

Focus Server – Integrations Map

Integration	Direction	Purpose	Main Code Location	Config/Deps	Notes
REST: POST <code>/configure</code>	Inbound	Initialize/configure a job and spawn gRPC sink	<code>pz/microservices/focus_server/focus_server.py (/configure)</code>	<code>Config.Focus.*</code>	Returns <code>job_id</code> , <code>stream_url</code> , <code>stream_port</code>
REST: GET <code>/channels</code>	Inbound	Expose available channel range	<code>focus_server.py (/channels)</code>	<code>focus_manager.channels</code>	Simple JSON response
REST: GET <code>/live_metadata</code>	Inbound	Live fiber metadata	<code>focus_server.py (/live_metadata)</code>	<code>focus_manager.fiber_metadata</code>	404 if no metadata
REST: GET <code>/metadata/{job_id}</code>	Inbound	Retrieve job configuration by id	<code>focus_server.py (/metadata/{job_id})</code>	<code>focus_manager.jobs</code>	404 if unknown job_id
REST: POST <code>/recordings_in_time_range</code>	Inbound	Check recording availability in time range	<code>focus_server.py (/recordings_in_time_range)</code>	<code>focus_manager.get_recordings_in_time_range</code>	Converts to epoch
MQ (RabbitMQ): Prpcast.Info consumer	Inbound	Update live metadata from messages	<code>pz/microservices/focus_server/metadata_consumer.py</code>	<code>aio_pika</code> , <code>pzpy.msgbus.AsyncConsumer</code>	Consumes messages and updates metadata
MQ (RabbitMQ): ingest/queue (live)	Outbound	Live input to analyzer via broker	<code>focus_server.py parse_task_configuration (live mode)</code>	<code>get_default_broker_uri()</code> , <code>queue_name</code> , <code>mq_max_length_bytes</code>	Ensure backpressure + DLQ in config
gRPC DataStream (Panda)	Outbound	Stream processed data to clients	<code>focus_server.py →</code>	<code>K8SGrpcLauncher / Supervisor</code>	Opens per-job gRPC server on

			<code>focus_manager.grpc_job_launcher.start(...)</code>	<code>socketGrpcLauncher / BabyThreadLauncher</code>	port
Baby Analyzer (CLI/SDK)	Outbound	Perform processing pipeline	<code>baby_analyzer.baby_sitter.format_command(...)</code>	Flags vary by <code>view_type</code>	<code>out_path=grpc://... sink</code>
Mongo (Recording Mongo Mapper)	Outbound	Time-range validation, historic mode	<code>focus_manager.check_time_range_validity + RecordingMongoMapper</code>	<code>Config.Focus.mongo_mapper_url</code>	Used when <code>start_time / end_time</code> provided
Kubernetes Orchestrator	Outbound	Launch/manage gRPC jobs in K8s	<code>focus_manager.py (K8SGrpcLauncher, orchestrator_service.get_node_port)</code>	<code>Config.Focus.k8s_mode</code>	NodePort allocated per job
Storage mount (historic in_path)	Outbound	Historic input path	<code>parse_task_configuration (baby_in_path = storage_path)</code>	<code>Config.Focus.storage_mount_path</code>	When running historic mode
CORS/HTTP serving	Inbound infra	Expose the API	<code>FastAPI + CORSMiddleware</code>		All origins allowed by default

Full Example Commands

• REST – `/configure`

```

1 curl -sS -X POST "http://<focus-host>:<port>/configure" \
2   -H "Content-Type: application/json" \
3   -d '{
4     "displayTimeAxisDuration": 10,
5     "nfftSelection": 2048,
6     "displayInfo": {"height": 600},
7     "channels": {"min": 1, "max": 64},
8     "frequencyRange": {"min": 20, "max": 3000},
9     "start_time": null,
10    "end_time": null,
11    "view_type": 0
12  }'
```

- REST – /channels

```
1 | curl -sS "http://<focus-host>:<port>/channels"
```

- REST – /live_metadata

```
1 | curl -sS "http://<focus-host>:<port>/live_metadata"
```

- REST – /metadata/{job_id}

```
1 | curl -sS "http://<focus-host>:<port>/metadata/<JOB_ID>"
```

- REST – /recordings_in_time_range

```
1 | curl -sS -X POST "http://<focus-host>:<port>/recordings_in_time_range" \
2 |   -H "Content-Type: application/json" \
3 |   -d '{"start_time": 1727200000, "end_time": 1727203600 }'
```

- gRPC – discovery and call (grpcurl)

```
1 | # If server reflection is enabled:
2 | grpcurl -plaintext <focus-host>:<stream_port> list
3 |
4 | # Attempt DataStream call (align service/method with your proto):
5 | grpcurl -plaintext -d '{"stream_id":0}' <focus-host>:<stream_port> \
6 |   pzpy.recording.backends.protocols.panda_datastream.DataStreamService/St
   |   reamData
```

