

Jawahar Education Societys Annasaheb Chudaman Patil College of Engineering, Kharghar, Navi Mumbai

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SUBJECT: COMPUTER GRAPHICS

PAGE NO.: DATE.: / / 20
Aim :- Program to perform 30 transformation.
theory 3D Teansformation.
the gamo goomatric transformation o play a viral role in generating of & 3.10 imensional object with the help of these transformation. The location of object recative to other can be easily expressed.
TYPOS
· TEanslating
· Scaling
Rotation etc
· Algorithm 3D TEansformation.
1. START
2. Initalize ta graphic mode.
3. Deaco a 3D orgect.
4.1 A) TEanslation
a) Got the translation value tx, ty.
6) Move the object with tx, ty (x1 = x+tre, y1 = 4+ty, 21 = 2+tz)
0) Plot (X', Y').
1
Total Circumstance of the
Teachers Signature

AIM: Program to perform 3D transformation.

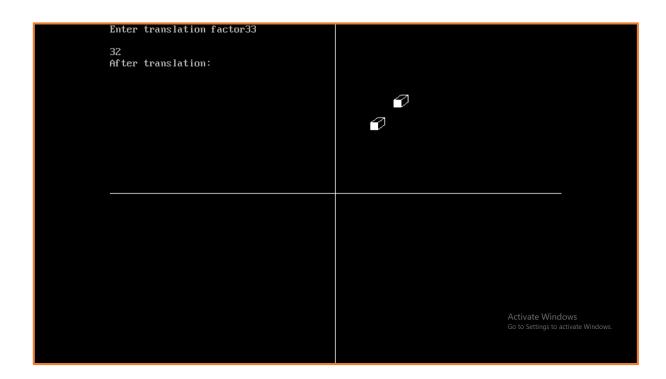
PAGE NO.: DATE.: / / 20
5 B > Scaling
9) Glet the scaling value 'Sx' S7
6] Resize the object with SXISY (x'=5*5X, Y'=5*5Y)
C) Plot (5'(4').
6.3 CY Rotation.
9) Gret the Rotation anyle
6) Rotate to object by angle o
$1. \alpha' = x \cos \phi - y \sin \phi$ $2. y' = x \sin \phi - y \cos \phi$
C) Plot (x, h)
Conclusion :
Here; we condenstronding about 30 toum for mation
and its implemental process.
2
Teachers Signature

Input:

Translation:

```
1 #include<stdio.h>
2 #include<conio.h>
3 #include<graphics.h>
4 #include<math.h>
5 Int maxx, maxy, midx, midy;
6 vold axis()
7 {
8 getch();
9 cleardevice();
10 line(midx,0,midx,maxy);
11 line(0,midy,maxx,midy);
12 }
13 void main()
14 {
15 int x,y,z,o,x1,x2,y1,y2;
16 int gd=DETECT.gm;
17 detectgraph(&gd,&gm);
18 initgraph(&gd,&gm,"C:\\TurboC3\\BGI");
19 //setfillstyle(0,getmaxcolor());
20 maxx=getmaxx();
21 maxy=getmaxy();
22 midx=maxx/2;
23 midy=maxy/2;
24 axis();
25 bar3d(midx+50,midy-100,midx+60,midy-90,10,1);
26 printf("Enter translation factor");
27 scanf("%d%d",&x,&y);
28 //axis();
29 printf("After translation:");
30 bar3d(midx+x+50,midy-(y+100),midx+x+60,midy-(y+90),10,1);
31 getch();
32 closegraph();
33 }
```

