# PCSE 595 Special Topics in Machine Learning

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#### Office Hours

- Please stop by!
- This is an Open Question Answering Time

Monday, Wednesday, Friday 11:00-12:00, 1:00-1:30 Or by appointment

Office hours are in-person (just come by my office, LUTR 325)

# Pizza My Mind

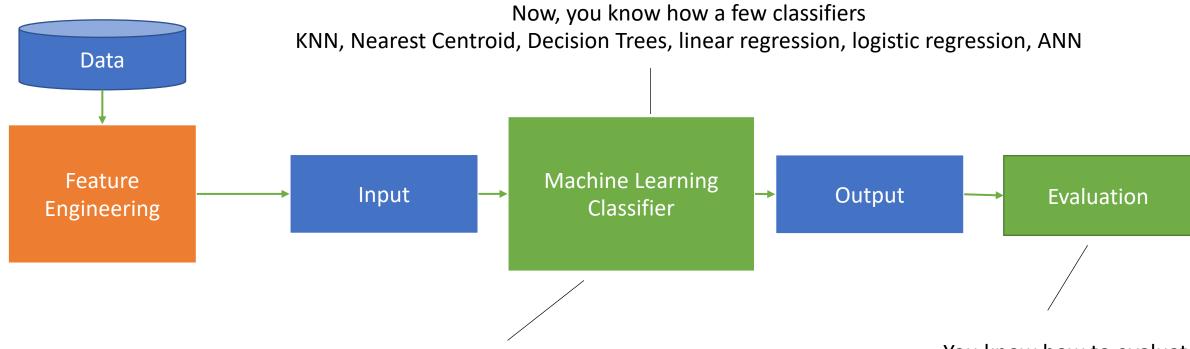
- You can get extra credit
  - Up to two extra points on your final grade for one PCSE course
- Attend them! They're fun, informative, and employers present
  - Don't wait until you need a job or internship, go now!
- Thursdays at 12:20

... and you get free pizza!!



Students in PCSE classes can get extra credit if they attend at least 10 events. 10-11 events: 1 extra point; 12-13 events: 2 extra points.

# A simple machine learning pipeline

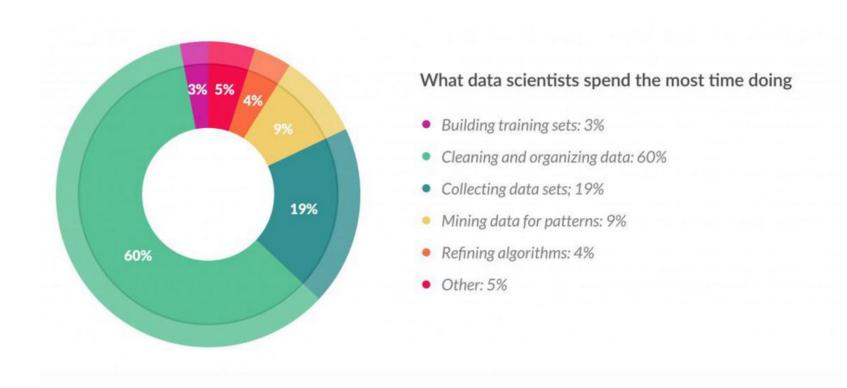


- 1. All supervised learning is focused on optimizing an objective function.
- 2. Optimizers all work kind of like gradient descent
- 3. Loss, regularization, over-fitting, under-fitting, hyper-parameter tuning, etc. are challenges of all classifiers

You know how to evaluate machine learning:

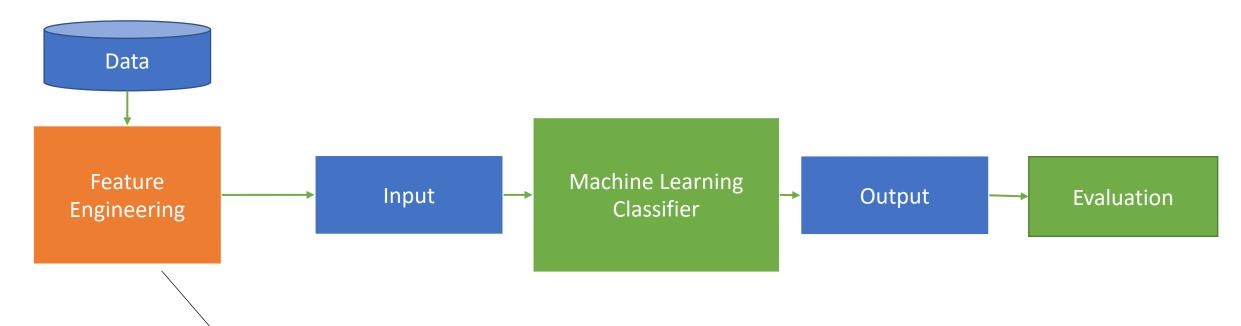
- Evaluation metrics
- Confusion matrices