- RabbitMQ – queues/consumers

```
1 | # List queues
2 | rabbitmqctl -n <node@host> list_queues name messages consumers
3 |
4 | # AMQP reachability
5 | nc -vz <rabbit-host> 5672
```

- Mongo – time-range inspection (mongosh)

```
1 | mongosh "mongodb://<user>:<pass>@<mongo-host>:27017/<db>?
2 |   authSource=admin" --quiet --eval '
3 |   db.recordings.find({
4 |     startTime: {$lte: ISODate("2025-09-25T10:00:00Z")},
5 |     $or: [{endTime: {$gte: ISODate("2025-09-25T10:10:00Z")}}, {endTime:
   |     null}]
6 |   }).limit(5).pretty()'
```

- Kubernetes – NodePort/pods/logs

```
1 | # Services with nodePort (namespace example)
2 | kubectl -n <ns> get svc -o wide | rg focus | rg grpc
3 |
4 | # Find pod and container
5 | kubectl -n <ns> get pods -o wide | rg focus
6 |
7 | # Logs
8 | kubectl -n <ns> logs <pod-name> -c <container> --tail=200
```

- Port readiness before gRPC client

```
1 | nc -vz <focus-host> <stream_port>
```

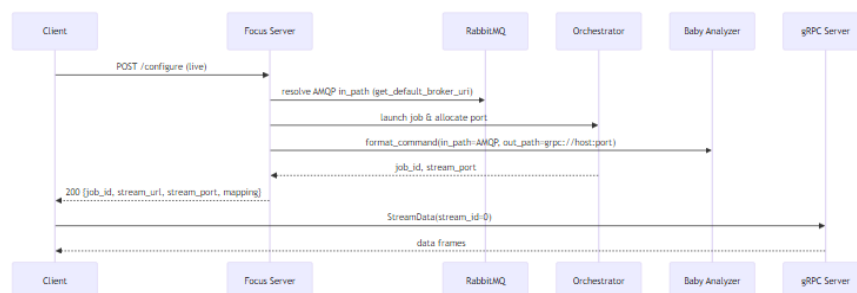
Focus Server flows – detailed, production-grade explanation

Live flow (real-time ingestion → processing → gRPC streaming)

- Preconditions
 - Focus Server REST is reachable; Orchestrator (K8s/Supervisor) healthy.

- RabbitMQ reachable; queues and permissions configured.
- Baby Analyzer binaries/SDK available on the processing node(s).
- Optional: metrics/observability pipeline enabled (Prometheus/OpenTelemetry).
- Request (client → Focus Server)
 - POST /configure without start_time/end_time.
 - Payload fields drive computation: view_type, nfftSelection, displayInfo.height, channels, frequencyRange.
 - The server derives:
 - lines_dt based on view_type and display window
 - internal_nfft and spectrogram overlap (raises internal_nfft if overlap < 0.5, with upper bounds)
 - stream_amount and channel_to_stream_index mapping
 - Validation:
 - Pydantic schema (422 on invalid structure/ranges)
 - Internal guards for overlap, nfft ceiling, and per-view constraints
- Data path selection
 - in_path: AMQP (RabbitMQ) for live data (get_default_broker_uri())
 - queue_name, mq_max_length_bytes, delay_params (when padding/missing chunks logic is enabled)
 - out_path: grpc://host:port (per-job DataStream sink created by orchestrator)
- Orchestration (job lifecycle)
 - Focus Server locks a critical section, generates job_id, chooses stream_port.
 - Orchestrator deploys the job (K8s Pod/Deployment or Supervisor process) and exposes a nodePort/port binding.
 - Baby Analyzer command is formatted with all flags (ROI, spectrogram params, keepalive, etc.) and executed via the launcher.
- Response (Focus Server → client)
 - 200 OK with:
 - job_id, stream_url (host), stream_port
 - channel_to_stream_index, stream_amount, channel_amount
 - frequencies_list, frequencies_amount
 - lines_dt, view_type
- Client consumption
 - Client waits for port readiness (TCP handshake), then opens a gRPC channel to stream frames (StreamData(stream_id)).
 - For multistream jobs, stream_id selection is based on channel_to_stream_index.
- Runtime behavior and backpressure
 - RabbitMQ buffers live input; slow consumers should not lead to unbounded memory growth.
 - Configure bounded queues and DLQ; set retry budgets with jittered backoff to avoid tight loops.
 - Keepalive/health: shorter keepalive for live (e.g., 30s) to fail fast and reconnect.
- Observability and SLOs (recommendations)
 - Metrics: focus_jobs_created_total, focus_jobs_running, focus_jobs_failed_total, focus_queue_depth, focus_config_apply_seconds_bucket
 - gRPC: time_to_first_msg (p95 target), sustained message_count/throughput, error_rate
 - Logs: per-request correlation IDs; classification of errors (client vs system)
- Failures and handling
 - 422: schema/validation errors (bad channels, bad frequency range, view_type mismatch)
 - 503: missing preconditions (validate_required_fields_or_fail)
 - 500: internal parsing/launching error
 - MQ/network hiccups: retries with exponential backoff + jitter, circuit-breaker thresholds
 - Orchestrator failures: job creation rollback, consistent error surfacing to client
- Tuning knobs

