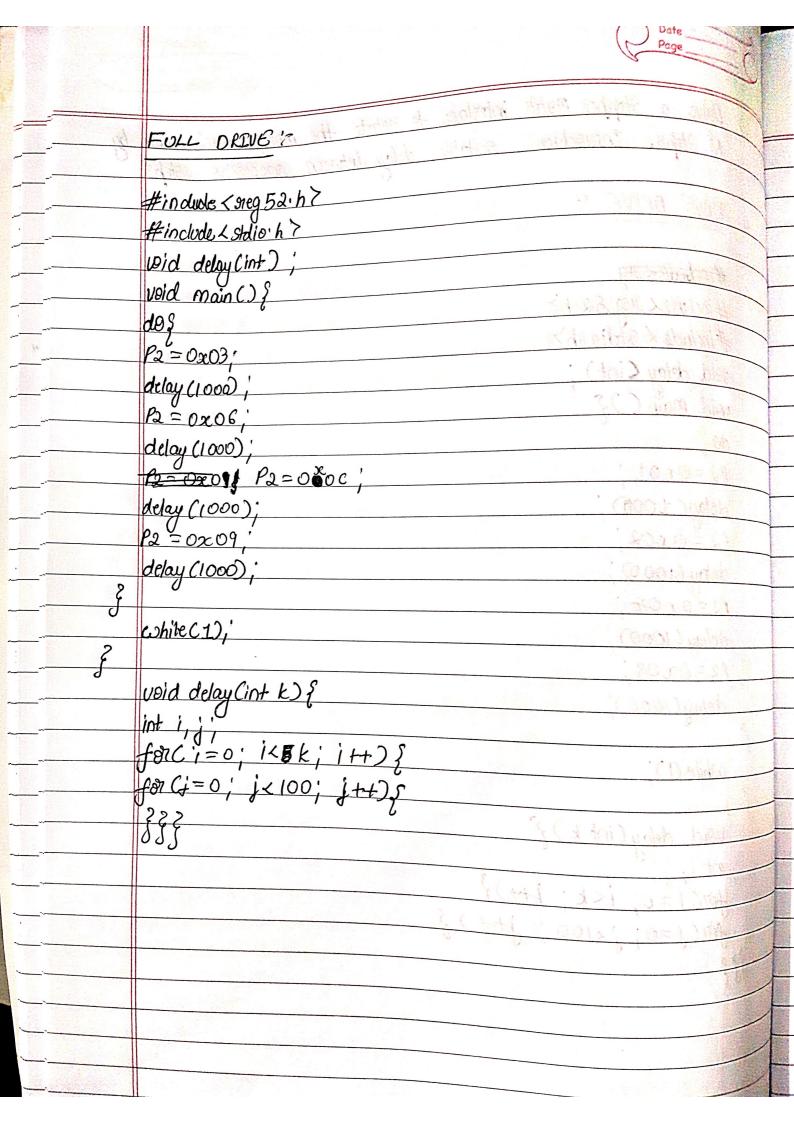
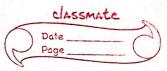
	Drive a Stepper Motor interface of N Steps. Introduce suitable		
A.	WAVE DRIVE !-	< 1 with 7 yellow to	
		CARL HARDEN LIVE D.	
	#ind-cde-< 319	Act woin The	
10.A	# include & sieg 52.ht	( N)	
	#include & stdio h>	Par 2003	
	void delay (int);	Alley (1000)	
	wid main () {	<u> </u>	
	do {	(Cont) with	
	P2=0x01;	the second Paradesco	
	delay(1000);	Stelay (1000)	-
	12 = 0x02;	- 10 x 0 3 (4)	
- 4 T	delay (1000); P2=0x04;	delay (1000);	2
	$P2 = 0 \times 0 + \frac{1}{12}$	* C v v . E v	
	delay (1000);	Karingto (12).	- <
	P2=0x08;	273 127 23 2	5
ې	delay (1000);	FCA tool year to be	
	while (1);	3 (41) 931 1 3	
2	wince,	7 (4-1 100) 11 100	
J	void delay Cint k) ?		
	Int I i.		
	forci=0; i <k; 1+t)="" td="" {<=""><td></td><td></td></k;>		
	forcj=0; j<100; j++) }		
25			
99			





	4
HALF DRIVE :-	
#include < steg 52.h>	
#indude, < stdie it >	
void delay(int);	
void delayCint); void main() {	
do §	
P2=0x01.	
delay = (1000);	
R=0x03;	
delay (1000); P2=0x02;	
delay (1000);	
delay (1000); P2= 0x06;	
delay (1000);	
delay(1000); $f2 = 0x04;$	
delay (1000);	
delay(1000); $l2 = 0x oC;$	
delay (1000);	
12=0008;	
delay (1000);	
delay (1000); 12 = 0x09;	
delay(1000);	
}	
while (1);	
3	
void delay (int k) }	
Int iii	
forci=0; i <k; i++)="" td="" }<=""><td></td></k;>	
for Cj=0; L<100; j+) }	
2 22	
015	