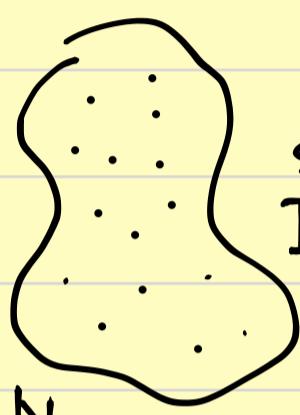


Dynamic Systems

1D & 2D Systems.

SEX & MATH

- 1D . Transmission of sexual diseases (Chlamydia)



At the time point .. t .. the number of infected students is given by the function $I(t)$.

$I(t)$

, t . Because the population is constant (N individuals), we can normalize $I(t)$ between 0 and 1.

We do so by dividing $I(t)$ between N .

$$i(t) = \frac{I(t)}{N} \in [0, 1]$$



We would like to understand the dynamics of $i(t)$.

for this, we define two processes :

1) Infection. Every infected person can infect other individuals with Rate β . The frequency, that an infected individual meets a healthy one is $i \cdot (1-i)$.

$\text{INFECTION RATE} = \beta \cdot i \cdot (1-i)$

2) Curation. Every infected person can get cured with rate γ . As a result :

$$\text{CURATION RATE} = \gamma \cdot i$$

The dynamic system describes $i(t)$ when time changes:

$$\frac{di(t)}{dt} = \text{Infection rate} - \text{Curation rate}$$

$$\frac{di(t)}{dt} = \beta \cdot i \cdot (1-i) - \gamma \cdot i = \beta \cdot i - \beta \cdot i^2 - \gamma \cdot i$$

$$\frac{di(t)}{dt} = (\beta - \gamma) i - \beta \cdot i^2$$

We define:

$$r = \beta - \gamma$$

$$k = \frac{r}{\beta} = \frac{\beta - \gamma}{\beta} = 1 - \frac{\gamma}{\beta} \equiv \beta = \frac{r}{k}$$

$$\frac{di(t)}{dt} = r \cdot i - \frac{r}{k} i^2 = r \cdot i \left[1 - \frac{i}{k} \right]$$

$$\frac{di(t)}{dt} = r \cdot i \left[1 - \frac{i}{k} \right]$$

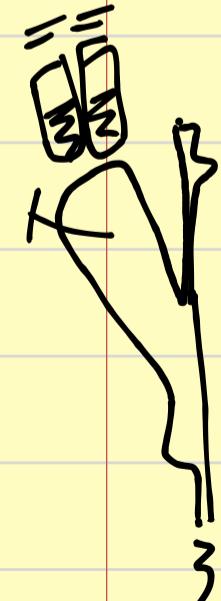
Logistic
Equation

$$1. \frac{d(\ln x)}{dx} = \frac{1}{x} \rightarrow \int \frac{1}{x} dx = \ln|x| + C$$

$$2. \frac{k}{x(1-x)} = \frac{A}{x} + \frac{B}{(1-x)} = \frac{A(1-x) + Bx}{x(1-x)}$$

$$x=0 \rightarrow k = A(1-0) + B \cdot 0 \rightarrow k = A$$

$$x=1 \rightarrow k = A(1-1) + B \cdot 1 \rightarrow k = B$$



$$\frac{\frac{di(t)}{dt}}{i \left[1 - \frac{i}{k} \right]} = r dt \rightarrow \int \frac{di(t)}{i \left(1 - \frac{i}{k} \right)} = \int r dt$$

$$\rightarrow \int \frac{k di(t)}{i(k-i)} = \int r dt \rightarrow (\bullet)$$

$$\frac{k}{i(k-i)} = \frac{A}{i} + \frac{B}{k-i} = \frac{A(k-i) + B \cdot i}{i(k-i)} \rightarrow$$

$$\rightarrow i=k \rightarrow k = A(k-k) + B \cdot k \rightarrow k = B \cdot k \rightarrow B=1$$

$$i=0 \rightarrow k = A(k-0) + B \cdot 0 \rightarrow k = A \cdot k \rightarrow A=1$$

$$\frac{k}{i(k-i)} = \frac{1}{i} + \frac{1}{k-i}$$

$$\rightarrow (\bullet) \rightarrow \int \frac{1}{i} di(t) + \int \frac{1}{k-i} di(t) = \int r dt \rightarrow$$

$$\rightarrow \ln|i| - \ln|k-i| = rt + C$$

Exponentiate:

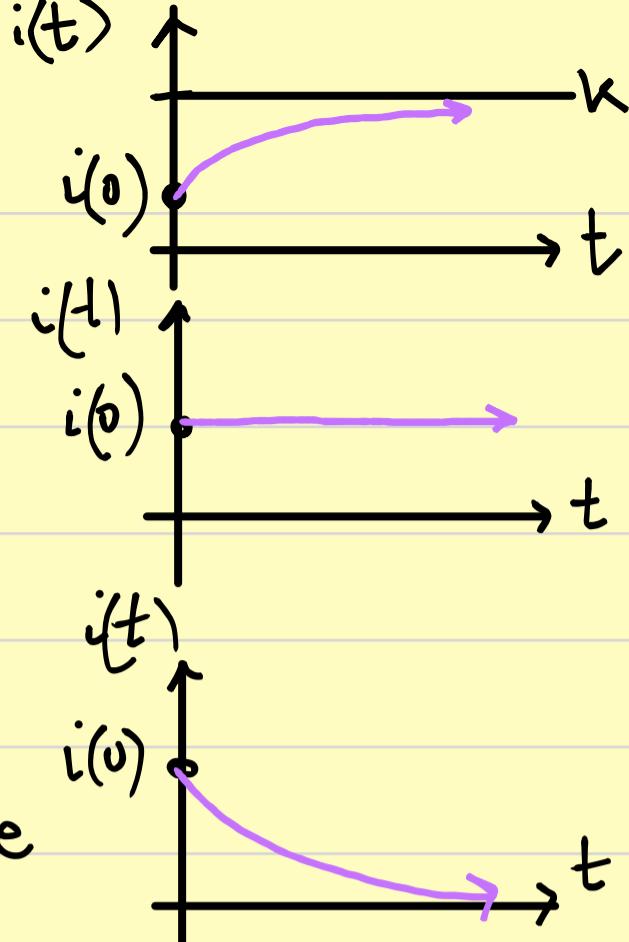
$$\frac{i}{k-i} = A e^{rt}$$

$$A = \frac{i(0)}{k-i(0)}$$

$$i(t) = \frac{k}{1 + \left[\frac{k-i(0)}{i(0)} \right] e^{-rt}}$$

✓

$r > 0$ We infect faster than we cure.



$r = 0$ We infect at the same rate as we cure.

$$r=0 \quad i'(t) = \frac{k}{1 + \left[\frac{k - i(0)}{i(0)} \right]} : \frac{k \cdot i(0)}{i(0) + k - i(0)} = i(0)$$

$r < 0$ We infect slower than we cure

Example separation of variables for integration:

$$\frac{1}{(x-2)(3x-1)} = \frac{1}{(x-2)3 \cdot \left(x - \frac{1}{3}\right)} = \frac{1}{3} \cdot \frac{1}{(x-2)\left(x - \frac{1}{3}\right)} = \frac{A}{x-2} + \frac{B}{x - \frac{1}{3}} \\ = \frac{A\left(x - \frac{1}{3}\right) + B\left(x - 2\right)}{(x-2)\left(x - \frac{1}{3}\right)}$$

$$\frac{1}{3} = A\left(x - \frac{1}{3}\right) + B\left(x - 2\right) \rightarrow$$

$$\rightarrow x = \frac{1}{3} \rightarrow \frac{1}{3} = B\left(\frac{1}{3} - 2\right) \rightarrow \frac{1}{3} = B \cdot -\frac{5}{3} \rightarrow B = -\frac{1}{5}$$

$$x = 2 \rightarrow \frac{1}{3} = A\left(2 - \frac{1}{3}\right) \rightarrow \frac{1}{3} = A \cdot \frac{5}{3} \rightarrow A = \frac{1}{5}$$

$$\frac{1}{(x-2)(3x-1)} = \frac{1}{5} \left(\frac{1}{x-2} - \frac{1}{x - \frac{1}{3}} \right)$$