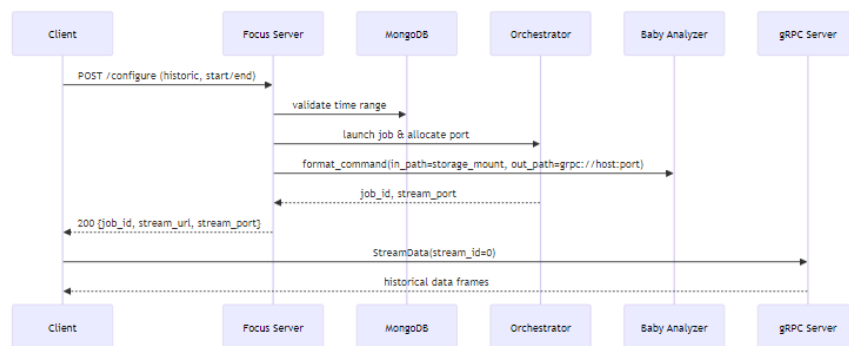
- mq_max_length_bytes, queue_name (namespacing per job)
- nfftSelection, displayTimeAxisDuration, displayInfo.height
- keepalive timeouts, streams_num, resource caps at orchestrator
- enable/disable padding for missing chunks
- Test checkpoints (live)
 - Invariants by view_type (SINGLECHANNEL \Rightarrow channel_amount=1, stream_amount=1)
 - lines_dt > 0 for all views; expected frequency list size
 - Mapping size equals channel_amount
 - Port readiness and successful gRPC frames within SLO
 - Queue depth bounded under slow consumer scenarios



Historic flow (time-range playback from storage → gRPC streaming)

- Preconditions
 - Storage mount with recordings is reachable.
 - MongoDB reachable with recording metadata (RecordingMongoMapper).
 - Orchestrator and Baby Analyzer available.
- Request (client → Focus Server)
 - POST /configure with start_time and end_time (epoch seconds).
 - Server validates time range against Mongo (400 if no recordings exist).
 - Derives same spectrogram and streaming parameters as live, but tuned for historic.
- Data path selection
 - in_path: storage mount (not AMQP)
 - out_path: grpc://host:port (per-job DataStream sink)
 - Additional flags: time_range, mongo_mapper_url; typically longer keepalive (e.g., 180s) to accommodate longer playback windows
- Orchestration (job lifecycle)
 - Same as live: job_id/port allocation, launch via orchestrator, per-job gRPC sink.
- Response (Focus Server → client)
 - 200 OK with job_id, stream_url, stream_port, lines_dt, mapping, etc.
- Client consumption
 - Client connects to gRPC server and reads frames for the requested time window.
 - No dependency on live backpressure patterns; completeness of the selected window is the key.
- Completeness and correctness
 - Ensure all expected frames for the time window are emitted (within defined padding policy).
 - Validate ordering, boundaries, and no duplicate overlaps across the requested ROI/time range.
- Observability and SLOs (recommendations)
 - Metrics: playback duration, frames emitted, gaps encountered (if any), time_to_first_msg (often longer than live)

- Logs: explicit indication of historic path and time window
- SLOs: predictable startup (p95 time_to_first_msg), steady throughput without long stalls
- Failures and handling
 - 400 if no recordings in the given interval (correct and explicit)
 - 422 on schema errors
 - 500/503 on internal/infra failures (storage unmounted, orchestrator unavailable)
 - For partial-read errors, return clear error codes and keep logs/audit
- Tuning knobs
 - time windows (start/end), ROI sizing (channels), nfft/overlap
 - buffer sizes, keepalive timeouts, resource caps for batch processing
- Test checkpoints (historic)
 - Mongo validation (precheck queries return at least one recording overlapping the window)
 - gRPC time_to_first_msg within budget
 - Window completeness (no unexpected gaps beyond configured padding)
 - Consistent frequencies_list and mapping with the provided ROI



Side-by-side (what goes first, where, and why)

- Client always starts with POST /configure → Focus Server decides the path:
 - Live: in_path = AMQP → Orchestrator spawns gRPC → Client streams from gRPC
 - Historic: in_path = Storage (validated by Mongo) → Orchestrator spawns gRPC → Client streams from gRPC
- Focus Server is the control-plane for:
 - Parameter derivation (view_type, lines_dt, nfft, overlap)
 - Job orchestration (launch/port assignment)
 - Selecting ingestion source (AMQP vs Storage)
- Baby Analyzer is the data-plane:
 - Consumes from the selected in_path
 - Emits into per-job gRPC sink
- Observability is end-to-end:
 - Focus Server surfaces job state, metrics, and errors
 - Orchestrator and gRPC servers expose runtime/health signals
 - For live, MQ health and DLQ are critical; for historic, storage and Mongo are critical

