

```

> f:=x->x^2-2*x
                                      $f := x \mapsto x^2 - 2 \cdot x$  (1)
=
> eqd:=diff(x(t),t)=f(x(t))
                                      $eqd := \frac{d}{dt} x(t) = x(t)^2 - 2 x(t)$  (2)
=
> equip:=solve(f(x)=0,x)
                                      $equip := 0, 2$  (3)
=
> equip[1]
                                     0 (4)
=
> D(f)(equip[1])
                                     -2 (5)
=
> D(f)(equip[2])
                                     2 (6)
=
> DEplot(eqd,x(t),t=-2..2,[x(0)=-3],[x(0)=-2],[x(0)=-1],[x(0)=-1/2],[x(0)=-1/3],[x(0)=0],[x(0)=1/3],[x(0)=1/2],[x(0)=1],[x(0)=2],[x(0)=3]])
DEplot( $\frac{d}{dt} x(t) = x(t)^2 - 2 x(t), x(t), t = -2..2, [x(0) = -3], [x(0) = -2], [x(0) = -1], [x(0) = -\frac{1}{2}], [x(0) = -\frac{1}{3}], [x(0) = 0], [x(0) = \frac{1}{3}], [x(0) = \frac{1}{2}], [x(0) = 1], [x(0) = 2], [x(0) = 3]$ ) (7)
=
> with(plots)
[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d, conformal, (8)
conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot, display,
dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot, implicitplot3d, inequal,
interactive, interactiveparams, intersectplot, listcontplot, listcontplot3d, listdensityplot, listplot,
listplot3d, loglogplot, logplot, matrixplot, multiple, odeplot, pareto, plotcompare, pointplot,
pointplot3d, polarplot, polygonplot, polygonplot3d, polyhedra_supported, polyhedraplot,
rootlocus, semilogplot, setcolors, setoptions, setoptions3d, shadebetween, spacecurve,
sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]
=
> DEplot(eqd,x(t),t=-2..2,[x(0)=-3],[x(0)=-2],[x(0)=-1],[x(0)=-1/2],[x(0)=-1/3],[x(0)=0],[x(0)=1/3],[x(0)=1/2],[x(0)=1],[x(0)=2],[x(0)=3]])
DEplot( $\frac{d}{dt} x(t) = x(t)^2 - 2 x(t), x(t), t = -2..2, [x(0) = -3], [x(0) = -2], [x(0) = -1], [x(0) = -\frac{1}{2}], [x(0) = -\frac{1}{3}], [x(0) = 0], [x(0) = \frac{1}{3}], [x(0) = \frac{1}{2}], [x(0) = 1], [x(0) = 2], [x(0) = 3]$ ) (9)

```

$$=2], [x(0)=3]]))$$

```
> with(DEtools)
[AreSimilar, Closure, DENormal, DEplot, DEplot3d, DEplot_polygon, DFactor, DFactorLCLM, (10)
DFactorsols, Dchangevar, Desingularize, FindODE, FunctionDecomposition, GCRD, Gosper,
Heunsols, Homomorphisms, IVPsol, IsHyperexponential, LCLM, MeijerGsols,
MultiplicativeDecomposition, ODEInvariants, PDEchangecoords, PolynomialNormalForm,
RationalCanonicalForm, ReduceHyperexp, RiemannPsols, Xchange, Xcommutator, Xgauge,
Zeilberger, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsym, canoni, caseplot,
casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys,
dalembertsol, dcoeffs, de2diffop, dfieldplot, diff_table, diffop2de, dperiodic_sols, dpolyform,
dsols, eigenring, endomorphism_charpoly, equinv, eta_k, eulersols, exactsol, expsols,
exterior_power, firint, firtest, formal_sol, gen_exp, generate_ic, genhomosol, gensys,
hamilton_eqs, hypergeometricsols, hypergeomsols, hyperode, indicialeq, infgen, initialdata,
integrate_sols, intfactor, invariants, kovacicsols, leftdivision, liesol, line_int, linearsol,
matrixDE, matrix_riccati, maxdimsystems, moser_reduce, muchange, mult, mutest,
newton_polygon, normalG2, ode_int_y, ode_y1, odeadvisor, odepde, parametricsol,
particularsol, phaseportrait, poincare, polysols, power_equivalent, rational_equivalent,
ratsols, redode, reduceOrder, reduce_order, regular_parts, regularsp, remove_RootOf,
riccati_system, riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, singularities,
solve_group, super_reduce, symgen, symmetric_power, symmetric_product, symtest, transinv,
translate, untranslate, varparam, zoom]
```

```
> DEplot(eqd, x(t), t=-2..2, [[x(0)=-3], [x(0)=-2], [x(0)=-1], [x(0)=-1/2], [x(0)=-1/3], [x(0)=0], [x(0)=1/3], [x(0)=-1/2], [x(0)=1], [x(0)=2], [x(0)=3]]))
```

Warning, plot may be incomplete, the following error(s) were issued:
cannot evaluate the solution further left of -.25541281, probably a singularity

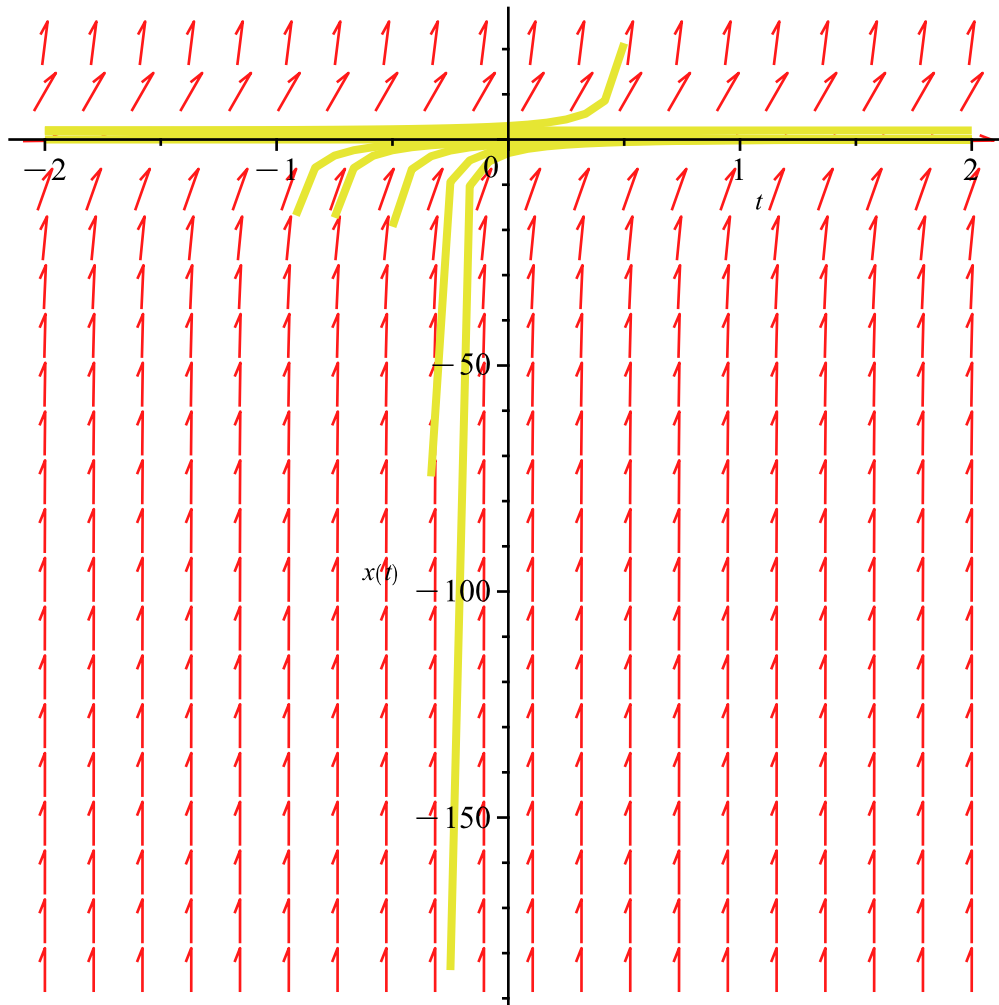
Warning, plot may be incomplete, the following error(s) were issued:
cannot evaluate the solution further left of -.34657359, probably a singularity

Warning, plot may be incomplete, the following error(s) were issued:
cannot evaluate the solution further left of -.54930616, probably a singularity

Warning, plot may be incomplete, the following error(s) were issued:
cannot evaluate the solution further left of -.97295514, probably a singularity

Warning, plot may be incomplete, the following error(s) were issued:
cannot evaluate the solution further left of -.80471900, probably a singularity

Warning, plot may be incomplete, the following error(s) were issued:
cannot evaluate the solution further right of .54930618, probably a singularity



>

> $f := x \mapsto x \cdot (x - 1) \cdot (x - 2)$

$f := x \mapsto x \cdot (x - 1) \cdot (x - 2)$

(11)

> $deq := \text{diff}(x(t), t) = f(x(t))$

$deq := \frac{d}{dt} x(t) = x(t) \cdot (x(t) - 1) \cdot (x(t) - 2)$

(12)

> $equip := \text{solve}(f(x) = 0, x)$

$equip := 0, 1, 2$

(13)

> $equip[1]$

0

(14)

> $D(f)(equip[1])$

2

(15)

> $D(f)(equip[2])$

-1

(16)

> $D(f)(equip[3])$

2

(17)

> $DEplot(deq, x(t), t = -2..2, \left[[x(0) = -3], [x(0) = -2], [x(0) = -1], \left[x(0) = -\frac{1}{2} \right], \left[x(0) = \right.$

$$-\frac{1}{3}], [x(0)=0], \left[x(0)=\frac{1}{3}\right], \left[x(0)=-\frac{1}{2}\right], [x(0)=1], [x(0)=2], [x(0)=3]\right)\right)$$

Warning, plot may be incomplete, the following errors(s) were issued:
cannot evaluate the solution further right of .32269256e-1,
probably a singularity

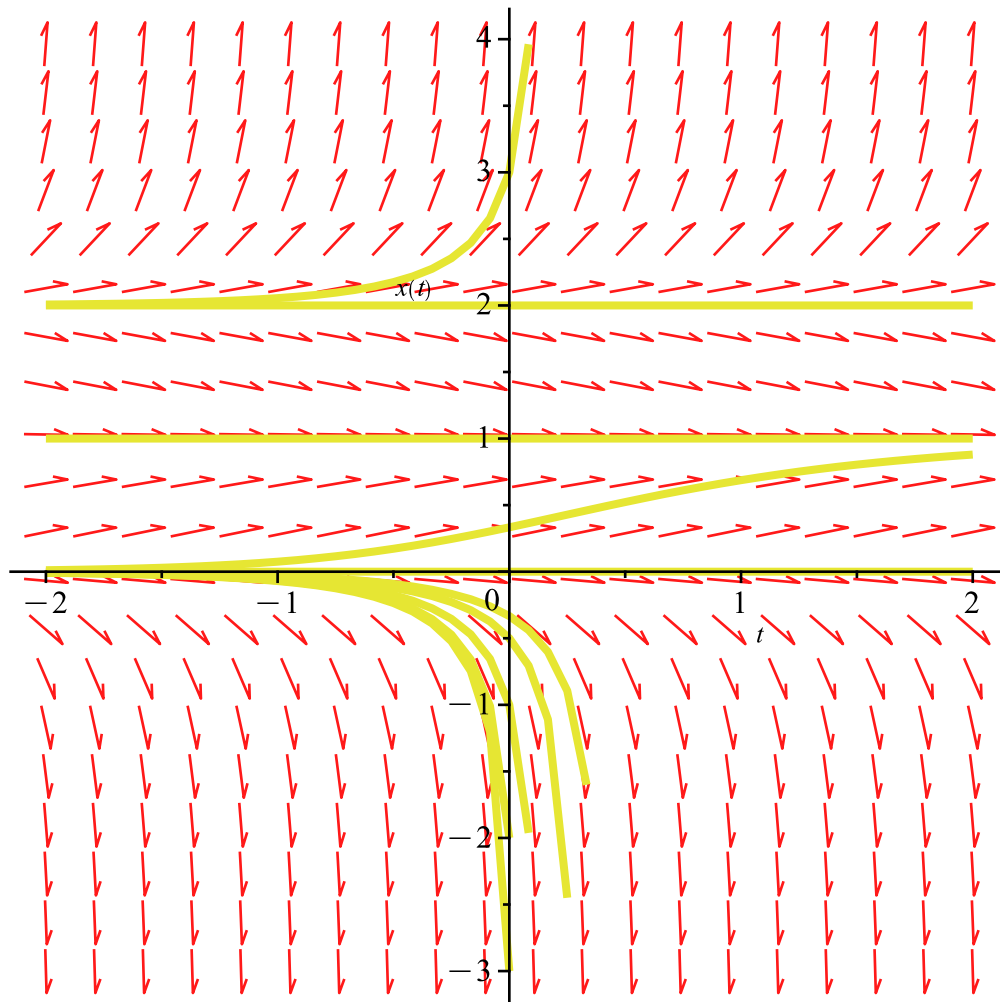
Warning, plot may be incomplete, the following errors(s) were issued:
cannot evaluate the solution further right of .58891510e-1,
probably a singularity