$$\int \frac{1}{(x-2)(3x-1)} dx = \frac{1}{5} \left[\int \frac{1}{x-2} dx - \int \frac{1}{x - \frac{1}{3}} dx \right] = \\ = \frac{1}{5} \left[\ln|x-2| - \ln|x - \frac{1}{3}| \right] + C$$

$$\int \frac{3}{(x-1)(2x-5)} dx$$

$$\begin{aligned} \frac{3}{(x-1)(2x-5)} &= \frac{3}{(x-1)2\left(x-\frac{5}{2}\right)} = \frac{3}{2} \cdot \frac{1}{(x-1)\left(x-\frac{5}{2}\right)} = \frac{\frac{3}{2}}{x-1} + \frac{\frac{3}{2}}{x-\frac{5}{2}} \\ &= \frac{\frac{3}{2}(x-\frac{5}{2}) + \frac{3}{2}(x-1)}{(x-1)(x-\frac{5}{2})} \end{aligned}$$

- $\frac{3}{2} = A\left(x-\frac{5}{2}\right) + B(x-1)$

$$x=1 \rightarrow \frac{3}{2} = A\left(1-\frac{5}{2}\right) + B(1-1) \rightarrow \cancel{\frac{3}{2}} = A\left(\frac{-3}{2}\right) \rightarrow A = -1$$

$$x=\frac{5}{2} \rightarrow \frac{3}{2} = A \cdot \left(\frac{5}{2}-\cancel{\frac{5}{2}}\right) + B\left(\frac{5}{2}-1\right) \rightarrow \frac{3}{2} = B\left(\frac{3}{2}\right) \rightarrow B = 1$$

$$\frac{3}{(x-1)(2x-5)} = \frac{-1}{x-1} + \frac{1}{x-\frac{5}{2}}$$

$$\int \frac{3 dx}{(x-1)(2x-5)} = \int \frac{-dx}{x-1} + \int \frac{dx}{x-\frac{5}{2}} = -\ln|x-1| + \ln\left|x-\frac{5}{2}\right| + C$$

• 2D System

LOVE & MATHEMATICS

ROMEO - JULIA

R(t)

J(t)

- Romeo & Julia interact, so the love functions for each other R(t) & J(t) depend mutually on each other.

To describe this interaction we need four parameters:

a. describes the intrinsic love of Romeo to Julia.

$a > 0$: Romeo increases love to Julia independent of Julia's behaviour.

$a < 0$: Romeo decreases love to Julia independent of Julia's behaviour.

b. describes the influence of Julia on Romeo's love.

$b > 0$: Romeo loves Julia more if she is charming.

$b < 0$: Romeo loves Julia more if she rejects him.

① $\frac{dR(t)}{dt} = a R(t) + b J(t)$

For c and d is the same changing the names

② $\frac{dJ(t)}{dt} = c R(t) + d J(t)$.

$$\frac{dR(t)}{dt} = a R(t) + b J(t)$$

$$\frac{dJ(t)}{dt} = c R(t) + d J(t)$$

$$X(t) = \begin{bmatrix} R(t) \\ J(t) \end{bmatrix} \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\frac{dX(t)}{dt} = A \cdot X(t)$$

General dynamic equation for 2 variables interacting.

In order to understand the qualitative behaviour of the system, we diagonalize our equation by finding the eigenvalues and eigenvectors of the matrix.

The general solution of the equation is:

$$\vec{x}(t) = \begin{bmatrix} R(t) \\ J(t) \end{bmatrix} = c_1 \cdot \vec{v}_1(t) \cdot e^{\lambda_1 t} + c_2 \cdot \vec{v}_2(t) e^{\lambda_2 t}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow \det[A - \lambda I] = 0 \rightarrow \det \begin{bmatrix} a-\lambda & b \\ c & d-\lambda \end{bmatrix} = 0$$

$$\rightarrow (a-\lambda)(d-\lambda) - cb = 0 \rightarrow \lambda^2 - \lambda(a+d) + (ad - cb) = 0$$

$$\lambda = \frac{a+d \pm \sqrt{(a+d)^2 - 4(ad - cb)}}{2} = \frac{a+d \pm \sqrt{a^2 + d^2 - 2ad + 4cb}}{2} =$$

$$\lambda = \frac{a+d \pm \sqrt{(a-d)^2 + 4cb}}{2} \quad \begin{array}{c} \xrightarrow{\lambda_1} \rightarrow \vec{v}_1 \\ \xrightarrow{\lambda_2} \rightarrow \vec{v}_2 \end{array}$$

