Bsc Thesis

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November 24, 2023

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1 Cahn Hillard Equation Overview

Partial Differential Equation (PDE) solving the state of a 2 Phase Fluid[2]. The form of the Cahn Hillard Equation used for the remainder of this thesis is:

$$\phi_t(x,t) = \Delta\mu \tag{1}$$

$$\mu = -\varepsilon^2 \Delta \Phi + W'(\Phi) \tag{2}$$

where ϕ is the so called phase field. Demarking the different states of the fluids through an Interval I = [-1, 1] and where $\partial I = \{-1, 1\}$ represents full state of one fluid. $\varepsilon > 0$ is a positive constant

, and μ is the chemical potential[2]. While the Cahn Hillard exist in a more general form taking the fluids mobility $M(\Phi)$ into account, we will assume $M(\Phi) = 1$, simplifying the CH-Equations used in[2][1] to what is stated above.

The Advantages of the Cahn Hillard Approach as compared to traditional fluid dynamics solvers are for example: "explicit tracking of the interface" [2], as well as "evolution of complex geometries and topological changes [...] in a natural way" [2]

1.1 TODO Derivation from paper

1.1.1 Free energy

The Cahn Hillard Equations can be motivated Using a **Ginzburg Landau** type free energy equation:

$$E^{\text{bulk}} = \int_{\Omega} \frac{\varepsilon^2}{2} |\nabla \phi|^2 + F(\phi) dx$$

where " $F(\phi)$ denotes the (Helmholtz) free energy density of mixing." [2] and will be approximated in further calculations as $F(\phi) = \frac{(1-\phi^2)^2}{4}$ as used in [1]

The chemical potential then follows as derivative of Energy in respect to time.

$$\mu = \frac{\delta E_{bulk}(\phi)}{\delta \phi} = -\varepsilon^2 \Delta \phi + W'(\phi)$$

1.1.2 Derivation by mass balance

The Cahn Hillard equation then can be motivated as follows: consider

$$\partial_t \phi + \nabla J = 0 \tag{3}$$

where J is mass flux. eq1 then states that the change in mass balances the change of the phasefield. using the no-flux boundry conditions:

$$J \cdot n = 0 \qquad \partial \Omega \times (0, T) \tag{4}$$

$$\partial_n \phi = 0 \qquad \partial\Omega \times (0, T) \tag{5}$$

conservation of mass follows see [2].

using:

$$J = -\nabla \mu \tag{6}$$

which conceptionally sets mass flux to equalize the the potential energy gradient, leads to the formulation of the CH equations as stated above. additionally the boundry conditions evaluate to:

$$-\nabla \mu = 0$$
$$\partial_n \phi = 0$$

ie no flow leaves and potential on the border doesn't change. then for ϕ then follows:

$$\frac{d}{dt}E^{bulk}(\phi(t)) = \int_{\Omega} (\varepsilon^2 \nabla \phi \cdot \nabla \partial_t \phi + W'(\phi)\partial_t \phi) dx$$

$$= -\int_{\Omega} |\nabla \mu|^2 dx, \qquad \forall t \in (0, T)$$

hence the Free Energy is decreasing in time.

2 Baseline Multigrid solver:

As baseline for further experiments a multi grid method based on finite differences by [1]. is used.

2.1 Discretization:

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it discretizes the phasefield and potential energy ϕ , μ into a grid wise functions ϕ_{ij} , μ_{ij} and defines the partial derivatives $D_x f_{ij}$, $D_y f_{ij}$ using the differential quotients:

$$D_x f_{i+\frac{1}{2}j} = \frac{f_{i+1j} - f_{ij}}{h}$$
 $D_y f_{ij+\frac{1}{2}} = \frac{f_{ij+1} - f_{ij}}{h}$

for ∇f , Δf then follows:

$$\nabla f_{ij} = (D_x f_{i+1j}, \ D_y f_{ij+1})$$

$$\Delta f_{ij} = \frac{D_x f_{i+\frac{1}{2}j} - D_x f_{i-\frac{1}{2}j} + D_y f_{ij+\frac{1}{2}} - D_y f_{ij-\frac{1}{2}}}{h} = \nabla_d \cdot \nabla_d f_{ij}$$

the authors further adapt the discretized phase field by the characteristic function of the domain Ω :

$$G(x,y) = \begin{cases} 1 & (x,y) \in \Omega \\ 0 & (x,y) \notin \Omega \end{cases}$$

