

## ... BODE DIAGRAMME ...

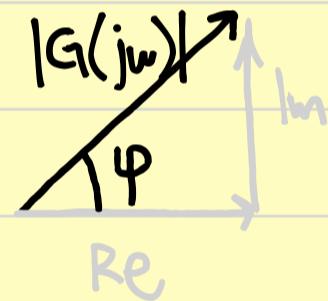
## 5. BODE DIAGRAMM PI · Regelkreisglied

PI · Glied = Parallelschaltung von P und I Glied.

$$G(s) = \frac{u_a(s)}{u_e(s)} = K_p + \frac{K_p}{sT_n} = K_p \left( 1 + \frac{1}{sT_n} \right)$$

$$s = j\omega \rightarrow G(j\omega) = K_p \left( 1 - j \frac{1}{\omega T_n} \right)$$

$$\operatorname{Re}(G(j\omega)) = K_p ; \quad \operatorname{Im}(G(j\omega)) = -\frac{K_p}{\omega T_n}$$



$$|G(j\omega)| = \sqrt{\operatorname{Re}(G(j\omega))^2 + \operatorname{Im}(G(j\omega))^2} =$$

$$= \sqrt{K_p^2 + K_p^2 \left( \frac{1}{\omega T_n} \right)^2} = K_p \sqrt{1 + \left( \frac{1}{\omega T_n} \right)^2} \circ$$

$$\log |G(j\omega)| = \log \left[ K_p \cdot \left( 1 + \left( \frac{1}{\omega T_n} \right)^2 \right)^{1/2} \right] = *$$

$$\boxed{\log(a \cdot b) = \log a + \log b} * = \log K_p + \log \left[ \left( 1 + \left( \frac{1}{\omega T_n} \right)^2 \right)^{1/2} \right] = **$$

$$\boxed{\log a^b = b \log a} ** = \log K_p + \frac{1}{2} \log \left[ 1 + \left( \frac{1}{\omega T_n} \right)^2 \right]$$

$$\tan \varphi(\omega) = \frac{\text{Im}(G(j\omega))}{\text{Re}(G(j\omega))} = \frac{-k_p}{\omega T_n} = \frac{-1}{\omega T_n}$$

$w \rightarrow 0$  →  $\frac{1}{\omega T_n} \gg 1$  →  $\log |G(j\omega)| =$

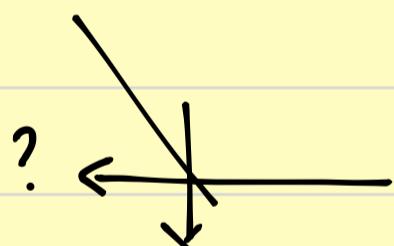
$$\approx \log k_p + \frac{1}{2} \log \left[ \left( \frac{1}{\omega T_n} \right)^2 \right] =$$

$$= \log k_p + \frac{1}{2} \cdot 2 \log \left[ (w T_n)^{-1} \right] =$$

$$= \log k_p - \log(w T_n)$$

GERADE MIT  
NEGATIVEN  
STEIGUNG

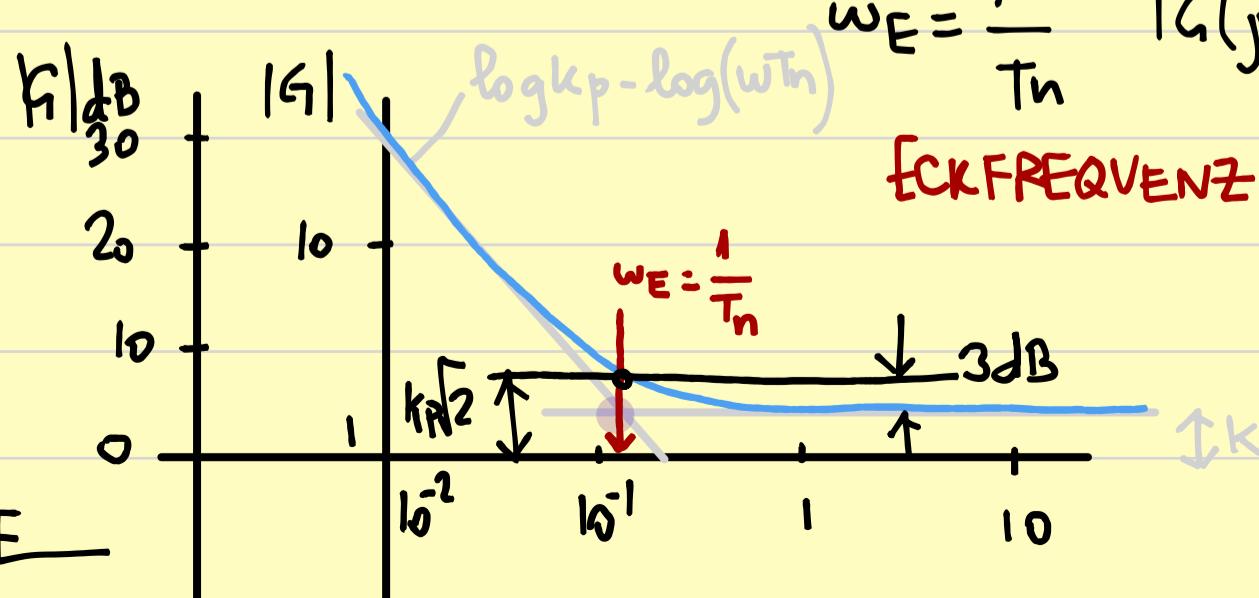
$w \rightarrow \infty$  →  $\frac{1}{\omega T_n} \ll 1$  →  $\log |G(j\omega)| = \log k_p$