Warning, plot may be incomplete, the following errors(s) were issued:
cannot evaluate the solution further right of .14384102, probably
a singularity

Warning, plot may be incomplete, the following errors(s) were issued:
cannot evaluate the solution further right of .41333927, probably
a singularity

Warning, plot may be incomplete, the following errors(s) were issued:
cannot evaluate the solution further right of .29389331, probably
a singularity

Warning, plot may be incomplete, the following errors(s) were issued:
cannot evaluate the solution further right of .14384100, probably
a singularity



```
>
>
>
```

$f := x \rightarrow \sin(x)$

$$f := x \mapsto \sin(x) \quad (18)$$

$$\begin{aligned} &> eqd := diff(x(t), t) = f(x(t)) \\ &eqd := \frac{d}{dt} x(t) = \sin(x(t)) \end{aligned} \quad (19)$$

$$\begin{aligned} &> equip := solve(f(x) = 0) \\ &equip := 0 \end{aligned} \quad (20)$$

$$\begin{aligned} &> _EnvAllSolutions := true \\ &_EnvAllSolutions := true \end{aligned} \quad (21)$$

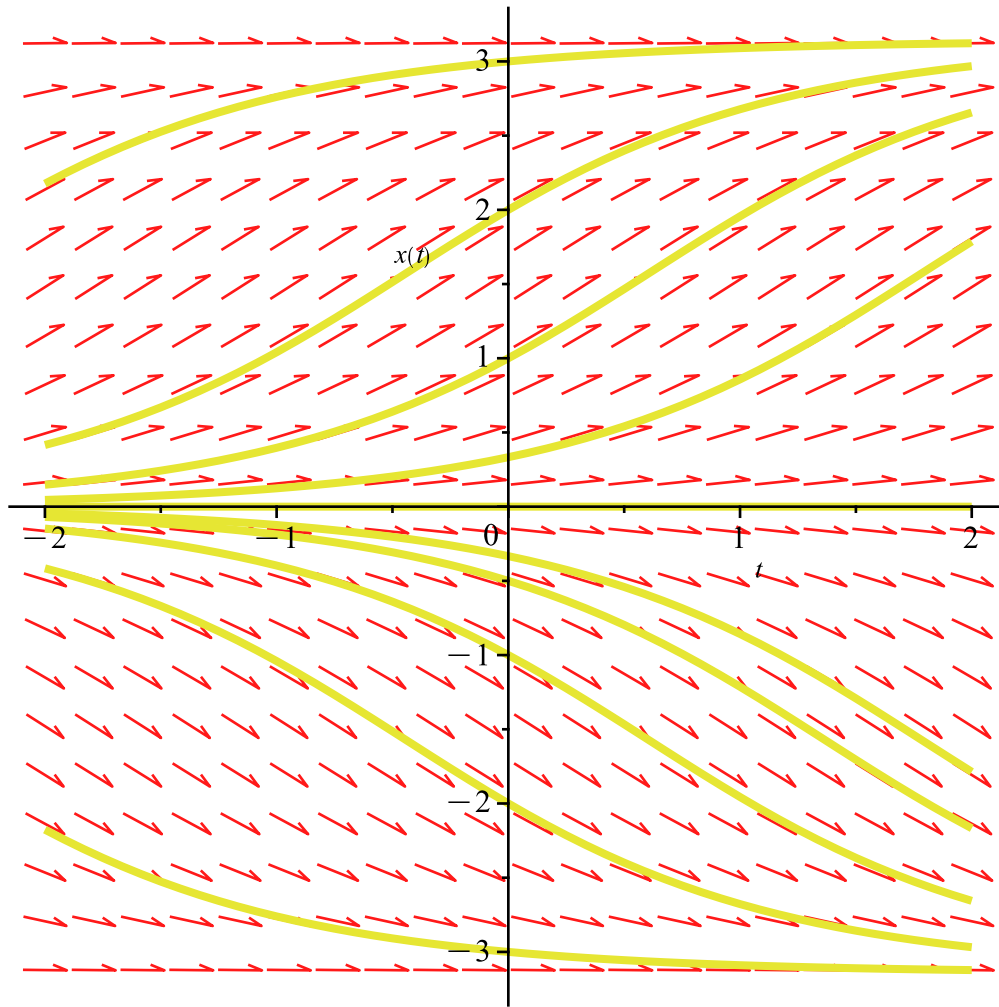
$$\begin{aligned} &> equip := solve(f(x) = 0) \\ &equip := \pi_Z1\sim \end{aligned} \quad (22)$$

$$\begin{aligned} &> equip[1] \\ &(\pi_Z1\sim)_1 \end{aligned} \quad (23)$$

$$\begin{aligned} &> equip[2] \\ &(\pi_Z1\sim)_2 \end{aligned} \quad (24)$$

$$\begin{aligned} &> D(f) (equip) \\ &(-1)^{-Z1\sim} \end{aligned} \quad (25)$$

$$\begin{aligned} &> DEplot\left(eqd, x(t), t = -2..2, \left[[x(0) = -3], [x(0) = -2], [x(0) = -1], \left[x(0) = -\frac{1}{2}\right], \left[x(0) = -\frac{1}{3}\right], [x(0) = 0], \left[x(0) = \frac{1}{3}\right], \left[x(0) = -\frac{1}{2}\right], [x(0) = 1], [x(0) = 2], [x(0) = 3] \right] \right) \end{aligned}$$



>

> with(linalg)

[BlockDiagonal, GramSchmidt, JordanBlock, LUdecomp, QRdecomp, Wronskian, addcol, addrow, adj, adjoint, angle, augment, backsub, band, basis, bezout, blockmatrix, charmat, charpoly, cholesky, col, coldim, colspace, colspan, companion, concat, cond, copyinto, crossprod, curl, definite, delcols, delrows, det, diag, diverge, dotprod, eigenvals, eigenvalues, eigenvectors, eigenvects, entermatrix, equal, exponential, extend, ffgausselim, fibonacci, forwardsub, frobenius, gausselim, gaussjord, geneqns, genmatrix, grad, hadamard, hermite, hessian, hilbert, htranspose, ihermite, indexfunc, innerprod, intbasis, inverse, ismith, issimilar, iszero, jacobian, jordan, kernel, laplacian, leastsqrs, linsolve, matadd, matrix, minor, minpoly, mulcol, mulrow, multiply, norm, normalize, nullspace, orthog, permanent, pivot, potential, randmatrix, randvector, rank, ratform, row, rowdim, rowspace, rowspan, rref, scalarmul, singularvals, smith, stackmatrix, submatrix, subvector, sumbasis, swapcol, swaprow, sylvester, toeplitz, trace, transpose, vandermonde, vecpotent, vectdim, vector, wronskian]

> eq1 := diff(x(t), t) = 2·x(t) + y(t)

$$eq1 := \frac{d}{dt} x(t) = 2 x(t) + y(t)$$

(26)

(27)

$$\begin{aligned} > \text{eq2} := \text{diff}(y(t), t) = x(t) + 2 \cdot y(t) \\ & \text{eq2} := \frac{d}{dt} y(t) = x(t) + 2 y(t) \end{aligned} \quad (28)$$

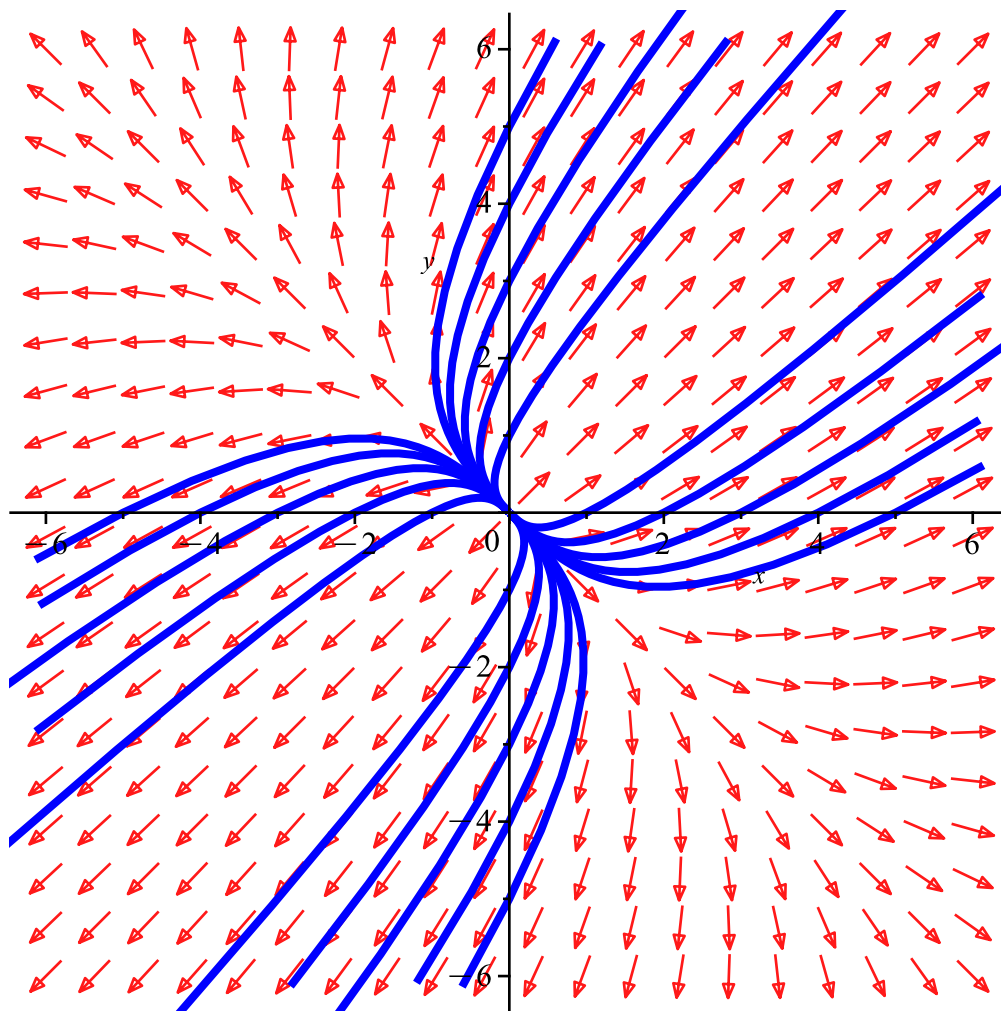
$$\begin{aligned} > \text{sist} := \text{eq1}, \text{eq2} \\ & \text{sist} := \frac{d}{dt} x(t) = 2 x(t) + y(t), \frac{d}{dt} y(t) = x(t) + 2 y(t) \end{aligned} \quad (29)$$

$$\begin{aligned} > A := \text{matrix}([[2, 1], [1, 2]]) \\ & A := \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \end{aligned} \quad (30)$$

$$\begin{aligned} > \text{eigenvals}(A) \\ & 3, 1 \end{aligned} \quad (31)$$

$$\begin{aligned} > \text{in_cond} := [x(0) = 0, y(0) = i] \$ i = 1 .. 5, [x(0) = -i, y(0) = 0] \$ i = 1 .. 5, [x(0) = 0, y(0) = -i] \$ i \\ & = 1 .. 5, [x(0) = i, y(0) = 0] \$ i = 1 .. 5 \\ \text{in_cond} := [x(0) = 0, y(0) = 1], [x(0) = 0, y(0) = 2], [x(0) = 0, y(0) = 3], [x(0) = 0, y(0) \\ & = 4], [x(0) = 0, y(0) = 5], [x(0) = -1, y(0) = 0], [x(0) = -2, y(0) = 0], [x(0) = -3, y(0) \\ & = 0], [x(0) = -4, y(0) = 0], [x(0) = -5, y(0) = 0], [x(0) = 0, y(0) = -1], [x(0) = 0, y(0) \\ & = -2], [x(0) = 0, y(0) = -3], [x(0) = 0, y(0) = -4], [x(0) = 0, y(0) = -5], [x(0) = 1, \\ & y(0) = 0], [x(0) = 2, y(0) = 0], [x(0) = 3, y(0) = 0], [x(0) = 4, y(0) = 0], [x(0) = 5, y(0) \\ & = 0] \end{aligned} \quad (32)$$

$$\begin{aligned} > \text{DEplot}([\text{sist}], [x(t), y(t)], t = -5 .. 5, x = -6 .. 6, y = -6 .. 6, [\text{in_cond}], \text{arrows} = \text{medium}, \\ & \text{linecolor} = \text{blue}, \text{stepsize} = 0.1) \end{aligned}$$



```
>
> eq1 := diff(x(t), t) = -3*x(t) + 4*y(t)
      eq1 :=  $\frac{d}{dt} x(t) = -3x(t) + 4y(t)$  (33)
```

```
> eq2 := diff(y(t), t) = -2*x(t) + 3*y(t)
      eq2 :=  $\frac{d}{dt} y(t) = -2x(t) + 3y(t)$  (34)
```

```
> sist := eq1, eq2
      sist :=  $\frac{d}{dt} x(t) = -3x(t) + 4y(t), \frac{d}{dt} y(t) = -2x(t) + 3y(t)$  (35)
```

