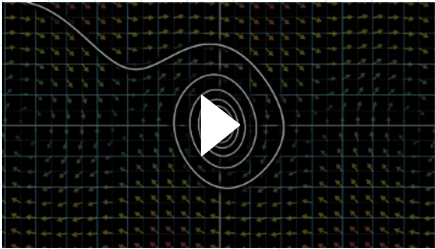


HW7

Monday, November 8, 2021 7:09 AM

1) watch

[Differential equations, a tourist's guide | DE1](#)



2) for the ode: $x'' + \epsilon(x'^3/3 - x') + x = 0$ Analyze the behavior of solutions near the equilibrium point $(0,0)$. Use Linstadt's Method (perturbation theory) writing $x = x_0 + \epsilon x_1 + \dots$. Find x_0 and compare that to the slopefield numerical approx. for the ode.

In[327]=

```
Clear["Global`*"];
```

In[328]=

```
x[t] = x0[t] + e x1[t] + e^2 x2[t];  
ode = w^2 D[x[t], {t, 2}] + e  $\left( \frac{\omega^3 D[x[t], \{t, 1\}]^3}{3} - \omega D[x[t], \{t, 1\}] \right) + x[t] == 0 /.  
w -> 1 + e \omega_1 + e^2 \omega_2  
Collect[  
ode,  
e]$ 
```

Out[329]=

$$x_0[t] + e x_1[t] + e^2 x_2[t] + e \left(- \left((1 + e \omega_1 + e^2 \omega_2) (x_0'[t] + e x_1'[t] + e^2 x_2'[t]) \right) + \frac{1}{3} (1 + e \omega_1 + e^2 \omega_2)^3 (x_0'[t] + e x_1'[t] + e^2 x_2'[t])^3 \right) + (1 + e \omega_1 + e^2 \omega_2)^2 (x_0''[t] + e x_1''[t] + e^2 x_2''[t]) == 0$$

