

Tangible User Interfaces... (TODO)

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Abstract

In this paper we compare and analyze different Tangible User Interfaces. TUIs move away from the common input devices like mouse and keyboard and towards a direct interaction with physical objects in order to make the operation with devices more natural. This includes for example the handling of physical objects on table-tops, projections of information onto pieces of paper [Holman et al. 2005] or using additional devices to get more detailed data. The examples we are going to cover in this paper include applications in architecture, information visualization and learning tools.

CR Categories: K.6.1 [Management of Computing and Information Systems]: Project and People Management—Life Cycle; K.7.m [The Computing Profession]: Miscellaneous—Ethics

Keywords: radiosity, global illumination, constant time TODO

1 Introduction

In common user interfaces the interaction is limited to indirect input methods such as mouse and keyboard. A more natural way of interaction would be to be able to directly touch and manipulate the objects of interest. One of the main goals in using Tangible User Interfaces is to combine visualization of data with direct interaction.

In this paper we first give a general overview on how Tangible User Interfaces (TUI) work and what the main challenges are.

In the next section we will give some examples of TUI and describe how some of the challenges can be solved.

2 Typical designs of Tangible User Interfaces

In this section we will discuss different hardware implementations of tangible user interfaces and take a look on the different design spaces they are used in. The graphical user interface (GUI) with the input devices of mouse and keyboard falls short in embracing the rich interface modalities between people and the physical environment they inhabit [Ullmer and Ishii 1997].

The interpretation of tangible user interfaces varies throughout the field. Ullmer and Ishii [Ullmer and Ishii 1997]

design spaces include but are not limited to - information visualization - architectural - geographical - "entertainment"

we give first example of stationary display with fixed devices, then more free ones

2.1 metaDESK

One of the attempts in broadening the input possibilities to different devices is the metaDESK system introduced by Ullmer and Ishii [Ullmer and Ishii 1997]. They describe a "Tangible User Interface" (TUI) as a user interface employing physical objects, instruments, surfaces, and spaces as physical interfaces to digital information. The metaDESK system consists of: a desk, a nearly-horizontal backprojected graphical surface; an active lens an arm-mounted flat-panel display; one or more passive lenses, an optically transparent surface through which the desk projects; and an assortment of physical objects and instruments which are used on the desk's surface. The components are sensed by an array of optical, mechanical and electromagnetic field sensors.

The focus lies on the use of real physical objects as driving elements of human-computer interaction. The approach of Ullmer and Ishii although tries to take elements of the GUI and bringing it into the real world as well as pushing forward from the unaugmented physical world, inheriting from various historical instruments and devices often "obsoleted" by the advent of the computer, like the active lens which is based on a jeweler's magnifying lens. The models for the objects are taken from everyday objects from home, scientific instruments or drawing and design tools. The material they used was transparent machined acrylic, designed to minimize occlusion of the desk surface.

The GUI icons are instantiated as "phicons" (physical icons), menus and handles are instantiated as TUI "trays" and "phandles" (physical handles), scales and scrollbars as TUI instruments such as a rotation constraint instrument.

To test the system they implemented a prototype application called "Tangible Geospace" allowing interaction with geographical space. The models themselves act as information containers about the object they represent as well as physical handles for manipulating the map.

The arm mounted active lens is coupled to the models and displays three-dimensional views of the scene and moving the lens makes it possible to navigate through 3D space. This allows a seamless interaction with three spaces at once: the physical space of the object, the 2D graphical space of the desk's surface and the 3D graphical space of the active lens.

It is also possible to place a second object on the table, allowing the user to scale or rotate the map by moving the objects with respect to each other. This also allows collaboration as each object may be manipulated by an individual user. The sensing is performed by a computer-vision system inside the desk unit, along with magnetic-field position sensors and electrical contact sensors.

The passive lenses consist of a transparent surface that functions as an independent display when augmented by the back-projected desk. Since they are passive transparent surfaces, many variously

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afforded lenses might be used simultaneously with no additional active display resources.

As alternative to the two phicon scaling/rotation interaction, a rotation constraint instrument made of two cylinders mechanically coupled by a sliding bar might be used. Albeit the extension of input methods it is not the goal of metaDESK to replace GUIs, but rather to complement them by providing new opportunities for human-computer interaction.