$$\omega_E = \frac{1}{T_n} \rightarrow \log k_p - \log(w_E T_n) = \log k_p$$

$$|G(j\omega)| = k_p \sqrt{1 + \left( \frac{1}{\omega T_n} \right)^2} = k_p \sqrt{1+1} = \sqrt{2} k_p$$

$$w_E = \frac{1}{T_n} \quad |G(j\omega)|_{dB} = 20 \log (\sqrt{2} k_p) = 20 \log k_p + 3 dB$$



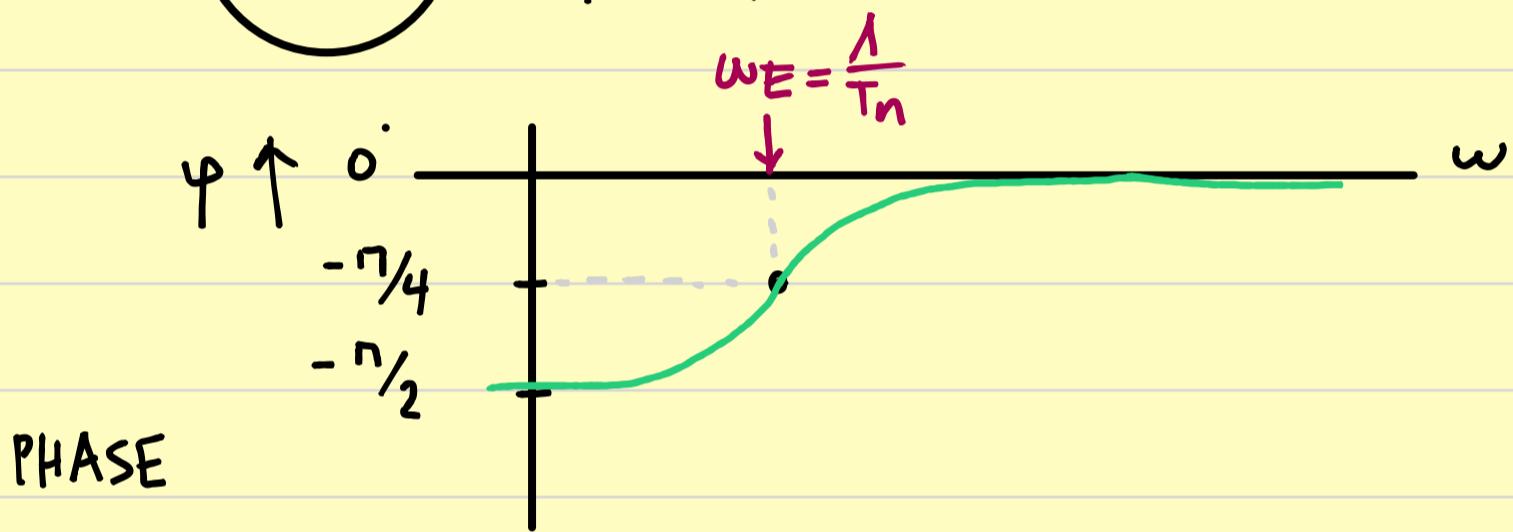
$$k_p = 2 \\ T_n = 5 s$$

$$\tan \varphi(\omega) = \frac{-1}{\omega T_n} \rightarrow \varphi = \arctan\left(\frac{-1}{\omega T_n}\right)$$

$\omega=0 \rightarrow \varphi = -\frac{\pi}{2} (-90^\circ)$

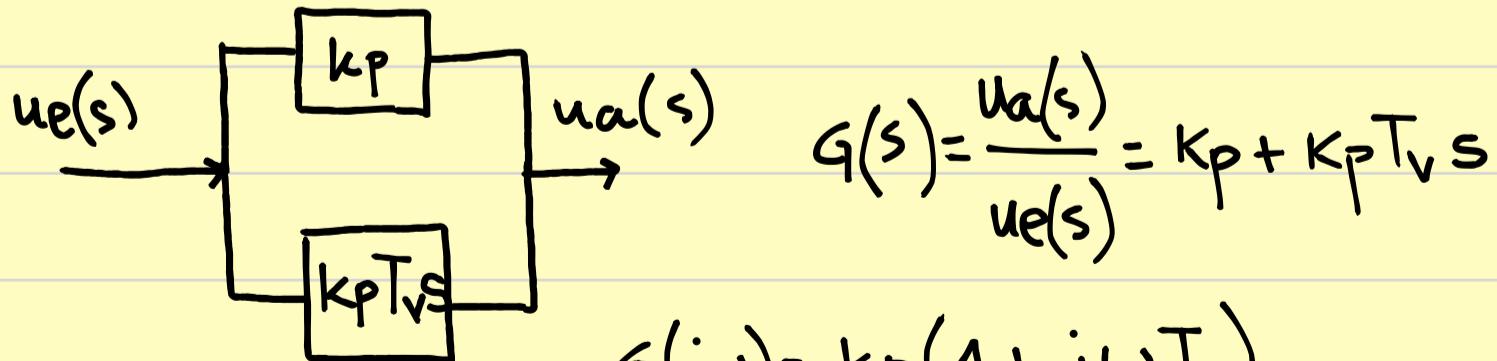
$\omega=\infty \rightarrow \varphi = 0^\circ (0^\circ)$