$$\begin{aligned}
& \mathbf{x}_0[\tau] + \frac{1}{3} \epsilon^{13} \omega_2^3 \mathbf{x}_2'[\tau]^3 + \\
& \epsilon^7 \left(-\frac{1}{3} \omega_2^3 \mathbf{x}_0'[\tau]^3 + 3 \omega_1 \omega_2^2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + 3 \omega_1^2 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + 3 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \right. \\
& \quad \frac{1}{3} \omega_1^3 \mathbf{x}_1'[\tau]^3 + 2 \omega_1 \omega_2 \mathbf{x}_1'[\tau]^3 + 3 \omega_1^2 \omega_2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_2^2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 2 \omega_1^3 \mathbf{x}_0'[\tau] \\
& \quad \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + 12 \omega_1 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + 3 \omega_1^2 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_2 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + \\
& \quad \left. 3 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_1 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \frac{1}{3} \mathbf{x}_2'[\tau]^3 \right) + \\
& \epsilon^8 \left(\omega_2^3 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + 3 \omega_1 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \omega_1^2 \omega_2 \mathbf{x}_1'[\tau]^3 + \omega_2^2 \mathbf{x}_1'[\tau]^3 + \right. \\
& \quad 3 \omega_1 \omega_2^2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 6 \omega_1^2 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + 6 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + \\
& \quad \omega_1^3 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + 6 \omega_1 \omega_2 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + \omega_1^3 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + \\
& \quad \left. 6 \omega_1 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_1^2 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_2 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \omega_1 \mathbf{x}_2'[\tau]^3 \right) + \\
& \epsilon^9 \left(\omega_2^3 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \omega_1 \omega_2^2 \mathbf{x}_1'[\tau]^3 + \omega_2^3 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 6 \omega_1 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + \right. \\
& \quad 3 \omega_2^2 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_2^2 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_1^2 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + \\
& \quad \left. \omega_1^3 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + 6 \omega_1 \omega_2 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \omega_1^2 \mathbf{x}_2'[\tau]^3 + \omega_2 \mathbf{x}_2'[\tau]^3 \right) + \\
& \epsilon^{10} \left(\frac{1}{3} \omega_2^3 \mathbf{x}_1'[\tau]^3 + 2 \omega_2^3 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + 3 \omega_1 \omega_2^2 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_1 \omega_2^2 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + \right. \\
& \quad \left. 3 \omega_1^2 \omega_2 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_2^2 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \frac{1}{3} \omega_1^3 \mathbf{x}_2'[\tau]^3 + 2 \omega_1 \omega_2 \mathbf{x}_2'[\tau]^3 \right) + \\
& \epsilon^{11} \left(\omega_2^3 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + \omega_2^3 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + 3 \omega_1 \omega_2^2 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \omega_1^2 \omega_2 \mathbf{x}_2'[\tau]^3 + \omega_2^2 \mathbf{x}_2'[\tau]^3 \right) + \\
& \epsilon^{12} \left(\omega_2^3 \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \omega_1 \omega_2^2 \mathbf{x}_2'[\tau]^3 \right) + \mathbf{x}_0''[\tau] + \\
& \epsilon \left(\mathbf{x}_1[\tau] - \mathbf{x}_0'[\tau] + \frac{1}{3} \mathbf{x}_0'[\tau]^3 + 2 \omega_1 \mathbf{x}_0''[\tau] + \mathbf{x}_1''[\tau] \right) + \\
& \epsilon^2 \left(\mathbf{x}_2[\tau] - \omega_1 \mathbf{x}_0'[\tau] + \omega_1 \mathbf{x}_0'[\tau]^3 - \mathbf{x}_1'[\tau] + \right. \\
& \quad \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + \omega_1^2 \mathbf{x}_0''[\tau] + 2 \omega_2 \mathbf{x}_0''[\tau] + 2 \omega_1 \mathbf{x}_1''[\tau] + \mathbf{x}_2''[\tau] \left. \right) + \\
& \epsilon^3 \left(-\omega_2 \mathbf{x}_0'[\tau] + \omega_1^2 \mathbf{x}_0'[\tau]^3 + \omega_2 \mathbf{x}_0'[\tau]^3 - \omega_1 \mathbf{x}_1'[\tau] + 3 \omega_1 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 - \right. \\
& \quad \mathbf{x}_2'[\tau] + \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 2 \omega_1 \omega_2 \mathbf{x}_0''[\tau] + \omega_1^2 \mathbf{x}_1''[\tau] + 2 \omega_2 \mathbf{x}_1''[\tau] + 2 \omega_1 \mathbf{x}_2''[\tau] \left. \right) + \\
& \epsilon^4 \left(\frac{1}{3} \omega_2^3 \mathbf{x}_0'[\tau]^3 + 2 \omega_1 \omega_2 \mathbf{x}_0'[\tau]^3 - \omega_2 \mathbf{x}_1'[\tau] + 3 \omega_1^2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + 3 \omega_2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + \right. \\
& \quad 3 \omega_1 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \frac{1}{3} \mathbf{x}_1'[\tau]^3 - \omega_1 \mathbf{x}_2'[\tau] + 3 \omega_1 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + \\
& \quad \left. 2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + \omega_2^2 \mathbf{x}_0''[\tau] + 2 \omega_1 \omega_2 \mathbf{x}_1''[\tau] + \omega_1^2 \mathbf{x}_2''[\tau] + 2 \omega_2 \mathbf{x}_2''[\tau] \right) + \\
& \epsilon^5 \left(\omega_1^2 \omega_2 \mathbf{x}_0'[\tau]^3 + \omega_2^2 \mathbf{x}_0'[\tau]^3 + \omega_1^3 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + 6 \omega_1 \omega_2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + 3 \omega_1^2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \right. \\
& \quad 3 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \omega_1 \mathbf{x}_1'[\tau]^3 - \omega_2 \mathbf{x}_2'[\tau] + 3 \omega_1^2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + \\
& \quad \left. 6 \omega_1 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + \omega_2^2 \mathbf{x}_1''[\tau] + 2 \omega_1 \omega_2 \mathbf{x}_2''[\tau] \right) + \\
& \epsilon^6 \left(\omega_1 \omega_2^2 \mathbf{x}_0'[\tau]^3 + 3 \omega_1^2 \omega_2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + 3 \omega_2^2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_1'[\tau] + \omega_1^3 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \right. \\
& \quad 6 \omega_1 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau]^2 + \omega_1^2 \mathbf{x}_1'[\tau]^3 + \omega_2 \mathbf{x}_1'[\tau]^3 + \omega_1^3 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + \\
& \quad 6 \omega_1 \omega_2 \mathbf{x}_0'[\tau]^2 \mathbf{x}_2'[\tau] + 6 \omega_1^2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + 6 \omega_2 \mathbf{x}_0'[\tau] \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau] + \\
& \quad \left. 3 \omega_1 \mathbf{x}_1'[\tau]^2 \mathbf{x}_2'[\tau] + 3 \omega_1 \mathbf{x}_0'[\tau] \mathbf{x}_2'[\tau]^2 + \mathbf{x}_1'[\tau] \mathbf{x}_2'[\tau]^2 + \omega_2^2 \mathbf{x}_2''[\tau] \right) = 0
\end{aligned}$$

In[331]:=

```
DSolve[{x0[τ] + x0''[τ] == 0, x0[0] == a0, x0'[0] == 0}, x0[τ], τ]
d0 = Cos[τ] a0;
```

