

HW6 - Lucas Fellmeth, Sven Bergmann

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The goal of this problem is to estimate the regression function of acceleration vs time for the `mcycle` data in the package `MASS`, using cubic smoothing splines.

```
library(MASS)
library(splines)
```

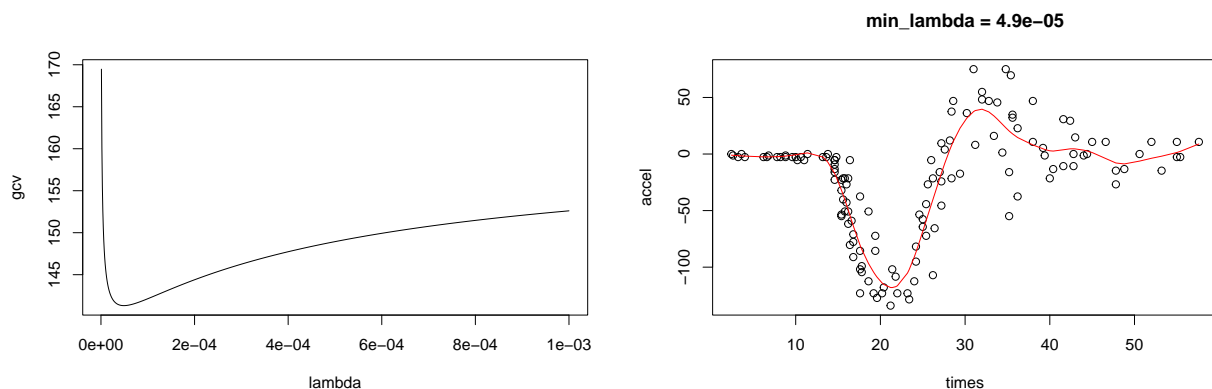
A

For a reasonable range of smoothing parameters λ , compute and plot the generalized cross validation measure $GCV(\lambda)$ and find the optimal smoothing parameter.

```
with(mcycle, {
  lambda <- seq(10^(-6), 10^(-3), by = 10^(-6))

  smoothing <- function(l, x, y) {
    return(smooth.spline(x, y, lambda = l)$cv.crit)
  }

  gcv <- sapply(lambda, smoothing, x = accel, y = times)
  tmp <- data.frame(lambda = lambda, gcv = gcv)
  plot(tmp, type = "l")
  plot.new()
  plot(times, accel, main = paste("min_lambda =", tmp[which.min(tmp$gcv), ]$lambda))
  lines(smooth.spline(x = times, y = accel, lambda = tmp[which.min(tmp$gcv), ]$lambda),
        col = "red", type = "l")
})
```



B

Using the Demmler-Reinsch basis representation, how many basis functions contribute significantly to the fit, as determined, for instance, by accumulating 90% of the total degrees of freedom?

<https://statisticaloddsandends.wordpress.com/2019/10/04/the-demmler-reinsch-basis-for-smoothing-splines/>