

# Data Science

# Statistics:

# Moments of a Distribution



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# Moments of a Distribution: Outline

- Moment: Measure of central location
- Moment: Measure of dispersion
- Moment: Measure of asymmetry
- Moment: Measure of peakedness

# Moments of a Distribution: Learning Objectives & Outcomes

- **Learning Objectives:** Course Instructor or Faculty aims
  - Statistics — Moments of a distribution
  - Moments in statistics are popularly used to describe the characteristic of a distribution.

# Moments of a Distribution: Introduction

- Statistics — Moments of a distribution
- Moments in statistics are popularly used to describe the characteristic of a distribution.

# Moments of a Distribution: Introduction

- First moment- Mean
- Measure the location of the central point.

$$\bar{x} = \frac{\sum_{i=1}^N x_i}{N}$$

# Moments of a Distribution: Second Moment

- Second moment- Standard Deviation (SD,  $\sigma$ (Sigma)):
- Measure the spread of values in the distribution OR how far from the normal.

$$\sigma^2 = \frac{\sum_{i=1}^N (X_i - \bar{X})^2}{N}$$

# Moments of a Distribution: Second Moment

- Small SD : Numbers are close to mean
- High SD : Numbers are spread out
- **For normal distribution:**

- Within 1 SD: 68.27% values lie
- Within 2 SD: 95.45% values lie
- Within 3 SD: 99.73% values lie

- **Advantages over Mean Absolute Deviation(MAD):**

- 1. Mathematical properties- Continuous, differentiable.
- 2. SD of a sample is more consistent estimate for a population
  - When drawing repeated samples from a normally distributed population, the standard deviations of samples are less spread out as compare to mean absolute deviations.

$$\sigma^2 = \frac{\sum_{i=1}^N (X_i - \bar{X})^2}{N}$$

# Moments of a Distribution: Third Moment

- Third moment- Skewness
- Measure the symmetry in the distribution.

$$Skew = \frac{1}{N} \sum_{i=1}^N \left[ \frac{(X_i - \bar{X})}{\sigma} \right]^3$$



# Moments of a Distribution: Third Moment

- Third moment- Skewness: Measure the symmetry in the distribution.

- Skewness=0 [Normal Distribution, Symmetric]

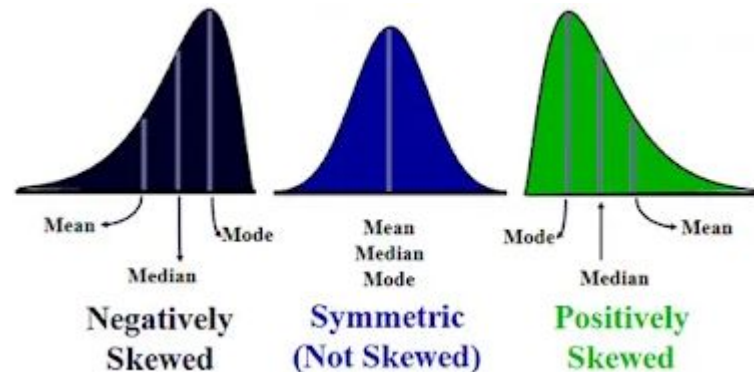
- **Other Formulas:**

- 1. Skewness = (Mean-Mode)/SD
  - 2. Skewness = 3\*(Mean-Median)/SD
  - (Mode = 3\*Median-2\*Mean)

- **Transformations** (to make the distribution normal):

- a. Positively skewed (right): Square root, log, inverse
  - b. Negatively skewed (left) : Reflect and square[sqrt(constant-x)], reflect and log, reflect and inverse

$$Skew = \frac{1}{N} \sum_{i=1}^N \left[ \frac{(X_i - \bar{X})}{\sigma} \right]^3$$



# Moments of a Distribution: Fourth Moment

- Fourth moment- Kurtosis:
- Measure the amount in the tails.

$$Kurt = \frac{1}{N} \sum_{i=1}^N \left[ \frac{(X_i - \bar{X})}{\sigma} \right]^4$$

# Moments of a Distribution: Fourth Moment

- Kurtosis=3 [Normal Distribution]

- Kurtosis<3 [Lighter tails]

- Kurtosis>3 [Heavier tails]