# Feature Engineering



Collecting, Cleaning, and organizing data takes a lot of time

# A simple machine learning pipeline



Feature Engineering is hard.

It is a manual process that requires a lot of domain expertise and data analysis which is expensive in terms of time and therefore money too.

Why Don't I automatically learn features which serve as input into a machine learning classifier!?

**Deep Learning** 

# Deep Learning



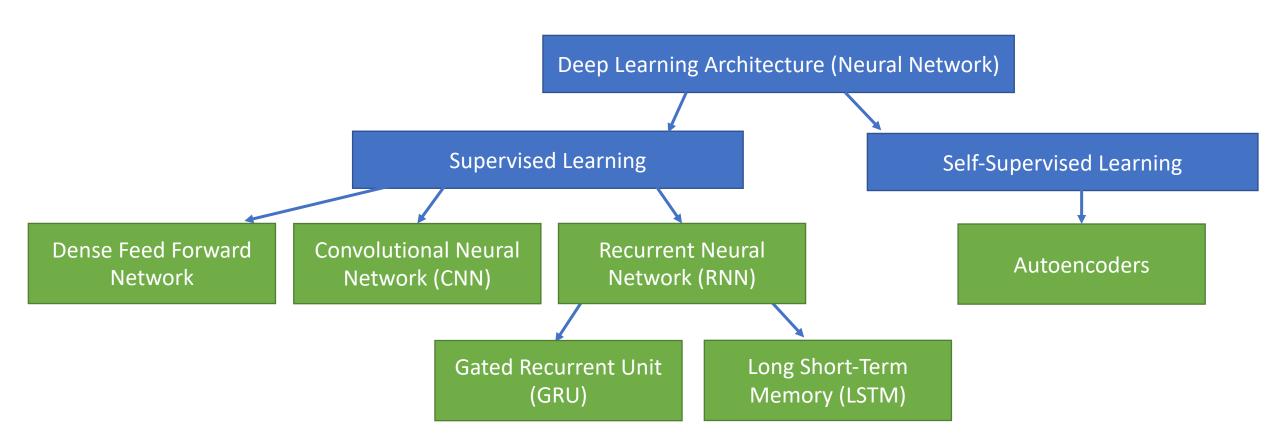
- Deep learning accepts raw data as input and automatically learns features
- Deep learning does this using deep (3+ layer) neural networks
- The actual classifier used can be any that we have learned about, but differentiable classifiers are
  usually used because this allows back-propagation through the entire network
- Deep learning typically requires a massive amount of data (millions of samples) to effectively learn these features (big data)
- There are various configurations of the deep neural networks used for feature engineering this is the variety of deep learning methods we will learn

# Deep Learning?

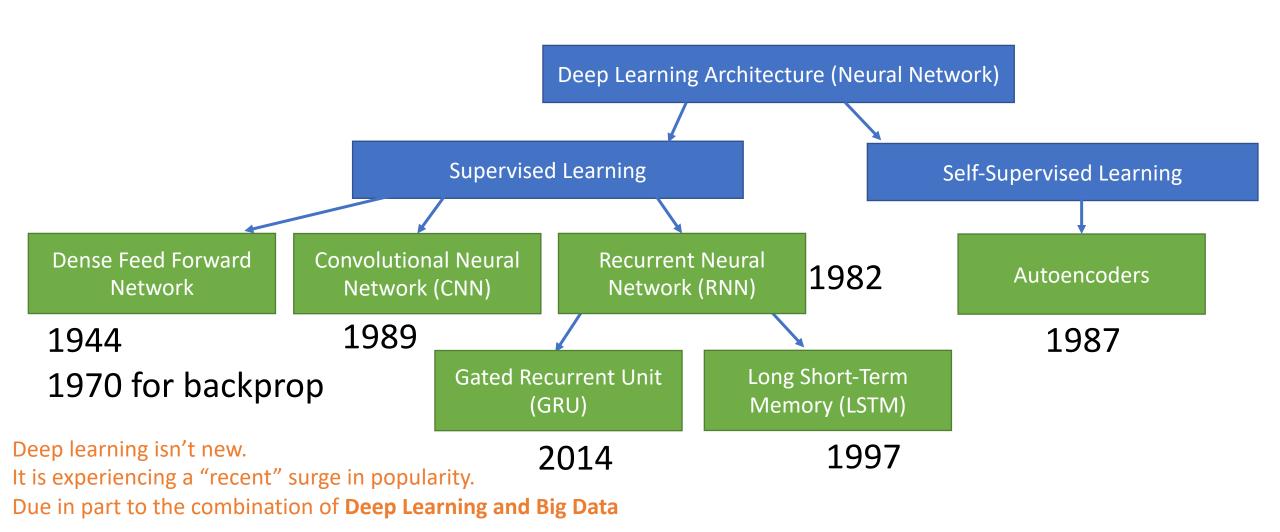
If I create a neural network that has 100 hidden layers am I doing deep learning?

