	Finolex Academy of Management and Technology, Ratnagiri							
रिशिविक्षेत्रीत कर्मजा	Department of Information Technology							
Subject name: Intelligent System Labs					Subject Code: BEITC703			
Class	BE IT	Semester – (CBGS)	VII	Academic year: 2019-20				
Name of Student	Kazi Jawwad A R	him QUIZ Score :						
Roll No	29	Assignment/Experiment No.			03			
Title: To implement 8 puzzle problem with Heuristic function using Hill climbing.								

1. Course objectives applicable: COB2.Understand the different informed search techniques to solve the different AI problems like 8 puzzle

2. Course outcomes applicable:

CO2 –Solve the problems based on informed searching techniques.

3. Learning Objectives:

- 1. To understand different informed search techniques.
- 2. To understand 8 puzzle problem
- 3. To program 8 puzzle problem using hill climbing algorithm.
- 4. To get the output this will calculate the elapsed time and heuristic function value to get goal state.
- 4. Practical applications of the assignment/experiment: sliding puzzle game application

5. Prerequisites:

- 1. To learn the use of intelligent agents in informed search.
- 2. To understand the programming methodology for 8 puzzle problem.

6. Hardware Requirements:

1. PC with minimum 2GB RAM

7. Software Requirements:

- 1. Windows installed
- 2. JDK/Net beans

8. Quiz Questions (if any): (Online Exam will be taken separately batchwise, attach the certificate/ Marks obtained)

- 1. How informed search strategies are defined?
- 2. In Best First search node is selected for expansion on which basis?
- 3. Which is the type of hill climbing?
- 4. Which is not drawback of hill climbing?

9. Experiment/Assignment Evaluation:								
Sr. No.	Parameters		Marks obtained	Out of				
1	Technical Understanding (Asse A <u>or</u> any other relevant method. method used -		6					
2	Neatness/presentation		2					
3	Punctuality		2					
	of performance (DOP) of checking (DOC)	Total marks obtained Signature of teacher		10				

11. Precautions:

- 1. Generate all possible next steps of the solution.
- 2. Set the directions in which tiles should be moved.

```
12. Installation Steps / Performance Steps –
import java.util.Arrays;
import java.util.Comparator;
import java.util.HashSet;
import java.util.PriorityQueue;
public class EightPuzzle {
  static final byte [] goalTiles = { 1, 2, 3, 4, 5, 6, 7, 8, 0 };//Tiles for completed puzzle
  final PriorityQueue <State> queue = new PriorityQueue <State>(100, new Comparator <State>()
     @Override
     public int compare(State a, State b) {
       return a.priority() - b.priority();
  });
  //The closed state set.
  final HashSet <State> closed = new HashSet <State>();
  class State
     final byte [] tiles; //Tiles left to right,top to bottom
     final int spaceIndex; //Index of spaces zero(blank slide)
     final int g;
                      //No of moves from start
     final int h;
                       //Heuristic value i.e.differencefrom goal state
     final State prev;
                         //previous state
     int priority()
       return g + h;
     State(byte [] initial) //Build starting state
       tiles = initial;
       spaceIndex = index(tiles, 0);
       g = 0;
       h = heuristic(tiles);
       prev = null;
     }
     State(State prev, int slideFromIndex) //Build successor to previous by sliding from current
state
       tiles = Arrays.copyOf(prev.tiles, prev.tiles.length);
```

tiles[prev.spaceIndex] = tiles[slideFromIndex];

```
tiles[slideFromIndex] = 0;
  spaceIndex = slideFromIndex;
  g = prev.g + 1;
  h = heuristic(tiles);
  this.prev = prev;
boolean isGoal() //Will return true value if goal test succeed
  return Arrays.equals(tiles, goalTiles);
}
//Successor moves to south, north, east aand west sides.
State moveS() { return spaceIndex > 2 ? new State(this, spaceIndex - 3) : null; }
State moveN() { return spaceIndex < 6 ? new State(this, spaceIndex + 3) : null; }
State moveE() { return spaceIndex \% 3 > 0 ? new State(this, spaceIndex - 1) : null; }
State moveW() { return spaceIndex \% 3 < 2 ? new State(this, spaceIndex + 1) : null; }
void print() //Printing the current state
  System.out.println(" p = " + priority() + " = h = " + h);
  for (int i = 0; i < 9; i += 3)
     System.out.println(" " + tiles[i] + " " + tiles[i+1] + " " + tiles[i+2]);
}
void printAll() //Print the solution chain fromstart state
  if (prev != null) prev.printAll();
  System.out.println();
  print();
}
@Override
public boolean equals(Object obj)
  if (obj instanceof State)
     State other = (State)obj;
     return Arrays.equals(tiles, other.tiles);
  return false;
}
@Override
public int hashCode()
  return Arrays.hashCode(tiles);
```