- **Other Formulas:**

- Excess Kurtosis = Kurtosis - 3

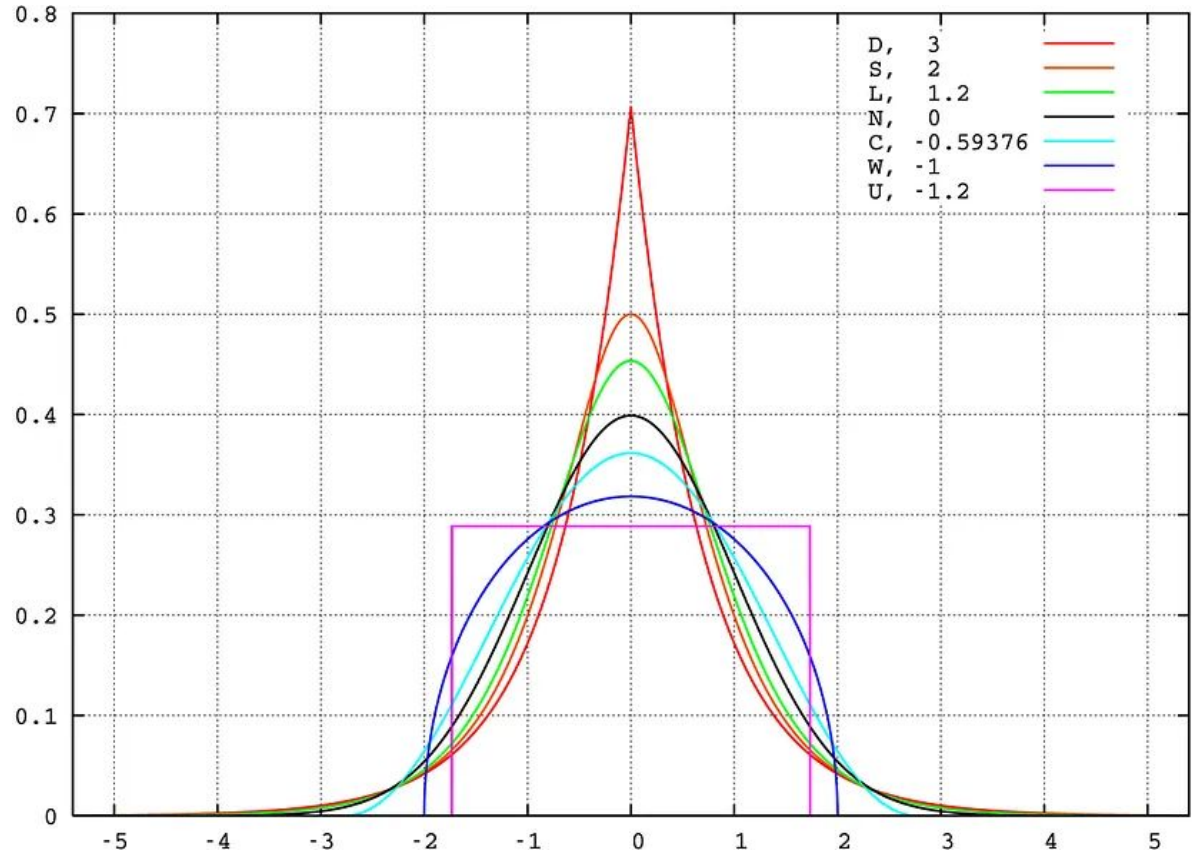
- **Understanding:**

- Kurtosis is the average of the standardized data raised to fourth power.
  - Any standardized values less than |1| (i.e. data within one standard deviation of the mean) will contribute petty to kurtosis.
  - The standardized values that will contribute immensely are the outliers.
  - High Kurtosis alerts about attendance of outliers.

$$Kurt = \frac{1}{N} \sum_{i=1}^N \left[ \frac{(X_i - \bar{X})}{\sigma} \right]^4$$

# Moments of a Distribution: Fourth Moment

- Excess Kurtosis for Distributions  
[Laplace (D)ouble exponential;  
Hyperbolic (S)ecant; (L)ogistic;  
(N)ormal; ©osine; (W)igner  
semicircle; (U)niform]



# Summary

- Statistical moments can be introduced as features of (the probability distribution of) a random variable (RV).
- Interpretation of Moment Statistics
- Mean ( $M_1$ ) - 1st moment about the origin - central tendency measure.
- Variance ( $m_2$ ) - 2nd moment about the mean - dispersion measure.
- Skewness ( $a_3$ ) - 3rd standardize moment - skewness measure.

# References

## A. Text Books:

1. Hand-book on STATISTICAL DISTRIBUTIONS for experimentalists by Christian Walck, Particle Physics Group, Fysikum, University of Stockholm, 2007.
2. Probability and Statistics: The Science of Uncertainty by Michael J. Evans and Jeffrey S. Rosenthal, University of Toronto.
3. Moments and Their Applications in Ordered Statistics by Faizan Mohammad, 2012.

## B. References:

4. SD and variance: <https://www.mathsisfun.com/data/standard-deviation.html>
5. Advantages of the mean deviation: <http://www.leeds.ac.uk/educol/documents/00003759.htm>

# Thank You.

