d. Illustrate how the reconstruction algorithm works on the  $(y, L)$  produced in part (a) for *babacaab*.

**Problem 2:** (20 points)

Let  $x$  and  $y$  be two vectors of 32 components each where  $x_k = \frac{k^2}{3}$ , and  $y_k = \sin((2k + 1)\frac{\pi}{32})$ , for  $k=0,1,\dots,31$ .

- a. Compute the Fourier transform  $X$  of  $x$  and  $Y$  of  $y$ .
- b. The magnitude of a number  $t$  is its absolute value, denoted  $|t|$ . This applies to both real numbers and complex numbers. Recall that the absolute value of a complex number  $z$ , where  $z=a+ib$ , is  $\sqrt{a^2 + b^2}$ . If  $V$  is a vector (row or column), then we denote by  $|V|$  the vector of the magnitudes of the components of  $V$ . For example, if  $V = [z_1, z_2, z_3]$ , then  $|V| = [|z_1|, |z_2|, |z_3|]$ . Compute  $|X|$  and  $|Y|$ .
- c. Identify the 17 smallest-magnitude elements in  $X$  and the 17 smallest-magnitude elements in  $Y$ .
- d. Let  $\hat{X}$  be derived from  $X$  by replacing each of the 17 smallest-magnitude elements of  $X$  by 0, and leaving the other elements intact. Define  $\hat{Y}$  similarly. Define by  $\hat{x}$  the inverse Fourier transform of  $\hat{X}$ , and  $\hat{y}$  the inverse Fourier transform of  $\hat{Y}$ . Compute  $\hat{x}$  and  $\hat{y}$ .
- e. Plot  $x$  and  $\hat{x}$  in one figure, and  $y$  and  $\hat{y}$  in another figure.

**Problem 3:** (20 points)

Let  $x$  and  $y$  be as in Problem 2. Let  $X$  be the DCT of  $x$ , and  $Y$  the DCT of  $y$ . Let  $\hat{X}$  be derived from  $X$  by replacing the last 17 elements of  $X$  by zeros while keeping the first 15 elements the

same, and define  $\hat{Y}$  similarly from  $Y$ . Finally, let  $\hat{x}$  be the inverse DCT of  $\hat{X}$ , and  $\hat{y}$  the inverse DCT of  $\hat{Y}$ .

- a. Compute  $X$ ,  $Y$ ,  $\hat{x}$ , and  $\hat{y}$ .
- b. Plot  $x$  and  $\hat{x}$  in one figure, and  $y$  and  $\hat{y}$  in another figure.

**Problem 4:** (20 points)

- a. Same as Problem 2 with 3 exceptions: (1) the transform is Haar, (2)  $\hat{X}$  is derived from  $X$  by zeroing out the 17 smallest-magnitude elements of  $X$ , and (3)  $\hat{Y}$  is derived from  $Y$  by zeroing out the 17 smallest-magnitude elements of  $Y$ .
- b. Same problem as (a) except that the Transform is the Walsh-Hadamard transform. Use the Matlab ``hadamard" command to generate the Hadamard matrix.

**Problem 5:** (20 points)

- a. Put in one figure the plots of  $x$  and the four  $\hat{x}$ 's of the last three problems.
- b. For each of the four  $\hat{x}$ 's, compute the mean square error relative to  $x$ .
- c. Which of the four  $\hat{x}$ 's is the best reconstruction of  $x$ ?
- d. Repeat (a), (b) and (c) for  $y$  and the four  $\hat{y}$ 's.