Machine Learning Model Evaluation





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Model Evaluation: Outline

- Need of Model Evaluation
- Loss Function
- Regularization: Controlling the Learning Process
- Apply Regularization to Learning Models
- Model Evaluation
 - Underfitting,
 - Overfitting,
 - Lasso regularization,
 - Ridge regularization,
 - Elastic Net regularization.

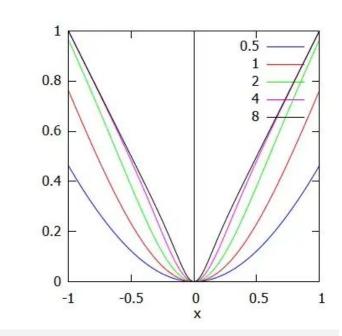
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Model Evaluation: Why Model Evaluation is Important

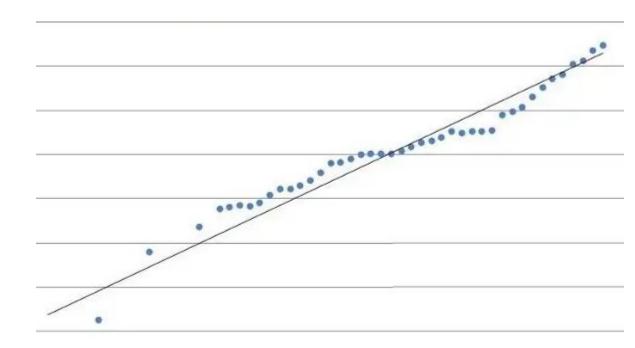
- Need of Model evaluation
 - o It is important to assess the efficacy of a model during initial research phases, and
 - It also plays a role in model monitoring.
 - Before deploying your ML model, it is essential to evaluate its performance on real-world data.
 - o If your model is trained on a clean dataset,
 - it is important to generate a dataset that simulates real-world data as closely as possible.
- Objectives
 - To understand the concept of overfitting and how regularization helps in reducing overfitting.
 - To understand if your model(s) is working well with new data, you can leverage a # of evaluation metrics.
 - To minimize an error function (loss function) or
 - To maximize the efficiency of production using Optimizers algorithms.

- LF along with optimization functions are directly responsible for fitting the model to the given training data.
- Learning Objectives:
 - o how loss functions are used in neural networks,
 - know different types of loss functions,
 - o writing custom loss functions in TensorFlow, and
 - o practical implementations of loss functions to process image/video training data
- NN processes the input data at each layer and eventually produces a predicted output value \hat{y} = AF(X' W + b)
- To training process makes the model maps the relationship between the training data and the outputs.
- To satisfy the equation $\hat{y} = AF(X'W + b)$, in this training process, the NN updates its **hyperparameters**:
 - W weights
 - o b biases

- Each training input is loaded into the NN in a process called **forward propagation**.
- Once model produces o/p (predicted o/p) is compared against given target o/p in a process called **backpropagation**
- In backpropagation process, hyperparameters of model are then
 - o adjusted to minimize (error=predicted-target) output
- This is where loss functions come in.
- A loss function
 - \circ compares the target (y) and predicted (\hat{y}) output values;
 - o measures how well the NN models the training data
- When training,
 - we aim to **minimize** this loss bet. ŷ and y
- The hyperparameters are adjusted to minimize the average loss
 - we find w and b, that minimize the value of J (average loss)



- Loss function is akin to residuals, in statistics.
- Residuals measure the distance of the actual y values from the regression line (predicted values)
 - the goal being to minimize the net distance



- Easy to demonstrate how loss functions are used in models.
 - Using Google's TensorFlow library to implement different loss functions
- In TensorFlow, the LF is specified as a parameter in model.compile()
 - This method trains the neural network eg. model.compile(loss='mse', optimizer='sgd')
- LF can be inputted either as
 - a String as shown above or
 - o as a function object either imported from TensorFlow or written as custom loss functions
 - o eg. from tensorflow.keras.losses import mean_squared_error
 - model.compile(loss=mean_squared_error, optimizer='sgd')
- All loss functions in TensorFlow have a similar structure:
 - def loss_function (y_true, y_pred): return losses
- The model.compile() method expects only two input parameters for the loss attribute i.e y_true and y_pred

