# CIS 604 Techniques in Artificial Intelligence Introduction

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Credits for slides: Dr. Iyad Rahwan

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#### The Instructor

#### **Education**

- B.Sc.\* Computer Science, Århus, Denmark
- M.Sc. Computational Logic, TU Dresden, Germany
- Ph.D. BioTec TU Dresden, Germany

#### Research

- Bioinformatics: Classification of Protein-Protein Interactions, Computational Miocrobial Ecology/Metagenomics, Phenotype prediction from genotype
- Text mining: Ontologies, Information Retrieval, Technology Forecasting

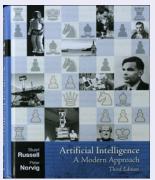
#### **More Details**

Masdar Faculty website, www.masdar.ac.ae

#### **Material**

#### Literature

 Main Textbook: Stuart Russell and Peter Norvig. Artificial Intelligence: A Modern Approach. Prentice Hall 3rd Edition, 2010



Various handouts

## **Further Reading**

# ... and watching $\ddot{-}$

- AIMA web site: http://aima.cs.berkeley.edu/
- Online book on Artificial Intelligence artint.info
- Stanford Online course by Norvig and Thrun www.ai-class.com
- Online classes by S. Thrun www.udacity.com (Robotics, Search Engine)
- bernardwelt.blogspot.com/2011/08/ human-body-is-machine-which-winds-its.html

#### **Assessment**

# **Teaching philosophy**

- Interactive, personalized classroom
- Detailed study at home

#### **Assessment**

- 20% Assigment 1
- 20% Mid-term exam (in class)
- 20% Assigment 2
- 30% Final exam
- 10% Participation: class, moodle, quizzes

Assignment	Handed	Due
1	Week 4	Week 10
2	Week 8	Week 14

## **Getting Help**

- Office hours: 1.30pm-2.30pm on class days (prior appointment required)
- Outside office hours:
  - Post questions on "the Source" (course management system) https://source.masdar.ac.ae
  - Other students who answer will get "participation credit"

## **Schedule**

Week	Topic (tentative)	Chapter
1	Introduction, search techniques	1,2,3
2	More search techniques	3,4
3	Adversarial Search + Constraint Satisfaction Problems	5,6
4	Propositional Logic	7
5	First Order Logic	8,9
6	Planning	10,11
7	Ontologies	12
8	Revision + Mid-term exam	-
9	Uncertainty	13
10	Probabilistic Reasoning with Bayesian Networks	14
11	Probabilistic Reasoning over Time	15
12	Decision Theoretic Agents	16
13	Sequential Decision Making & Markov Decision Processes	17
14	Reinforcement Learning	21
15	Hidden Markov Models and NLP	
16	Revision + Final Exam	-

## **Prerequisites**

#### Math

- Basic set theory and discrete mathematics
- Basic probability theory

# **Algorithms**

- Basic data structures (lists, queues, trees, graphs)
- Basic algorithmic techniques (loops, conditions, recursion)

You can learn these things as we go!

## **Programming**

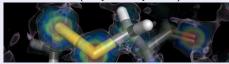
# **Python**

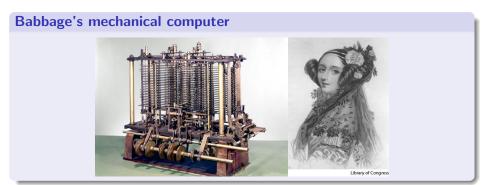
- Easy-to-learn, easy-to-read
- Interpreted language, interactive (slow, but...)
- Widespread (also in AI, see Further Material), multi-purpose
- AIMA pseudo code uses similar syntax
- Extensive libraries:





- NIP: NITK
- Graph theory (networkx)
- Visualization (MayaVi, PyMOL)





# **Rodney Brooks Robotics**



http://www.youtube.com/watch?v=Uqt\_pRbR8rI&feature=player\_embedded#!

