IMPLEMENTATION OF IMAGE PROCESSING TOOLS USING PYTHON PROGRAMMING LANGUAGE IN GOOGLE COLAB

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DURATION: OCT-DEC 2022

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ACKNOWLEDGEMENT:

I would like to extend my sincere gratitude to my professor, Dr. Vivek Singh for providing me with the opportunity to work with OpenCV, Python, and related libraries like Matplotlib, Pandas, and NumPy on a breast cancer dataset using Google Colab. Through this experience, I have gained invaluable knowledge about image processing techniques and machine learning algorithms, and I have developed a deeper understanding of data analysis and visualization.

His guidance and support have been instrumental in my professional development, and I feel incredibly grateful to have had the chance to learn from his expertise. The skills and knowledge that I have gained during this project will undoubtedly serve me well in my future academic and professional pursuits.

<u>AIM:</u> To implement Open CV and image processing tools in Python Programming Language using Google Colab.

ALGORITHMS:

1. GEOMETRIC TRANSFORMATION OF IMAGES:

a. Scaling:

CODE:

import cv2

import numpy as np

from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/benign/benign
(1).png')

res = cv2.resize(img,None,fx=2, fy=2, interpolation = cv2.INTER CUBIC)

cv2_imshow(img)
print(img.shape)



b. <u>Translation:</u>

CODE:

import cv2

import numpy as np

from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/normal/normal
(56).png')

rows,cols = img.shape[:2]

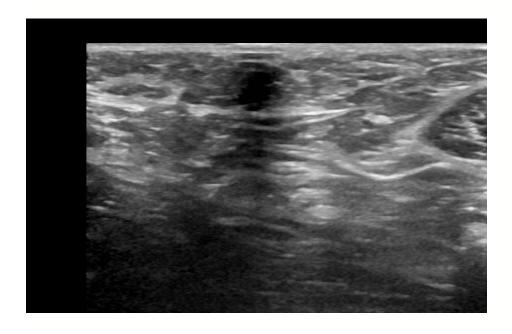
M = np.float32([[1,0,100],[0,1,50]])

dst = cv2.warpAffine(img,M,(cols,rows))

cv2_imshow(dst)

cv2.waitKey(0)

cv2.destroyAllWindows()



c. Rotation:

CODE:

import cv2

import numpy as np

from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab

 $Notebooks/Dataset_BUSI_with_GT/malignant/malignant~(56).png')$

rows,cols = img.shape[:2]

M = cv2.getRotationMatrix2D((cols/2,rows/2),90,1)

dst = cv2.warpAffine(img,M,(cols,rows))

cv2_imshow(dst)

cv2.waitKey(0)

cv2.destroyAllWindows()



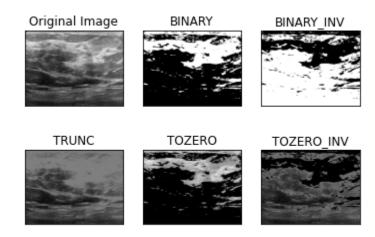
2. IMAGE THRESHOLDING:

```
CODE:
import cv2
import numpy as np
from matplotlib import pyplot as plt
from google.colab.patches import cv2 imshow
img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset BUSI with GT/normal/normal
(33).png')
ret,thresh1 = cv2.threshold(img,127,255,cv2.THRESH_BINARY)
ret,thresh2 = cv2.threshold(img,127,255,cv2.THRESH_BINARY_INV)
ret,thresh3 = cv2.threshold(img,127,255,cv2.THRESH_TRUNC)
ret,thresh4 = cv2.threshold(img,127,255,cv2.THRESH TOZERO)
ret,thresh5 = cv2.threshold(img,127,255,cv2.THRESH TOZERO INV)
titles = ['Original Image', 'BINARY', 'BINARY INV', 'TRUNC', 'TOZERO', 'TOZERO INV']
images = [img, thresh1, thresh2, thresh3, thresh4, thresh5]
for i in range(6):
  plt.subplot(2,3,i+1),plt.imshow(images[i],'gray')
  plt.title(titles[i])
```

plt.xticks([]),plt.yticks([])

plt.show()

