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| **SUBJECT** | DAA |
| **EXPERIMENT NO:** | 08 |
| **AIM:** | To implement Branch and Bound Strategy |
| **Algorithm:** | 1. Start by initializing the algorithm with the initial configuration of the puzzle and an empty set of explored states. 2. Create a node representing the initial configuration of the puzzle and add it to the list of promising nodes. 3. While there are unexplored nodes in the search tree, select the most promising node to explore next. The most promising node can be chosen based on some heuristic, such as the number of misplaced tiles or the Manhattan distance between the current configuration and the goal configuration. 4. Generate the child nodes of the selected node by moving the empty space in each of the four directions (up, down, left, and right). Each child node represents a new configuration of the puzzle. 5. For each child node, check if it represents a previously explored state. If it does, discard it and continue to the next child node. Otherwise, compute the heuristic value for the child node and add it to the list of promising nodes. 6. If the heuristic value for a child node is zero, it represents the goal state of the puzzle, and the optimal solution has been found. Return the sequence of moves that lead from the initial state to the goal state. 7. If there are no promising nodes left, the puzzle cannot be solved from the initial configuration. Return "unsolvable". 8. Repeat steps 3-7 until a solution is found or the search is exhausted. |
| **Code:** | #include<stdio.h>  #include<conio.h>  int m=0,n=4;  int cal(int temp[10][10],int t[10][10])  {  int i,j,m=0;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  {  if(temp[i][j]!=t[i][j])  m++;  }  return m;  }  int check(int a[10][10],int t[10][10])  {  int i,j,f=1;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  if(a[i][j]!=t[i][j])  f=0;  return f;  }  void main()  {  int p,i,j,n=4,a[10][10],t[10][10],temp[10][10],r[10][10];  int m=0,x=0,y=0,d=1000,dmin=0,l=0;  clrscr();  printf("\nEnter the matrix to be solved,space with zero :\n");  for(i=0;i < n;i++)  for(j=0;j < n;j++)  scanf("%d",&a[i][j]);  printf("\nEnter the target matrix,space with zero :\n");  for(i=0;i < n;i++)  for(j=0;j < n;j++)  scanf("%d",&t[i][j]);  printf("\nEntered Matrix is :\n");  for(i=0;i < n;i++)  {  for(j=0;j < n;j++)  printf("%d\t",a[i][j]);  printf("\n");  }  printf("\nTarget Matrix is :\n");  for(i=0;i < n;i++)  {  for(j=0;j < n;j++)  printf("%d\t",t[i][j]);  printf("\n");  }  while(!(check(a,t)))  {  l++;  d=1000;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  {  if(a[i][j]==0)  {  x=i;  y=j;  }  }  //To move upwards  for(i=0;i < n;i++)  for(j=0;j < n;j++)  temp[i][j]=a[i][j];  if(x!=0)  {  p=temp[x][y];  temp[x][y]=temp[x-1][y];  temp[x-1][y]=p;  }  m=cal(temp,t);  dmin=l+m;  if(dmin < d)  {  d=dmin;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  r[i][j]=temp[i][j];  }  //To move downwards  for(i=0;i < n;i++)  for(j=0;j < n;j++)  temp[i][j]=a[i][j];  if(x!=n-1)  {  p=temp[x][y];  temp[x][y]=temp[x+1][y];  temp[x+1][y]=p;  }  m=cal(temp,t);  dmin=l+m;  if(dmin < d)  {  d=dmin;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  r[i][j]=temp[i][j];  }  //To move right side  for(i=0;i < n;i++)  for(j=0;j < n;j++)  temp[i][j]=a[i][j];  if(y!=n-1)  {  p=temp[x][y];  temp[x][y]=temp[x][y+1];  temp[x][y+1]=p;  }  m=cal(temp,t);  dmin=l+m;  if(dmin < d)  {  d=dmin;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  r[i][j]=temp[i][j];  }  for(i=0;i < n;i++)  for(j=0;j < n;j++)  temp[i][j]=a[i][j];  if(y!=0)  {  p=temp[x][y];  temp[x][y]=temp[x][y-1];  temp[x][y-1]=p;  }  m=cal(temp,t);  dmin=l+m;  if(dmin < d)  {  d=dmin;  for(i=0;i < n;i++)  for(j=0;j < n;j++)  r[i][j]=temp[i][j];  }  printf("\nCalculated Intermediate Matrix Value :\n");  for(i=0;i < n;i++)  {  for(j=0;j < n;j++)  printf("%d\t",r[i][j]);  printf("\n");  }  for(i=0;i < n;i++)  for(j=0;j < n;j++)  {  a[i][j]=r[i][j];  temp[i][j]=0;  }  printf("Minimum cost : %d\n",d);  }  getch() |
| **Output:** |  |
| **Conclusion:** | Thus we have solved the 15 Puzzle Problem Using Branch and Bound Strategy. |