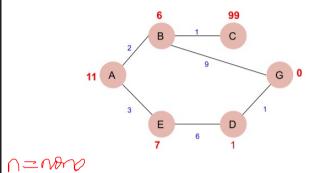
```
if n == node_goal:
        while parent[n] != n:
            path.append(n)
         path.append(node start)
        path.reverse()
        print(path)
    open list.remove(n)
    closed_list.append(n)
f neighbours(i):
   return Graph[i]
 return h_dist[n]
```

remove A

$$G = \{A:0, B:2, E:3\}$$
 $C = \{A:0, B:2, E:3\}$
 $P = \{A:0, B:4, E:A\}$
 $G:B$

```
f a star(node start ,node goal):
         open list = [node start]
         closed list = []
         g[node_start] = 0
                if n == None or g[i] + h(i) < g[n] + h(n):
            if n -- node_goal or Graph[n] -- None:
                for (m, weight) in neighbours(n):
                        open_list.append(m)
                        g[n] = g[n] + weight
                        if g[m] > g[n] + weight:
                            g[m] - g[n] + weight
                            parent[m] = n
                             if m in closed list:
                                closed list.remove(m)
                                open list.append(m)
      if n == node_goal:
             n = parent[n]
          path.append(node_start)
         path.reverse()
         print(path)
      open_list.remove(n)
     closed_list.append(n)
  print("Path does not exist")
 neighbours(i):
 if i in Graph:
    return Graph[i]
ef h(n):
  return h_dist[n]
```



$$F = n \rightarrow E$$

$$g(C) + h(C) > g(C) + h(C)$$

$$g(G) + h(G)$$

$$g($$

$$G = \{A:0, B:2, E:3, G:10\}$$
 $C = \{A:0, B:2, E:3, G:10\}$
 $P = \{A:A, E:A\}$
 $G:D, C:B, D:E$

```
f a star(node start ,node goal):
         open_list = [node_start]
         closed list = []
         g[node start] = 0
         parent[node start] - node start
         while len(open list) > 0:
                if n == None \text{ or } g[i] + h(i) < g[n] + h(n):
            if n -- node goal or Graph[n] -- None:
                for (m, weight) in neighbours(n):
                    if m not in open list and m not in closed list:
                        open_list.append(m)
                        if g[m] > g[n] + weight:
                            if m in closed list:
                                closed list.remove(m)
                                open list.append(m)
         print("Path does not exist")
     if n -- node goal:
             path.append(n)
             n = parent[n]
          path.append(node_start)
         path.reverse()
         print(path)
     open_list.remove(n)
     closed list.append(n)
 print("Path does not exist")
 if i in Graph:
    return Graph[i]
of h(n):
  return h_dist[n]
```

$$\begin{array}{c}
C = \begin{bmatrix} \begin{pmatrix} A \\ A \end{pmatrix} \\
B & 1 \\
C & 0
\end{array}$$

$$\begin{array}{c}
A & B & 1 \\
B & 1 & C
\end{array}$$

$$\begin{array}{c}
A & B & 1 \\
A & B & 1
\end{array}$$

$$\begin{array}{c}
A & B & 1 \\
A & C & C
\end{array}$$

$$\begin{array}{c}
A & B & C
\end{array}$$

$$G = \{A:0, B:2, E:3, G:100\}$$
 $C = \{A:0, B:2, E:3, G:100\}$
 $P = \{A:0, B:4, E:A\}$
 $G:D, G:B, D:E$