2.2 Other solutions to Tangible Interfaces

Spindler, Tominski, Schuhmann and Dachselt [Spindler et al. 2010] introduce 'tangible views' for use in Information Visualization as spatially aware lightweight displays that can be interacted with by moving them through the physical space on or above a tabletop surface.

The motivation for their project is the difficulty of encoding all information in a single image once a data set exceeds a certain size or complexity. This problem can be solved spatially by providing multiple views on the data or embedding additional local views in the visualization or it can be solved temporally by changing the representations over time. They define a tangible view as a physical surface, that users can hold in their hands with no restrictions on size and shape.

Tangible views serve two purposes: It is used as a local display in conjunction with a tabletop display, and as an input device. The specific graphical information is projected onto the tangible view and three dimensional manipulation of a tangible view is tracked in space to make six degrees of freedom available: position (x , y , z) with respect to the interaction space and local orientation of the tangible view (α , β , γ). It is also possible to use multiple tangible views at the same time.

In summary tangible views:

- Integrate display and interaction device.
- Enhance common 2D interaction with additional 3D interaction
- Replace virtual views by physical, tangible views.

Tangible views do not exist on their own, but are integrated into an environment of one or more stationary displays of arbitrary size, shape and orientation. They also describe a basic display configuration consisting of a horizontal tabletop for the main context view and tangible views as local views into the information space. This relates to the focus and context concept.

2.3 Including social aspects

Hornecker and Buur [Hornecker and Buur 2006] extend the thought of tangible user interfaces further to 'tangible interactions'. They introduce a framework that focuses on the interweaving of the material/physical and the social, laying the ground for collaboration-sensitive tangible interaction design. It relies on tangibility and full-body interaction and gives computational resources and data material form, embedding computing in the everyday environment, digitally augmenting physical space and supporting intuitive use.

Designing tangible interfaces requires not only designing the digital but also the physical, and their interrelationships within hybrid ensembles, as well as designing new types of interaction that can be

characterized as full-body, haptic, and spatial. Applications previously not considered interfaces are turning into such and computing is increasingly embedded in physical environments.

They distinguished three different views on tangible interfaces:

- Data-centered view: Here 'tangible interfaces' are understood as utilizing physical representation and manipulation of digital data, offering interactive couplings of physical artifacts with "computationally mediated digital information", Eg. Ullmer and Ishii
- Expressive-Movement-centered view: Aiming to design interaction itself by emphasizing bodily interaction with objects, exploiting the "sensory richness and action potential of physical objects" so that "meaning is created in the interaction".
- Space-centered view: 'Interactive spaces' as "Interactive systems, physically embedded within real spaces, offer opportunities for interacting with tangible devices" and so "trigger display of digital content or reactive behaviours" The body is used as interaction device and display.

Tangible interaction encompasses a broad range of systems and interfaces, building upon and synthesizing these views. These share the following characteristics: tangibility and materiality, physical embodiment of data, embodied interaction and bodily movement as an essential part of interaction, and embeddedness in real space, designing the interaction itself and exploiting the richness of bodily movement.

Their framework is structured around four interrelated themes:

- Tangible Manipulation: material representations with distinct tactile qualities which are physically manipulated.
- Spatial Interaction: tangible interaction is embedded in real space and therefore occurs by movement in space.
- Embodied Facilitation: how the configuration of material objects and space affects and directs group behaviour.
- Expressive Representation: material and digital representations employed by tangible interaction systems, their expressiveness and legibility.

3 Examples of Tangible User Interfaces

There is a wide variety of Tangible User Interfaces (TUIs). Possible applications for TUIs are literally endless. Many systems of TUIs have been explored and published in the past, but still a lot of new ideas are coming up and new applications for TUIs are going to be explored. In this section, we will give examples of TUIs and give an overview of different domains where TUIs have been successfully deployed.

3.1 Table-top environments

Many TUIs rely on table-top environments as their interaction technique. In these environments, a IR camera is set underneath the table-top to track fiducial markers placed onto the table. The camera can also track touch interactions of users. Marker and touch-based interactions are used as user input to the TUI system. The system responds to the user interactions by projecting visual feedback onto the table-top. Figure 1 shows the reactAble in action. Multiple users work together on a digital performance.

