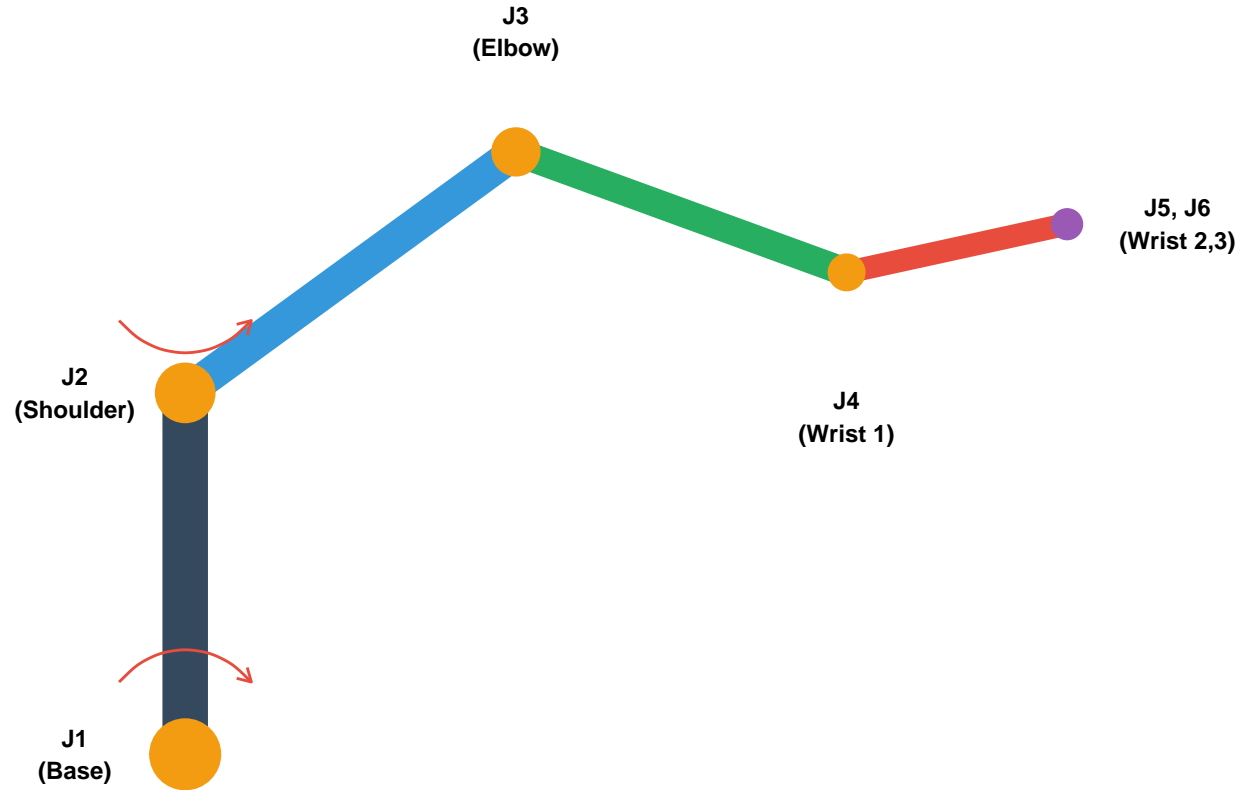


6–Axis Articulated Robot – Joint Nomenclature

Each joint provides one degree of freedom



6–Axis Robot Joints:

J1: Base rotation

J2: Shoulder pivot

J3: Elbow pivot

J4: Wrist rotation

J5: Wrist bend

J6: Tool rotation