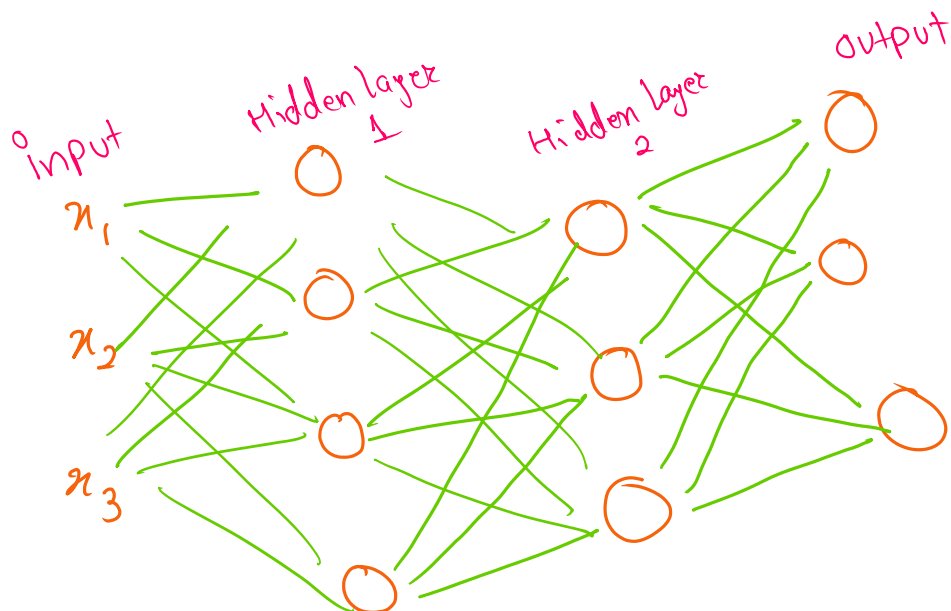


Activation function

$$y = f(\vec{x} \vec{w})$$

output



→ mnist Dataset (fashion/clothing)

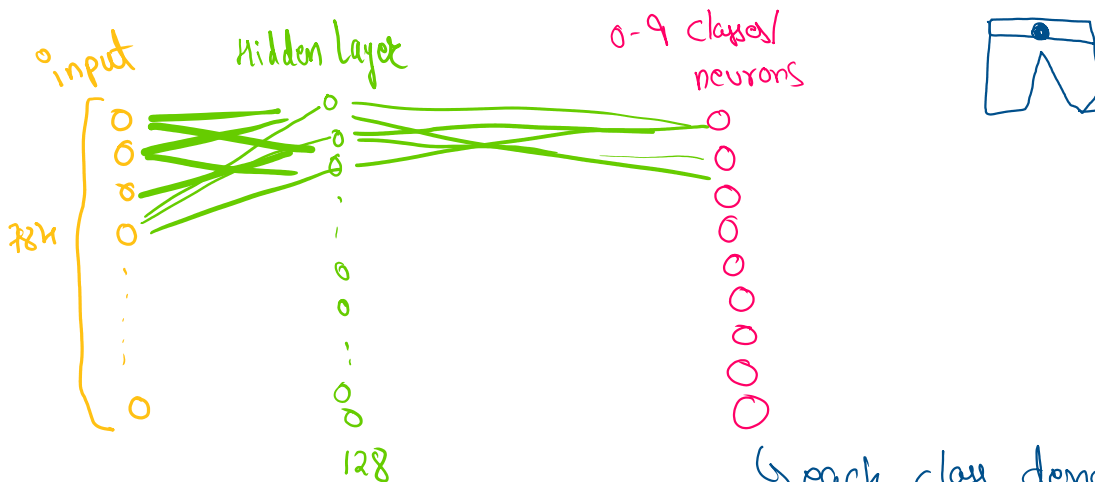
data is in a form of  $(28 \times 28)$

$$\begin{bmatrix} [0.1, 0.2, \dots \times 28], \\ \vdots \\ \times 28 \\ [0.3, 0.4, \dots \times 28] \end{bmatrix}$$

this cont of data can't be used as it is to the neuron.

∴ we will flatten the data

$$(28 \times 28) \rightarrow [784]$$



In the case of a  $28 \times 28$  grayscale image, there would be  $28 \times 28 = 784$  neurons in the input layer. Each neuron would receive the pixel intensity value of a corresponding pixel in the image as its input.

Passing the entire image through a single neuron would lose spatial information and wouldn't effectively capture the complex patterns present in the image. Instead, neural networks use multiple layers of neurons, each layer learning different features of the input data, to extract relevant information and make predictions.