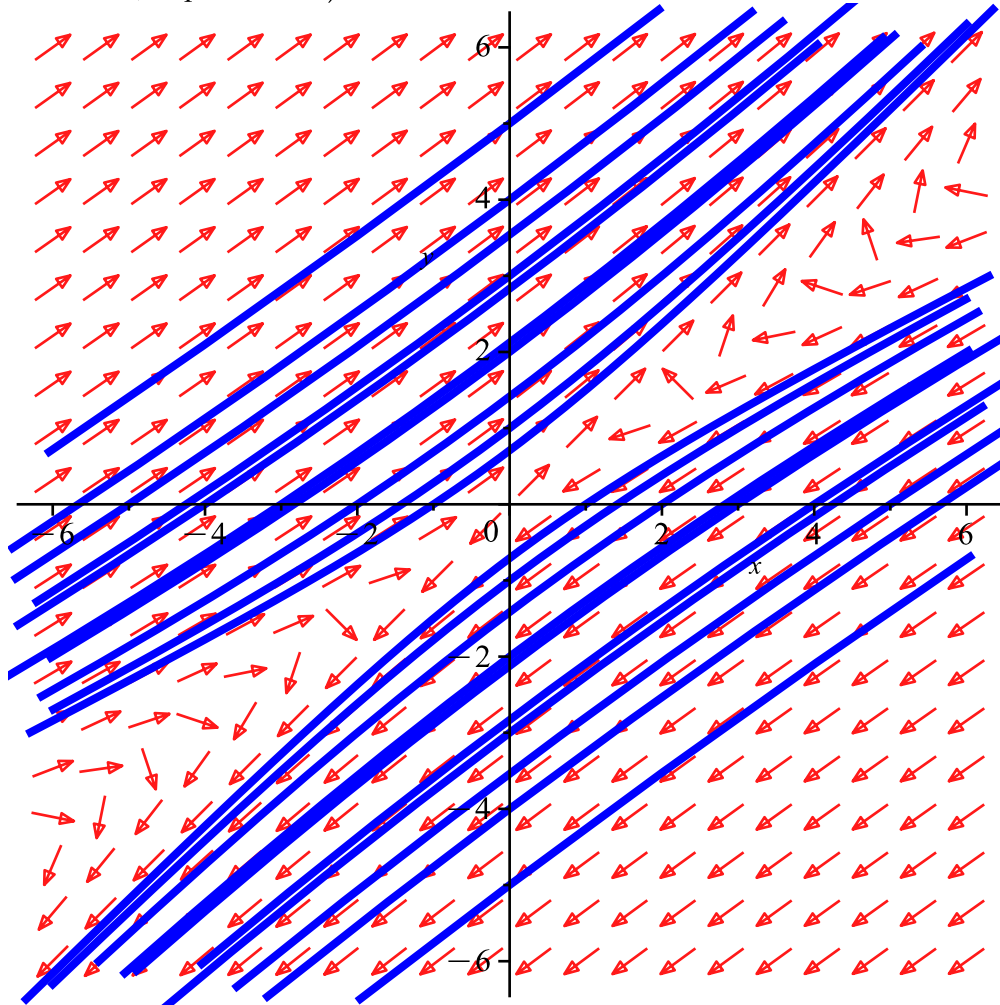
```
> A := matrix([[ -3, 4], [ -2, 3]])
      A :=  $\begin{bmatrix} -3 & 4 \\ -2 & 3 \end{bmatrix}$  (36)
```

```
> eigenvals(A)
      1, -1 (37)
```

```
> in_cond := [x(0)=0, y(0)=i]$i=1..5, [x(0)=-i, y(0)=0]$i=1..5, [x(0)=0, y(0)=-i]$i=1..5, [x(0)=i, y(0)=0]$i=1..5
in_cond := [x(0)=0, y(0)=1], [x(0)=0, y(0)=2], [x(0)=0, y(0)=3], [x(0)=0, y(0)=4], [x(0)=0, y(0)=5], [x(0)=-1, y(0)=0], [x(0)=-2, y(0)=0], [x(0)=-3, y(0)=0], [x(0)=-4, y(0)=0], [x(0)=-5, y(0)=0], [x(0)=0, y(0)=-1], [x(0)=0, y(0)=-2], [x(0)=0, y(0)=-3], [x(0)=0, y(0)=-4], [x(0)=0, y(0)=-5], [x(0)=1, y(0)=0], [x(0)=2, y(0)=0], [x(0)=3, y(0)=0], [x(0)=4, y(0)=0], [x(0)=5, y(0)=0] (38)
```


=4], [x(0)=0,y(0)=5], [x(0)=-1,y(0)=0], [x(0)=-2,y(0)=0], [x(0)=-3,y(0)=0]=0], [x(0)=-4,y(0)=0], [x(0)=-5,y(0)=0], [x(0)=0,y(0)=-1], [x(0)=0,y(0)=-2], [x(0)=0,y(0)=-3], [x(0)=0,y(0)=-4], [x(0)=0,y(0)=-5], [x(0)=1,y(0)=0], [x(0)=2,y(0)=0], [x(0)=3,y(0)=0], [x(0)=4,y(0)=0], [x(0)=5,y(0)=0]

> DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)



>

> eq1 := diff(x(t), t) = -x(t) - y(t)

$$eq1 := \frac{d}{dt} x(t) = -x(t) - y(t) \quad (39)$$

> eq2 := diff(y(t), t) = x(t) - 3*y(t)

$$eq2 := \frac{d}{dt} y(t) = x(t) - 3y(t) \quad (40)$$

> sist := eq1, eq2

$$sist := \frac{d}{dt} x(t) = -x(t) - y(t), \frac{d}{dt} y(t) = x(t) - 3y(t) \quad (41)$$

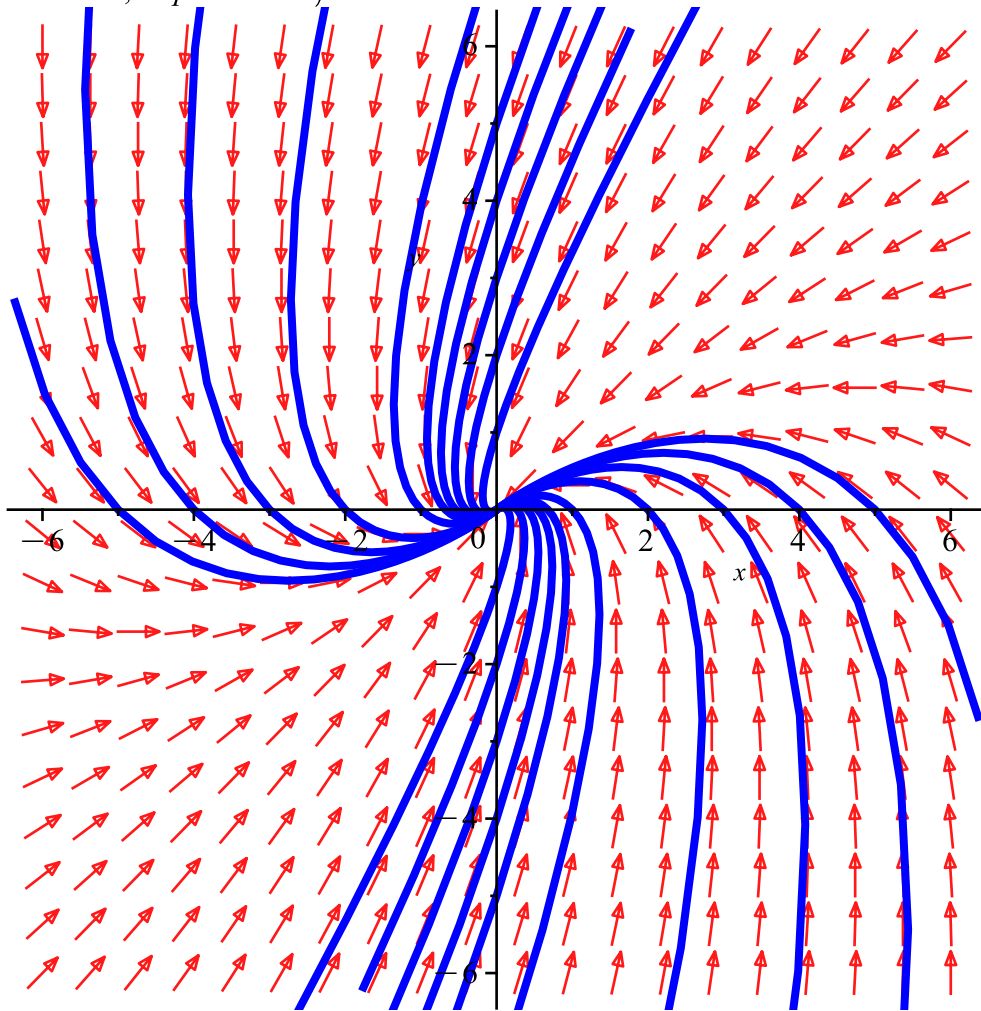
> A := matrix([[-1, -1], [1, -3]])

$$A := \begin{bmatrix} -1 & -1 \\ 1 & -3 \end{bmatrix} \quad (42)$$

> *eigenvals(A)*

$$-2, -2 \quad (43)$$

> *DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)*



>

> *eq1 := diff(x(t), t) = -2·x(t)*

$$eq1 := \frac{d}{dt} x(t) = -2 x(t) \quad (44)$$

> *eq2 := diff(y(t), t) = -4·x(t) - 2·y(t)*

$$eq2 := \frac{d}{dt} y(t) = -4 x(t) - 2 y(t) \quad (45)$$

> *sist := eq1, eq2*

$$sist := \frac{d}{dt} x(t) = -2 x(t), \frac{d}{dt} y(t) = -4 x(t) - 2 y(t) \quad (46)$$

> *A := matrix([[-2, 0], [-4, -2]])*

(47)