OUTPUT:



3. **SMOOTHING IMAGES - 2D Convolution(Image Filtering):**

CODE:

import cv2

import numpy as np

from matplotlib import pyplot as plt

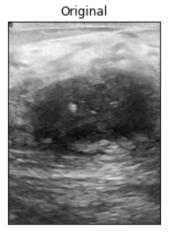
from google.colab.patches import cv2_imshow

 $img = cv2.imread('/gdrive/My\ Drive/Colab\ Notebooks/Dataset_BUSI_with_GT/benign/benign\ (10).png')$

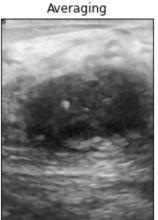
```
plt.subplot(121),plt.imshow(img),plt.title('Original')
plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(blur),plt.title('Blurred')
plt.xticks([]), plt.yticks([])
```

OUTPUT:

plt.show()



blur = cv2.blur(img,(5,5))



4. IMAGE BLURRING:

a. Averaging:

CODE:

import cv2

import numpy as np

from matplotlib import pyplot as plt

from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/benign/benign
(10).png')

blur = cv2.blur(img,(5,5))
plt.subplot(121),plt.imshow(img),plt.title('Original')
plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(blur),plt.title('Blurred')
plt.xticks([]), plt.yticks([])
plt.show()

OUTPUT:





b. Gaussian Filtering:

CODE:

import cv2

import numpy as np

from matplotlib import pyplot as plt

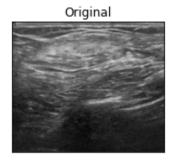
from google.colab.patches import cv2 imshow

img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/normal/normal
(2).png')

blur = cv2.GaussianBlur(img,(5,5),0)

plt.subplot(121),plt.imshow(img),plt.title('Original')
plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(blur),plt.title('Blurred')
plt.xticks([]), plt.yticks([])
plt.show()

OUTPUT:





c. Median Filtering:

CODE:

import cv2

import numpy as np

from matplotlib import pyplot as plt

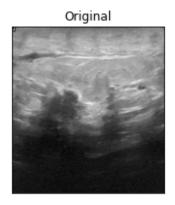
from google.colab.patches import cv2_imshow

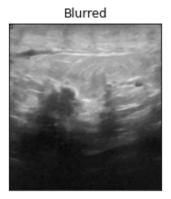
img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (4).png')

median = cv2.medianBlur(img,5)

plt.subplot(121),plt.imshow(img),plt.title('Original')
plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(blur),plt.title('Blurred')
plt.xticks([]), plt.yticks([])
plt.show()

OUTPUT:





d. <u>Bilateral Filtering:</u>

CODE:

import cv2

import numpy as np

from matplotlib import pyplot as plt

from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/benign/benign
(18).png')

blur = cv2.bilateralFilter(img,9,75,75)

plt.subplot(121),plt.imshow(img),plt.title('Original')

plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(blur),plt.title('Blurred')

plt.xticks([]), plt.yticks([])

plt.show()





5. MORPHOLOGICAL TRANSFORMATIONS:

a. Erosion:

```
CODE:
```

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow
```

```
img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset BUSI with GT/malignant/malignant (10).png')
```

kernel = np.ones((5,5),np.uint8)

erosion = cv2.erode(img,kernel,iterations = 1)

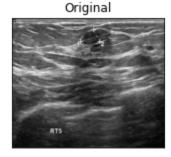
plt.subplot(121),plt.imshow(img),plt.title('Original')

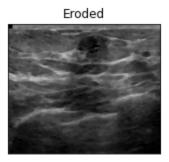
plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(erosion, cmap='gray'),plt.title('Eroded')

plt.xticks([]), plt.yticks([])

plt.show()





b. <u>Dilation:</u>

CODE:

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (10).png')

kernel = np.ones((5,5),np.uint8)

dilation = cv2.dilate(img,kernel,iterations = 1)

plt.subplot(121),plt.imshow(img),plt.title('Original')

plt.xticks([]), plt.yticks([])

plt.xticks([]), plt.yticks([])
```

