

Prithvijit Chattopadhyay

<https://prithv1.github.io/>

Email : prithvijit3@gatech.edu

Mobile : +1-540-277-7523

EDUCATION

- **Georgia Institute of Technology** Atlanta, GA
Master of Science in Computer Science; Advised by Dr. Devi Parikh Aug. 2017
- **Delhi Technological University (DTU)** Delhi, India
Bachelor of Technology in Electrical Engineering; GPA: 4.00 Aug. 2012 – Dec. 2016

RESEARCH INTERESTS

Computer Vision, Machine Learning, AI, Interpretability in Deep Networks, Human-AI Collaboration

PUBLICATIONS

- **Choose Your Neuron: Incorporating Domain Knowledge Through Neuron-Importance**
*European Conference on Computer Vision (ECCV) 2018, **Poster***
R. Selvaraju*, **P. Chattopadhyay***, M. Elhoseiny, T. Sharma, D. Batra, D. Parikh, S. Lee
- **Do Explanations make VQA models more predictable to a human?**
*Submitted to Conference on Empirical Methods in Natural Language Processing (EMNLP) 2018, **Poster***
A. Chandrasekaran*, V. Prabhu*, D.Yadav*, **P. Chattopadhyay***, D. Parikh
- **Evaluating Visual Conversational Agents via Cooperative Human-AI Games**
*AAAI Conference on Human Computation and Crowdsourcing (HCOMP) 2017, **Oral***
P.Chattopadhyay*, D.Yadav*, V. Prabhu, A. Chandrasekaran, A. Das, S. Lee, D. Batra, D. Parikh
- **It Takes Two to Tango: Towards Theory of AI's Mind**
Chalearn Looking at People Workshop, CVPR 2017 - Explainable Computer Vision Track
A. Chandrasekaran*, D.Yadav*, **P. Chattopadhyay*** V. Prabhu*, D. Parikh
- **Counting Everyday Objects in Everyday Scenes**
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2017, **Spotlight***
P.Chattopadhyay*, R.Vedantam*, R. Selvaraju, D. Batra, D. Parikh
- **Delhi Technological University: Design and Development of the Littoral AUV Zyra 2.0**
*AUVSI RoboSub Journal 2014, **Journal***

ACHEIVEMENTS

- **Recipient:** MS Research Award 2018 - College of Computing, Georgia Tech
- **Winner:** VT-Hacks, 2017, a Major League Hacking event.
- **Semi-Finalists:** ROBOSUB - AUVSI, 2013
- **Finalists:** NIOT SAVe, 2013
- **Selected:** KVPY and INSPIRE Fellowships, 2012
- **National Top 1 Percent:** Indian National Physics Olympiad (InPhO), 2013

EXPERIENCE

- **Deep Learning Group, Microsoft Research AI** Redmond, WA
Research Intern, mentored by Hamid Palangi May 2018 - August 2018
Improving goal-driven visually grounded dialog under the presence of an adversarial utterance evaluator.
- **Computer Vision Lab, Georgia Tech** Atlanta, GA
Research Assistant, mentored by Dr. Devi Parikh and Dr. Dhruv Batra Fall 2017 - Current
Working on problems at the intersection of computer vision and natural language processing with a focus towards building intelligent and interpretable systems and subsequently studying their behavior in the context of human-AI interaction.

- CVMLP Lab, Virginia Tech** Blacksburg, VA
Research Assistant, mentored by Dr. Devi Parikh and Dr. Dhruv Batra *Jun 2015 - May 2017*
 Worked on scene-understanding problems such as object detection and counting in everyday scenes with a downstream focus towards visual question answering.
- Robotics Research Lab, IIIT Hyderabad** Hyderabad, India
Research Intern, mentored by Dr. K Madhava Krihsna *Dec 2014 - Jan 2015*
 Implemented an efficient strategy for a robot to discover, recognize and navigate to a selected few objects among some scattered in an environment, based on a - guess from far and recognize from near - strategy.
- Indian Association for the Cultivation of Science, Kolkata** Kolkata, India
Research Intern, mentored by Dr. Soumitra Sengupta *Jun 2014 - Aug 2014*
 Worked on finding Charged Rotating Black Hole solutions in Einstein-Gauss-Bonnet dilaton coupled gravity and simulated the conditions for the existence of multiple horizons in constant scalar curvature $f(R)$ gravity.
- Autonomous Underwater Vehicle Team, DTU** New Delhi, India
Undergraduate Researcher, mentored by Dr. R K Sinha *Aug 2012 - Aug 2016*
 - Underwater Acoustics:** Developed and implemented range estimation algorithms for Passive Source Localization from Time Difference of Arrival (TDOA) values in conjunction with machine vision techniques.
 - Control Systems:** Designed control modules of the AUV. Implemented simultaneous PID loops to maintain the orientation of the AUV in motion.

SELECTED PROJECTS

- Incorporating Domain Knowledge in Neurons:** We introduce a simple, highly efficient zero-shot learning approach that learns to map domain knowledge about novel classes onto the neurons in a deep network by solving for network parameters which can effectively combine ‘concepts’ learned by neurons - essentially learning novel deep classifiers. Inverting these mappings allows us to provide visual and textual explanations for predictions made by the newly learned classifiers for unseen classes.
- Evaluating Visual Conversational Agents:** We designed a cooperative ‘image-guessing’ game - GuessWhich - to evaluate state-of-the-art visual conversational agents by pairing them with humans under a dialog-based image retrieval setting. Our human studies suggest a counter-intuitive trend - that while AI literature shows that while RL finetuned chatbot teams perform better compared to chatbots trained in a supervised fashion for this task; this improvement in performance does not translate to human-AI teams suggesting a potential disconnect between benchmarking of AI in isolation and in the context of human-AI teams.
- Theory of AI’s Mind:** We argue that for human-AI teams to be effective, humans must also develop a theory of AI’s mind (ToAIM) - get to know its strengths, weaknesses, beliefs, and quirks. Instantiating these ideas within the domain of Visual Question Answering (VQA), we find that using just a few examples (50), lay people can be trained to better predict responses and oncoming failures of a complex VQA model. We further evaluate the role existing explanation (or interpretability) modalities play in helping humans build ToAIM. Our results indicate that existing explanation modalities do not make VQA models more *legible*.
- EvalAI:** We designed an open source platform to help researchers, students and data scientists to host and participate in AI challenges. By simplifying and standardizing the process of benchmarking AI, EvalAI aims to circumvent many of the factors impeding the rate of progress in AI such as - standardized evaluation protocols, faster evaluation, etc.
- Counting in Everyday Scenes:** We build dedicated models for counting designed to tackle the large variance in counts, appearances, and scales of objects found in natural scenes. Our approach is inspired by the phenomenon of subitizing - the ability of humans to make quick assessments of counts given a perceptual signal, for small count values. Given a natural scene, we employ a divide and conquer strategy while incorporating context across the scene to adapt the subitizing idea to counting.

PROGRAMMING SKILLS

- Languages:** C++, Python, Matlab, Lua, \LaTeX , Shell
- Frameworks:** Caffe, Torch/PyTorch, Keras, Tensorflow, ROS, PCL, OpenCV, Qt