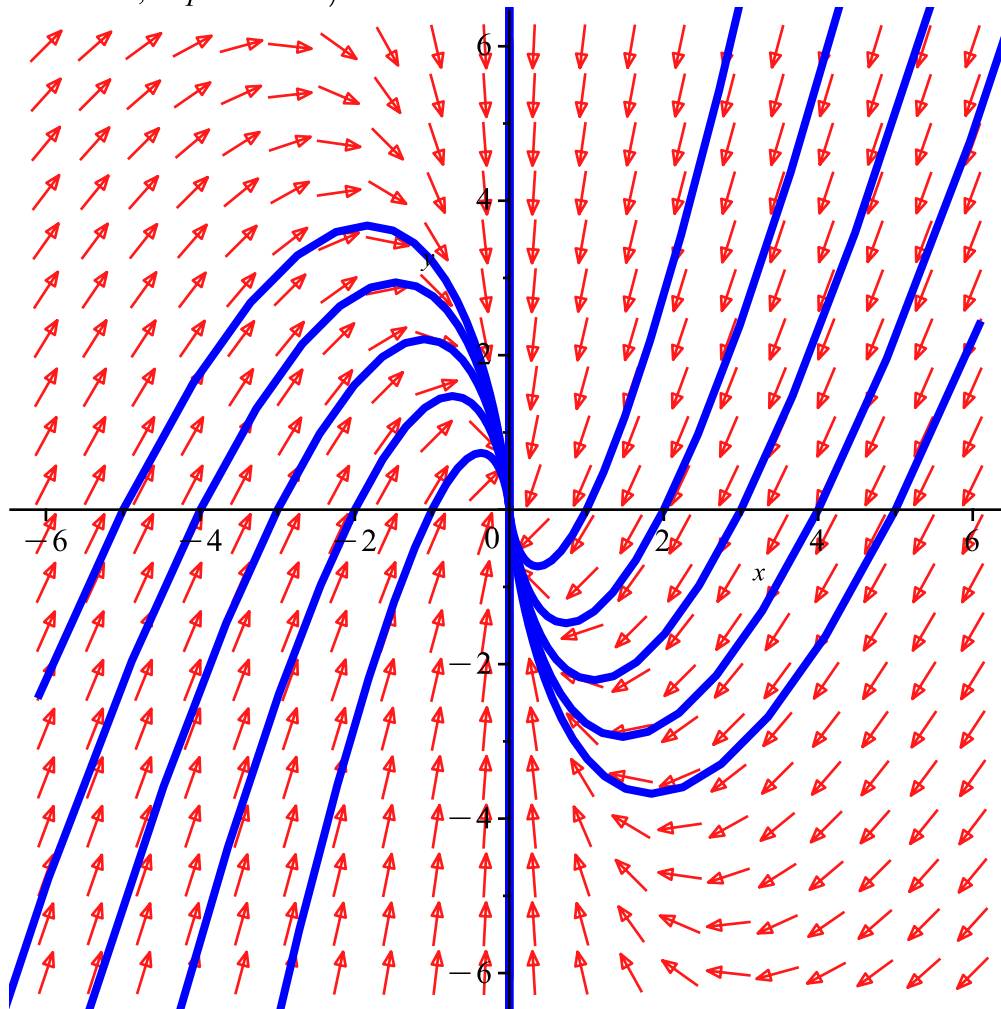
$$A := \begin{bmatrix} -2 & 0 \\ -4 & -2 \end{bmatrix} \quad (47)$$

> `eigenvals(A)`

$-2, -2$

(48)

> `DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)`



>

> `eq1 := diff(x(t), t) = x(t) + 4*y(t)`

$$eq1 := \frac{d}{dt} x(t) = x(t) + 4y(t) \quad (49)$$

> `eq2 := diff(y(t), t) = x(t) + y(t)`

$$eq2 := \frac{d}{dt} y(t) = x(t) + y(t) \quad (50)$$

> `sist := eq1, eq2`

$$sist := \frac{d}{dt} x(t) = x(t) + 4y(t), \frac{d}{dt} y(t) = x(t) + y(t) \quad (51)$$

> `A := matrix([[1, 4], [1, 1]])`

(52)

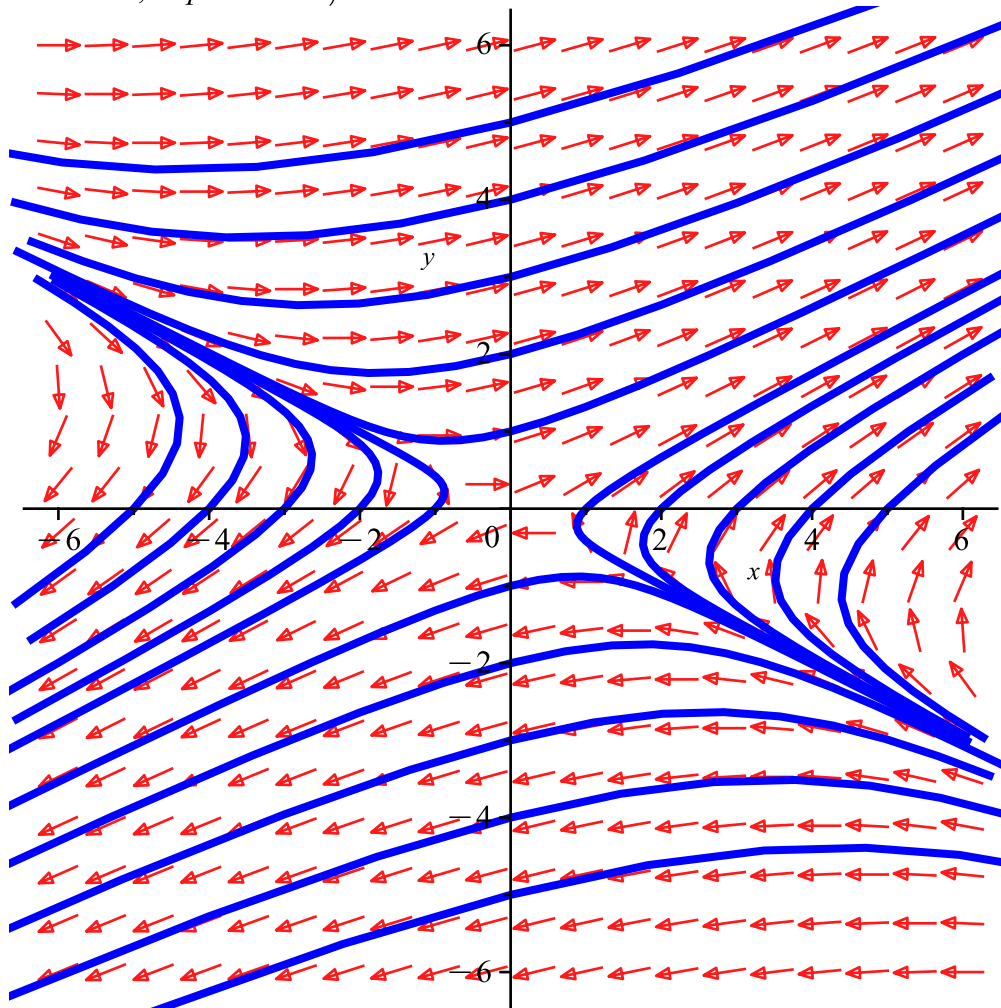
$$A := \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix} \quad (52)$$

> *eigenvals(A)*

3, -1

(53)

> *DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)*



>

> *eq1 := diff(x(t), t) = 2·x(t) - y(t)*

$$eq1 := \frac{d}{dt} x(t) = 2x(t) - y(t) \quad (54)$$

> *eq2 := diff(y(t), t) = x(t) + 2·y(t)*

$$eq2 := \frac{d}{dt} y(t) = x(t) + 2y(t) \quad (55)$$

> *sist := eq1, eq2*

$$sist := \frac{d}{dt} x(t) = 2x(t) - y(t), \frac{d}{dt} y(t) = x(t) + 2y(t) \quad (56)$$

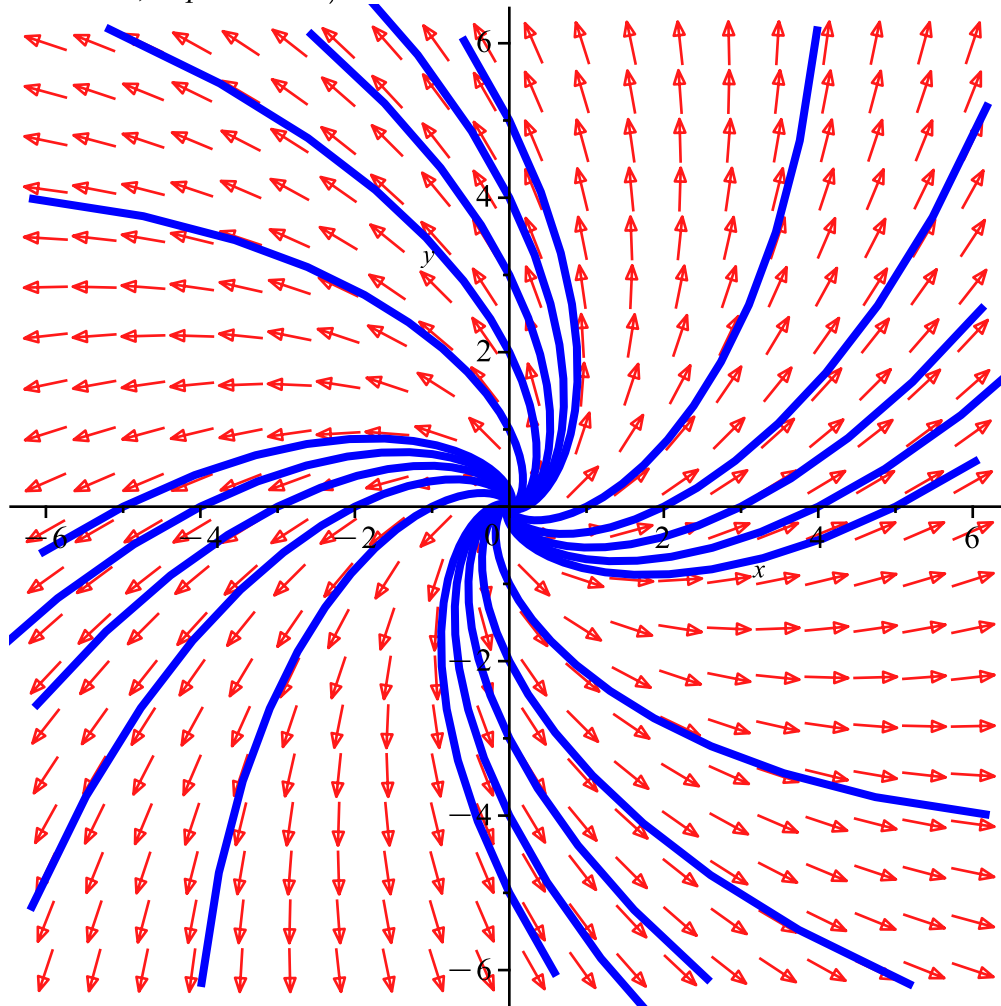
> *A := matrix([[2, -1], [1, 2]])*

$$A := \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \quad (57)$$

> *eigenvals(A)*

$$2 + i, 2 - i \quad (58)$$

> *DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)*



>

> *eq1 := diff(x(t), t) = -y(t)*

$$eq1 := \frac{d}{dt} x(t) = -y(t) \quad (59)$$

> *eq2 := diff(y(t), t) = x(t)*

$$eq2 := \frac{d}{dt} y(t) = x(t) \quad (60)$$

> *sist := eq1, eq2*

$$sist := \frac{d}{dt} x(t) = -y(t), \frac{d}{dt} y(t) = x(t) \quad (61)$$

> *A := matrix([[0, -1], [1, 0]])*

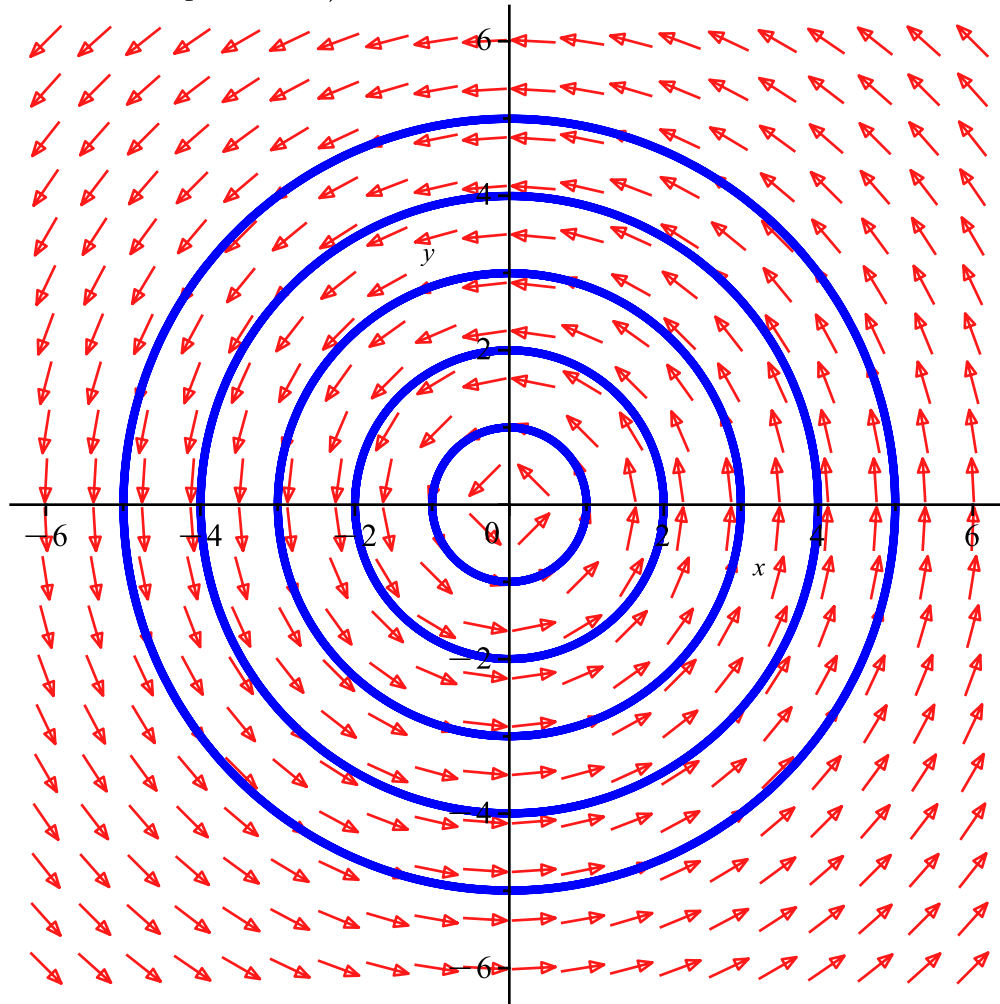
$$A := \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad (62)$$