Technically, but really deep learning's goal is for feature engineering Layers are typically connected in specific configurations to encourage the learning of features

# Deep Learning Overview



# Deep Learning Overview



# Why the Surge in Popularity

- Deep learning works really well
- It allows us to solve problems that we can do naturally
  - e.g. understanding vision, language, sounds
- Deep learning algorithms require a lot of data, but most (all?) provably perform better with more data
- The rise of Big Data storage is cheap, and we can record and save everything
- Efficient backpropagation, GPUs and Tensor cores
  - You can parallelize backpropagation
  - GPUs have had a rapid increase in power
  - Tensor cores are specialized cores for matrix multiplication

# Why the Surge in Popularity

 Today a Nvidia RTX 3090 has 35 Tflops of single precision (32bit) performance which is the same as the fastest supercomputer in the world in 2002





# Implementation: TensorFlow and Keras

- Keras is a Python package for deep learning
  - Allows you to program deep neural networks at a high level
- TensorFlow is the first (and most common) backend of Keras
- Theano is an alternative backend

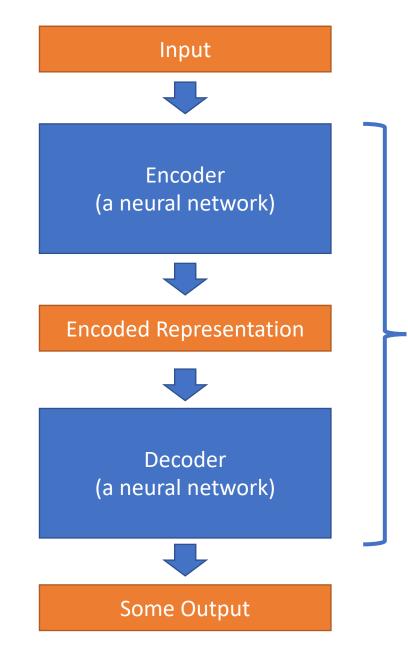
• **Pytorch** is an alternative to Keras

# Encoder-Decoder Architecture

#### Encoder-Decoder

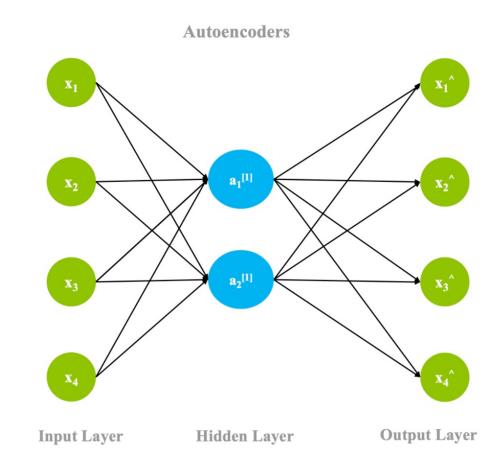
Encoder-Decoders consist of two components

- Encoder transforms the input into a reduced dimensionality encoded representation
- Decoder uses the encoded representation as input and produces some output
- 3. The whole system is set up as a single neural network and the encoder learns efficient encodings for the task via back-propagation
- 4. The encoder can be removed and used for other tasks (transfer learning)

