Bottom-Up FSA implementation - Michele Proverbio

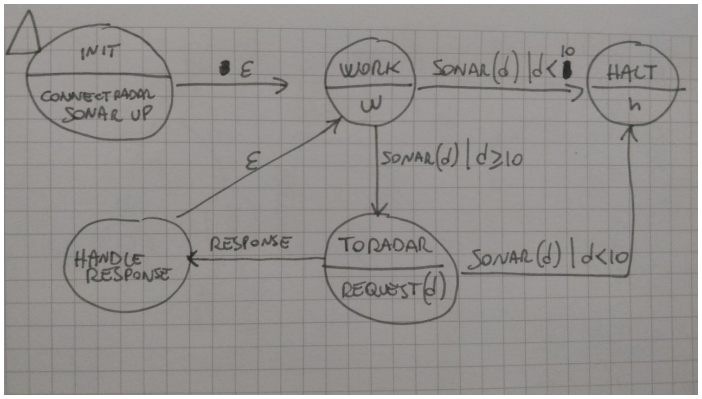
Requirements

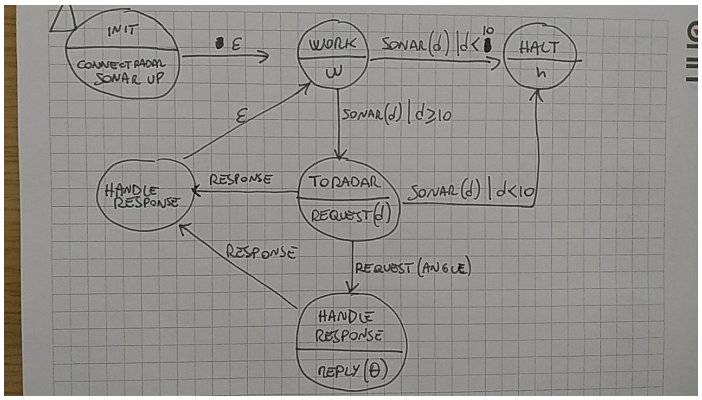
Build a bottom-up implementation of a FSA describing the behaviour of a robot with those specifics:

- the robot moves forward until an obstacle is detected
- the robot must send sonar data to a radar with a request-response pattern

Expand the previous requirements: the radar might request an angle to the robot before responding to the request sending the sonar data.

Requirement analysis





Problem analysis

The FSA is implemented through a transition matrix and an event loop that checks if a tarnsition gets applied.

States actions are implemented by procedures that get called by the event loop once a transition gets activated.

The current state is stored in a variable.

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