> *eigenvals(A)*

I, -I

(63)

> *DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)*



>

> *eq1 := diff(x(t), t) = x(t) - 4·y(t)*

$$eq1 := \frac{d}{dt} x(t) = x(t) - 4 y(t) \quad (64)$$

> *eq2 := diff(y(t), t) = 5·x(t) - 3·y(t)*

$$eq2 := \frac{d}{dt} y(t) = 5 x(t) - 3 y(t) \quad (65)$$

> *sist := eq1, eq2*

$$sist := \frac{d}{dt} x(t) = x(t) - 4 y(t), \frac{d}{dt} y(t) = 5 x(t) - 3 y(t) \quad (66)$$

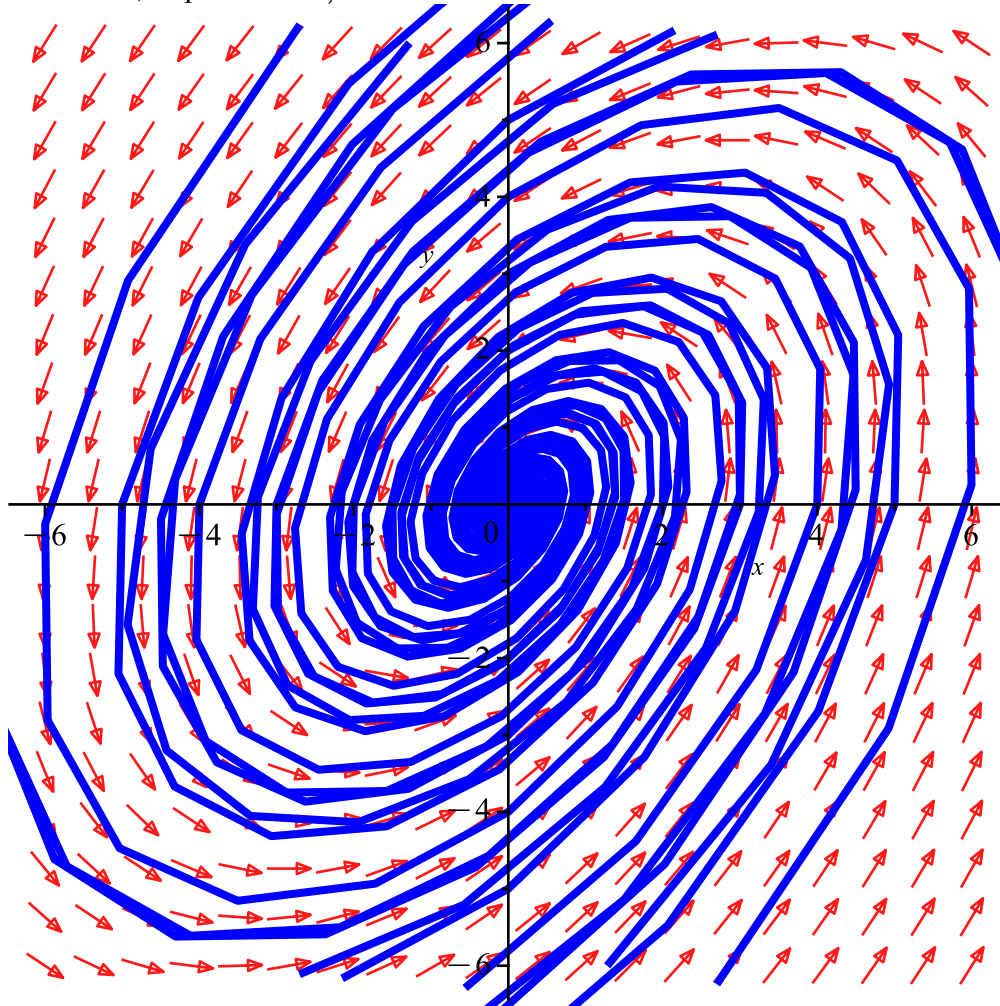
> *A := matrix([[1, -4], [5, -3]])*

$$A := \begin{bmatrix} 1 & -4 \\ 5 & -3 \end{bmatrix} \quad (67)$$

> *eigenvals(A)*

$$-1 + 4I, -1 - 4I \quad (68)$$

> *DEplot([sist], [x(t), y(t)], t=-5..5, x=-6..6, y=-6..6, [in_cond], arrows=medium, linecolor=blue, stepsize=0.1)*



>

> *f1 := (x,y)→y*

$$f1 := (x, y) \mapsto y \quad (69)$$

> *f2 := (x,y)→x·(1-x²) + y*

$$f2 := (x, y) \mapsto x \cdot (1 - x^2) + y \quad (70)$$

> *eq1 := diff(x(t), t) = f1(x(t), y(t))*

$$eq1 := \frac{d}{dt} x(t) = y(t) \quad (71)$$

> *eq2 := diff(y(t), t) = f2(x(t), y(t))*

$$eq2 := \frac{d}{dt} y(t) = x(t) (1 - x(t)^2) + y(t) \quad (72)$$

$$\begin{aligned} &> \text{sist2} := \text{eq1}, \text{eq2} \\ &\text{sist2} := \frac{d}{dt} x(t) = y(t), \frac{d}{dt} y(t) = x(t) (1 - x(t)^2) + y(t) \end{aligned} \quad (73)$$

$$\begin{aligned} &> \text{EquiP} := \text{solve}(\{f1(x, y) = 0, f2(x, y) = 0\}, \{x, y\}) \\ &\text{EquiP} := \{x = 0, y = 0\}, \{x = 1, y = 0\}, \{x = -1, y = 0\} \end{aligned} \quad (74)$$

$$\begin{aligned} &> \text{EquiP}[1, 1] \\ &x = 0 \end{aligned} \quad (75)$$

$$\begin{aligned} &> \text{EquiP}[1, 2] \\ &y = 0 \end{aligned} \quad (76)$$

$$\begin{aligned} &> J := \text{jacobian}([f1(x, y), f2(x, y)], [x, y]) \\ &J := \begin{bmatrix} 0 & 1 \\ -3x^2 + 1 & 1 \end{bmatrix} \end{aligned} \quad (77)$$

$$\begin{aligned} &> A1 := \text{subs}(\text{EquiP}[1, 1], \text{EquiP}[1, 2], y = 0, \text{eval}(J)) \\ &A1 := \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \end{aligned} \quad (78)$$

$$\begin{aligned} &> \text{eigenvals}(A1) \\ &\frac{1}{2} + \frac{\sqrt{5}}{2}, \frac{1}{2} - \frac{\sqrt{5}}{2} \end{aligned} \quad (79)$$

$$\begin{aligned} &> A2 := \text{subs}(\text{EquiP}[2, 1], \text{EquiP}[2, 2], \text{eval}(J)) \\ &A2 := \begin{bmatrix} 0 & 1 \\ -2 & 1 \end{bmatrix} \end{aligned} \quad (80)$$

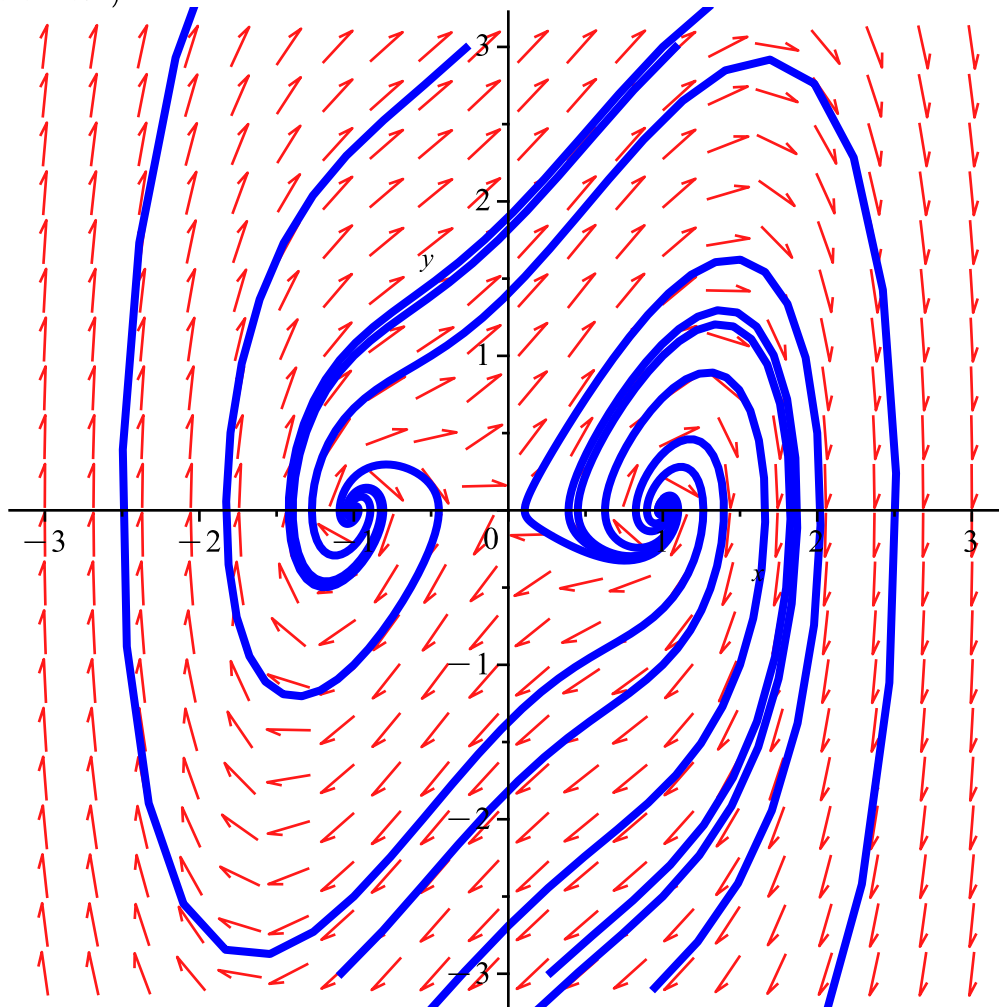
$$\begin{aligned} &> \text{eigenvals}(A2) \\ &\frac{1}{2} + \frac{I\sqrt{7}}{2}, \frac{1}{2} - \frac{I\sqrt{7}}{2} \end{aligned} \quad (81)$$

$$\begin{aligned} &> A3 := \text{subs}(\text{EquiP}[3, 1], \text{EquiP}[3, 2], \text{eval}(J)) \\ &A3 := \begin{bmatrix} 0 & 1 \\ -2 & 1 \end{bmatrix} \end{aligned} \quad (82)$$

$$\begin{aligned} &> \text{eigenvals}(A3) \\ &\frac{1}{2} + \frac{I\sqrt{7}}{2}, \frac{1}{2} - \frac{I\sqrt{7}}{2} \end{aligned} \quad (83)$$

$$\begin{aligned} &> \text{condin} := [x(0) = -1, y(0) = 1], [x(0) = -0.5, y(0) = 1], [x(0) = 1, y(0) = 1], [x(0) = 1, y(0) = 3], \\ &\quad [x(0) = 2, y(0) = 0.5], [x(0) = -1, y(0) = -1], [x(0) = -0.5, y(0) = 1], [x(0) = -1, y(0) = -2.5], \\ &\quad [x(0) = 1, y(0) = -1], [x(0) = 1.5, y(0) = -1], [x(0) = 1, y(0) = -2.5]; \\ &\text{condin} := [x(0) = -1, y(0) = 1], [x(0) = -0.5, y(0) = 1], [x(0) = 1, y(0) = 1], [x(0) = 1, y(0) = 3], \\ &\quad [x(0) = 2, y(0) = 0.5], [x(0) = -1, y(0) = -1], [x(0) = -0.5, y(0) = 1], [x(0) = -1, y(0) = -2.5], \\ &\quad [x(0) = 1, y(0) = -1], [x(0) = 1.5, y(0) = -1], [x(0) = 1, y(0) = -2.5] \end{aligned} \quad (84)$$


```
> DEplot([sist2], [x(t), y(t)], t=-10..10, x=-3..3, y=-3..3, [condin], linecolor=blue,
         stepsize=0.1)
```