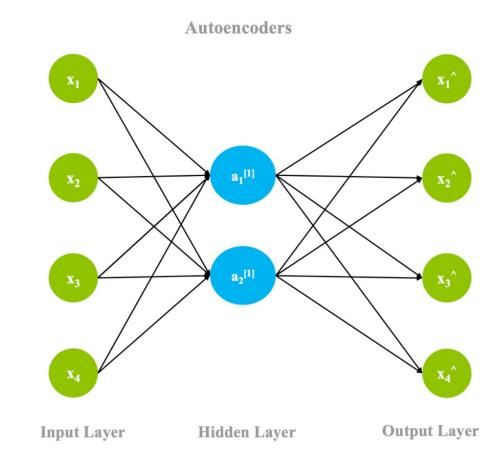


# One example of an Encoder-Decoder Architecture are Autoencoders

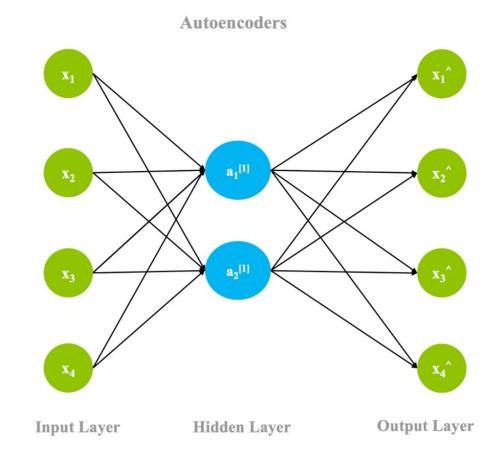
- The first known usage of autoencoders was LeCun in 1987.
- ANN composed of 3 layers: input, hidden, and output
- The goal is to find a compressed data representation that minimizes data loss.
  - These are essentially compression algorithms



- 1. The input layer is encoded into the hidden layer
- 2. The hidden layer contains the compressed representation of the original input
  - The number of nodes in the hidden layer should be much less than the number of nodes in the input layer
- 3. The output layer aims to reconstruct the input layer



- During the training phase:
  - The difference between the input and the output layer is calculated using an error function
  - The weights are adjusted to minimize the error
  - Thereby minimizing the difference between the input and output functions

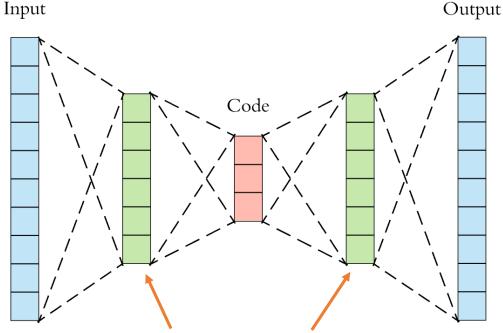


- Autoencoders are mainly compression algorithms
- Example applications:
  - Data Compression for transmitting or storing data
  - Data Interpolation if a dataset or image has some missing values, the autoencoder will likely fill in those values
  - Dimensionality reduction for feature reduction, or even visualizing data

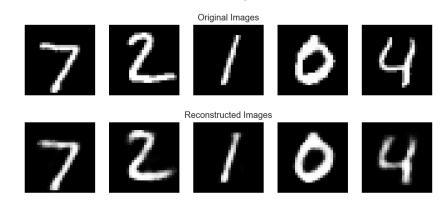
# Self Supervised Learning

- Auto-encoders self-supervised algorithms
- Self-supervised algorithms fall somewhere between unsupervised and supervised learning
  - Unsupervised learning learns patterns in data without labels (input is just the data, X)
  - Supervised learning learns to assign labels to data with labels (input is data, X and labels, Y)
- **Self-supervised algorithms** automatically generate labels (Y) from the input data (X), then learn using supervised learning methods.
  - Autoencoders learn using backward propagation.