$\omega_E = \frac{1}{T_n} \rightarrow \varphi = -\frac{\pi}{4} (-45^\circ)$

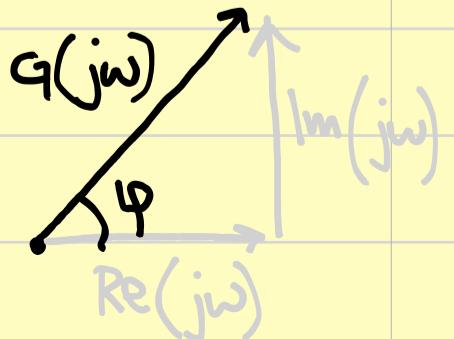


## 6. BODE-DIAGRAMM FÜR EIN PD-GLEID

PD-GLEID  $\equiv$  PARALLELSCHALTUNG P + D GLEID



$$\operatorname{Re} G(j\omega) = k_p ; \operatorname{Im} G(j\omega) = k_p \omega T_v$$



$$|G(j\omega)| = \sqrt{k_p + (k_p w T_v)^2} = k_p \sqrt{1 + (w T_v)^2} = k_p (1 + (w T_v)^2)^{\frac{1}{2}}$$

$$\log(ab) = \log a + \log b$$

$$\log |G(j\omega)| = \log k_p + \log [1 + (w T_v)^2]^{\frac{1}{2}} =$$

\*

$$= \log k_p + \frac{1}{2} \log [1 + (w T_v)^2]$$

$$\tan \varphi(w) = \frac{\operatorname{Im}(G(j\omega))}{\operatorname{Re}(G(j\omega))} = w T_v \rightarrow \varphi = \arctan(w T_v)$$