Examples:

1) The behaviour of Julia does not influence Romeo . $b = 0$
 The behaviour of Romeo does not influence Julia . $c = 0$

$$\lambda = \frac{a+d \pm \sqrt{(a-d)^2 + 0}}{2} = \frac{a+d \pm (a-d)}{2} = \begin{array}{c} \xrightarrow{\lambda_1 = a} \\ \xrightarrow{\lambda_2 = d} \end{array}$$

$$A \cdot \vec{v}_1 = \lambda_1 \vec{v}_1 \rightarrow \begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = a \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} \rightarrow$$

$$\begin{aligned} \rightarrow a v_{11} &= a v_{11} \\ d v_{12} &= a v_{12} \rightarrow v_{12} = 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} v_{11} = 1$$

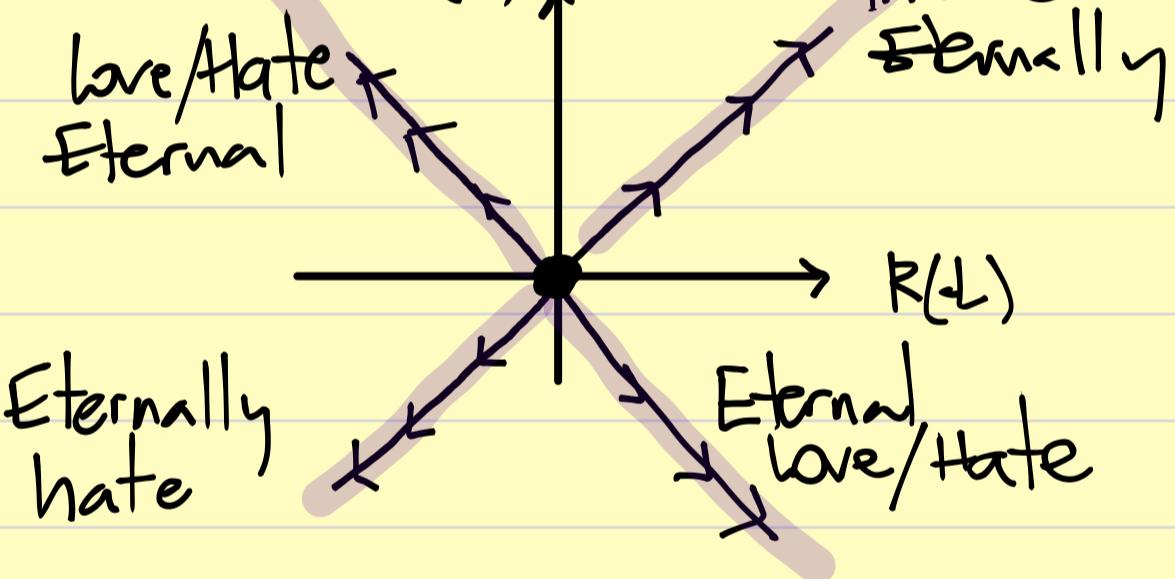
The behaviour of Romeo & Julia are independent.

$$X(t) = c_1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^{at} + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{dt} = \begin{bmatrix} R(t) \\ J(t) \end{bmatrix}$$

$$R(t) = c_1 e^{at}$$

$$J(t) = c_2 e^{dt}$$

IDEALIZED/PLATONIC LOVE



2) Romeo likes charming Julia.
Julia likes asshole Romeo.

$a = -0.5$. Romeo does not find Julia attractive

$b = 1$. If Julia is charming, Romeo falls in love.

$c = -1$. Julia does not find Romeo attractive.