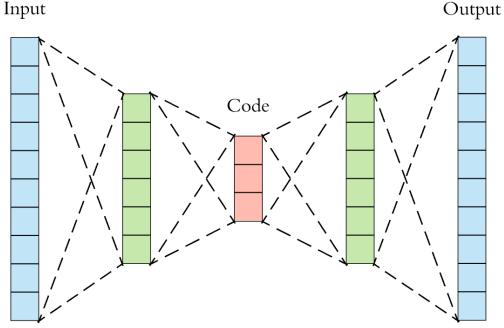
```
input size = 784
hidden_size = 128
code_size = 32
input img = Input(shape=(input size,))
hidden_1 = Dense(hidden_size, activation='relu')(input_img)
code = Dense(code size, activation='relu')(hidden 1)
hidden 2 = Dense(hidden size, activation='relu')(code)
output img = Dense(input size, activation='sigmoid')(hidden 2)
autoencoder = Model(input img, output img)
autoencoder.compile(optimizer='adam', loss='binary_crossentropy')
autoencoder.fit(x_train, x_train, epochs=5)
```



Auto-encoders generally have 1 or more layers between input and encoded layer and output and encoded layer



```
input size = 784
hidden size = 128
code size = 32
input_img = Input(shape=(input_size,))
hidden_1 = Dense(hidden_size, activation='relu')(input_img)
code = Dense(code_size, activation='relu')(hidden 1)
hidden_2 = Dense(hidden_size, activation='relu')(code)
output img = Dense(input size, activation='sigmoid')(hidden 2)
autoencoder = Model(input img, output img)
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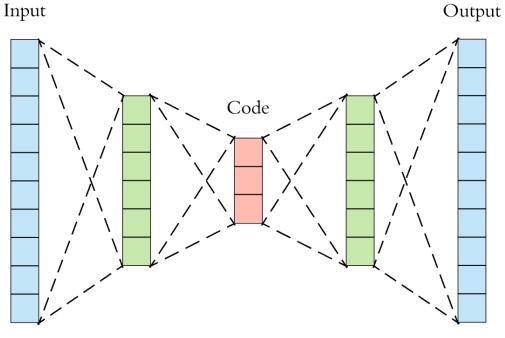


They are constructing the network layer by layer.

They create a new layer, then specify which layer it is connected to in parenthesis afterwards

... this is an older syntax, but I included it so that you would be able to read in when searching online

```
input_size = 784
hidden size = 128
code size = 32
input img = Input(shape=(input size,))
hidden 1 = Dense(hidden size, activation='relu')(input img)
code = Dense(code size, activation='relu')(hidden 1)
hidden_2 = Dense(hidden_size, activation='relu')(code)
output_img = Dense(input_size, activation='sigmoid')(hidden_2)
autoencoder = Model(input img, output img)
autoencoder.compile(optimizer='adam', loss='binary_crossentropy')
autoencoder.fit(x_train, x_train, epochs=5)
```



Create the network, specifying the input and output layers (connections are already specified)

Then, compile and Train it