# IBM's Deep Blue beats Garry Kasparov in 1997





# "Curiosity" spectacularly lands on Mars



## **Driverless cars**



http:

//www.youtube.com/watch?v=C9p8B7-5MTI

#### Roots of Al

#### Fields of relevance

- **Philosophy** logic, methods of reasoning, mind as physical system foundations of learning, language, rationality,
- Mathematics formal representation and proof, algorithms, computation, (un)decidability, (in)tractability probability
- **Psychology** adaptation, phenomena of perception and motor control, experimental techniques (psychophysics, etc.)
- **Economics** formal theory of rational decisions
- **Linguistics** knowledge representation, grammar
- Neuroscience plastic physical substrate for mental activity
- **Control theory** homeostatic systems, stability, simple optimal agent designs

# **Al History**

1943	McCulloch & Pitts: Artificial Neuron		
1950	Turing's "Computing Machinery and Intelligence"		
1950s	Early AI programs, Checkers, Backgammon		
	"General Problem solver"		
1956	Dartmouth meeting: "Artificial Intelligence" adopted		
1966–74	Al discovers computational complexity		
	Neural network research almost disappears		
1969–79	Early development of knowledge-based systems		
1980-88	Expert systems industry booms		
1988–93	Expert systems industry busts: "Al Winter"		
1985–95	Neural networks return to popularity		
1988–	Resurgence of probability; Genetic Algorithms, ALife, soft		
	computing		
1995–	Agents, agents, everywhere		
2003-	Human-level AI back on the agenda		

# **AI Technologies**

# Technologies invented in Al labs

- Time Sharing
- GUIs + mouse
- Rapid development environments
- The linked list data type
- Automatic storage management
- Symbolic programming (e.g. PROLOG)
- Functional programming (e.g. LISP)
- Object-oriented programming
- Dynamic programming

## **AI Technologies Today**

- Knowledge representation and reasoning
- Search Algorithms, Constraint Processing
- Machine Learning
- Natural Language Processing
- Planning and Scheduling
- Computer Vision
- Robotic Control
- Multi-agent systems (distributed AI)

# **Applications of AI**

- Finance
- Medicine
- Electrical Engineering
- Security
- Bioinformatics
- Military

#### What is AI?

## **Traditional views**

	human-centered	rationality-centered
Think	think like humans	think rationally
Act act like humans act ratio		act rationally

## Thinking humanly

## **Cognitive Science**

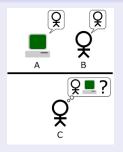
- based on information-processing psychology (1960s)
- Validation requires scientific theories of internal activities of the brain
  - Cognitive Science (predicting and testing behavior of human subjects)



- Cognitive Neuroscience (Neurological data)
- Both fields nowadays distinct from AI

# **Acting humanly**

## **Turing Test**





Turing Test

Alan M. Turing (1950)

- Turing's prediction: By 2000, a bot can fool 30% of judges
- 2014 Eugene Goostman: simulating an Ukrainian boy could fool 33% of judges, considered the first "pass", disputed
- Problem: Turing test is not reproducible, constructive, or amenable to mathematical analysis

## Thinking rationally

# "Laws of thought" approach

- Logic: precise notation for statements about all kinds of objects
- Problems:
  - Formalization
  - Uncertainty
  - Computable often only for small instances

## **Acting rationally**

- An agent is an entity that can perceive and act
- This course is about designing rational agents
- Rational behavior: doing the right thing
- The right thing: what is expected to maximize goal achievement, given available information, doesn't necessarily involve thinking

# **Environment Types**

## **Types**

- Fully observable (vs. partially observable)
  - An agent's sensors give it access to the complete state of the environment at each point in time
- Deterministic (vs. stochastic)
  - Next state determined by current state and agent's action
  - If environment is deterministic except for the actions of other agents: environment is strategic
- Episodic (vs. sequential)
  - Agent's experience divided into atomic "episodes": each episode consists of the agent perceiving and then performing a single action, choice of action in each episode depends only on current episode