To account for boundry conditions and arbitrary shaped domains. The authors [1] then define the discrete CH Equation adapted for Domain, as:

$$\frac{\phi_{i+1j} - \phi_{ij}}{\Delta t} = \nabla_d \cdot (G_{ij} \nabla_d \mu_{ij}^{n+1})$$
$$\mu_{ij}^{n+1} = 2\phi_{ij}^{n+1} - \varepsilon^2 \nabla_d \cdot (G_{ij} \nabla_d \phi_{ij}^{n+1}) + W'(\phi_{ij}^n) - 2\phi_{ij}^n$$

and derive the iteration operator $L(\phi^{n+1},\mu^{n+\frac{1}{2}})=(\zeta^n,\psi^n)$

$$L\begin{pmatrix} \phi^{n+1} \\ \mu^{n+\frac{1}{2}} \end{pmatrix} = \begin{pmatrix} \frac{\phi^{n+1}}{\Delta t} - \nabla_d \cdot (G_{ij} \nabla_d \mu^{n+\frac{1}{2}}) \\ \varepsilon^2 \nabla_d \cdot (G_{ij} \nabla_d \phi_{ij}^{n+1}) - 2\phi_{ij}^{n+1} + \mu_{ij}^{n+\frac{1}{2}} \end{pmatrix}$$

initialized as $(\zeta^n, \psi^n) = \begin{pmatrix} \frac{\phi_{ij}^{n+1}}{\Delta t} \\ W'(\phi_{ij}^n) - 2\phi_{ij}^n \end{pmatrix}$ the algorithm is then defined as:

wherein SMOOTH consists of point-wise Gauß Seidel Relaxation , by solving L for $\overline{\phi}, \overline{\mu}$ with the initial guess for ζ^n, ψ^n .

2.2 adaptations to the simplified problem

even tough this work uses rectangular domains, the adaptation of the algorithm is simplified by the domain indicator function, as well as 0 padding, in order to correctly include the boundry conditions of the CH equation. therefore the internal representation of the adapted algorithm considers phasefield and potential field ϕ , μ as 2D arrays of shape (N_X+2,N_y+2) in order to accommodate padding. Where N_x and N_y are the number of steps in x-/y-Direction respectively. Hence, we define the discrete domain function as:

$$G_{ij} = \begin{cases} 1 & (i,j) \in [1, N_x + 1] \times [1, N_y + 1] \\ 0 & \text{else} \end{cases}$$

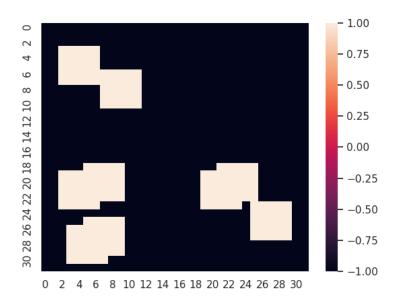
2.3 tests_{data}:

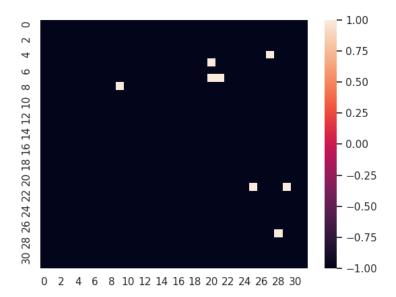
2.3.1 squares

For testting and later training, a multitude o different phasefields where used, notably an assortment of rnadomly lpaced circles, squares, and arbetrary generated values



Figure 1: FAS Multigrid v-cycle as defined by [1]