Out[331]=

```
{{x0[τ] → Cos[τ] a0}}
```

```
TrigExpand[
```

```
DSolve[{x1[τ] - (D[d0, {τ, 1}]) + 1/3 (D[d0, {τ, 1}])^3 + 2 ω1 (D[d0, {τ, 2}]) + x1''[τ] == 0,
x1[0] == 0, x1'[0] == 0}, x1[τ], τ]]
```

```
Expand[FullSimplify[1/2 τ Cos[τ] a0 - 1/2 Sin[τ] a0 - 1/8 τ Cos[τ] a0^3 + 3/32 Sin[τ] a0^3 + 1/32 Cos[τ]^2
Sin[τ] a0^3 - 1/96 Sin[τ]^3 a0^3 + τ Sin[τ] a0 ω1]] /. {τ Cos[τ] → 0, τ Sin[τ] → 0}
```

```
d1 = Expand[1/96 × (48 (-Sin[τ]) a0 + (9 Sin[τ] + Sin[3 τ]) a0^3)];
```

Out[333]=

```
{{x1[τ] → 1/2 τ Cos[τ] a0 - 1/2 Sin[τ] a0 - 1/8 τ Cos[τ] a0^3 +
3/32 Sin[τ] a0^3 + 1/32 Cos[τ]^2 Sin[τ] a0^3 - 1/96 Sin[τ]^3 a0^3 + τ Sin[τ] a0 ω1}}
```

Out[334]=

```
-1/2 Sin[τ] a0 + 3/32 Sin[τ] a0^3 + 1/96 Sin[3 τ] a0^3
```

In[353]:=

```
TrigExpand[DSolve[{x2[τ] - ω1 (D[d0, {τ, 1}]) + ω1 (D[d0, {τ, 1}])^3 - (D[d1, {τ, 1}]) +
(D[d0, {τ, 1}])^2 (D[d0, {τ, 1}]) + ω1^2 (D[d0, {τ, 2}]) + 2 ω2 (D[d0, {τ, 2}]) +
2 ω1 (D[d1, {τ, 2}]) + x2''[τ] == 0, x2[0] == 0, x2'[0] == 0}, x2[τ], τ]]
```

```
Expand[FullSimplify[-1/4 τ Sin[τ] a0 + 1/256 Cos[τ] a0^3 - 3/8 τ Cos[τ] a0^3 -
1/256 Cos[τ]^3 a0^3 + 9/32 Sin[τ] a0^3 + 3/64 τ Sin[τ] a0^3 + 3/32 Cos[τ]^2 Sin[τ] a0^3 +
3/256 Cos[τ] Sin[τ]^2 a0^3 - 1/32 Sin[τ]^3 a0^3 + τ Cos[τ] a0 ω1 - Sin[τ] a0 ω1 -
15/32 τ Cos[τ] a0^3 ω1 + 57/128 Sin[τ] a0^3 ω1 + 3/128 Cos[τ]^2 Sin[τ] a0^3 ω1 - 1/128 Sin[τ]^3 a0^3 ω1 +
1/2 τ Sin[τ] a0 ω1^2 + τ Sin[τ] a0 ω2]] /. {τ Cos[τ] -> 0, τ Sin[τ] -> 0}
d2 = 1/256 Cos[τ] a0^3 - 1/256 Cos[3 τ] a0^3 + 9/32 Sin[τ] a0^3 + 1/32 Sin[3 τ] a0^3;
```

Out[353]=

```
{ {x2[τ] -> -1/4 τ Sin[τ] a0 + 1/256 Cos[τ] a0^3 - 3/8 τ Cos[τ] a0^3 - 1/256 Cos[τ]^3 a0^3 +
9/32 Sin[τ] a0^3 + 3/64 τ Sin[τ] a0^3 + 3/32 Cos[τ]^2 Sin[τ] a0^3 + 3/256 Cos[τ] Sin[τ]^2 a0^3 -
1/32 Sin[τ]^3 a0^3 + τ Cos[τ] a0 ω1 - Sin[τ] a0 ω1 - 15/32 τ Cos[τ] a0^3 ω1 + 57/128 Sin[τ] a0^3 ω1 +
3/128 Cos[τ]^2 Sin[τ] a0^3 ω1 - 1/128 Sin[τ]^3 a0^3 ω1 + 1/2 τ Sin[τ] a0 ω1^2 + τ Sin[τ] a0 ω2} }
```

Out[354]=

```
1/256 Cos[τ] a0^3 - 1/256 Cos[3 τ] a0^3 + 9/32 Sin[τ] a0^3 +
1/32 Sin[3 τ] a0^3 - Sin[τ] a0 ω1 + 57/128 Sin[τ] a0^3 ω1 + 1/128 Sin[3 τ] a0^3 ω1
```

In[359]:=

d0 + ε d1 + ε^2 d2

Out[359]=

```
Cos[τ] a0 + ε (-1/2 Sin[τ] a0 + 3/32 Sin[τ] a0^3 + 1/96 Sin[3 τ] a0^3) +
ε^2 (1/256 Cos[τ] a0^3 - 1/256 Cos[3 τ] a0^3 + 9/32 Sin[τ] a0^3 + 1/32 Sin[3 τ] a0^3)
```

