



Part 2 = Gonecting LED objective is to turn on LEO when obstacle is detected 1 Connected arzog follow theboard to the breadboard. 2 Connect the point of LED to breadboard 3. connect negative pant of LED to the breadboard Now we are ready to send signal based on 110 received from TR sonor to turn on loft the 40. Part 3 8code to connect IR sensor IP with LFD status Part 4 :- Executing the code - open terminal - Navigate to directory where the above code is waved Type & python3 is obstacle by a press enter Conclusion :-Thus, we done connectivity of Responery pil Beggle board circuit with TIR sensor. wite an application to detect obstacle + notity usee using LED's.



IR Sensor Fig.1