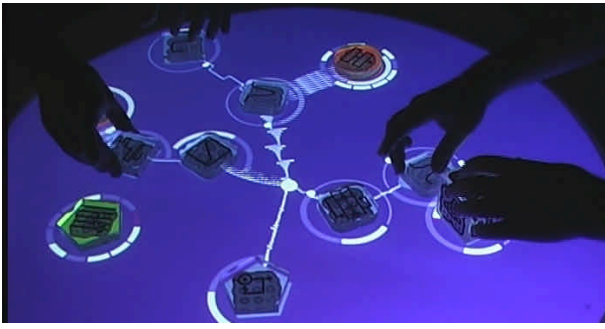


Figure 1: The reacTable in action (compare [2007])

3.1.1 reacTable

The reactAble, presented by [Jordà et al. 2007], is a musical instrument based on a table-top TUI. Fiducial Markers represent musical objects, which generate sound according to their relation to each other. The markers are tracked by an IR camera. According to their attached symbol, each object has a dedicated function. The objects can be categorized in six different functional groups: audio generators, audio filters, controllers, control filters, mixers and global objects. [2007]

ReacTIVision, the computer vision system behind reactAble, tracks the fiducial markers and sends the output data to an audio synthesizer. The waveforms generated by the synthesizer, as well as the data from the ReacTIVision tracker are sent to a visual synthesizer. The visual synthesizer projects visual feedback back onto the table-top. The audio lines that connect objects show the real resulting waveforms. Visual feedback is also used to monitor the objects state and internal parameters. Fingers can be used to either modify the objects parameters, or to cut (i.e. mute) audio connections between objects. [2007]

Modular synthesis is used for the sound generation process. Modular synthesis is based on the interconnection of sound generators and sound processor units. In reactAble, automatic connections between objects are made depending on the type of objects involved and the proximity between them. By moving objects around and bringing them into relation to each other, performers construct and play instruments at the same time. reactAble is also a collaborative tool for interactive live music. Because of the rather big size of the table-top, multiple artists can perform together on a single reacTable. [2007]

3.1.2 TARboard

TARBoard is a tangible augmented reality system designed for table-top game environment. The purpose of TARboard is to let users enjoy games in a more interactive and intuitive way and to make games more realistic and immersive. [?]

Markers are attached to objects or cards used in a game. Similar to reactAble, these markers are tracked on a table-top environment by a camera underneath it. The augmenting camera is placed above the table-top. It provides the video stream for augmenting a game with virtual objects. [?]

[?] implemented a card game as a prototype for TARboard. Each player has cards which represent mystic creatures. The marker on the bottom of each card is tracked by the tracking camera. When

the players flip a card and place it near the battle zone, the creatures get augmented on the battle zone and fight against each other.

3.2 Urban Planning Workbenches

In urban planning, designers usually employ three forms of representation: Two-dimensional drawings on sheets of papers, three-dimensional physical models and computer models, which can be two and three-dimensional. Each of these representations are created and displayed independently. Urban planning workbenches try to bridge the gap between these forms of representation, by simultaneously layering 2D drawings, 3D physical models, and digital simulation over each other. First, the 2D drawings and sketches are laid out on a table. Next, the 3D models are placed on top of the drawings. Finally, video projectors project digital simulations onto the surface. Video cameras capture the activity on the table and adjust the dynamic representation according to the position of the drawings and models with optical tags. [Ishii et al. 2002]

The advantage of urban planning workbenches lies in the combination and fusion of digital and analog content. The dynamic simulation of features like shadows, traffic and wind bring the analog content placed on the workbench to life. Users gain a more thorough understanding of the implications of their designs. Furthermore, the two- and three-dimensional physical representations together with the digital projection add to a more realistic simulation of an urban design space.[Ishii et al. 2002]

3.2.1 Urp

Urp is an implementation of an urban planning workbench. Urp is classified as an luminous-tangible interface. The accurate casting of shadows and reflections of the 3D models is a very important part of the system. The Urp urban planning workbench consists of the following five key functions:

- **Shadows:** Urp casts accurate shadows of the 3D models onto the projection table. With a clock object, the user can change the position of the computational sun and see how the shadows of the models change accordingly.
- **Distance Measurements:** With the distance-tool, a line between two buildings can be drawn. The drawn line connects two structures, with the lines length displayed beneath. This number continuously changes as the connected structures are moved.
- **Reflections:** When a user touches any building with a transparent wand, its facades become glass, so that solar reflections are generated and projected onto the table.
- **Wind Effects:** Urp is able to project an airflow simulation onto the workbench. The user can choose between eight quantized wind directions. The simulation is displayed as a regular array of white segments, whose direction and length correspond to the instantaneous direction and magnitude of the wind at that position.
- **Site Views:** Since the model buildings 3D forms are already resident in the system (because of the shadow generation), they can be rendered in perspective and with simple shader arguments. Placing a camera object in the workspace results in a real-time rendering of the current arrangement of buildings in the site, viewed from the height of a pedestrian and the position and orientation of the camera. [1999]



