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eYRC 2020-21: Nirikshak Bot (NB)

# Introduction to Control Systems

[ Last Updated on: 25th November 2020, 22:30 Hrs ]

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## Introduction

In order to understand about control systems, we will need to first understand some definitions.

### 1. System

- A **system** is a **combination** or an arrangement **of different physical components** which act together as an entire unit to achieve certain objective.
- For example, **a classroom** or **a lamp**.

### 2. Control System

- To **control means to regulate**, to direct or to command.
- Hence a **control system** is an arrangement of **different physical elements** connected in such a manner so as to regulate, direct or command itself or some other system.
- An **important classification** of control systems is as follows:
  - **Open loop systems**

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- A **system** in which output is dependent on input but **controlling action or input is totally independent of the output** or changes in the output of the system, is called an **Open Loop System**.

- An open loop system is also **called an uncontrolled system**.

- The output of such a system is not controlled as **the system has no feedback**.

- For example, **an electric toaster**.

- The quality of the toast totally depends on the timer the user sets and it is to be judged by the user.

#### o Closed loop systems

- A system in which the controlling action or **input is somehow dependent on the output** or changes in the output is called a **Closed Loop System**.

- A closed loop system is also **called a controlled system**.

- The output of such a system is controlled **as it receives feedback**. **Proportional Integral Derivative** aka **PID** is an example of a close loop system.

- For example, **a human being**. Yes you read correctly. The best example is us i.e. humans. Lets see how.

- Suppose you want to pick up a book.

- The first thing that you will do is to locate the book using your eyes. Right?

- Once you locate the book, you will estimate the position of your hand with respect to the book.

- This is **called as feedback**.

- The difference in the positions is nothing but the distance your hand will have to move to grab the book.

- This is **called as error**.

- Now, your brain will give signal to your hands.

- This process will continue till you grab the book.

- Need a **much more complicated example**? Watch this video by **KUKA - Robots & Automation** to understand the importance of control theory in robotics industry.

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## The Revenge: Timo Boll vs. KUKA Robot



- Here is one more by **SpaceX** where they landed the first stage of a rocket on a droneship.

## CRS-8 | First Stage Landing on Droneship



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- This what control systems are all about. You have **1000s of control systems** around you.
- Look around and determine **at least 3 control systems** and discuss with your team mates.
- Control Systems is a **huge** field of engineering and you have just started your journey.
- Here are some **references** for you to get more information:
- These resources cover material that is **typically taught over the course of one engineering semester**.
- Do not worry, **you will not require** all of this material to solve the Theme tasks.

**Voilà !!**

**You just completed the starter pack of control systems.**

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## References

1. **Feedback Control Systems: A conceptual Approach** by U.A. Bakshi, V.U. Bakshi
2. **Control Theory** YouTube Playlist **by Brian Douglas**:

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## Why Learn Control Theory



3. Control Systems Course offered by **National Programme on Technology Enhanced Learning** (NPTEL) [here](#).

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**ALL THE BEST**

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