Prithvijit Chattopadhyay

https://prithv1.github.io/

EDUCATION

School of Interactive Computing, Georgia Tech

Atlanta, GA

Doctor of Philosophy in Computer Science; Advised by Prof. Judy Hoffman

Aug 2019 - Present

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College of Computing, Georgia Tech

Atlanta, GA

Master of Science in Computer Science; Advised by Prof. Devi Parikh

Aug 2017 - May 2019

Delhi Technological University (DTU)

Delhi, India

Bachelor of Technology in Electrical Engineering; CPI: 81.30/100

Aug 2012 - Dec 2016

Research Interests

Computer Vision, Natural Language Processing, Few-shot and Continual Learning, Reinforcement Learning

RESEARCH EXPERIENCE

Deep Learning Group, Microsoft Research AI

Redmond, WA

Research Intern, mentored by Hamid Palangi

May 2018 - Aug 2018

Improving goal-driven visually grounded dialog under the presence of an adversarial utterance evaluator.

Visual Intelligence Lab, Georgia Tech

Atlanta, GA

Research Assistant, mentored by Prof. Devi Parikh and Prof. Dhruv Batra

Aug 2017 - Aug 2019

Working on problems at the intersection of computer vision and natural language processing with a focus towards building intelligent and interpretable systems.

CVMLP Lab, Virginia Tech

Blacksburg, VA

Research Assistant, mentored by Prof. Devi Parikh and Prof. Dhruv Batra

Jun 2015 - May 2017

Worked on scene-understanding problems such as object detection and counting in everyday scenes with a downstream focus towards visual question answering.

Robotics Research Lab, IIIT Hyderabad

Hyderabad, India

Research Intern, mentored by Prof. K Madhava Krishna

Dec 2014 - Jan 2015

Implemented an efficient strategy for a robot to discover, recognize and navigate to a selected few objects among some scattered in an environment, based on a - guess from far and recognize from near - strategy.

Indian Association for the Cultivation of Science, Kolkata

Kolkata, India

Research Intern, mentored by Prof. Soumitra Sengupta

Jun 2014 - Aug 2014

Worked on finding Charged Rotating Black Hole solutions in Einstein-Gauss-Bonnet dilaton coupled gravity and simulated the conditions for the existence of multiple horizons in constant scalar curvature f(R) gravity.

Autonomous Underwater Vehicle Team, DTU

New Delhi, India

Undergraduate Researcher, mentored by Prof. R K Sinha

Aug 2012 - Aug 2016

- Underwater Acoustics: Developed and implemented range estimation algorithms for Passive Source Localization from Time Difference of Arrival (TDOA) values in conjunction with machine vision techniques.
- Control Systems: Designed control modules of the AUV. Implemented simultaneous PID loops to maintain the orientation of the AUV in motion.

ACHEIVEMENTS

- Outstanding Reviewer: ICLR 2019
- Recipient: IC Student Travel Grant to attend NeurIPS 2018
- Among Top 30% Reviewers: NeurIPS 2018
- Recipient: MS Research Award 2018 College of Computing, Georgia Tech
- Winner: VT-Hacks, 2017, a Major League Hacking event.
- Semi-Finalists: ROBOSUB AUVSI, 2013 out of 30 participating teams
- Finalists: NIOT SAVe, 2013 out of 27 participating teams
- Recipient: Merit Scholarships for Academic Performance (2012-2014)
- Selected: KVPY and INSPIRE Fellowships, 2012
- National Top 1%: Indian National Physics Olympiad (InPhO), 2013

(* denotes equal contribution)

- Improving Generative Visual Dialog by Answering Diverse Questions

 Conference on Empirical Methods in Natural Language Processing (EMNLP) 2019,

 V. Murahari, P. Chattopadhyay, D. Batra, D. Parikh, A. Das
- Choose Your Neuron: Incorporating Domain Knowledge Through Neuron-Importance
 European Conference on Computer Vision (ECCV) 2018, (Poster)
 Continual Learning Workshop, NeurIPS 2018, (Poster)
 Visually Grounded Interaction and Language (ViGIL), NeurIPS 2018, (Poster)
 R. Selvaraju*, P. Chattopadhyay*, M. Elhoseiny, T. Sharma, D. Batra, D. Parikh, S. Lee
- Do Explanations make VQA models more predictable to a human?

