1D Sedimentation of a sphere

> Introduction

This study models the sedimentation of a single spherical particle in a viscous fluid (silicon oil) inside a closed box using an **overset mesh** method. The setup replicates the experiment by ten Cate et al. (2002), where the particle Reynolds number is varied up to ~32 to capture a full range of flow regimes — from creeping to transitional.

> Simulation Setup

• Geometry:

- The computational domain consists of a static **background mesh** and a moving **overset mesh** enclosing the sphere.
- o Background mesh size: cube of length ~133.3 mm
- o Overset mesh: smaller cube moving with the sphere.

Meshing:

- o blockMesh + snappyHexMesh used to define sphere and background domains.
- o transformPoints used to scale geometry to physical size.
- o topoSet assigns zone IDs (0 for background, 1 for overset).

Physics:

- o **Solver used:** overSedDymFoam rbgh (includes 6DoF motion).
- o Motion model: sixDoFRigidBodyMotionSedFoam
- The sphere's motion is governed by the balance of buoyancy and drag, with gravity acting downward.
- o The simulation tracks free fall from rest to near-wall interaction.

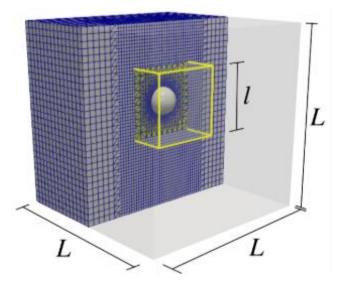


Figure 1: Geometrical domain for the falling sphere using an overset mesh.

Material Properties:

Properties	Value
Sphere density	1120 (kg/m^3)
Fluid Density	970 (kg/m^3)
Fluid Viscosity	3.845E-4 (m^2/s)
Sphere diameter	0.015 m

> Simulation Objectives

- Reproduce the **settling dynamics** and **terminal velocity** of the sphere.
- Compare results with benchmark experimental data (ten Cate et al., 2002) and OpenFOAM Wiki reference (Settling Sphere by Michael Alletto).
- Observe flow features: vortex formation, wake symmetry, lubrication effect near bottom wall.

Simulation Results:

The simulation was executed using overSedDyMFoam on 4 cores for a single sphere settling in silicon oil. Below is the result plotted from post-processed Lagrangian data.

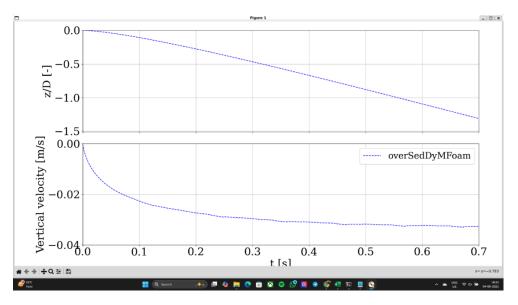


Figure 2: **Top plot:** Dimensionless position z/D vs time **Bottom plot:** Vertical velocity vs time

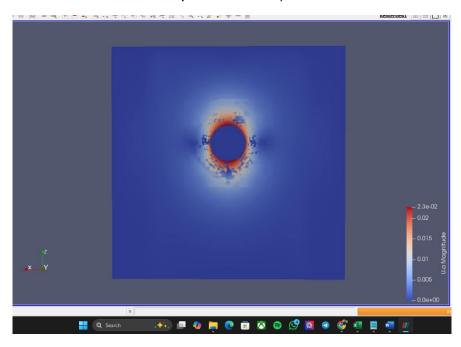


Figure 3: Initial position of the sphere and the fluid interaction

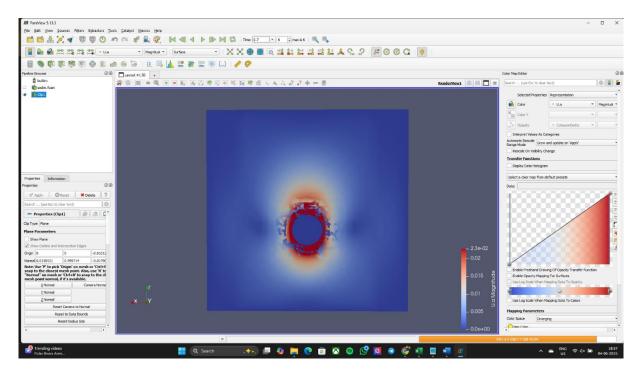


Figure 4: Final position of the sphere and the fluid interaction

Observations

- The sphere starts from rest (Vz=0) and accelerates due to gravity.
- **Velocity increases rapidly at first** but quickly reaches a plateau around -0.026m/s, suggesting the approach to terminal velocity.
- The **position curve** (**z/D**) is smooth and convex, typical of a body accelerating and then entering a steady-fall regime.
- The simulation shows **no significant rebound or oscillation**, consistent with expectations at Reynolds number $\approx 1-5$ (as in ten Cate et al., 2002).
- Steady-state appears to be reached around **0.5 seconds**, after which velocity stabilizes, validating the dynamic mesh and 6DoF setup.

Comparison with Literature

As reported by ten Cate et al. (2002):

- For Re \approx 1.5–4.1, **no rebound** was observed and settling was smooth.
- Velocity profiles match qualitatively with the experiment, where the sphere reached ~90–95% of the theoretical terminal velocity before wall interaction.