OUTPUT:

plt.show()





c. **Opening:**

CODE:

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (10).png')

kernel = np.ones((5,5),np.uint8)

opening = cv2.morphologyEx(img, cv2.MORPH_OPEN, kernel)

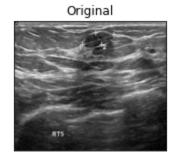
plt.subplot(121),plt.imshow(img),plt.title('Original')

plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(opening, cmap='gray'),plt.title('Opening')

plt.xticks([]), plt.yticks([])

plt.show()
```





d. Closing:

CODE:

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (10).png')

kernel = np.ones((5,5),np.uint8)

closing = cv2.morphologyEx(img, cv2.MORPH_CLOSE, kernel)

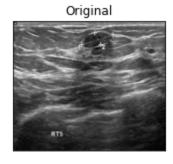
plt.subplot(121),plt.imshow(img),plt.title('Original')

plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(closing, cmap='gray'),plt.title('Closing')

plt.xticks([]), plt.yticks([])

plt.xticks([]), plt.yticks([])
```





e. Morphological Gradient:

CODE:

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab

Notebooks/Dataset_BUSI_with_GT/malignant/malignant (10).png')

kernel = np.ones((5,5),np.uint8)

gradient = cv2.morphologyEx(img, cv2.MORPH_GRADIENT, kernel)

plt.subplot(121),plt.imshow(img),plt.title('Original')

plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(gradient, cmap='gray'),plt.title('Morphological Gradient')

plt.xticks([]), plt.yticks([])

plt.show()
```





f. Top Hat:

CODE:

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (10).png')

kernel = np.ones((5,5),np.uint8)

tophat = cv2.morphologyEx(img, cv2.MORPH_TOPHAT, kernel)

plt.subplot(121),plt.imshow(img),plt.title('Original')

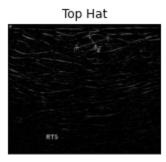
plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(tophat, cmap='gray'),plt.title('Top Hat')

plt.xticks([]), plt.yticks([])

plt.xticks([]), plt.yticks([])
```





g. Black Hat:

CODE:

import cv2

import numpy as np

```
from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (10).png')

kernel = np.ones((5,5),np.uint8)

blackhat = cv2.morphologyEx(img, cv2.MORPH_BLACKHAT, kernel)

plt.subplot(121),plt.imshow(img),plt.title('Original')

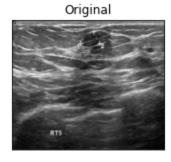
plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(tophat, cmap='gray'),plt.title('Black Hat')

plt.xticks([]), plt.yticks([])
```

OUTPUT:

plt.show()





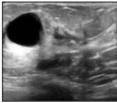
6. IMAGE GRADIENTS:

plt.show()

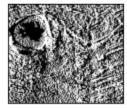
```
CODE:
import cv2
import numpy as np
from matplotlib import pyplot as plt
from google.colab.patches import cv2 imshow
img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset BUSI with GT/benign/benign
(10).png')
laplacian = cv2.Laplacian(img,cv2.CV 64F)
sobelx = cv2.Sobel(img,cv2.CV 64F,1,0,ksize=5)
sobely = cv2.Sobel(img,cv2.CV 64F,0,1,ksize=5)
plt.subplot(2,2,1),plt.imshow(img,cmap = 'gray')
plt.title('Original'), plt.xticks([]), plt.yticks([])
plt.subplot(2,2,2),plt.imshow(laplacian,cmap = 'gray')
plt.title('Laplacian'), plt.xticks([]), plt.yticks([])
plt.subplot(2,2,3),plt.imshow(sobelx,cmap = 'gray')
plt.title('Sobel X'), plt.xticks([]), plt.yticks([])
plt.subplot(2,2,4),plt.imshow(sobely,cmap = 'gray')
plt.title('Sobel Y'), plt.xticks([]), plt.yticks([])
```

