Prithvijit Chattopadhyay

CODA, 756 West Peachtree St. NW, Atlanta, Georgia - 30308

prithv1.xyz prithvijit3@gatech.edu (+1) 470-535-9524

RESEARCH AREAS Out-of-Distribution Generalization, Robust Machine Learning, Embodied RL

EDUCATION

School of Interactive Computing, Georgia Tech

2019 - Present

Ph.D. in Computer Science Advised by Prof. Judy Hoffman

College of Computing, Georgia Tech

2017 - 2019

M.S. in Computer Science Advised by Prof. Devi Parikh

Thesis: Evaluating Visual Conversational Agents via Cooperative Human-AI Games

Awarded M.S. Research Award

Delhi Technological University (Formerly DCE)

2012 - 2016

B. Tech. in Electrical Engineering

AWARDS & RECOGNITION

Outstanding reviewer for CVPR 2022 Highlighted reviewer for ICLR 2022 Outstanding reviewer for CVPR 2021 Among top 33% reviewers for ICML 2020

NVIDIA Best Runner Up Paper Award at AROW, ECCV 2020

Recipient: CS-7001 Research Award (2020) - Interactive Computing, Georgia Tech Invited to mentor students at the "New in ML" workshop at NeurIPS 2019

Recognized as one of the highest-scoring reviewers for NeurIPS 2019

Outstanding Reviewer for ICLR 2019

Recipient: IC Student Travel Grant to attend NeurIPS 2018

Among top 30% reviewers for NeurIPS 2018

Recipient: MS Research Award (2018) - College of Computing, Georgia Tech

Winner: VT-Hacks, 2017, a Major League Hacking event.

Semi-Finalists: ROBOSUB - AUVSI, 2013 out of 30 participating teams

Finalists: NIOT SAVe, 2013 out of 27 participating teams

Recipient: Merit Scholarships for Undergraduate Academic Performance (2012-2014)

Recipient: KVPY and INSPIRE Fellowships, 2012

National Top 1%: Indian National Physics Olympiad (InPhO), 2013

PUBLICATIONS & PRE-PRINTS (*denotes equal

contribution)

RobustNav: Towards Benchmarking Robustness in Embodied Navigation

International Conference on Computer Vision (ICCV) 2021 (Oral)

Embodied AI Workshop, CVPR 2021

P. Chattopadhyay, J. Hoffman, R. Mottaghi, A. Kembhavi

Likelihood Landscapes: A Unifying Principle Behind Many Adversarial Defenses

Adversarial Robustness in the Real World (AROW), ECCV 2020 (Talk)

NVIDIA Best Paper Runner Up

F. Lin, R. Mittapali, P. Chattopadhyay, D. Bolya, J. Hoffman

Learning to Balance Specificity and Invariance for In and Out of Domain Generalization

European Conference on Computer Vision (ECCV) 2020 (Poster) Visual Learning with Limited Labels (LwLL), CVPR 2020 (Poster)

P. Chattopadhyay, Y. Balaji, J. Hoffman

IR-VIC: Unsupervised Discovery of Sub-goals for Transfer in RL

International Joint Conference on Artificial Intelligence (IJCAI) 2020 (Poster)

N. Modhe, P. Chattopadhyay, M. Sharma, A. Das, D. Parikh, D. Batra, R. Vedantam

DS-VIC: Unsupervised Discovery of Decision States for Transfer in RL

Task-Agnostic Reinforcement Learning (TARL) Workshop, ICLR 2019 (Poster)

N. Modhe, P. Chattopadhyay, M. Sharma, A. Das, D. Parikh, D. Batra, R. Vedantam

Improving Generative Visual Dialog by Answering Diverse Questions

Conference on Empirical Methods in Natural Language Processing (EMNLP) 2019 (Poster) V. Murahari, P. Chattopadhyay, D. Batra, D. Parikh, A. Das

EvalAI: Towards Better Evaluation Systems for AI Agents

arXiv 2019 (Technical Report)

Workshop on AI Systems, SOSP 2019 (Poster)

D. Yadav, R. Jain, H. Agrawal, <u>P. Chattopadhyay</u>, T. Singh, A. Jain, S. Singh, S. Lee, D. Batra

Choose Your Neuron: Incorporating Domain Knowledge Through Neuron-Importance

European Conference on Computer Vision (ECCV) 2018 (Poster)

Continual Learning Workshop, NeurIPS 2018 (Poster)

Visually Grounded Interaction and Language (ViGIL), NeurIPS 2018 (Poster)

R. Selvaraju*, P. Chattopadhyay*, M. Elhoseiny, T. Sharma, D. Batra, D. Parikh, S. Lee

Do Explanations make VQA models more predictable to a human?