$w \rightarrow 0$  →  $\log |G(j\omega)| \approx \log k_p$

$w \rightarrow \infty$  →  $\log |G(j\omega)| \approx \log k_p + \log(w T_v)$

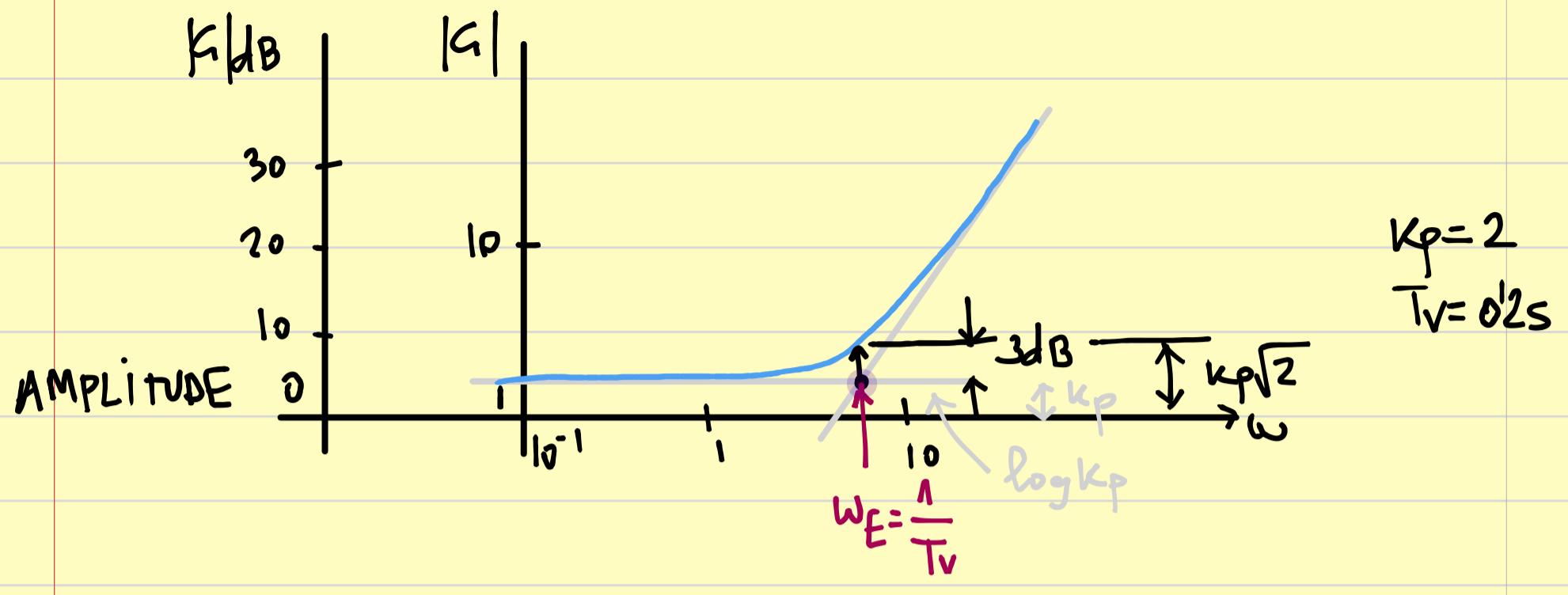
GERADE MIT  
POSITIVEN  
STEIGUNG

$w_E \equiv \log k_p = \log k_p + \log(w_E T_v) \rightarrow w_E = \frac{1}{T_v}$

\*  $\log |G(j\omega)| = \log k_p + \frac{1}{2} \log [1 + (w T_v)^2] =$   
 $\underset{w \rightarrow \infty}{\approx} \log k_p + \frac{1}{2} \log [(w T_v)^2] =$   
 $= \log k_p + \frac{1}{2} \cdot 2 \log(w T_v) =$   
 $= \log k_p + \log(w T_v)$

○  $|G(j\omega)| = k_p \sqrt{1 + (w_E T_v)^2} = k_p \sqrt{2}$   
 $w = w_E$

$$|G(j\omega)|_{w=w_E} = 20 \cdot \log k_p + 3 \text{ dB}$$

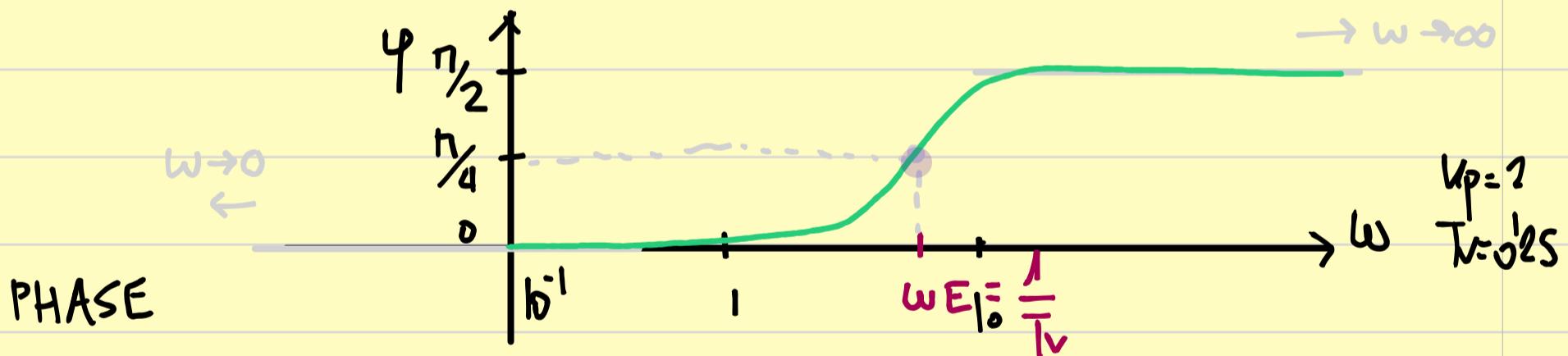


$$\varphi = \arctan(\omega T_V)$$

$$\omega = 0 \rightarrow \varphi = 0$$

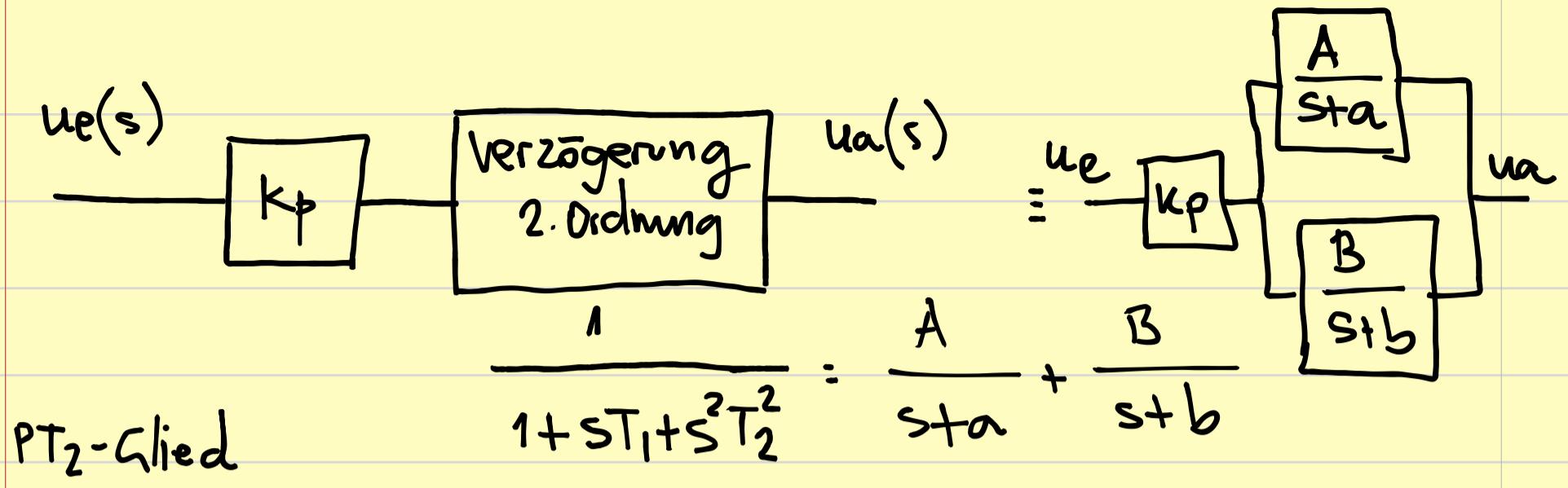
$$\omega = \infty \rightarrow \varphi = \frac{\pi}{2} (90^\circ)$$