Model Evaluation: Types of Loss function

- Regression Loss Functions used in regression neural networks;
 - o given an input value, the model predicts a corresponding output value (rather than pre-selected labels);
 - Ex. Mean Squared Error, Mean Absolute Error
- Classification Loss Functions used in classification neural networks;
 - o given an input, the NN produces a vector of probabilities of the input belonging to various pre-set categories
 - o can then select the category with the highest probability of belonging;
 - Ex. Binary Cross-Entropy, Categorical Cross-Entropy
- Loss function in Machine Learning / Deep Learning
- 1. Regression: MSE(Mean Squared Error), MAE(Mean Absolute Error), Huber loss
- 2. Classification: Binary cross-entropy, Categorical cross-entropy
- 3. AutoEncoder: KL Divergence
- 4. GAN: Discriminator loss, Minmax GAN loss

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^2$$

def mse (y_true, y_pred):
 return tf.square (y_true - y_pred)

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y^{(i)} - \hat{y}^{(i)}|$$

def mae (y_true, y_pred):
 return tf.abs(y_true - y_pred)

$$CE Loss = -\frac{1}{n} \sum_{i=1}^{N} \sum_{j=1}^{M} y_{ij} \cdot log(p_{ij})$$

Binary cross-entropy is a special case of categorical cross-entropy (above), where M = 2 (the number of categories)

Huber Loss =
$$\frac{1}{n} \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^2$$
 $|y^{(i)} - \hat{y}^{(i)}| \le \delta$
 $\frac{1}{n} \sum_{i=1}^{n} \delta(|y^{(i)} - \hat{y}^{(i)}| - \frac{1}{2}\delta)$ $|y^{(i)} - \hat{y}^{(i)}| > \delta$

$$CE Loss = \frac{1}{n} \sum_{i=1}^{N} - (y_i \cdot log(p_i) + (1 - y_i) \cdot log(1 - p_i))$$