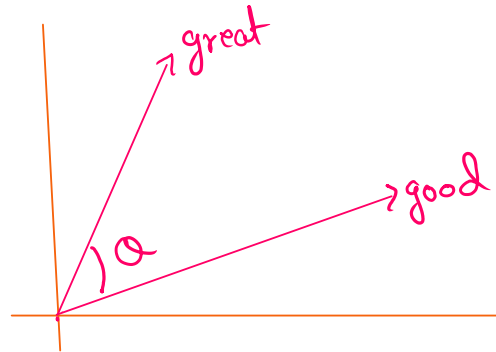
Each class denotes a type of clothing apparel

For testing with the highest % with some particular class is likely the clothing.

# → Text classification (Imdb Movie Review dataset)

① ② ③ ④  
 Have a good day  
 ① ② ③ ④  
 Have a great day

[1, 2, 3, 4]  
 [1, 2, 5, 4]



```

# Model
model = keras.Sequential()
model.add(keras.layers.Embedding(10000, 16))
model.add(keras.layers.GlobalAveragePooling1D())
model.add(keras.layers.Dense(16, activation = 'relu'))
model.add(keras.layers.Dense(1, activation='sigmoid'))

model.summary() # prints a summary of the model
  
```

Defined the dimension of

→ it will create 10,000 word vector

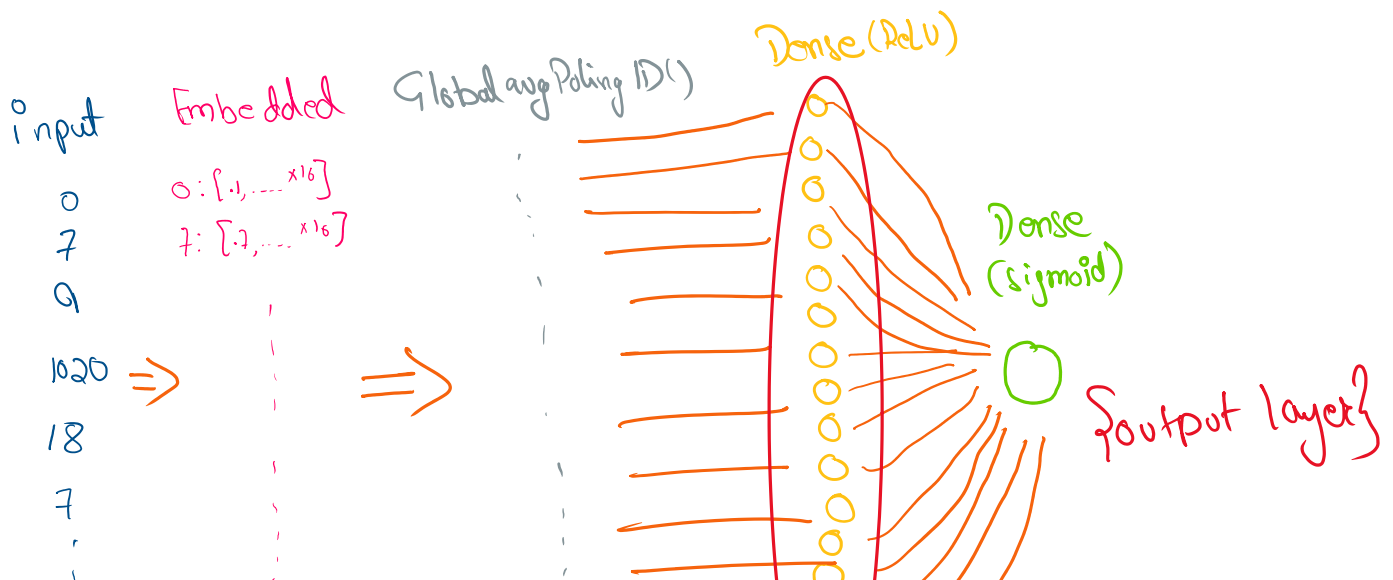
This is where a word embedding layer comes in. We want a way to determine not only the contents of a sentence but the **context** of the sentence. A word embedding layer will attempt to determine the meaning of each word in the sentence by mapping each word to a position in vector space.

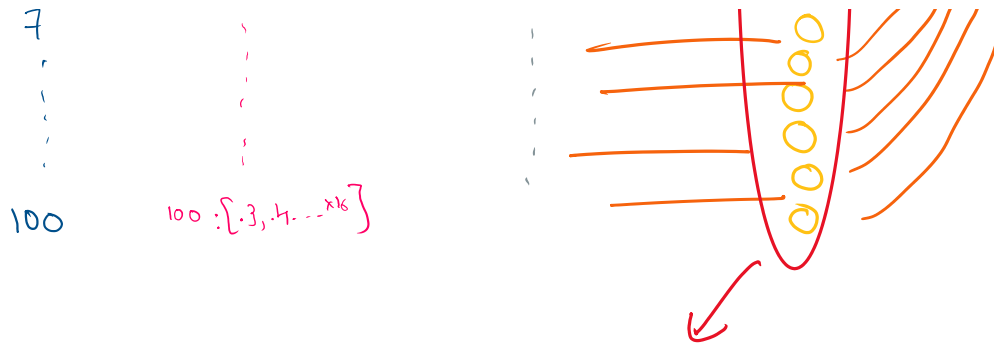
An example of something we'd hope an embedding layer would do for us: Maybe "good", "great", "fantastic" and "awesome" are placed close to each other and words like "bad", "horrible", "sucks" are placed far apart from each other representing that they have very different meanings.