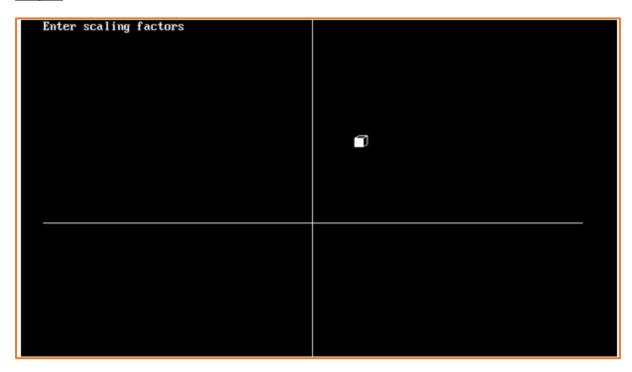
Output:-

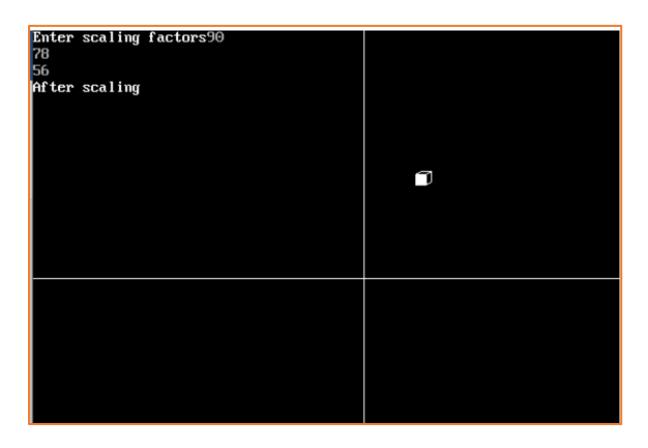


Scaling:

```
1#include<stdio.h>
2 #include<conio.h>
3 #include<graphics.h>
4 #include<math.h>
5 Int maxx, maxy, midx, midy;
6 vold axis()
7 {
8 getch();
9 cleardevice();
10 line(midx,0,midx,maxy);
11 line(0,midy,maxx,midy);
12 }
13 vold main()
14 {
15 int x,y,z,o,x1,x2,y1,y2;
16 Int gd=DETECT,gm;
17 detectgraph(&gd,&gm);
18 initgraph(&gd,&gm,"C:\\TurboC3\\BGI");
19 //setfillstyle(0,getmaxcolor());
20 maxx=getmaxx();
21 maxy=getmaxy();
22 midx=maxx/2;
23 midy=maxy/2;
24 axis();
25 bar3d(midx+50,midy-100,midx+60,midy-90,5,1);
26 printf("Enter scaling factors");
27 scanf("%d%d%d", &x,&y,&z);
28 //axis();
29 printf("After scaling");
30 bar3d(midx+(x*50),midy-(y*100),midx+(x*60),midy-(y*90),5*z,1);
31 //axis();
32 getch();
33 closegraph();
34
```

Output:

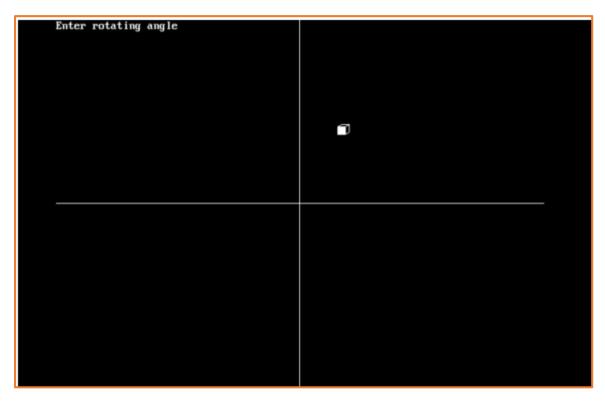


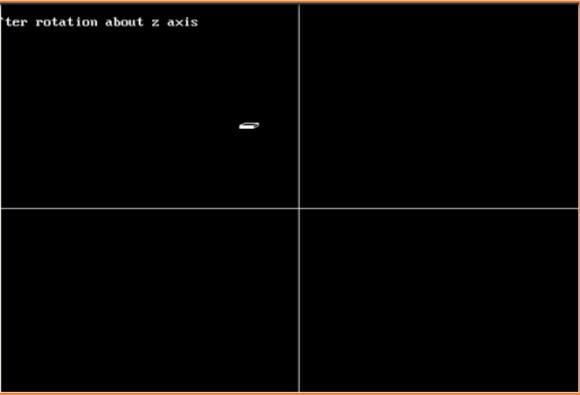


Rotation:

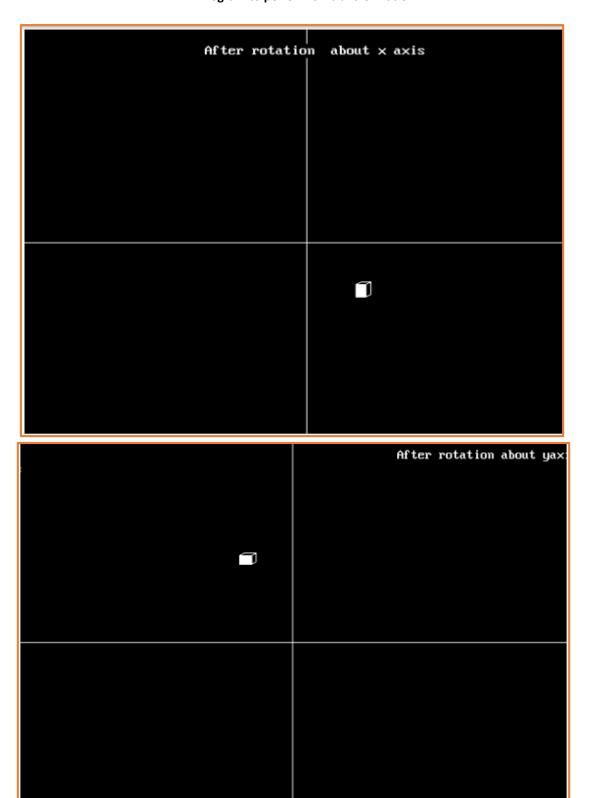
```
1 #include<stdio.h>
2 #include<conio.h>
3 #include<graphics.h>
4 #include<math.h>
5 Int maxx, maxy, midx, midy;
6 vold axis()
8 getch();
9 cleardevice();
10 line(midx,0,midx,maxy);
11 line(0,midy,maxx,midy);
12 }
13 vold main()
14 {
15 int x,y,z,o,x1,x2,y1,y2;
16 int gd=DETECT.gm;
17 detectgraph(&gd,&gm);
18 initgraph(&gd,&gm," C:\\TurboC3\\BGI ");
19 //setfillstyle(0,getmaxcolor());
20 maxx=getmaxx();
21 maxy=getmaxy();
22 midx=maxx/2
23 midy=maxy/2;
24 axis();
25 bar3d(midx+50,midy-100,midx+60,midy-90,5,1);
26 printf("Enter rotating angle");
27 scanf("%d",&o);
28 x1=50*cos(o*3.14/180)-100*sin(o*3.14/180);
29 y1=50*sin(o*3.14/180)+100*cos(o*3.14/180);
30 x2=60*cos(o*3.14/180)-90*sin(o*3.14/180);
31 y2=60*sin(o*3.14/180)+90*cos(o*3.14/180);
32 axis():
33 printf("After rotation about z axis");
34 bar3d(midx+x1,midy-y1,midx+x2,midy-y2,5,1);
35 axis();
36 printf("After rotation about x axis");
37 bar3d(midx+50,midy-x1,midx+60,midy-x2,5,1);
38 axis():
39 printf("After rotation about yaxis");
40 bar3d(midx+x1,midy-100,midx+x2,midy-90,5,1);
41 getch():
42 closegraph():
43
```

OUTPUT:





AIM: Program to perform 3D transformation.



 $\underline{\textbf{Conclusion}} : \textbf{-Here, we understanding about 3D} \ \underline{\textbf{Transformation}} \ \textbf{and its implementation process} \ .$