$$\omega = \omega_E \rightarrow \varphi = \frac{\pi}{4} (45^\circ)$$



## 7. BODE-DIAGRAMM VON EINEM PT<sub>2</sub>-GLIED

Als PT<sub>2</sub>-Glied bezeichnet man ein proportionales Übertragungsverhalten (P-Glied) mit einer Verzögerung 2. Ordnung.

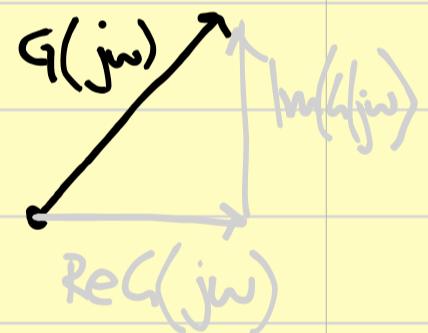


$$\text{Dämpfung} = D = \frac{T_1}{2T_2}$$

$$G(s) = \frac{u_a(s)}{u_e(s)} = \frac{K_p}{1+sT_1+s^2T_2^2}$$

$$G(j\omega) = \frac{K_p}{1+j\omega T_1 - (\omega T_2)^2} = \frac{K_p}{1-(\omega T_2)^2} + \frac{K_p}{\omega T_1} j$$

$$\operatorname{Re}(G(j\omega)) = \frac{K_p}{1-(\omega T_2)^2} ; \quad \operatorname{Im}(G(j\omega)) = \frac{K_p}{\omega T_1}$$



$$|G(j\omega)| = \sqrt{\operatorname{Re}(G(j\omega))^2 + \operatorname{Im}(G(j\omega))^2} = \frac{K_p}{\sqrt{(1-(\omega T_2)^2)^2 + (\omega T_1)^2}}$$

$$\log |G(j\omega)| = \log K_p - \frac{1}{2} \log \left[ [1-(\omega T_2)^2]^2 + (\omega T_1)^2 \right]$$

$$\omega \rightarrow 0 \rightarrow \log |G(j\omega)| \approx \log K_p \quad \text{GERADE}$$

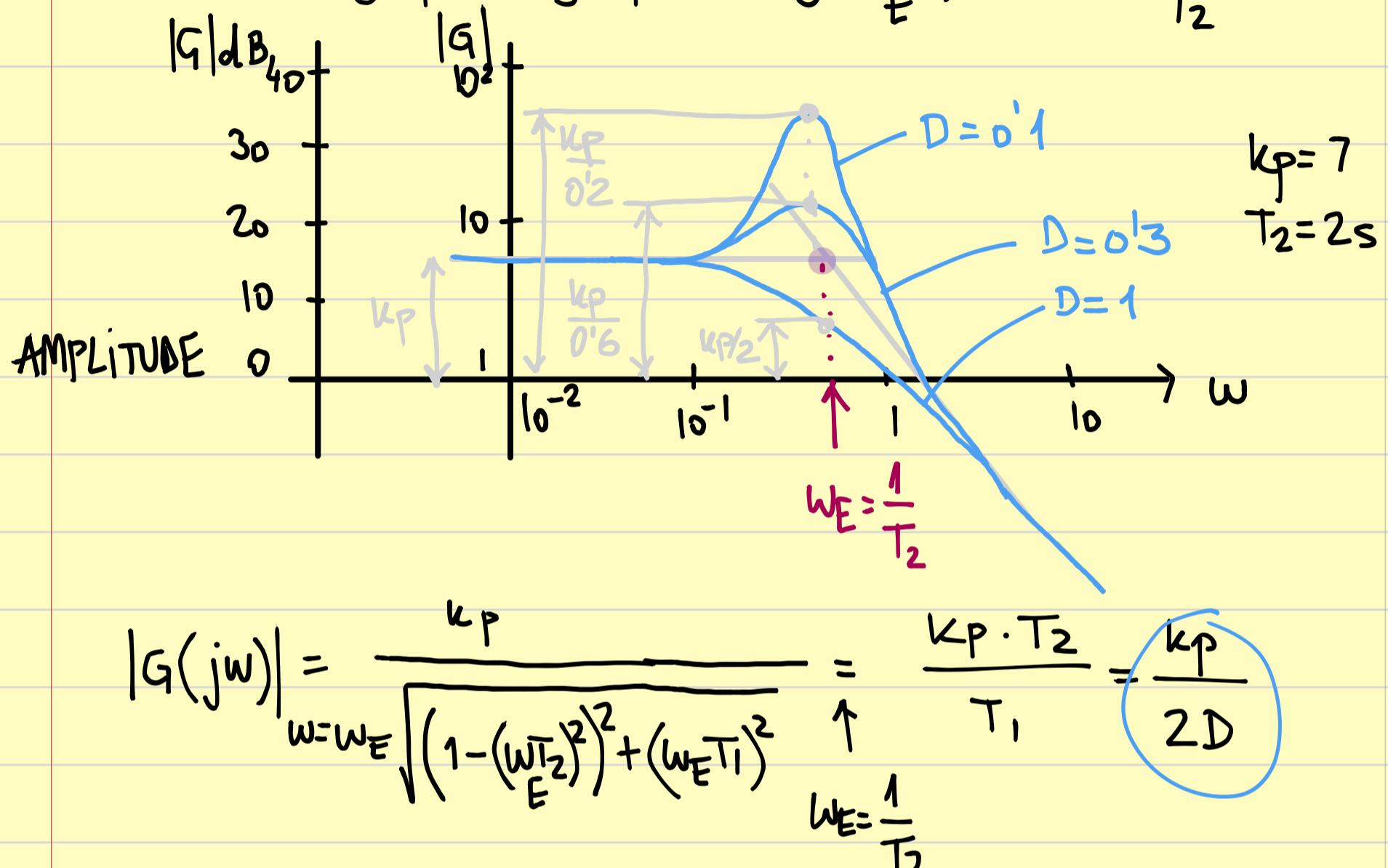
$$\omega \rightarrow \infty \rightarrow (\omega T_2)^2 \gg 1 \quad \text{und} \quad (\omega T_2)^2 \gg \omega T_1$$

