Machine Learning from Data HW 5

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October 2017

Exercise 2.8

a

The definition of \bar{g} is:

$$\bar{g}(x) \approx \frac{1}{K} \sum_{k=1}^{K} g_k(x)$$

This averaging definition is, by definition, linear.

b

Most binary classifications won't have \bar{g} in the \mathcal{H} . The \bar{g} won't be a -1 or +1 unless \mathcal{H} labels all the points the same each time, which would be a pointless \mathcal{H} .

C

No, \bar{g} won't be a binary function. \bar{g} will most likely land somewhere between -1 and 1.

Problem 2.14

\mathbf{a}

We want to show that $d_{vc}(\mathcal{H}) < K(d_{vc} + 1)$

Let's define a point $k^* = d_{vc} + 1$. We know $d_{vc} < k^*$

We also know that $d_{vc}(\mathcal{H})$ is at most K times our previously defined k^* , so:

$$d_{vc}(\mathcal{H}) < Kk^*$$

Which means...

$$d_{vc}(\mathcal{H}) < K(d_{vc} + 1)$$

b

From part a, we know that for some number ℓ :

$$m_{\mathcal{H}}(\ell) \leq \Sigma_K m_{\mathcal{H}_k}(\ell)$$

$$m_{\mathcal{H}}(\ell) \le \Sigma_K(\ell^{d_{vc}} + 1)$$

We can now do some mathematical manipulation:

$$m_{\mathcal{H}}(\ell) \le \Sigma_K(\ell^{d_{vc}} + 1)$$

$$m_{\mathcal{H}}(\ell) \le K\ell^{d_{vc}} + K$$

$$m_{\mathcal{H}}(\ell) \le 2K\ell^{d_{vc}}$$

So our results is:

$$m_{\mathcal{H}}(\ell) \le 2K\ell^{d_{vc}} < 2^{\ell}$$

C

I started by getting the derivative of our problem

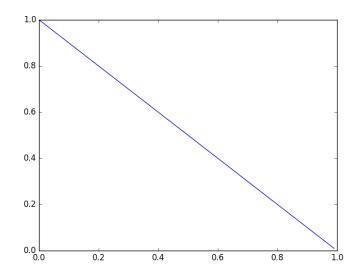
$$K(d_{vc}+1), 7(d_{vc}+K)log_2(d_{vc}K))$$

and then setting it equal to zero. However, when I do this, I get a very large problem that I can't set to 0 easily. I was stuck here and didn't know how to continue.

Problem 2.15

a

A simple example of a monotonic classifier is a linear perceptron that only goes down and to the right. The image below shows this:



The upper right quadrant is +1, while the bottom left quadrant is -1.

$$\mathbf{b}$$
 $m_{\mathcal{H}}(N) = 2^N, d_{vc} = \infty$

If we consider the set in the example:

A set of N points generated by first choosing one point, and then generating the next point by increasing the first component and decreasing the second component until N points are obtained

None of these points have $x_1 > x_2$, so our hypotheses set has no specification on how it can label these points. Therefore, it can always be shattered.

Problem 2.24

a

If we analytically calculate \bar{g} , it would be in the form ax + b. In this case, since our uniform random variable is between [-1,1], our \bar{g} is 0x + 0, or 0.

b

We start by generating 100 data sets. Then, our learning algorithm uses these two points to return to us a g in the form of ax + b. We will use our set of 100 gs to calculate bias(x) and var(x). These will be mean squared error.

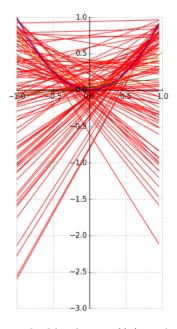
bias(x) =
$$\frac{1}{K} * \sum_{k=1}^{K} (g_k(x) - f(x))^2$$

$$var(x) = \frac{1}{K} * \sum_{k=1}^{K} (\bar{g} - f(x))^2$$

Then, we will integrate bias(x) and var(x) from [-1,1] and multiply by $\frac{1}{b-a}$ to get var and bias. Then, we can add these to get $E_x[E_{out}]$

 \mathbf{c}

I ran the experiment with 100 data sets. I have achieved this result:



The red lines are our gs, the blue line is f(x), and the green line is \bar{g} . When I run these results into our calculation, I get bias = 0.195 and var = 0.139. This totals $E_x[E_{out}]$ to 0.335

d

We know that $\bar{g}(x) = 0$ right from the start because the expected value of both a and b in ax + b are 0.

$$bias = E_x[bias(x)]$$

$$= E_x[(\bar{g}(x) - f(x))^2]$$

$$= E_x[(0-x^2)^2]$$

$$= E_x[x^4]$$

We use the expectation formula, with [a,b] as [-1,1]:

$$\frac{1}{b-a} \int_a^b f(x) dx$$

bias = 0.2

var is calculated in a very similar way, yielding 0.2 as well.

This gives us a calculated $E_x[E_{out}]$ of 0.4. This is given unlimited data sets.