OUTPUT:

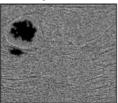
Original



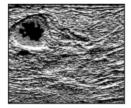
Sobel X



Laplacian



Sobel Y



7. CANNY EDGE DETECTION:

CODE:

import cv2

import numpy as np

from matplotlib import pyplot as plt

from google.colab.patches import cv2 imshow

img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/normal/normal
(4).png')

edges = cv2.Canny(img,100,200)

plt.subplot(121),plt.imshow(img,cmap = 'gray')

plt.title('Original Image'), plt.xticks([]), plt.yticks([])

plt.subplot(122),plt.imshow(edges,cmap = 'gray')

plt.title('Edge Image'), plt.xticks([]), plt.yticks([])

plt.show()

OUTPUT:

Original Image



Edge Image

8. IMAGE PYRADMIDS:

CODE:

import cv2

import numpy as np,sys

import matplotlib.pyplot as plt

from google.colab.patches import cv2_imshow

A = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/benign/benign (26).png')

B = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/malignant/malignant (43).png')

A = cv2.resize(A, (512, 512))

B = cv2.resize(B, (512, 512))

```
# generate Gaussian pyramid for A
G = A.copy()
gpA = [G]
for i in range(6):
 G = cv2.pyrDown(G)
 gpA.append(G)
# generate Gaussian pyramid for B
G = B.copy()
gpB = [G]
for i in range(6):
 G = cv2.pyrDown(G)
 gpB.append(G)
# generate Laplacian Pyramid for A
lpA = [gpA[5]]
for i in range(5,0,-1):
 GE = cv2.pyrUp(gpA[i])
 L = cv2.subtract(gpA[i-1],GE)
 lpA.append(L)
```

```
# generate Laplacian Pyramid for B
lpB = [gpB[5]]
for i in range(5,0,-1):
 GE = cv2.pyrUp(gpB[i])
 L = cv2.subtract(gpB[i-1],GE)
 lpB.append(L)
# Now add left and right halves of images in each level
LS = []
for la,lb in zip(lpA,lpB):
 rows,cols,dpt = la.shape
 ls = np.hstack((la[:,0:cols//2], lb[:,cols//2:]))
 LS.append(ls)
# now reconstruct
ls_{-} = LS[0]
for i in range(1,6):
 ls_ = cv2.pyrUp(ls_)
 ls_= cv2.add(ls_, LS[i])
```

image with direct connecting each half

real = np.hstack((A[:,:cols//2],B[:,cols//2:]))

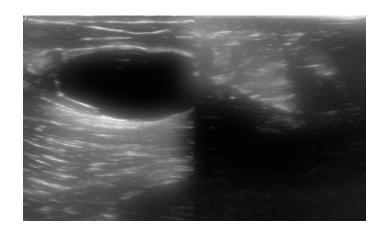
cv2_imshow(ls_)

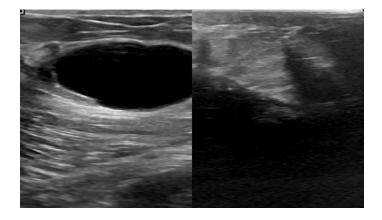
cv2.waitKey(0)

cv2_imshow(real)

cv2.waitKey(0)

cv2.destroyAllWindows()