> $fl := (x, y) \rightarrow -2 \cdot x + y + 2$

$$fl := (x, y) \mapsto -2 \cdot x + y + 2 \quad (85)$$

> $f2 := (x, y) \rightarrow x \cdot y$

$$f2 := (x, y) \mapsto y \cdot x \quad (86)$$

```
> eq1 := diff(x(t), t) = f1(x(t), y(t))
```

$$eq1 := \frac{d}{dt} x(t) = -2x(t) + y(t) + 2 \quad (87)$$

```
> eq2 := diff(y(t), t) = f2(x(t), y(t))
```

$$eq2 := \frac{d}{dt} y(t) = y(t) x(t) \quad (88)$$

$$\triangleright \textit{sist2} := \textit{eq1}, \textit{eq2}$$

$$sist2 := \frac{d}{dt} x(t) = -2 x(t) + y(t) + 2, \frac{d}{dt} y(t) = y(t) x(t) \quad (89)$$

> $EquiP := solve(\{f1(x, y) = 0, f2(x, y) = 0\}, \{x, y\})$

$$Equip := \{x=0, y=0\} \quad (90)$$

$$\begin{aligned} &> J := \text{jacobian}([f1(x,y), f2(x,y)], [x,y]) \\ &J := \begin{bmatrix} 0 & 2y \\ 1 & 0 \end{bmatrix} \end{aligned} \quad (91)$$

$$\begin{aligned} &> A1 := \text{subs}(\text{Equip}[1], \text{Equip}[2], \text{eval}(J)) \\ &A1 := \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \end{aligned} \quad (92)$$

$$\begin{aligned} &> f1 := (x,y) \rightarrow y^2 \\ &f1 := (x,y) \mapsto y^2 \end{aligned} \quad (93)$$

$$\begin{aligned} &> f2 := (x,y) \rightarrow x \\ &f2 := (x,y) \mapsto x \end{aligned} \quad (94)$$

$$\begin{aligned} &> eq1 := \text{diff}(x(t), t) = f1(x(t), y(t)) \\ &eq1 := \frac{d}{dt} x(t) = y(t)^2 \end{aligned} \quad (95)$$

$$\begin{aligned} &> eq2 := \text{diff}(y(t), t) = f2(x(t), y(t)) \\ &eq2 := \frac{d}{dt} y(t) = x(t) \end{aligned} \quad (96)$$

$$\begin{aligned} &> sist2 := eq1, eq2 \\ &sist2 := \frac{d}{dt} x(t) = y(t)^2, \frac{d}{dt} y(t) = x(t) \end{aligned} \quad (97)$$

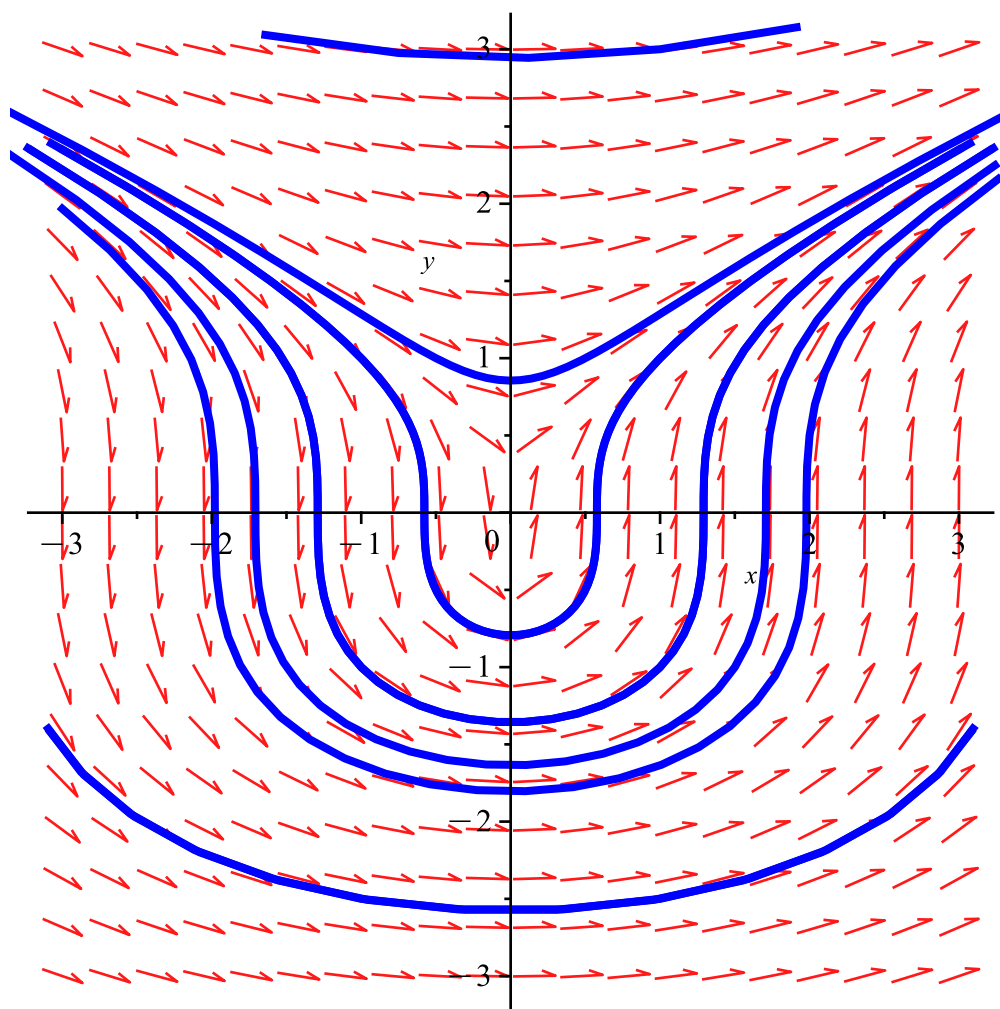
$$\begin{aligned} &> Equip := \text{solve}(\{f1(x,y)=0, f2(x,y)=0\}, \{x,y\}) \\ &Equip := \{x=0, y=0\} \end{aligned} \quad (98)$$

$$\begin{aligned} &> J := \text{jacobian}([f1(x,y), f2(x,y)], [x,y]) \\ &J := \begin{bmatrix} 0 & 2y \\ 1 & 0 \end{bmatrix} \end{aligned} \quad (99)$$

$$\begin{aligned} &> A1 := \text{subs}(\text{Equip}[1], \text{Equip}[2], \text{eval}(J)) \\ &A1 := \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \end{aligned} \quad (100)$$

$$\begin{aligned} &> \text{eigenvals}(A1) \\ &0, 0 \end{aligned} \quad (101)$$

$$\begin{aligned} &> \text{DEplot}([sist2], [x(t), y(t)], t=-10..10, x=-3..3, y=-3..3, [\text{condin}], \text{linecolor}=\text{blue}, \\ &\quad \text{stepsize}=0.1) \end{aligned}$$



```
>
> f1 := (x,y)→-2·x + y + 2
      f1 := (x,y) ↦ -2·x + y + 2 (102)
```

```
> f2 := (x,y)→x·y
      f2 := (x,y) ↦ y·x (103)
```

```
> eq1 := diff(x(t), t) = f1(x(t), y(t))
      eq1 := d/dt x(t) = -2 x(t) + y(t) + 2 (104)
```

```
> eq2 := diff(y(t), t) = f2(x(t), y(t))
      eq2 := d/dt y(t) = y(t) x(t) (105)
```

```
> sist2 := eq1, eq2
      sist2 := d/dt x(t) = -2 x(t) + y(t) + 2, d/dt y(t) = y(t) x(t) (106)
```

```
> Equip := solve( { f1(x,y) = 0, f2(x,y) = 0 }, {x,y} )
      Equip := {x = 1, y = 0}, {x = 0, y = -2} (107)
```

```
> J := jacobian( [ f1(x,y), f2(x,y) ], [x,y] )
```

$$J := \begin{bmatrix} -2 & 1 \\ y & x \end{bmatrix} \quad (108)$$

> $A1 := \text{subs}(\text{Equip}[1, 1], \text{Equip}[1, 2], \text{eval}(J))$

$$A1 := \begin{bmatrix} -2 & 1 \\ 0 & 1 \end{bmatrix} \quad (109)$$

> $\text{eigenvals}(A1)$

$$-2, 1 \quad (110)$$

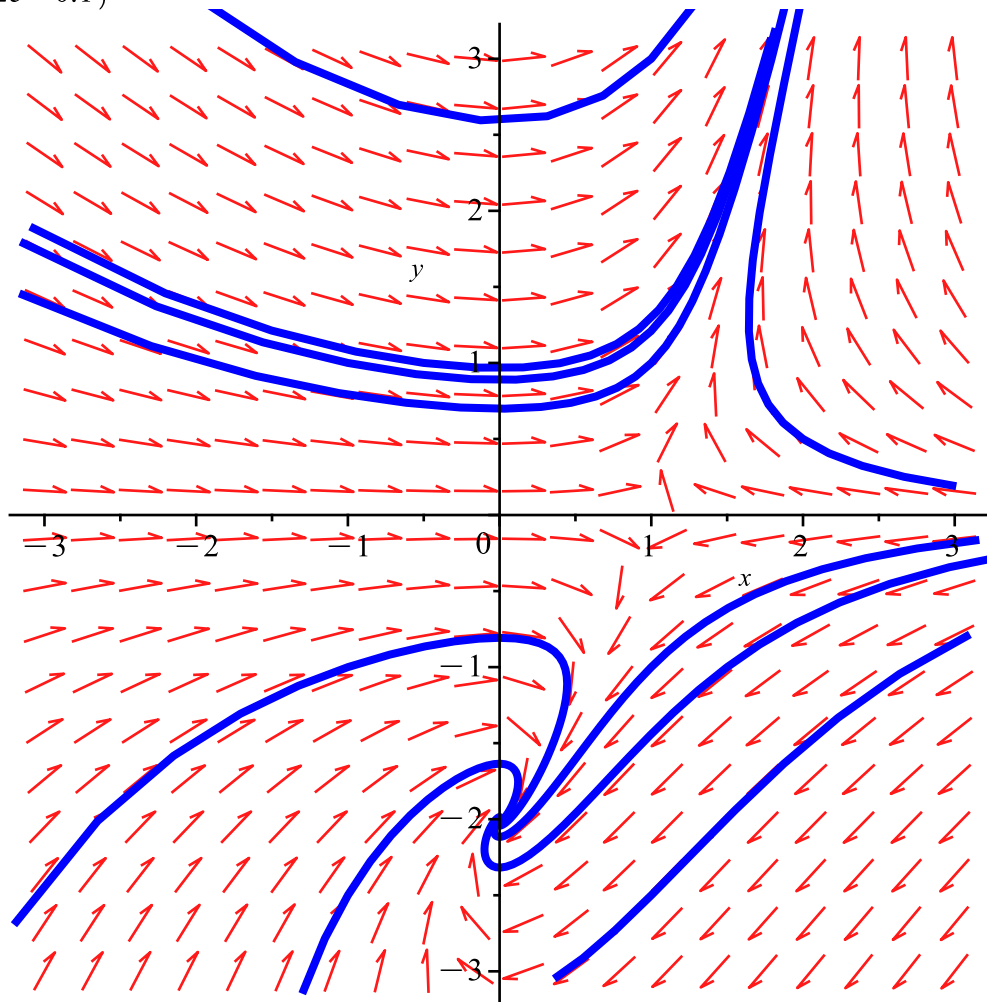
> $A2 := \text{subs}(\text{Equip}[2, 1], \text{Equip}[2, 2], \text{eval}(J))$

$$A2 := \begin{bmatrix} -2 & 1 \\ -2 & 0 \end{bmatrix} \quad (111)$$

> $\text{eigenvals}(A2)$

$$-1 + I, -1 - I \quad (112)$$

> $\text{DEplot}([sist2], [x(t), y(t)], t = -10..10, x = -3..3, y = -3..3, [condin], \text{linecolor} = \text{blue}, \text{stepsize} = 0.1)$