$$\log |G(j\omega)| \approx \log K_p - \frac{1}{2} \log [(\omega T_2)^2]^2 =$$

$$= \log k_p - 2 \log(\omega T_2)$$

GERADE MIT NEGATIVEN STEIGUNG

$$w_E \rightarrow \log k_p = \log k_p - 2 \log(\omega T_2) \rightarrow w_E = \frac{1}{T_2}$$



$$|G(j\omega)| = \frac{k_p}{\omega = w_E \sqrt{\left(1 - (\omega T_2)^2\right)^2 + (w_E T_1)^2}} = \frac{k_p \cdot T_2}{T_1} = \frac{k_p}{2D}$$

$$D=1 \rightarrow |G(jw_E)| = \frac{k_p}{2}$$

$$D=0.3 \rightarrow |G(jw_E)| = \frac{k_p}{0.6}$$

$$D=0.1 \rightarrow |G(jw_E)| = \frac{k_p}{0.2}$$

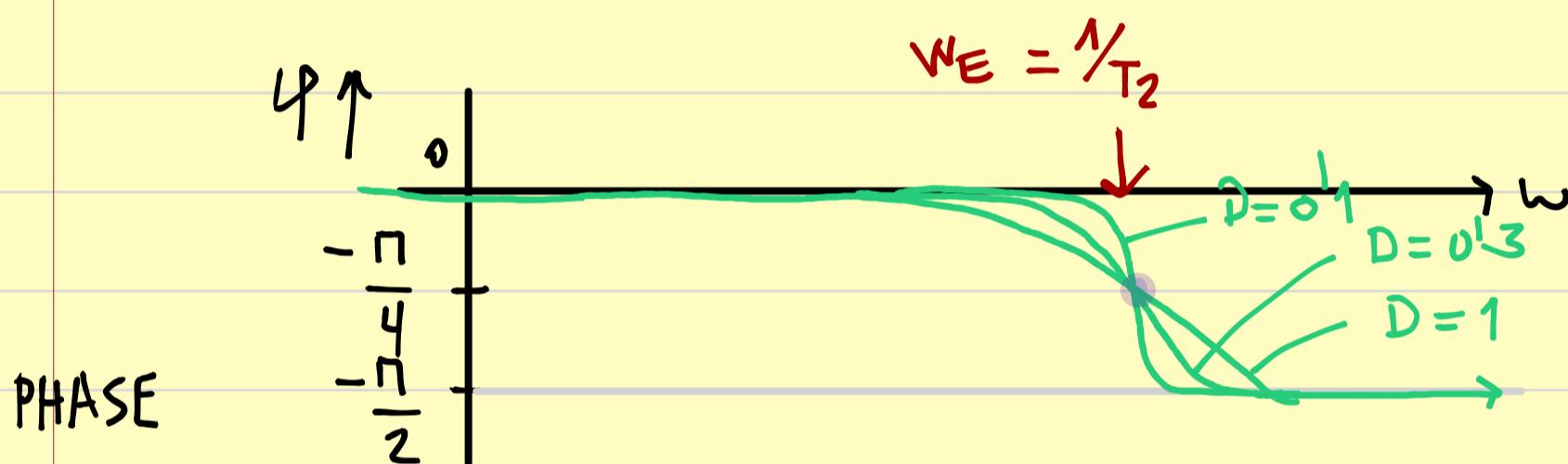
Wenn  $D > 1$  ist, so lässt sich das  $PT_2$ -Glied in zwei  $PT_1$ -Glieder in Reihenschaltung zerlegen.