```
input size = 784
hidden size = 128
code size = 32
input_img = Input(shape=(input_size,))
hidden 1 = Dense(hidden size, activation='relu')(input img)
code = Dense(code size, activation='relu')(hidden 1)
                                                                 Code from the internet, but then I saw this
                                                                Does anyone know what's weird with this?
hidden_2 = Dense(hidden_size, activation='relu')(code)
output_img = Dense(input_size, activation='sigmoid')(hidden_2)
autoencoder = Model(input img, output img)
autoencoder.compile(optimizer='adam', loss='binary crossentropy')
autoencoder.fit(x train, x train, epochs=5)
```

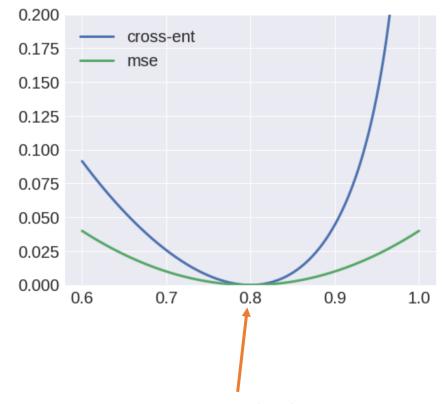
From: https://towardsdatascience.com/applied-deep-learning-part-3-autoencoders-1c083af4d798

#### Potential Problems with this code

- Goal of the network is to minimize the error between the input and output layers
- Applying a sigmoid means that the output will be between 0 and 1
  - This implies that the input must be scaled between 0 and 1 too
    - In the article they briefly mention that they do scale their input between 0 and 1.
    - But, this is a pretty weird thing to do. Why scale pixel values between 0 and 1?

#### Problems with this code

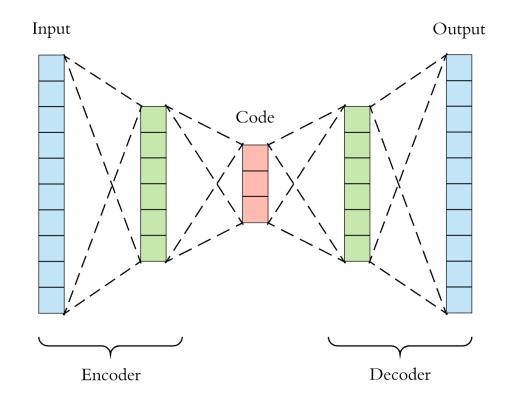
- Using BCE as a loss function isn't really appropriate either
  - It may work, but again, its weird.
  - You are minimizing the error between the input and output pixels
  - Do we expect the pixels to have values either0 and 1?
  - Do the pixel values indicate any kind of probability of belonging to a class?
- This is really a regression tasks, so use Mean Squared Error (MSE) or something similar



Target Pixel value is 0.8 Why penalize more for 0.9 than 0.7?

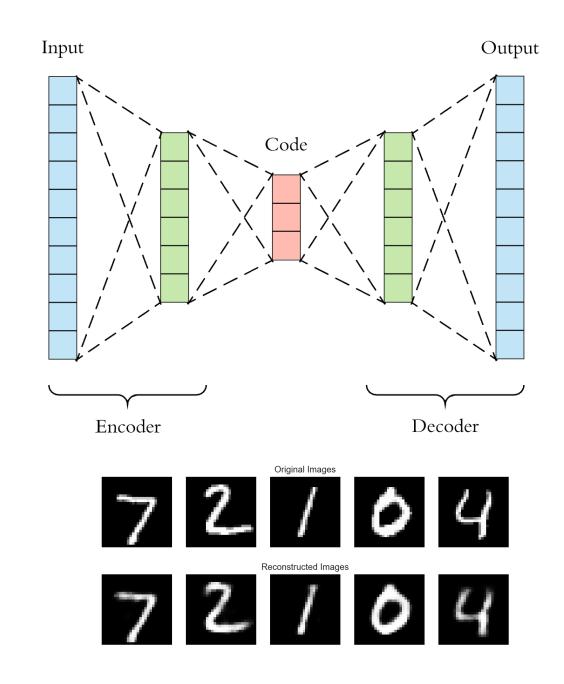
#### Encoder-Decoders

- More Generally, auto-encoders have an Encoder-Decoder architecture