>

> $f1 := (x, y) \rightarrow x^2 - y^2$

(113)

$$f1 := (x, y) \mapsto x^2 - y^2 \quad (113)$$

$$> f2 := (x, y) \mapsto x \cdot y - 1$$

$$f2 := (x, y) \mapsto y \cdot x - 1 \quad (114)$$

$$> eq1 := \text{diff}(x(t), t) = f1(x(t), y(t))$$

$$eq1 := \frac{d}{dt} x(t) = x(t)^2 - y(t)^2 \quad (115)$$

$$> eq2 := \text{diff}(y(t), t) = f2(x(t), y(t))$$

$$eq2 := \frac{d}{dt} y(t) = y(t) x(t) - 1 \quad (116)$$

$$> sist2 := eq1, eq2$$

$$sist2 := \frac{d}{dt} x(t) = x(t)^2 - y(t)^2, \frac{d}{dt} y(t) = y(t) x(t) - 1 \quad (117)$$

$$> \text{EquiP} := \text{solve}(\{f1(x, y) = 0, f2(x, y) = 0\}, \{x, y\})$$

$$\text{EquiP} := \{x = -\text{RootOf}(_Z^2 + 1), y = \text{RootOf}(_Z^2 + 1)\}, \{x = 1, y = 1\}, \{x = -1, y = -1\} \quad (118)$$

$$> J := \text{jacobian}([f1(x, y), f2(x, y)], [x, y])$$

$$J := \begin{bmatrix} 2x & -2y \\ y & x \end{bmatrix} \quad (119)$$

$$> A1 := \text{subs}(\text{EquiP}[1, 1], \text{EquiP}[1, 2], \text{eval}(J))$$

$$A1 := \begin{bmatrix} -2 \text{RootOf}(_Z^2 + 1) & -2 \text{RootOf}(_Z^2 + 1) \\ \text{RootOf}(_Z^2 + 1) & -\text{RootOf}(_Z^2 + 1) \end{bmatrix} \quad (120)$$

$$> \text{eigenvals}(A1)$$

$$\text{RootOf}(3 \text{RootOf}(_Z^2 + 1) _Z + _Z^2 - 4) \quad (121)$$

$$> A2 := \text{subs}(\text{EquiP}[2, 1], \text{EquiP}[2, 2], \text{eval}(J))$$

$$A2 := \begin{bmatrix} 2 & -2 \\ 1 & 1 \end{bmatrix} \quad (122)$$

$$> \text{eigenvals}(A2)$$

$$\frac{3}{2} + \frac{\text{I}\sqrt{7}}{2}, \frac{3}{2} - \frac{\text{I}\sqrt{7}}{2} \quad (123)$$

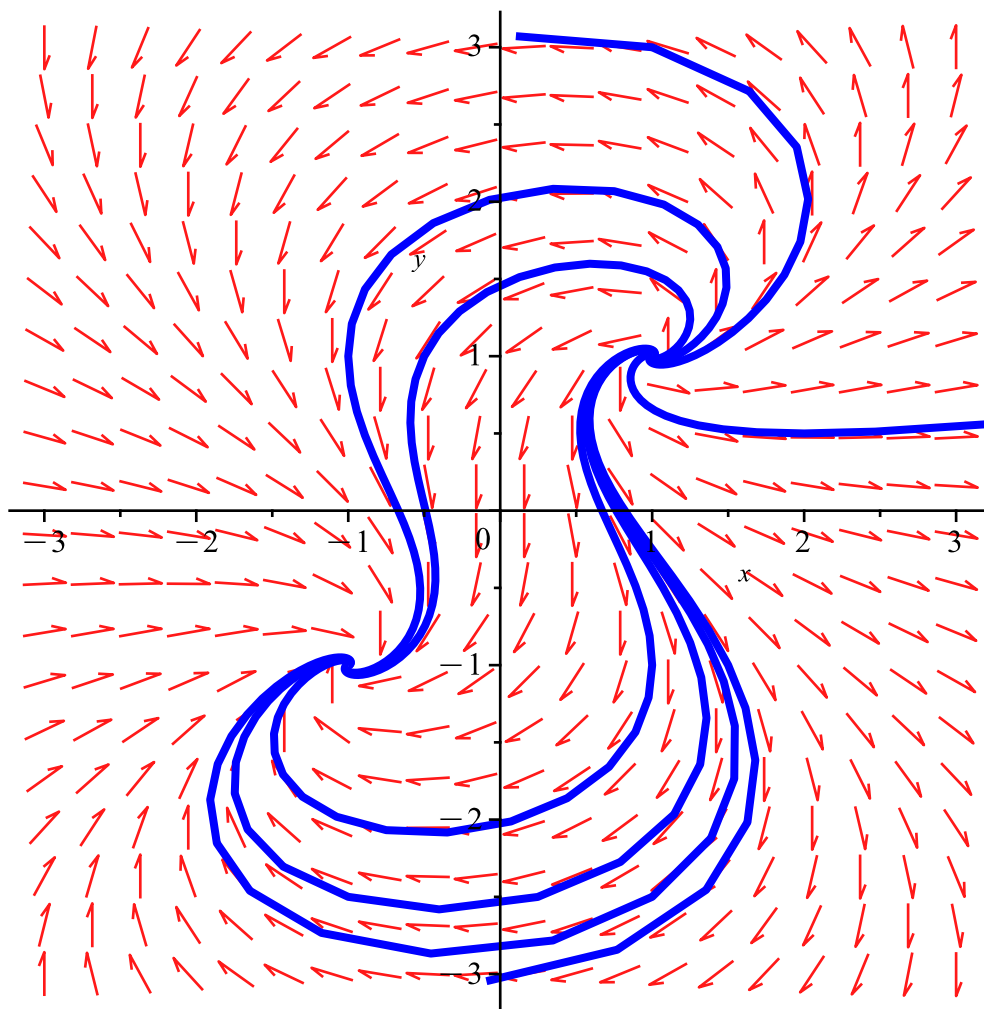
$$> A3 := \text{subs}(\text{EquiP}[3, 1], \text{EquiP}[3, 2], \text{eval}(J))$$

$$A3 := \begin{bmatrix} -2 & 2 \\ -1 & -1 \end{bmatrix} \quad (124)$$

$$> \text{eigenvals}(A3)$$

$$-\frac{3}{2} + \frac{\text{I}\sqrt{7}}{2}, -\frac{3}{2} - \frac{\text{I}\sqrt{7}}{2} \quad (125)$$

$$> \text{DEplot}([sist2], [x(t), y(t)], t = -10..10, x = -3..3, y = -3..3, [condin], \text{linecolor} = \text{blue}, \text{stepsize} = 0.1)$$



>

> $f1 := (x, y) \rightarrow 2 \cdot x - 1.2 \cdot x \cdot y$

$$f1 := (x, y) \mapsto 2 \cdot x + (-1) \cdot 1.2 \cdot x \cdot y$$

(126)

> $f2 := (x, y) \rightarrow -y + 0.9 \cdot x \cdot y$

$$f2 := (x, y) \mapsto -y + 0.9 \cdot x \cdot y$$

(127)

> $eq1 := \text{diff}(x(t), t) = f1(x(t), y(t))$

$$eq1 := \frac{d}{dt} x(t) = 2 x(t) - 1.2 y(t) x(t)$$

(128)

> $eq2 := \text{diff}(y(t), t) = f2(x(t), y(t))$

$$eq2 := \frac{d}{dt} y(t) = -y(t) + 0.9 y(t) x(t)$$

(129)

> $sist := eq1, eq2$

$$sist := \frac{d}{dt} x(t) = 2 x(t) - 1.2 y(t) x(t), \frac{d}{dt} y(t) = -y(t) + 0.9 y(t) x(t)$$

(130)

> $in_cond := x(0) = 0.5, y(0) = 2$

$$in_cond := x(0) = 0.5, y(0) = 2$$

(131)

> $sol := \text{dsolve}(\{sist, in_cond\}, \{x(t), y(t)\})$

$$sol := x(t) = RootOf \left(-2 \right) \quad (132)$$

\int_{-a}^{-Z}

$$\left(\begin{array}{c} \text{LambertW}\left(-Z_{\sim}, \frac{\text{e}^{-1} \text{RootOf}\left(-Z \left(5 \text{LambertW}\left(-Z_{\sim}, \frac{\sqrt{2} Z (-1)^{-Z2\sim}}{2 \text{e}^{\frac{31}{40}}} \right) + 6 \right) \right) \text{e}^{\frac{9 \sqrt{f}}{20}}}{2 \sqrt{-f} (-1)^{-Z2\sim}} \right) \\ \text{e} \end{array} \right) (-1)^{-Z2\sim}$$

$$\left(e^{-1} \operatorname{RootOf} \left(-Z \left(5 \operatorname{LambertW} \left(-Z^4, \frac{\sqrt{2} Z (-1)^{-Z^2}}{2 e^{\frac{31}{40}}} \right) + 6 \right) \right) e^{\frac{9 \sqrt{f}}{20}} \sqrt{f} \right)$$

$$+ 2 \sqrt{f} e^{\text{LambertW}\left(-Z^4, \frac{e^{-1} \text{RootOf}\left(-Z \left(5 \text{LambertW}\left(-Z^4, \frac{\sqrt{2} Z (-1) Z^2}{2 e^{\frac{31}{40}}}\right) + 6\right)\right) e^{\frac{9 f}{20}}}{2 \sqrt{-f} (-1) Z^2}\right)} (-1)^{-Z^2}$$

$$\left. d_f \right|_{-a}^{\frac{1}{2}} + \left. 1 \right|_{-a}^{\frac{1}{2}} \left/ \left(f \left(\text{LambertW} \left(-Z_4 \right) \right) \right) \right.$$

$$\left. \frac{\operatorname{RootOf}\left(-Z\left(5\operatorname{LambertW}\left(-Z4^{\sim},\frac{\sqrt{2}\text{ }Z(-1)^{-Z2^{\sim}}}{2\text{ }e^{\frac{31}{40}}}\right)+6\right)\right)e^{\frac{9\text{ }f}{20}}}{2\text{ }e^{\sqrt{\text{ }f}}(-1)^{-Z2^{\sim}}}\right)+1\right)\right)\text{d}\text{ }f+2\text{ }t\right),$$

$$y(t) = - \left(5 \, \mathrm{e}^{-1} \, \mathit{RootOf} \left(-Z \left(5 \, \mathit{LambertW} \left(-Z 4^{\sim}, \frac{\sqrt{2} \, Z \, (-1)^{-Z 2^{\sim}}}{2 \, \mathrm{e}^{\frac{31}{40}}} \right) \right) \right)$$

$$+ 6 \Big) \Big)$$

$$e^{\frac{1}{20} \left(9 \operatorname{RootOf} - 2 \right)}$$

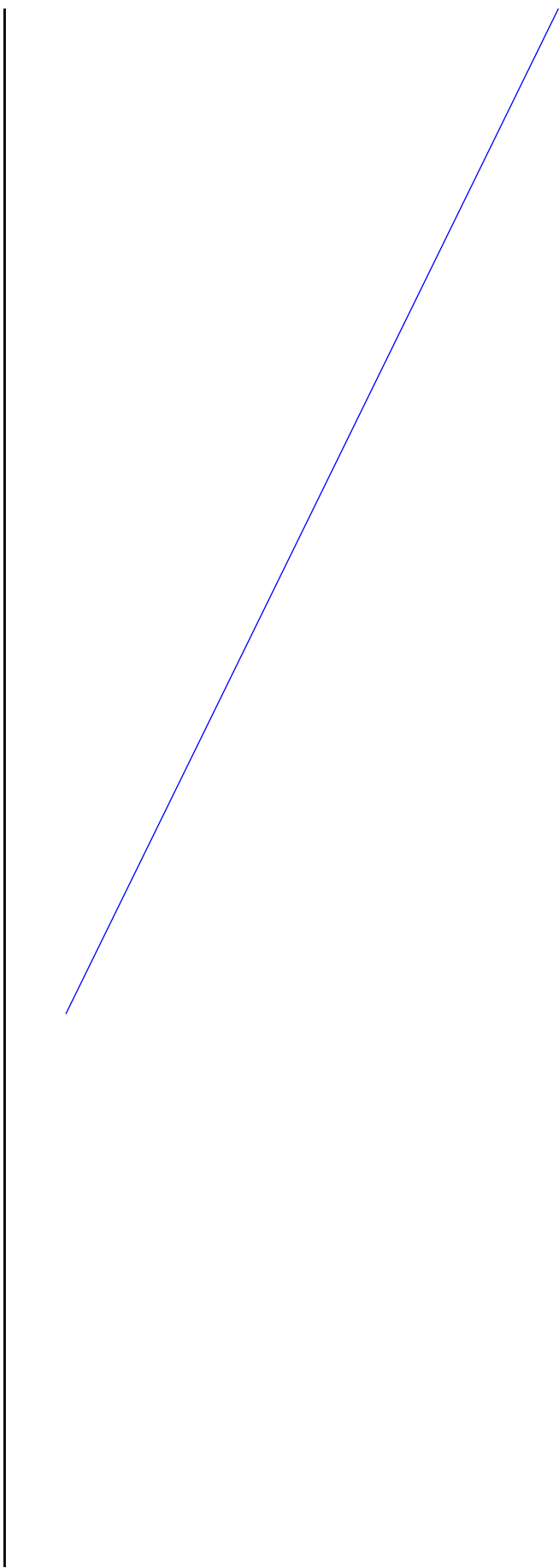
$$\frac{Z}{e} \left(\text{LambertW} \left(-Z4\sim, \frac{e^{-1} \text{RootOf} \left(-Z \left(5 \text{LambertW} \left(-Z4\sim, \frac{\sqrt{2} - Z(-1) - Z2\sim}{2 e^{\frac{31}{40}}} \right) + 6 \right) \right) e^{\frac{9-f}{20}}}{2 \sqrt{-f} (-1) - Z2\sim} \right) (-1) - Z2\sim \right)$$