## Dense Layers

The last two layers in our network are dense fully connected layers. The output layer is one neuron that uses the sigmoid function to get a value between a 0 and a 1 which will represent the likelihood of the review being positive or negative. The layer before that contains 16 neurons with a relu activation function designed to find patterns between different words present in the review.

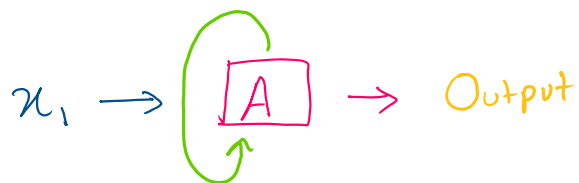
→ Scales down the data's dimension to make it easy for computation



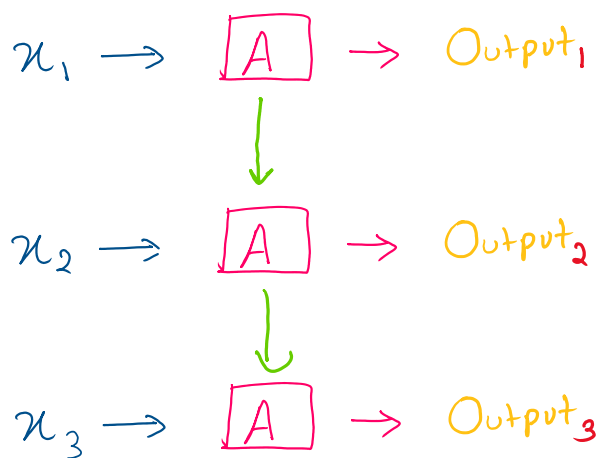


tries to find Pattern of words & tries to classify into a positive or negative review