$$\tan \varphi = \frac{\operatorname{Im} G(j\omega)}{\operatorname{Re} G(j\omega)} = \frac{-\omega T_1}{1 - (\omega T_2)^2} \rightarrow \varphi = -\operatorname{atan} \frac{\omega T_1}{1 - (\omega T_2)^2}$$

$$\omega \rightarrow 0 : \varphi = 0$$

$$\omega \rightarrow \infty : \varphi = -\frac{\pi}{2}$$

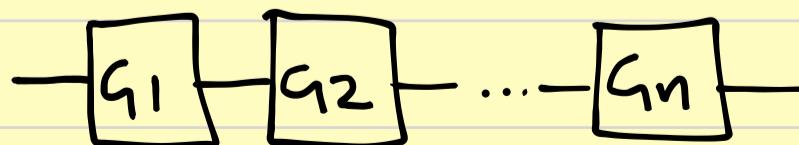
$$\omega = \omega_E = \frac{1}{T_2} : \varphi = -\frac{\pi}{4}$$



### DARSTELLUNG IN REIHE GESCHALTETER GLIEDER

#### IN BODE-DIAGRAMM

Sind  $n$  Glieder mit Frequenzgängen  $G_1(j\omega), G_2(j\omega), \dots, G_n(j\omega)$  in Reihe geschaltet, so ist der Gesamtfrequencygang gleich dem Produkt der einzelnen Frequencygänge.



$$G(s) = \prod_{i=1}^n G_i(s)$$

$$G(j\omega) = \prod_{i=1}^n G_i(j\omega) \quad (\text{↗})$$

Zur Darstellung im Bode-Diagramm wird  $G(j\omega)$  zerlegt:

$$G(j\omega) = |G(j\omega)| \cdot e^{j\varphi(j\omega)}$$

Angewandt (\*) wird:

$$G(j\omega) = |G_1(j\omega)| e^{j\varphi_1(j\omega)} |G_2(j\omega)| e^{j\varphi_2(j\omega)} \dots |G_n(j\omega)| e^{j\varphi_n(j\omega)} = \\ = |G_1(j\omega)| |G_2(j\omega)| \dots |G_n(j\omega)| e^{j(\varphi_1 + \varphi_2 + \dots + \varphi_n)}$$

Es folgt dann:

$$|G(j\omega)| = |G_1(j\omega)| |G_2(j\omega)| \dots |G_n(j\omega)|$$

$$\varphi(j\omega) = \varphi_1(j\omega) + \varphi_2(j\omega) + \dots + \varphi_n(j\omega) \quad (***)$$

Infolge der logarithmischen Darstellung des Amplitudenganges:

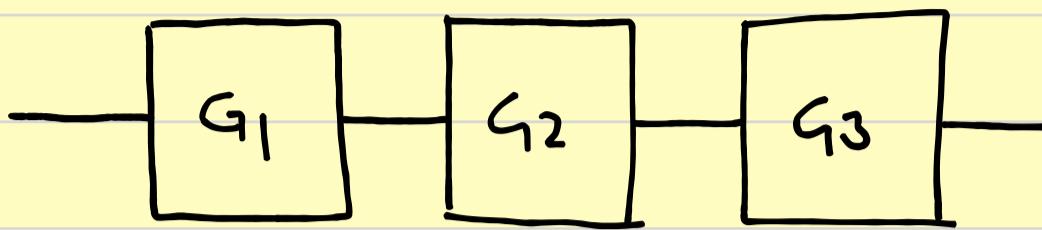
$$\log |G(j\omega)| = \log |G_1(j\omega)| + \log |G_2(j\omega)| + \dots + \log |G_n(j\omega)|$$

$$|G(j\omega)|_{dB} = \sum_{i=1}^n |G_i(j\omega)|_{dB} \quad (**) \quad \text{!}$$

Der Amplitudengang des Gesamt-frequenzganges  $|G(j\omega)|_{dB}$  ergibt sich durch einfache Addition der einzelnen Ordinaten der Amplitudengänge  $|G_i(j\omega)|_{dB}$  (\*).

Das gleiche gilt auch für die Asymptoten (\*\*\*)

Beispiel. Bitte Bode-Diagramm von folgenden Gliedern darstellen



$$G_1(s) = \frac{K_{P1}}{1+sT_1} \quad K_{P1} = 2 \quad T_1 = 5s$$

$$G_2(s) = \frac{K_{P2}}{1+sT_2} \quad K_{P2} = 4 \quad T_2 = 1s$$

$$G_3(s) = K_{P3}(1+sT_V) \quad K_{P3} = 8 \quad T_V = 0.25s$$

$$G(s) = G_1 \cdot G_2 \cdot G_3 = \frac{64(1+0.25s)}{(1+5s)(1+s)} = \frac{A}{(1+5s)} + \frac{B}{(1+s)}$$