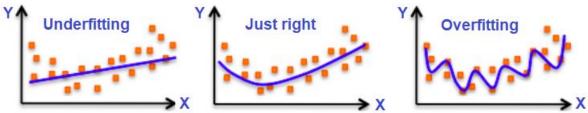
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def log_loss (y_true, y_pred):
    y_pred = tf.clip_by_value(y_pred, le-7, 1 - le-7)
    error = y_true * tf.log(y_pred + le-7) (1-y_true) * tf.log(1-y_pred + le-7)
    return -error
```

- Model evaluation
 - o Process of using different evaluation metrics to understand performance (strengths and weaknesses) of model
 - Assess the efficacy of a model during initial research phases, and it also plays a role in model monitoring.
- Regularization
 - Process of limiting (controlling) the learning process during training of a model
 - by adding another term to the loss (cost) function (trying to minimize).
 - Objective function $(\theta) = L(\theta) + \Omega(\theta)$
 - L(θ) is loss function
 - $\Omega(\theta)$ is regularization term
 - The main benefit of regularization is to mitigate overfitting.
 - Regularized models are able to generalize well on the unseen data.
 - A complex NN makes training model more prone to overfitting.
 - Regularization makes slight modifications to the learning algorithm such that the model generalizes better.

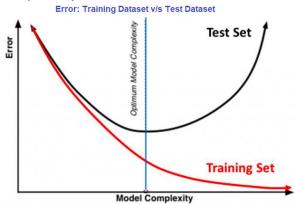
- Two ways to apply regularization to learning models:
- By adding another term to the loss function
 - We are trying to minimize
 - The objective function consists of two parts: loss function and regularization term:
 - Objective function $(\theta) = L(\theta) + \Omega(\theta)$
 - **L**(θ) is loss function
 - \square $\Omega(\theta)$ is regularization term
- By early stopping the learning process
 - during the training phase
 - The perfect example of this method is stopping the growth of a decision tree at an early stage.

- Performing L2 regularization encourages the weight values towards zero (but not exactly zero)
- Performing L1 regularization encourages the weight values to be zero
- Intuitively speaking smaller weights reduce the impact of the hidden neurons.
- Less complex models typically avoid modeling noise in the data, and therefore, there is no overfitting.
- When choosing the regularization term α .
- The goal is to strike the right balance between low complexity of the model and accuracy
- If your alpha value is too high, your model will be simple, but you run the risk of underfitting your data.
- Your model won't learn enough about the training data to make useful predictions.
- If α value is too low, your model will be more complex, and you run the risk of overfitting your data.
- Your model will learn too much about the particularities of the training data, and
 - won't be able to generalize to new data.

- As we move towards the right in this image our model tries to learn too well the details and
- the noise from the training data, which ultimately results in poor performance on the unseen data.

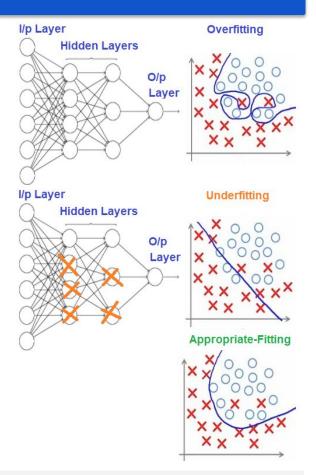


- While going towards the right
 - o Complexity of the model increases such that the training error reduces but the testing error doesn't.



Model Evaluation: Regularization

- How does Regularization help reduce Overfitting?
- NN which is overfitting on the training data (TD) as shown (top)
- In ML, Regularization penalizes the coefficients
- In DL, it actually penalizes the weight matrices of the nodes.
- Assume that our regularization coefficient is so high
 - that some of the weight matrices are nearly equal to zero.
- It result in a much simpler linear NN & slight underfitting of TD (middle)
- Such a large value of the regularization coefficient is not that useful
- We need to **optimize** the value of regularization coefficient in order to obtain a well-fitted model as shown (bottom)



Model Evaluation: Regularization Techniques

- Different techniques in order to apply regularization in learning for reducing overfitting
 - Ridge (apply L2 regularization)
 - Lasso (apply L1 regularization)
 - Elastic Net (Apply both L1 and L2 regularization)
 - Dropout regularization
 - Data augmentation
 - Early stopping
- What does Regularization achieve?
- Performing L2 regularization encourages the weight values towards zero (but not exactly zero)
- Performing L1 regularization encourages the weight values to be zero
 - o Intuitively speaking smaller weights reduce the impact of the hidden neurons.
 - o These hidden neurons become neglectable (dropouts) and
 - Overall complexity of the neural network gets reduced

Model Evaluation: Regularization Techniques

- L1 and L2 Regularization update the general cost function by adding another term known as regularization term
 - Cost function = Loss (say, binary cross entropy) + Regularization term
- Due to the addition of this regularization term
 - Values of wt. matrices decrease because it assumes NN with smaller wt. matrices leads to simpler models
 - Therefore, it will also reduce overfitting to quite an extent.
- However, this regularization term differs in L1 and L2
- L2 regularization:
 - Lambda is the regularization parameter
 - It is the hyperparameter whose value is optimized for better results.
 - It is also known as weight decay as it forces the weights to decay towards zero (but not exactly zero)
- L1 regularization:
 - We penalize the absolute value of the weights
 - Unlike L2, the weights may be reduced to zero here.
 - Hence, it is very useful when we are trying to compress our model.