$d = -0.5$. Julia rejects Romeo when he shows love.
(she likes bad guys).

$$\lambda = \frac{(a+d) \pm \sqrt{(a-d)^2 + 4cb}}{2} = \frac{-1 \pm \sqrt{0 - 4}}{2} = -0'5 \pm i$$

$$\lambda_1 = -0'5 + i \quad \lambda_2 = -0'5 - i$$

$$A\vec{v}_1 = \lambda_1 \vec{v}_1 \rightarrow \begin{bmatrix} 0'5 & 1 \\ -1 & -0'5 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = (-0'5 + i) \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} \rightarrow$$

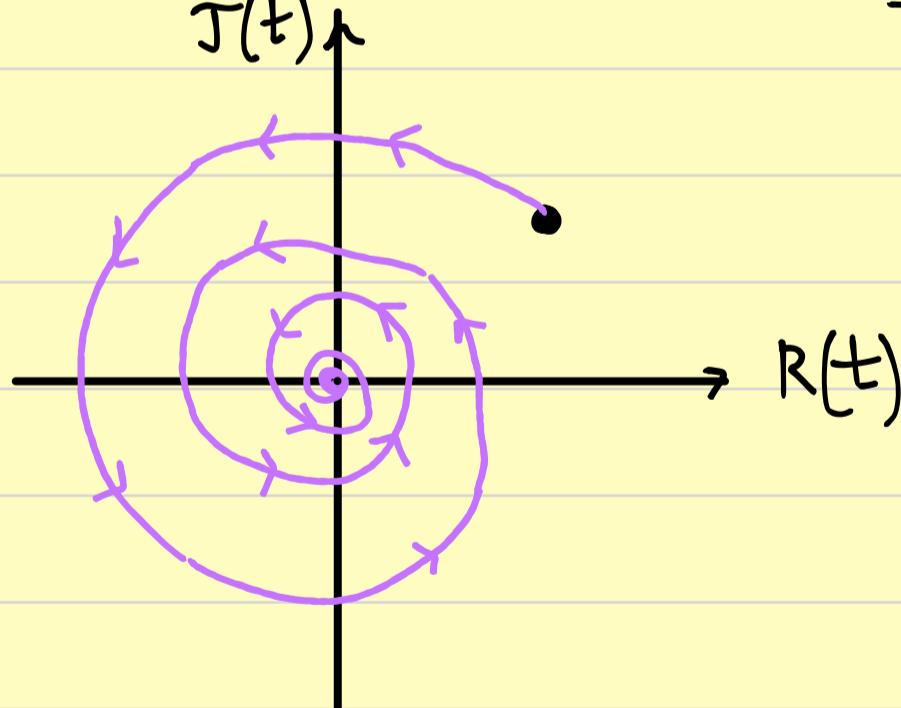
$$\rightarrow -0'5 v_{11} + v_{12} = (-0'5 + i) v_{11} \rightarrow$$

$$-v_{11} - 0'5 v_{12} = (-0'5 + i) v_{12}$$

$$\rightarrow v_{12} = i v_{11} \rightarrow v_{11} = 1 \quad \vec{v}_1 = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$v_{12} = i v_{11} \quad v_{12} = i$$

$$\begin{bmatrix} R(t) \\ J(t) \end{bmatrix} = e^{-0'5t} \begin{bmatrix} A \begin{bmatrix} \cos(t) \\ \sin(t) \end{bmatrix} + B \begin{bmatrix} -\sin(t) \\ \cos(t) \end{bmatrix} \end{bmatrix}$$



3) JULIA is an "ICE" WOMAN. $c = d = 0$
ROMEO is FIRE $. a, b > 0$

$$\lambda = \frac{a \pm \sqrt{(a)^2}}{2} = \begin{cases} \lambda_1 = a \\ \lambda_2 = 0 \end{cases}$$

$$\vec{x}(t) = \begin{bmatrix} R(t) \\ J(t) \end{bmatrix} = c_1 \cdot \vec{v}_1(t) \cdot e^{at} + c_2 \cdot \vec{v}_2(t)$$

$$\begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = a \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} \rightarrow \begin{array}{l} v_{11}=1 \\ v_{12}=0 \end{array} \rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} = 0 \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} \rightarrow \begin{array}{l} v_{21}=0 \\ v_{22}=1 \end{array} \text{ degenerate } \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$x(t) = c_1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^{at} + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