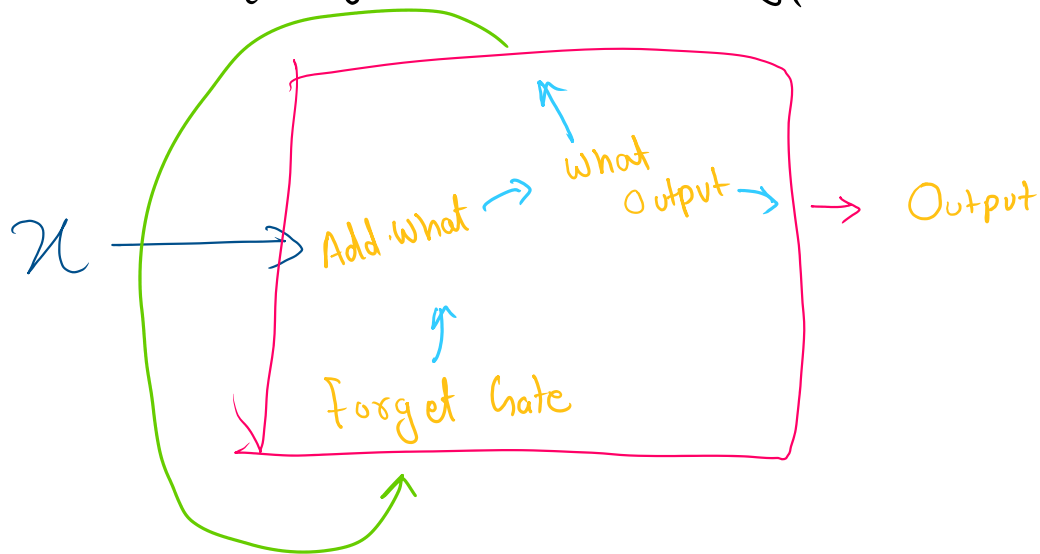
→ Recurrent Neural Network



Output of one Layer becomes input for another + n



LSTM { Long Short Term Memory }



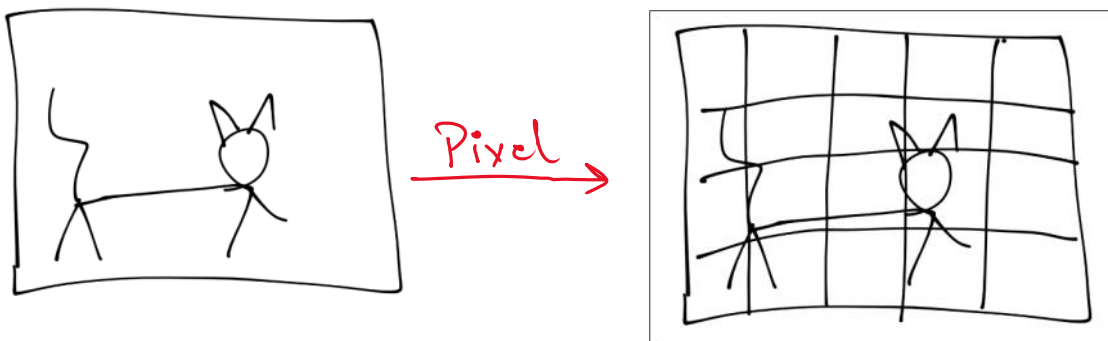
Recurring data goes through what is referred to as the Keep Gate or Forget Gate, basically which decides what to keep and what to remove from the recurring data. From here, we get to the new input data, determining what new to add from it, then, finally, we decide what our new output will be.

If you would like more information on the Recurrent Neural Network and the LSTM, check out [Understanding LSTM Networks](#).

→ Convolutional Neural Network

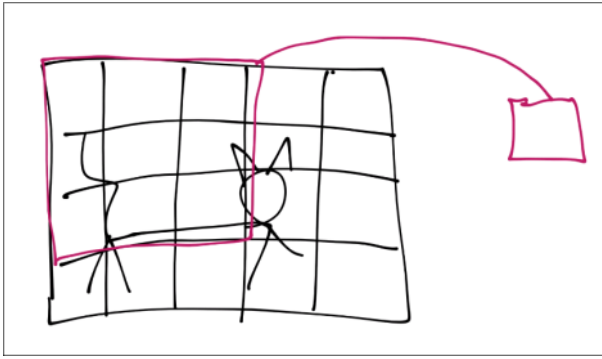
Basic Structures

Convolution → Pooling → Convolution → Pooling → fully Connected → Output

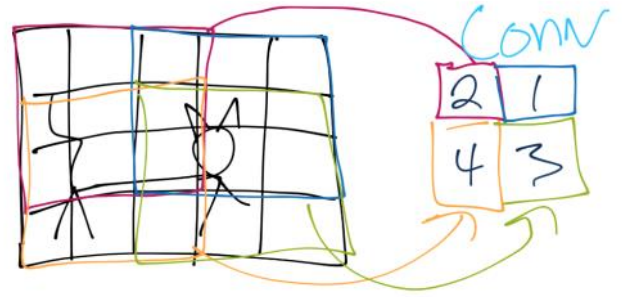


Perform convolution on the low & find features

Perform  
Convolution on the  
window & find features



Feature map

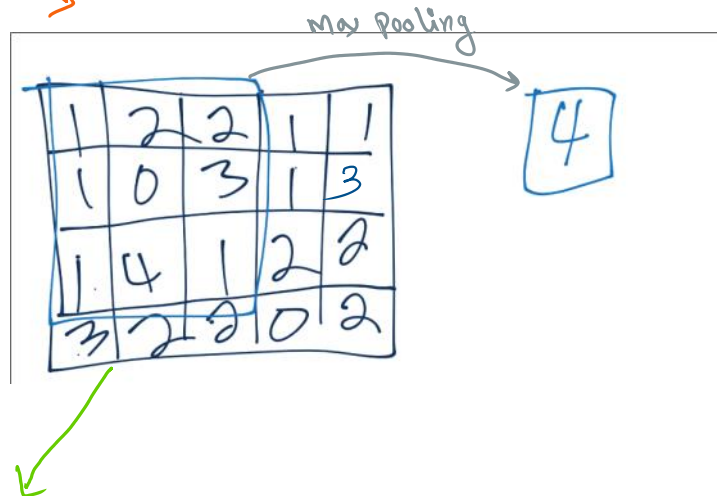


Let's say our convolution gave us:

1	2	2	1	1
1	0	3	1	3
1	4	1	2	2
3	2	2	0	2

we will apply pooling after the  
Convolution

max  
pooling



1	2	2	1	1
1	0	3	1	3
1	4	1	2	2
3	2	2	0	2

4	3
4	3

  
Conv + Pool = HL
  
 > this Complete  
 will represent  
 1 Hidden layer

∴ Basically, we will 1<sup>st</sup> Convert img into pixels.

Then we will use sliding window to find features for the complete image. This is Convolution

After Convolution we will apply pooling (max pooling) which will also move in windows.

In case of max pooling it will find out max value in that particular window.