 Conference on Empirical Methods in Natural Language Processing (EMNLP) 2018, (Poster)

 A. Chandrasekaran*, V. Prabhu*, D.Yadav*, P. Chattopadhyay*, D. Parikh
- Evaluating Visual Conversational Agents via Cooperative Human-AI Games AAAI Conference on Human Computation and Crowdsourcing (HCOMP) 2017, (Oral) P.Chattopadhyay*, D.Yadav*, V. Prabhu, A. Chandrasekaran, A. Das, S. Lee, D. Batra, D. Parikh
- It Takes Two to Tango: Towards Theory of AI's Mind

 Chalearn Looking at People Workshop, CVPR 2017 Explainable Computer Vision Track, (Oral)

 A. Chandrasekaran*, D.Yadav*, P. Chattopadhyay*, V. Prabhu*, D. Parikh
- Counting Everyday Objects in Everyday Scenes

 IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2017, (Spotlight)

 P.Chattopadhyay*, R.Vedantam*, R. Selvaraju, D. Batra, D. Parikh

Manuscripts

- Unsupervised Discovery of Decision States for Transfer in Reinforcement Learning ArXiv 2019, (Under Review)

 Task-Agnostic Reinforcement Learning (TARL) Workshop, ICLR 2019, (Poster)

 N. Modhe, P. Chattopadhyay, M. Sharma, A. Das, D. Parikh, D. Batra, R. Vedantam
- EvalAI: Towards Better Evaluation Systems for AI Agents

 ArXiv 2019, (Technical Report)

 D. Yadav, R. Jain, H. Agrawal, P. Chattopadhyay, T. Singh, A. Jain, S. Singh, S. Lee, D. Batra
- Delhi Technological University: Design and Development of the Littoral AUV Zyra 2.0 AUVSI RoboSub Journal 2014, (Technical Report)

Professional Services

• Conference: Reviewer for CVPR 2018, ECCV 2018, NeurIPS (2018, 2019), ICLR (2019, 2020), ICML 2019, ACL 2019

Coursework

- Graduate Coursework: Deep Learning, Machine Learning, Probabilistic Graphical Models in Machine Learning, Machine Learning Theory, Computability and Algorithms, Adaptive Control and Reinforcement Learning
- Selected Undergraduate Coursework: Control Systems, Advanced Analog Circuit Design, Network Analysis and Circuit Theory, Microprocessors, Electromagnetic Field Theory, Pattern Recognition, Digital Electronics

Selected Projects

- Incorporating Domain Knowledge in Neurons: We propose a simple, efficient, interpretable zero-shot learning approach. By explicitly grounding intermediate concepts captured by neurons in human-interpretable domains, our approach Neuron-Importance Aware Weight Transfer (NIWT) not only allows learning deep classifiers for novel classes but also helps in explaining the decisions made by such classifiers at a fine-grained level of neurons.
- Evaluating Visual Conversational Agents: We designed a cooperative 'image-guessing' game GuessWhich to evaluate the utility of state-of-the-art visual dialog agents by pairing them with humans. While AI literature suggests agents (chatbots) trained in such a collaborative self-play setting via RL perform better than their SL counterparts our human studies suggest this improvement in performance does not translate to human-AI teams.

SKILLS

- Languages: C++, Python, Matlab, Lua
- Libraries: Torch, PyTorch, Tensorflow, Keras, Caffe, OpenCV, ROS, NLTK

References

- Prof. Devi Parikh, Georgia Tech (email: parikh@gatech.edu)
- Prof. Dhruv Batra, Georgia Tech (email: dbatra@gatech.edu)
- Prof. Stefan Lee, Oregon State University (email: steflee@gatech.edu)
- Prof. Mohamed H. Elhoseiny, KAUST (email: mohamed.elhoseiny@kaust.edu.sa)