Assignment 1

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PROBLEM II (2I)

1 Solution

Let the points be

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix} \; ; \; \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \; = \begin{pmatrix} 7 \\ 6 \end{pmatrix} \tag{1.0.1}$$

In order to convert to rectangular coordinate system, the y-axis should be rotated by 30° in anticlockwise. Transformed coordinates of $\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} & \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$

be
$$\begin{pmatrix} x_3 \\ y_3 \end{pmatrix}$$
 & $\begin{pmatrix} x_4 \\ y_4 \end{pmatrix}$ respectively.
 $x_3 = OX_1 + X_1X_3 = x_1 + y_1\cos 60^\circ$
 $y_3 = OY_1\cos 30^\circ = y_1\cos 30^\circ$

$$\begin{pmatrix} x_3 \\ y_3 \end{pmatrix} = \begin{pmatrix} 1 & \cos 60^\circ \\ 0 & \cos 30^\circ \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix}$$
 (1.0.2)

Similarly,

$$x_4 = OX_2 + X_2X_4 = x_2 + y_2\cos 60^\circ$$

 $y_4 = OY_2\cos 30^\circ = y_2\cos 30^\circ$

$$\begin{pmatrix} x_4 \\ y_4 \end{pmatrix} = \begin{pmatrix} 1 & \cos 60^\circ \\ 0 & \cos 30^\circ \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$$
 (1.0.3)

The generalised equation for transformed coordinates $\begin{pmatrix} x_t \\ y_t \end{pmatrix}$ when the angle between axes ' θ is,

$$\begin{pmatrix} x_t \\ y_t \end{pmatrix} = \begin{pmatrix} 1 & \cos(\theta) \\ 0 & \sin(\theta) \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$
 (1.0.4)

Substituting (1.0.1) in (1.0.2) & (1.0.3)

$$\begin{pmatrix} x_3 \\ y_3 \end{pmatrix} = \begin{pmatrix} \frac{13}{2} \\ \frac{5\sqrt{3}}{2} \end{pmatrix}; \ \begin{pmatrix} x_4 \\ y_4 \end{pmatrix} = \begin{pmatrix} 10 \\ 3\sqrt{3} \end{pmatrix}$$
 (1.0.5)

Find the distance between points $\binom{7}{6}$ and $\binom{4}{5}$ with The distance between points is $\left\| \begin{pmatrix} x_3 \\ y_3 \end{pmatrix} - \begin{pmatrix} x_4 \\ y_4 \end{pmatrix} \right\| =$ the axes at 60° $\left\| \begin{pmatrix} 10 \\ 3\sqrt{3} \end{pmatrix} - \begin{pmatrix} \frac{13}{2} \\ \frac{5\sqrt{3}}{2} \end{pmatrix} \right\| = \sqrt{13} \text{ units}$

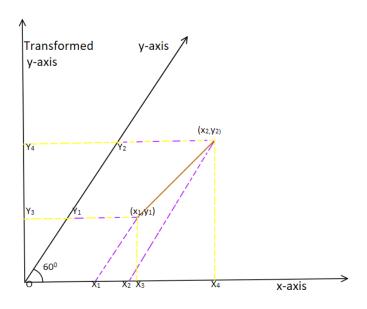


Fig1: Points defined on angular & rectangular axes

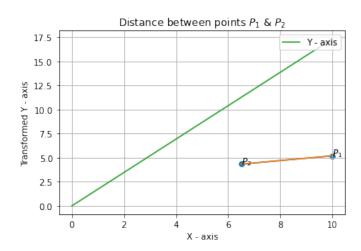


Fig2: Points plotted in Python