$$64 + 16s = A(1+s) + B(1+5s)$$

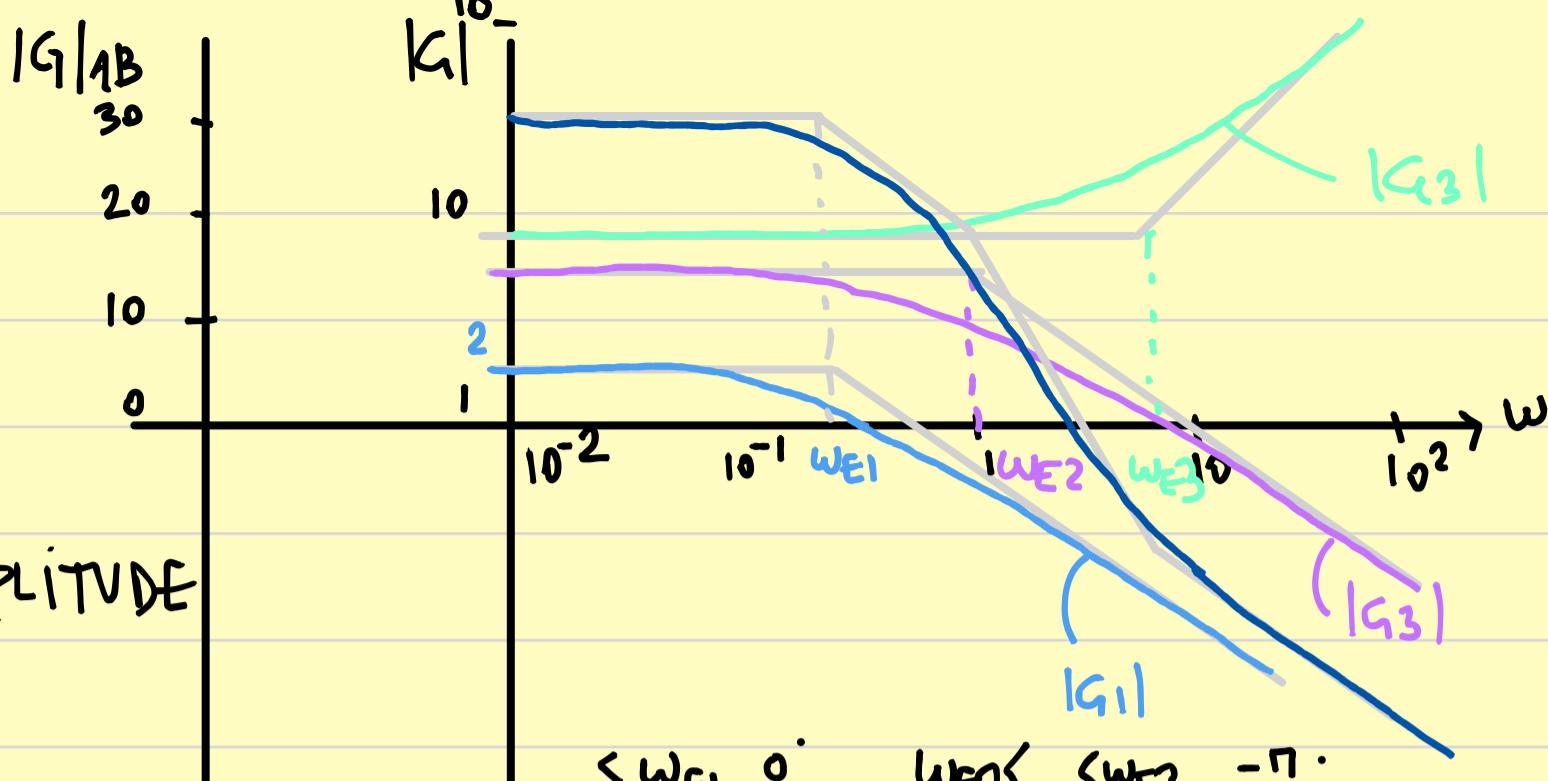
$$s = -1 \rightarrow 48 = 4B \rightarrow B = 12; s = -0.2 \rightarrow 60.8 = 0.8A \rightarrow A = 76$$

$$G(s) = \frac{76}{1+5s} + \frac{12}{1+s} \equiv \dots$$

bereits bekannt

Zunächst werden die Asymptoten der einzelnen Amplitudengänge gezeichnet (siehe oben):

$$\omega_E1 = \frac{1}{T_1} = 0.2s^{-1}; \omega_E2 = \frac{1}{T_2} = 1s^{-1}; \omega_E3 = \frac{1}{T_V} = 4s^{-1}$$



$$G_1(s) = \frac{2}{1+5s}$$

$$\begin{aligned} < \omega_{E1} & 0^\circ \\ \omega_{E1} < & \omega_2 < \omega_{E3} \\ & -\frac{\pi}{4}^\circ > \omega_{E3} & -\frac{\pi}{4}^\circ \end{aligned}$$

$$G(j\omega) = \frac{2}{1+5\omega j} \cdot \frac{1-5\omega j}{1-5\omega j} : \frac{2-10\omega j}{1+(5\omega)^2} \rightarrow |G(j\omega)| = \frac{1}{1+(5\omega)^2} \sqrt{4-(\omega)^2}$$

$$\omega \rightarrow 0 : |G(j\omega)| \approx 2$$

$$\omega \rightarrow \infty : |G(j\omega)| = -\infty$$