9. HOUGH LINE TRANSFORM:

y1 = int(y0 + 1000*(a))

```
CODE:
import cv2
import numpy as np
from google.colab.patches import cv2_imshow
img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset BUSI with GT/normal/normal
(4).png')
gray = cv2.cvtColor(img,cv2.COLOR BGR2GRAY)
edges = cv2.Canny(gray,50,150,apertureSize = 3)
lines = cv2.HoughLines(edges,1,np.pi/180,200)
if lines is not None:
  for rho, theta in lines[0]:
   a = np.cos(theta)
   b = np.sin(theta)
   x0 = a*rho
   y0 = b*rho
   x1 = int(x0 + 1000*(-b))
```

```
x2 = int(x0 - 1000*(-b))
y2 = int(y0 - 1000*(a))

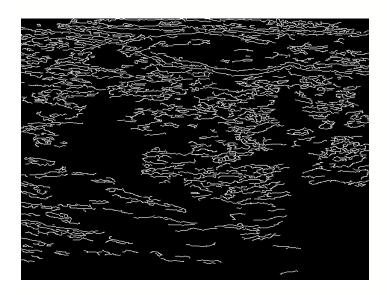
cv2.line(img,(x1,y1),(x2,y2),(0,0,255),2)

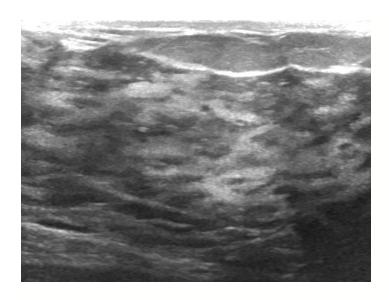
cv2.imwrite('houghlines3.jpg',img)

cv2_imshow(edges)

cv2_imshow(img)

if cv2.waitKey(1) & 0xff == ord('q'):
    cam.release()
    cv2.destroyAllWindows()
```





10. INTERACTIVE FOREGROUND EXTRACTION:

CODE:

import numpy as np

import cv2

from matplotlib import pyplot as plt

from google.colab.patches import cv2_imshow

img = cv2.imread('/gdrive/My Drive/Colab
Notebooks/Dataset_BUSI_with_GT/malignant/malignant (30).png')

mask = np.zeros(img.shape[:2],np.uint8)

bgdModel = np.zeros((1,65),np.float64)

fgdModel = np.zeros((1,65),np.float64)

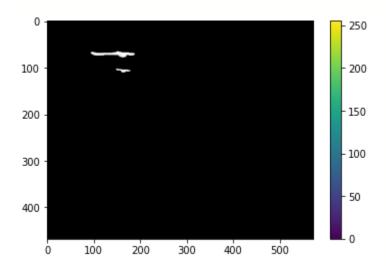
rect = (50,50,450,290)

cv2.grabCut(img,mask,rect,bgdModel,fgdModel,5,cv2.GC INIT WITH RECT)

mask2 = np.where((mask==2)|(mask==0),0,1).astype('uint8')
img = img*mask2[:,:,np.newaxis]

plt.imshow(img),plt.colorbar(),plt.show()

OUTPUT:



11. IMAGE SEGMENTATION:

CODE:

import numpy as np

import cv2

from matplotlib import pyplot as plt

from google.colab.patches import cv2_imshow

```
img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset BUSI with GT/normal/normal
(4).png')
gray = cv2.cvtColor(img,cv2.COLOR BGR2GRAY)
ret, thresh = cv2.threshold(gray,0,255,cv2.THRESH_BINARY_INV+cv2.THRESH_OTSU)
# noise removal
kernel = np.ones((3,3),np.uint8)
opening = cv2.morphologyEx(thresh,cv2.MORPH OPEN,kernel, iterations = 2)
# sure background area
sure bg = cv2.dilate(opening,kernel,iterations=3)
# Finding sure foreground area
dist transform = cv2.distanceTransform(opening,cv2.DIST L2,5)
ret, sure fg = cv2.threshold(dist transform, 0.7*dist transform.max(), 255,0)
# Finding unknown region
sure fg = np.uint8(sure fg)
unknown = cv2.subtract(sure bg,sure fg)
# Marker labelling
ret, markers = cv2.connectedComponents(sure fg)
# Add one to all labels so that sure background is not 0, but 1
```

markers = markers+1

Now, mark the region of unknown with zero

markers[unknown==255] = 0

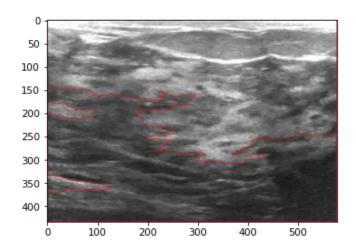
markers = cv2.watershed(img,markers)

img[markers == -1] = [255,0,0]

plt.imshow(img)

plt.show()