 - Otherwise, we usually prefer L2 over it



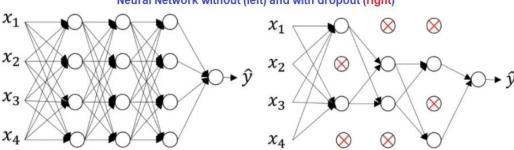
Model Evaluation: Regularization Techniques

- How to apply regularization to any layer in keras
- Sample code to apply L2 regularization to a Dense layer.
 - from keras import regularizers
 - model.add(Dense(64, input_dim=64, kernel_regularizer=regularizers.l2(0.01)
- Note:
 - Here, value of regularization parameter, i.e., lambda = 0.01, which we need to optimize further
 - We can optimize it using the grid-search method.
- Similarly, we can also apply L1 regularization

Model Evaluation: Dropout Regularization

- Dropout Regularization is simple and famous and powerful regularization technique
- Dropout means that with some probability P a neuron of the NN gets turned off during training (see figure)
 - Left side of Fig.: Assume we have a feedforward neural network with no dropout
 - Right side of Fig.: Using dropout with say a probability of P=0.5 that a random neuron gets turned off
- Observe that approximately half of the neurons are not active and are not considered as a part of the NN
- Now NN is no more complex rather observe that the NN becomes simpler.
- A simpler version of the NN results in less complexity that can reduce overfitting.
- Deactivation of neurons with a certain probability P is applied at each forward propagation and weight update step.

 Neural Network without (left) and with dropout (right)



Model Evaluation: Dropout Regularization

- At every iteration
 - o Dropout operation randomly selects few nodes & removes it along with in and outgoing wt. connections
- So each iteration has a different set of nodes and this results in a different set of outputs.
- It can also be thought of as an ensemble technique in machine learning.
- Ensemble models usually perform better than a single model as they capture more randomness.
- Similarly, dropout also performs better than a normal NN model.
- This probability of choosing how many nodes should be dropped is the hyperparameter of the dropout function.
- Dropout can be applied to both the hidden layers as well as the input layers.
- Due to these reasons, dropout is usually preferred when we have a large/complex NN structure
- The probability (say .25) of dropping can decided for tune the model
- We can tune it further for better results using the grid search method.
- In keras, we can implement dropout using the keras core layer.

Model Evaluation: Regularization

- Data Augmentation
- The simplest way to reduce overfitting is to increase the size of the training data
- In machine learning, we were not able to increase the size of training data as the labeled data was too costly.
- In case images, there are a few ways of increasing the size (some transformation) of the training data
 - o rotating the image, flipping, scaling, shifting, etc.
- This technique of applying transformation is known as data augmentation
- This usually provides a big leap in improving the accuracy of the model
- It can be considered as a mandatory trick in order to improve our predictions.
- In keras, we can perform all of these transformations using ImageDataGenerator.
 - It has a big list of arguments which you you can use to pre-process your training data.

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Model Evaluation: Regularization

- Early stopping
- If performance on validation set is getting worse, we stop training immediately. This is known as early stopping.
- It is a kind of cross-validation strategy where we keep one part of the training set as the validation set
- Stop training at the dotted line since after that our model will start overfitting on the training data.
- In keras, we can apply early stopping using the callbacks function.
 - o from keras.callbacks import EarlyStopping
 - EarlyStopping(monitor='val_err', patience=5)
- Here, monitor denotes the quantity that needs to be monitored and 'val_err' denotes the validation error.
- Patience denotes the number of epochs with no further improvement after which the training will be stopped
- After the dotted line, each epoch will result in a higher value of validation error.
- So, patience (5 epochs) after the dotted line, our model will stop because no further improvement is seen.
- Note: We need to take extra care while tuning this hyperparameter
 - As after 5 epochs, the model may starts improving again and the validation error starts decreasing as well.

Summary

- Overfitting occurs in more complex neural network models (many layers, many neurons)
- Complexity of the neural network can be reduced by using L1 and L2 regularization as well as dropout
- L1 regularization
 - o forces the weight parameters to become zero
- L2 regularization
 - o forces the weight parameters towards zero (but never exactly zero)
- ullet Smaller weight parameters make some neurons neglectable o NN becomes less complex o less overfitting
- During dropout
 - \circ Some neurons get deactivated with a random probability P \to NN becomes less complex \to less overfitting

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Model Improvement (Ensemble Learning)

- Refer slide
 - vsat2k_ML_Ch1c Model Improvement (Ensemble Learning) [PDF]

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References

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Thank You.