Figure 2: Students using the Luminous Table (compare [2002])

Urp can also simulate traffic on roads, when traffic strips are placed onto the workspace. When two plastic strips cross each other, the simulation creates an intersection with implicit traffic-control signals. Cars come to a halt in one direction, while the traffic in the other direction flows. [1999]

3.2.2 The Luminous Table

The luminous table is based upon the Urp urban planning workbench, but extends its functionality to a more mature form. The luminous table software allows more flexibility in the computation of shadows by allowing users to interactively change the latitude (Urp has a fixed latitude) and set the time of the simulation more precisely. The traffic simulation in the luminous table is also more advanced compared to Urp. Users can change the road length, road width, traffic density and traffic cycle time of the simulation. Furthermore, the luminous desk supports more geometry formats for models of urban structures and implements the ability to save and restore work. Figure 2 shows students interacting with the luminous table. [2002]

3.3 Other forms of Tangible User Interfaces

There are many other different forms of Tangible User Interfaces for a variety of devices. We will discuss some of them in this section.

3.3.1 Portico

Portico is a portable system for enabling tangible interaction on and around tablet computers. Two cameras mounted on small, foldable arms are positioned above the display to recognize a variety of physical objects. These objects can be placed on the tablet or around it. The cameras have a large field-of-view, so the interaction can be extended beyond the tablet. The prototype developed by [Avrahami et al. 2011] uses a 12" inch tablet, but the interaction space is six times the size of the tablet screen. Portico allows tablets to increase both their interaction space and sensing capabilities, without sacrificing portability. Portico can be used for games or educational purposes. Because physical objects are more graspable than touch surfaces, Portico would be suited as a learning device for young children. [?]

3.3.2 Paper Windows

Paper Windows simulates the use of digital paper displays by projecting digital content onto physical paper. IR cameras track the

motion and the shape of the paper for an accurate projection. Pens, fingers, hands and other objects are also tracked by the computer vision system to allow enhanced interaction with the paper documents. [Holman et al. 2005] introduce a set of new interaction techniques to allow interactions between different paper documents. The rubbing technique for example allows users to transfer contents between paper documents. The flipping interaction allows users to navigate through the document by flipping the paper in their hands. Paper can also be stacked to organize them in piles on a desk. On the paper document itself, items can be selected through a one handed pointing gesture. Interactions like Copy & Paste, Scrolling, Browsing and Sharing are also possible. [2005]

3.3.3 3D Tractus

[Lapides et al. 2008] present a three-dimensional user interface to monitor and control a team of independent robots in a spatial tasks. The 3D Tractus is a tangible user interface, which allows to change the height in a three-dimensional environment. It is a mechanical device consisting of a table surface that slides up and down on four vertical tracks. A tablet is placed on top of the table surface to control a 2D map. The user can move the table surface up and down to change the height in the environment. The purpose of the system is to control a robotic team inside a three-dimensional building, where a bomb has to be defused. A single human operator controls multiple robots by giving them instructions on the tablet PC. The tablet provides a topdown view of the building. [2008]

4 Tangible User Interfaces in Visualization

The purpose of this chapter is to introduce Tangible User Interfaces which are settled in the domain of Visualization. We will give an overview of TUIs in Visualization we consider noteworthy. In the previous chapter, some of the presented TUIs could also be labeled as TUIs for Visualization, because some output is visualized by the system. In the reactTable for example, the sound waves between different musical objects are visualized on the tabletop. However, the reactTable is designed as a musical instrument. In this chapter, we will focus explicitly on TUIs, which sole purpose is the Visualization of data.

5 Tangible Views for Information Visualization

Tangible Views is a Tangible User Interface for Information Visualization presented by [Spindler et al. 2010]. It consists of several handheld displays, which allow to interact with the visualized data in a more direct way. Similar to Paper Windows, a TUI presented by [Holman et al. 2005], the information is project onto cardboard displays (tangible views) as well as a tabletop. The setup also consists of several IR cameras, which track the tangible views and make them spatially aware. Gestures performed on the tangible view are recognized by the system as well.

6 Discussion

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