# **Environment Types cont.**

## **Types**

- Static (vs. dynamic):
  - ▶ The environment is unchanged while an agent is deliberating.
  - The environment is semidynamic: if environment does not change but performance score does
- Discrete (vs. continuous):
  - A finite number of distinct, clearly defined percepts and actions
- Single agent (vs. multi-agent)
  - An agent operating by itself in an environment

# **Environment Types cont.**

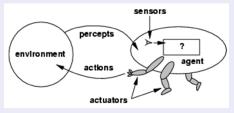
# **Examples**

	Chess	Taxi drive
Fully observable		
Deterministic		
Episodic		
Static		
Discrete		
Single agent		

## What is an Agent?

# Agent Terminology

 An agent is anything that can be viewed as perceiving its environment through sensors and acting upon that environment through actuators



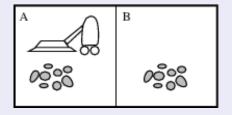
ullet Autonomous: Actions  ${\mathcal A}$  determined by Percepts  ${\mathcal P}$ 

$$f: \mathcal{P}^* \to \mathcal{A}$$

 We want: best performance for every environment → requires performance measure

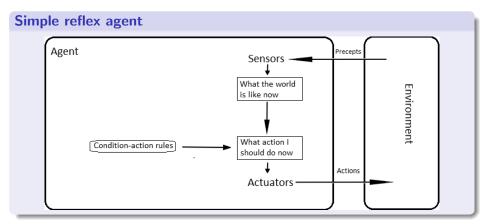
## **Example Agent**

#### Vacuum cleaner



- ullet  $\mathcal{P}$ : location, dirty/clean [A, dirty]
- A: GoLeft, GoLeft, Clean, Idle
- Question: Size of State space?
- for 10 rooms, 5 levels of dirt?

# **Simple Reflex Agent**



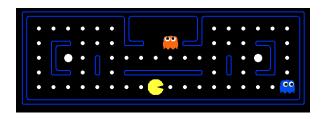
# Reflex agents cont.

# Rodney Brooks - Behavioral Robotics



- One school of thought: "The world is its own best model"
- Cog Project ("Cockroach robotics")

## Reflex Agent cont.

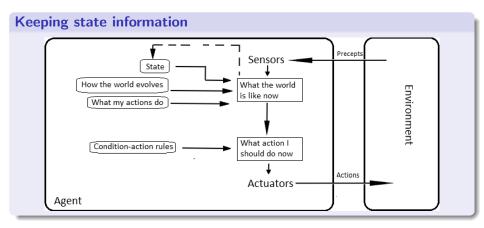


# **PacmanReflexAgent**

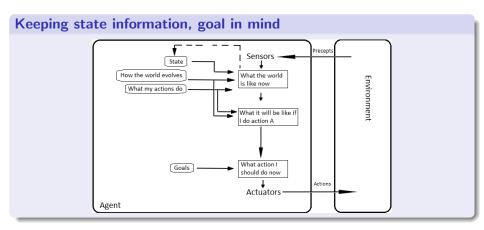
if wall in front of me then
 turn right
else
 move forward
end if

Can a reflex agent be rational (optimal)?

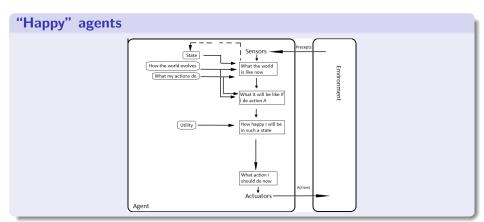
# Model based reflex agent



# Model based goal based agent



# **Utility based agent**



## **Required Reading**

#### Literature

- Stuart Russell and Peter Norvig. Artificial Intelligence: A Modern Approach. Prentice Hall, 3rd edition, 2010
  - Chapter 1
  - Chapter 2

"Education is the path from cocky ignorance to miserable uncertainty"

Mark Twain