- Specifically, they are a special case of encoder-decoders, where the input and output are the same
- Encoder-Decoders have two parts
  - 1. Encoder represent input in some encoded (typically compressed format)
  - 2. Decoder use the encoded representation as input for some task



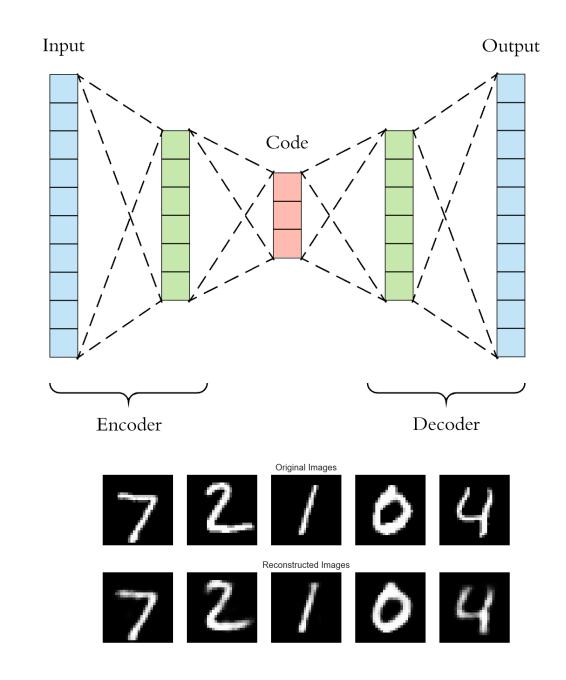
#### Encoder

- The encoder encodes data by finding weights that map it to a compressed format
- The idea is that the compression removes variation in the input to a more general representation
- The removed variation can be thought of as noise



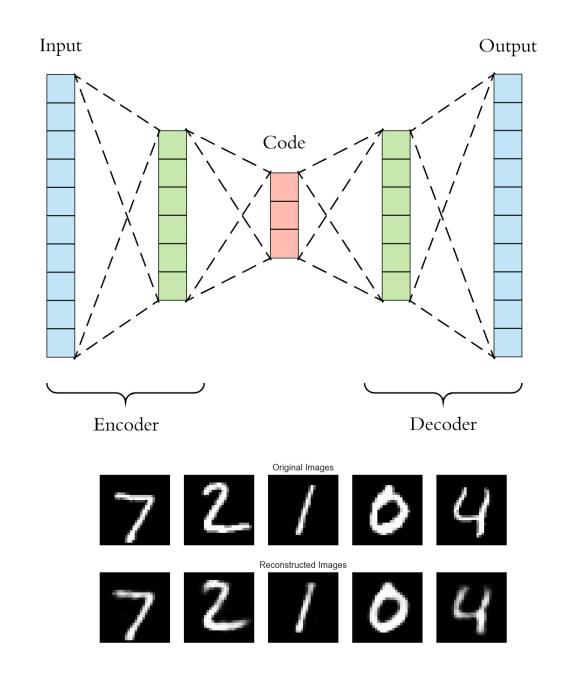
#### Decoder

- The decoder decodes the compressed format by finding weights that minimize loss.
- Since the encoded representation reduces noise, ideally it makes the task of the decoder easier

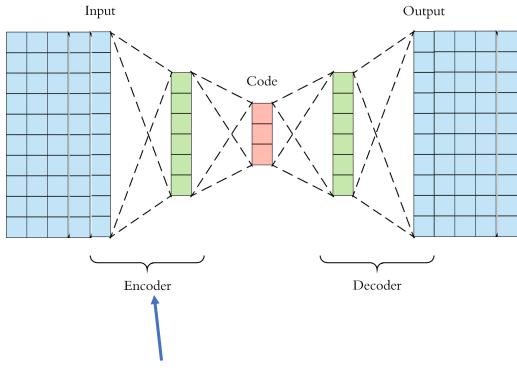


# Transfer Learning

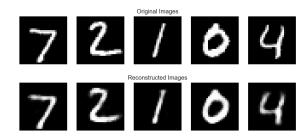
- Encoder-Decoder architectures are often used to facilitate transfer learning
- Transfer learning using the weights of a model trained for one task as the starting point of the weights of a network for another task



# Transfer Learning with Encoder-Decoders



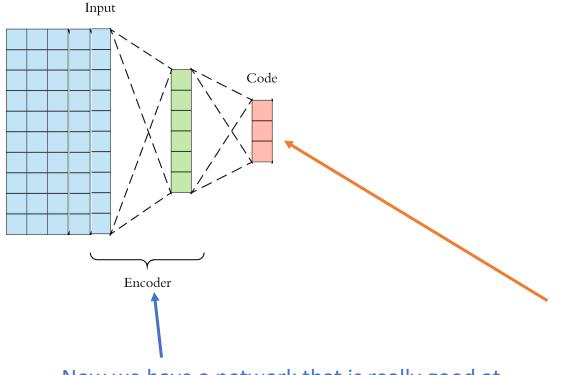
The encoder gets really good at compressing the images into a meaningful representation that removes noise and that is good at generalizing to new samples



What if we remove the decoder part of the architecture and put a neural network for a different task on?

Input and output are an image (so I added more vectors)

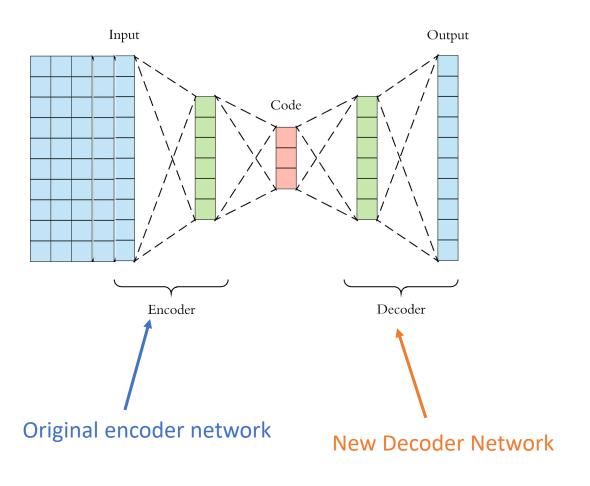
# Transfer Learning with Encoder-Decoders



Now we have a network that is really good at encoding things

This is a great compressed representation of the input image

# Transfer Learning with Encoder-Decoders



- 1. Remove the old decoder
- 2. Replace it with a new network
- 3. Train the network for the new task