OUTPUT:



12. HOUGH CIRCLE TRANSFORM:

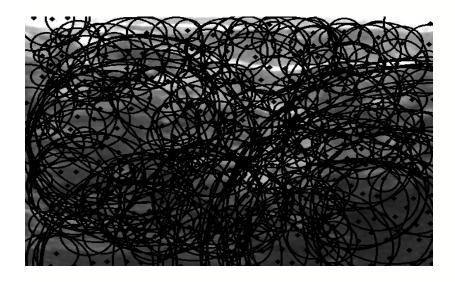
CODE:

import cv2

import numpy as np

from google.colab.patches import cv2_imshow

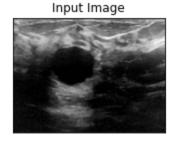
```
img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset_BUSI_with_GT/normal/normal
(4).png')
print(img.shape)
img = cv2.medianBlur(img,5)
img = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
circles = cv2.HoughCircles(img,cv2.HOUGH_GRADIENT,1,20,
               param1=50,param2=30,minRadius=0,maxRadius=0)
circles = np.uint16(np.around(circles))
for i in circles[0,:]:
  cv2.circle(img,(i[0],i[1]),i[2],(0,255,0),2)
  cv2.circle(img,(i[0],i[1]),2,(0,0,255),3)
cv2_imshow(img)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

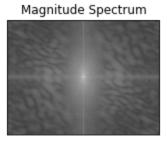


13. FOURIER TRANSFORM IN OPEN CV:

```
CODE:
import numpy as np
import cv2
from matplotlib import pyplot as plt
from google.colab.patches import cv2_imshow
img = cv2.imread('/gdrive/My Drive/Colab Notebooks/Dataset BUSI with GT/benign/benign
(48).png')
img = cv2.cvtColor(np.float32(img), cv2.COLOR BGR2GRAY)
dft = cv2.dft(np.float32(img), flags=cv2.DFT COMPLEX OUTPUT)
dft shift = np.fft.fftshift(dft)
magnitude spectrum = 20*np.log(cv2.magnitude(dft shift[:,:,0],dft shift[:,:,1]))
plt.subplot(121),plt.imshow(img, cmap = 'gray')
plt.title('Input Image'), plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(magnitude spectrum, cmap = 'gray')
plt.title('Magnitude Spectrum'), plt.xticks([]), plt.yticks([])
plt.show()
```

```
rows, cols = img.shape
crow,ccol = rows/2, cols/2
# create a mask first, center square is 1, remaining all zeros
mask = np.zeros((rows,cols,2),np.uint8)
mask[crow-30:crow+30, ccol-30:ccol+30] = 1
# apply mask and inverse DFT
fshift = dft shift*mask
f ishift = np.fft.ifftshift(fshift)
img_back = cv2.idft(f_ishift)
img back = cv2.magnitude(img back[:,:,0],img back[:,:,1])
plt.subplot(121),plt.imshow(img, cmap = 'gray')
plt.title('Input Image'), plt.xticks([]), plt.yticks([])
plt.subplot(122),plt.imshow(img_back, cmap = 'gray')
plt.title('Magnitude Spectrum'), plt.xticks([]), plt.yticks([])
plt.show()
```





KNOWLEDGE GAINED:

Working with OpenCV, Python, and image processing tools on the breast cancer dataset using Google Colab allowed me to gain knowledge in several areas. Firstly, I learned about image pre-processing techniques such as resizing, grayscale conversion, and edge detection to prepare the images for analysis.

Secondly, I learned how to use OpenCV and Python to extract features from the images, such as texture, color, and shape, etc. I have also become proficient in using visualization tools like Matplotlib to plot and analyze data, as well as the Pandas library for data manipulation and analysis.

Overall, working with OpenCV, Python, and related libraries has provided me with a solid foundation in image processing and machine learning, and I have gained practical experience working with real-world datasets and tools like Google Colab.