Conference on Empirical Methods in Natural Language Processing (EMNLP) 2018 (Poster) A. Chandrasekaran*, V. Prabhu*, D.Yadav*, P. Chattopadhyay*, D. Parikh

Evaluating Visual Conversational Agents via Cooperative Human-AI Games

AAAI Conference on Human Computation and Crowdsourcing (HCOMP) 2017 (Oral)

 $\mbox{\bf P.Chattopadhyay}^*,$ D.Yadav *, V. Prabhu, A. Chandrasekaran, A. Das, S. Lee, $\overline{\mbox{\bf D. Batra, D. Parikh}}$

It Takes Two to Tango: Towards Theory of AI's Mind

Chalearn Looking at People Workshop, CVPR 2017 (Oral)

A. Chandrasekaran*, D.Yadav*, P. Chattopadhyay*, V. Prabhu*, D. Parikh

Counting Everyday Objects in Everyday Scenes

IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2017 (Spotlight)

P.Chattopadhyay*, R.Vedantam*, R. Selvaraju, D. Batra, D. Parikh

Delhi Technological University: Design and Development of the Littoral AUV $\mathbf{Z}\mathbf{yra}$ 2.0

AUVSI RoboSub Journal 2014 (Technical Report)

EXPERIENCE

PRIOR, Allen Institute for AI

May 2022 - Aug 2022

Research Intern, mentored by Ani Kembhavi, Roozbeh Mottaghi and Judy Hoffman Learning representations of environments to improve sample efficiency and generalization for embodied agents across tasks and simulators

PRIOR, Allen Institute for AI

May 2020 - Aug 2020

Research Intern, mentored by Ani Kembhavi, Roozbeh Mottaghi and Judy Hoffman Assessing the robustness of embodied navigation agents to visual and dynamics corruptions

Deep Learning Group, Microsoft Research AI

May 2018 - Aug 2018

Research Intern, mentored by Hamid Palangi

Improving goal-driven visually grounded dialog under the presence of an adversarial utterance evaluator ${\bf r}$

Visual Intelligence Lab, Georgia Tech

Aug 2017 - Aug 2019

Research Assistant, mentored by Prof. Devi Parikh and Prof. Dhruv Batra

Worked on problems at the intersection of computer vision and natural language processing with a focus towards building intelligent and interpretable systems.

CVMLP Lab, Virginia Tech

Jun 2015 - May 2017

Research Assistant, mentored by Prof. Devi Parikh and Prof. Dhruv Batra

Worked on scene-understanding problems such as object detection and counting in everyday scenes with a downstream focus towards visual question answering

Robotics Research Lab, IIIT Hyderabad

Dec 2014 - Jan 2015

Research Intern, mentored by Prof. K Madhava Krishna

Implemented an efficient strategy for a robot to discover, recognize and navigate to a selected few objects among some scattered in an environment, based on a "guess from far and recognize from near" strategy.

IACS, Kolkata Jun 2014 - Aug 2014

Research Intern, mentored by Prof. Soumitra Sengupta

Worked on finding Charged Rotating Black Hole solutions in Einstein-Gauss-Bonnet dilaton coupled gravity and simulated the conditions for the existence of multiple horizons in constant scalar curvature f(R) gravity.

Autonomous Underwater Vehicle Team, DTU

Aug 2012 - Aug 2016

Undergraduate Researcher, mentored by Prof. R K Sinha

Underwater Acoustics: Developed and implemented range estimation algorithms for Passive Source Localization from Time Difference of Arrival (TDOA) values in conjunction with machine vision techniques.

PROFESSIONAL SERVICES

Reviewing

IEEE Conference on Computer Vision and Pattern Recognition (CVPR)	2018 - 2022
Neural Information Processing Systems (NeurIPS)	2018 - 2021
Association for Computational Linguistics (ACL)	2019
International Conference on Learning Representations (ICLR)	2019 - 2022
IEEE International Conference on Robotics and Automation (ICRA)	2021 - 2022
International Conference on Machine Learning (ICML)	2019 - 2020
European Conference on Computer Vision (ECCV)	2018
Challenge Organization	
Visual Dialog Challenge	CVPR 2020
(co-organized with Vishvak Murahari)	

TEACHING EXPERIENCE

Teaching Assistant

 CS 4476: Introduction to Computer Vision

Spring 2021

Instructor: Prof. Judy Hoffman

Teaching Assistant

 CS 8803: Machine Learning with Limited Supervision

 $\operatorname{Fall}\ 2022$

Instructor: Prof. Judy Hoffman

REFERENCES (available upon request)

- Prof. Judy Hoffman, Georgia Tech (email: judy@gatech.edu)
- Dr. Ani Kembhavi, PRIOR AllenAI (email: anik@allenai.org
- Dr. Roozbeh Mottaghi, PRIOR AllenAI (email: roozbehm@allenai.org)
- Prof. Devi Parikh, Georgia Tech (email: parikh@gatech.edu)
- Prof. Mohamed H. Elhoseiny, KAUST (email: mohamed.elhoseiny@kaust.edu.sa)