2.3.2 circles

2.4 Tests

3 Relaxed Problem

In effort to decrease the order of complexity, the following relaxation to the classical CH Equation is proposed:

3.1 TODO relaxed operators:

3.1.1 L Relaxed

$$L\begin{pmatrix} \phi^{n+1} \\ \mu^{n+1} \end{pmatrix} = \begin{pmatrix} \frac{\phi_{ij}^{n+1,m}}{\Delta t} - \nabla_d \cdot (G_{ji} \nabla_d \mu_{ji}^{n+\frac{1}{2},m}) \\ \varepsilon^2 (c^{\alpha} - (\phi_{ij}^{n+1,m})^{\alpha}) - 2\phi_{ij}^{n+1,m} - \mu_{ji}^{n+\frac{1}{2},m} \end{pmatrix}$$

3.1.2 **SMOOTH**

$$SMOOTH(\phi_{ij}^{n+1,m}, \mu_{ji}^{n+\frac{1}{2},m}, L_h, \zeta^n, \psi^n)$$

$$\overline{\mu}_{ji}^{n+\frac{1}{2},m} = \frac{\phi_{ij}^{n+1,m}}{\Delta t} - \zeta_{ij}^{n} \\
- \frac{1}{h^{2}} (G_{i+\frac{1}{2}j} \mu_{i+1j}^{n+\frac{1}{2},m} + G_{i-1j} \mu_{i-1j}^{n+\frac{1}{2},m} + G_{ij+1} \mu_{ij+1}^{n+\frac{1}{2},m} + G_{ij-1} \mu_{ij-1}^{n+\frac{1}{2},m}) \\
\cdot (G_{i+1j} + G_{i-1j} + G_{ij+1} + G_{ij-1})^{-1}$$

$$\varepsilon^2 (\overline{\phi}_{ij}^{n+1,m})^{\alpha} + 2\phi_{ij}^{n+1,m} = \varepsilon^2 c^{\alpha} - \mu_{ii}^{n+\frac{1}{2},m} - \psi_{ij}$$

1. Proposal design newton method to solve second equation (in conjunction with the first one) hopefully solving is faster than the original multiple SMOOTH Iterations. The iteration is to solve for $\phi_{ij}^{n+1,m}$ as free variable. Therefore it follows for F(x)

$$F(x) = \varepsilon^{2} x^{\alpha} + 2x - \varepsilon^{2} c^{\alpha} + y + \psi_{ij}$$

$$y = \frac{x}{\Delta t} - \zeta_{ij}^{n}$$

$$- \frac{1}{h^{2}} (G_{i+\frac{1}{2}j} \mu_{i+1j}^{n+\frac{1}{2},m} + G_{i-1j} \mu_{i-1j}^{n+\frac{1}{2},m} + G_{ij+1} \mu_{ij+1}^{n+\frac{1}{2},m} + G_{ij-1} \mu_{ij-1}^{n+\frac{1}{2},m})$$

$$\cdot (G_{i+1j} + G_{i-1j} + G_{ij+1} + G_{ij-1})^{-1}$$

And the derivative for the iteration is

$$\frac{d}{dx}F(x) = \alpha \varepsilon^2 x^{\alpha - 1} + 2 + \frac{d}{dx}y$$
$$\frac{d}{dx}y = \frac{1}{\Delta t}$$

4 References

References

- [1] Jaemin Shin, Darae Jeong, and Junseok Kim. "A conservative numerical method for the Cahn-Hilliard equation in complex domains". In: Journal of Computational Physics 230.19 (2011), pp. 7441-7455. ISSN: 0021-9991. DOI: https://doi.org/10.1016/j.jcp.2011.06.009. URL: https://www.sciencedirect.com/science/article/pii/S0021999111003585.
- [2] Hao Wu. "A review on the Cahn-Hilliard equation: classical results and recent advances in dynamic boundary conditions". In: *Electronic Research Archive* 30.8 (2022), pp. 2788–2832. DOI: 10.3934/era.2022143. URL: https://doi.org/10.3934%2Fera.2022143.