$$\frac{Z}{e} \left(\text{LambertW} \left(-Z4\sim, \frac{e^{-1} \text{RootOf} \left(-Z \left(5 \text{LambertW} \left(-Z4\sim, \frac{\sqrt{2} - Z(-1) - Z2\sim}{2 e^{\frac{31}{40}}} \right) + 6 \right) \right) e^{\frac{9-f}{20}}}{2 \sqrt{-f} (-1) - Z2\sim} \right) (-1) - Z2\sim \right)$$

$$\left(e^{-1} \operatorname{RootOf}\left(-Z \left(5 \operatorname{LambertW}\left(-Z \sqrt[4]{2}, \frac{\sqrt{2} Z (-1) - Z^2}{2 e^{40}} \right) + 6 \right) \right) e^{\frac{9 \sqrt{f}}{20}} \sqrt{f} \right)$$

$$+ 2_f e^{\text{LambertW}\left(-Z\sim, \frac{e^{-1} \text{RootOf}\left(-Z\left(5 \text{LambertW}\left(-Z4\sim, \frac{\sqrt{2}_Z(-1)_Z2\sim}{2 e^{\frac{31}{40}}}\right) + 6\right)\right) e^{\frac{9_f}{20}}}{2 \sqrt{-f} (-1)_Z2\sim}\right) (-1)_Z2\sim} d_f \right)$$

$$\begin{aligned}
& + \int_{-a}^{\frac{1}{2}} \left(\frac{1}{\sqrt{f} \left(\text{LambertW} \left(-Z\sqrt{-f}, \frac{\text{RootOf} \left(-Z \left(5 \text{LambertW} \left(-Z\sqrt{-f}, \frac{\sqrt{2} Z (-1) - Z^2}{2 e^{\frac{31}{40}}} \right) + 6 \right) e^{\frac{9\sqrt{f}}{20}} \right) + 1 \right)} \right)} \right) d\sqrt{f} + 2t \Bigg) \Bigg) \Bigg)
\end{aligned}$$



$$\left(6 \sqrt[6]{\sqrt[6]{\sqrt[6]{\sqrt[6]{\sqrt[6]{\sqrt[6]{-2}}}}}} \right)$$

\int_{-a}^{-Z}

$$\left(\frac{\text{LambertW}\left(-Z\sim,\frac{\text{e}^{-1}\text{RootOf}\left(-Z\left(5\text{LambertW}\left(-Z4\sim,\frac{\sqrt{2}-Z(-1)-Z2\sim}{2\text{e}^{\frac{31}{40}}}\right)+6\right)\right)\text{e}^{\frac{9-f}{20}}}{2\sqrt{-f}(-1)-Z2\sim}\right)}{\text{e}}\right)(-1)^{-Z2\sim}$$

$$\sqrt{e^{-1} \operatorname{RootOf}\left(-Z \left(5 \operatorname{LambertW}\left(-Z^{4\sim}, \frac{\sqrt{2} _Z (-1)^{-Z2\sim}}{2 \, e^{\frac{31}{40}}}\right) + 6\right)\right) e^{\frac{9_f}{20}} \sqrt{_f}}$$

$$\begin{aligned}
& + 2 \sqrt{f} e^{\text{LambertW}\left(-Z4\sim, \frac{e^{-1} \text{RootOf}\left(-Z\left(5 \text{LambertW}\left(-Z4\sim, \frac{\sqrt{2} \sqrt{Z} (-1)^{-Z2\sim}}{2 e^{\frac{31}{40}}}\right) + 6\right)\right) e^{\frac{9 \sqrt{f}}{20}}}{2 \sqrt{f} (-1)^{-Z2\sim}}\right)} (-1)^{-Z2\sim}
\end{aligned}$$

$$\left. d_f \right) + \int_{-a}^{\frac{1}{2}} 1 \, / \, \left(f \left(\text{LambertW} \left(-Z4 \sim, \right. \right. \right.$$

$$\left(\frac{\text{RootOf} \left(-Z \left(5 \text{LambertW} \left(-Z4\sim, \frac{\sqrt{2} -Z (-1)^{-Z2\sim}}{2 e^{\frac{31}{40}}} \right) + 6 \right) \right) e^{\frac{9\text{f}}{20}}}{2 e^{\sqrt{\text{f}} (-1)^{-Z2\sim}}} + 1 \right) \text{d_f} + 2 t \right)$$

$$\left(\text{LambertW}\left(-Z4\sim,\right. \right. \\ \left. \left. \text{e}^{-1} \text{RootOf}\left(-Z\left(5 \text{LambertW}\left(-Z4\sim,\frac{\sqrt{2}-Z\left(-1\right)-Z2\sim}{\frac{31}{2 \text{e}^{40}}}\right)\right)\right)\right) \right)$$

e

$$+ 6 \Big) \Big)$$

$$\frac{1}{e^{20}} \left(\begin{array}{c} 9 \operatorname{RootOf} - 2 \end{array} \right)$$

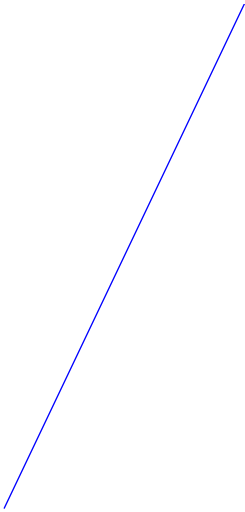
$$\left. \begin{array}{l} -Z \\ e \end{array} \right\} \left(\text{LambertW}_{-Z4\sim}, \frac{e^{-1} \text{RootOf}_{-Z} \left(5 \text{LambertW}_{-Z4\sim}, \frac{\sqrt{2} \text{ } (-1)_{-Z2\sim}}{2 e^{\frac{31}{40}}} \right) + 6 \right) e^{\frac{9 \text{ } -f}{20}}}{2 \sqrt{-f} \text{ } (-1)_{-Z2\sim}} \right)_{(-1)_{-Z2\sim}} \Big/$$

$-a$

$$\left(\mathrm{e}^{-1} \operatorname{RootOf}\left({}_Z\left(5 \operatorname{LambertW}\left({}_{-Z4\sim}, \frac{\sqrt{2} {}_Z(-1) {}_{Z2\sim}}{2 \mathrm{e}^{\frac{31}{40}}}}\right) + 6 \right) \right) \mathrm{e}^{\frac{9 {}_f}{20}} \sqrt{{}_f} \right)$$

$$+ 2_{\underline{f}} \mathbf{e}^{\text{LambertW}\left(-Z_{\sim}, \frac{\mathbf{e}^{-1} \text{RootOf}\left(-Z \left(5 \text{LambertW}\left(-Z_{\sim}, \frac{\sqrt{2} (-1)_{\sim} Z_{\sim}}{2 \mathbf{e}^{\frac{31}{40}}}\right) + 6\right)\right) \mathbf{e}^{\frac{9_{\sim} f}{20}}}{2 \sqrt{\underline{f}} (-1)_{\sim} Z_{\sim}}\right) (-1)_{\sim} Z_{\sim} \, \mathrm{d}_{\underline{f}}}\right)$$

$$+ \left[\begin{array}{c} \frac{1}{2} \\ -a \end{array} \right] \left(\frac{1}{\sqrt{f} \left(\text{LambertW} \left(-Z \sqrt[4]{\frac{\text{RootOf} \left(-Z \left(5 \text{LambertW} \left(-Z \sqrt[4]{\frac{\sqrt{2} - Z(-1) - Z^2}{2 e^{\frac{31}{40}}}} \right) + 6 \right)} e^{\frac{9 - f}{20}} \right) + 1 \right)} \right)} \right) \sqrt{f} + 2 t \right)$$



$$\left(2\sqrt[4]{\sqrt[4]{2}\sqrt[4]{\sqrt[4]{2}}}\right)^2$$

$$\frac{1}{2\sqrt{f}}\left(\frac{e^{-1}\sqrt[4]{2}\sqrt[4]{\sqrt[4]{2}}\sqrt[4]{\sqrt[4]{2}}}{2e^{\frac{9f}{20}}}\right)^2$$

$$\left(\mathrm{e}^{-1} \operatorname{RootOf} \left(_Z \left(5 \operatorname{LambertW} \left(_Z4_, \frac{\sqrt{2} _Z (-1) _Z2\sim}{2 \mathrm{e}^{\frac{31}{40}}} \right) + 6 \right) \right) \mathrm{e}^{\frac{9 _f}{20}} \sqrt{_f} \right.$$

$$\left. + 2 _f \mathrm{e}^{\operatorname{LambertW} \left(_Z4_, \frac{\mathrm{e}^{-1} \operatorname{RootOf} \left(_Z \left(5 \operatorname{LambertW} \left(_Z4_, \frac{\sqrt{2} _Z (-1) _Z2\sim}{2 \mathrm{e}^{\frac{31}{40}}} \right) + 6 \right) \right) \mathrm{e}^{\frac{9 _f}{20}} \right)}{2 \sqrt{_f} (-1) _Z2\sim}} \right) (-1) _Z2\sim} \mathrm{d} _f \right)$$

$$+ \left[\frac{1}{2} \right]_{-a} \left(\frac{1}{\left(\text{LambertW} \left(-Z \sim, \frac{\text{RootOf} \left(-Z \left(5 \text{LambertW} \left(-Z \sim, \frac{\sqrt{2} - Z(-1) - Z2 \sim}{2 e^{\frac{31}{40}}} \right) + 6 \right) e^{\frac{9 - f}{20}}} \right) + 1 \right)} \right) d f + 2 t \right)$$

$$\left[\frac{1}{2} \right]_{-a} \left((-1)^{-Z2 \sim} \right) \left((-1)^{-Z2 \sim} \right)$$

```

>
> Equip := solve( {f1(x,y)=0,f2(x,y)=0}, {x,y})
> Equip := {x=0.,y=0.}, {x=1.111111111,y=1.666666667}
> J := jacobian([f1(x,y),f2(x,y)], [x,y])

```

(133)

$$J := \begin{bmatrix} 2 - 1.2y & -1.2x \\ 0.9y & -1 + 0.9x \end{bmatrix} \quad (134)$$

> $A1 := \text{subs}(\text{Equip}[1, 1], \text{Equip}[1, 2], \text{eval}(J))$

$$A1 := \begin{bmatrix} 2. & -0. \\ 0. & -1. \end{bmatrix} \quad (135)$$

> $\text{eigenvals}(A1)$

$$-1., 2. \quad (136)$$

> $A2 := \text{subs}(\text{Equip}[2, 1], \text{Equip}[2, 2], \text{eval}(J))$

$$A2 := \begin{bmatrix} 0. & -1.333333333 \\ 1.500000000 & -1. \times 10^{-10} \end{bmatrix} \quad (137)$$

> $\text{eigenvals}(A2)$

$$-5.000000000000000 \times 10^{-11} + 1.41421356219632 \text{ I}, -5.000000000000000 \times 10^{-11} - 1.41421356219632 \text{ I} \quad (138)$$

> $\text{DEplot}([\text{sist}], [x(t), y(t)], t = -10..10, x = -3..3, y = -3..3, [\text{condin}], \text{linecolor} = \text{blue}, \text{stepsize} = 0.1)$