}

```
void addSuccessor(State successor) //adds the valid successor i.e.non null and not closed
  if (successor != null && !closed.contains(successor))
     queue.add(successor);
void solve(byte [] initial) //Running the solver
     {
  queue.clear();
  closed.clear();
  long start = System.currentTimeMillis(); //capturing the systems time elapsed to solve
  queue.add(new State(initial));
  while (!queue.isEmpty()) {
     State state = queue.poll();
     if (state.isGoal())
       long elapsed = System.currentTimeMillis() - start;
       state.printAll();
       System.out.println(" Elapsed (ms) = " + elapsed);
       return;
     closed.add(state); //To make sure that we are not evisiting states
     addSuccessor(state.moveS());
     addSuccessor(state.moveN());
     addSuccessor(state.moveW());
     addSuccessor(state.moveE());
  }
}
static int index(byte [] a, int val) //Returns the index of value in given byte of array
  for (int i = 0; i < a.length; i++)
     if (a[i] == val) return i;
  return -1;
}
```

static int manhattanDistance(int a, int b) //Returns manhatan distance between tiles with indices a and b

```
{
  return Math.abs(a / 3 - b / 3) + Math.abs(a % 3 - b % 3);
}

static int heuristic(byte [] tiles)
{
  int h = 0;
  for (int i = 0; i < tiles.length; i++)
      if (tiles[i] != 0)
      h = Math.max(h, manhattanDistance(i, tiles[i]));
  return h;
}

public static void main(String[] args) {

  byte [] initial = { 7, 2, 3, 5, 8, 0, 1, 6, 4 };//Initial state is provided to system

  //byte [] initial = { 1, 4, 2, 3, 0, 5, 6, 7, 8 };

  new EightPuzzle().solve(initial);
}
</pre>
```

14. Results:

```
E:\Practicals\ISL\exp3>javac EightPuzzle.java
E:\Practicals\ISL\exp3>java EightPuzzle
 p = 3 = h = 3
 5 8 0
 1 6 4
 p = 4 = h = 3
   2 3
 5 0 8
  1 6 4
  p = 5 = h = 3
  723
  5 6 8
  1 0 4
 p = 6 = h = 3
  7 2 3
 5 6 8
 1 4 0
   = 7 = h = 3
   2 3
  5 6 0
  1 4 8
```

```
p = 8 = h = 3
7 2 3
5 0 6
1 4 8
p = 9 = h = 3
0 5 6
1 4 8
p = 10 = h = 3
0 2 3
1 4 8
p = 11 = h = 3
2 0 3
7 5 6
1 4 8
p = 12 = h = 3
2 5 3
7 0 6
1 4 8
p = 13 = h = 3
2 5 3
0 7 6
1 4 8
p = 14 = h = 3
2 5 3
1 7 6
0 4 8
p = 15 = h = 3
2 5 3
4 0 8
p = 16 = h = 3
2 5 3
1 0 6
4 7 8
p = 17 = h = 3
2 0 3
1 5 6
4 7 8
p = 18 = h = 3
0 2 3
1 5 6
4 7 8
p = 19 = h = 3
1 2 3
0 5 6
4 7 8
```

```
p = 20 = h = 3
1 2 3
4 5 6
0 7 8

p = 21 = h = 3
1 2 3
4 5 6
7 0 8

p = 22 = h = 3
1 2 3
4 5 6
7 8 0
Elapsed (ms) = 62

E:\Practicals\ISL\exp3>
```

15. Learning Outcomes Achieved

- 1. Understood the concept of informed search.
- 2. Used heuristic function to solve 8 puzzle problem using hill climbing algorithm.

16. Conclusion:

1. Applications of the studied technique in industry

a. Heuristic functions are used to find the solution path based on path cost which is used to develop game application like sliding puzzle.

2. Engineering Relevance

a. Such algorithms are very useful in searching techniques where problems are more complex.

3. Skills Developed

a. Implementation of hill climbing algorithm to solve 8 puzzle problem.

17. References:

- [1] G. Görz, C.-R. Rollinger, J. Schneeberger (Hrsg.) "Handbuch der künstlichen Intelligenz" Oldenbourg Verlag, 2003, Fourth edition
- [2] Turing, A. "Computing Machinery and Intelligence", Mind LIX (236): 433–460, Ocotober, 1950.
- [3] Aristotle "On Interpretation", 350 B.C.E, see: http://classics.mit.edu/Aristotle/interpretation.html
- [4] Newell, A., Simon, H.A. "Human Problem Solving" Englewood Cliffs, N.J.: Prentice Hall, 1972.