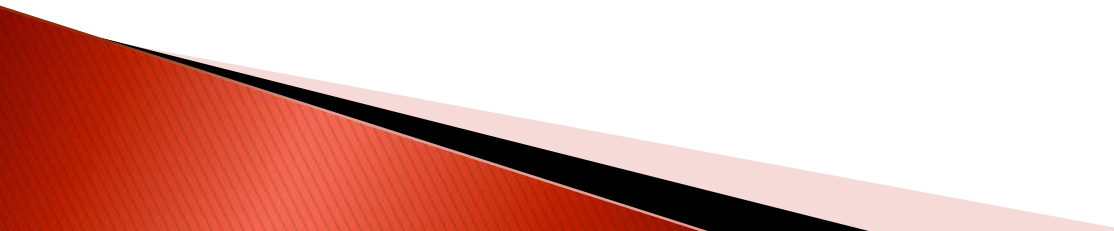


# CSI 3200 Micro-Computer Graphics Collision Detection/Response

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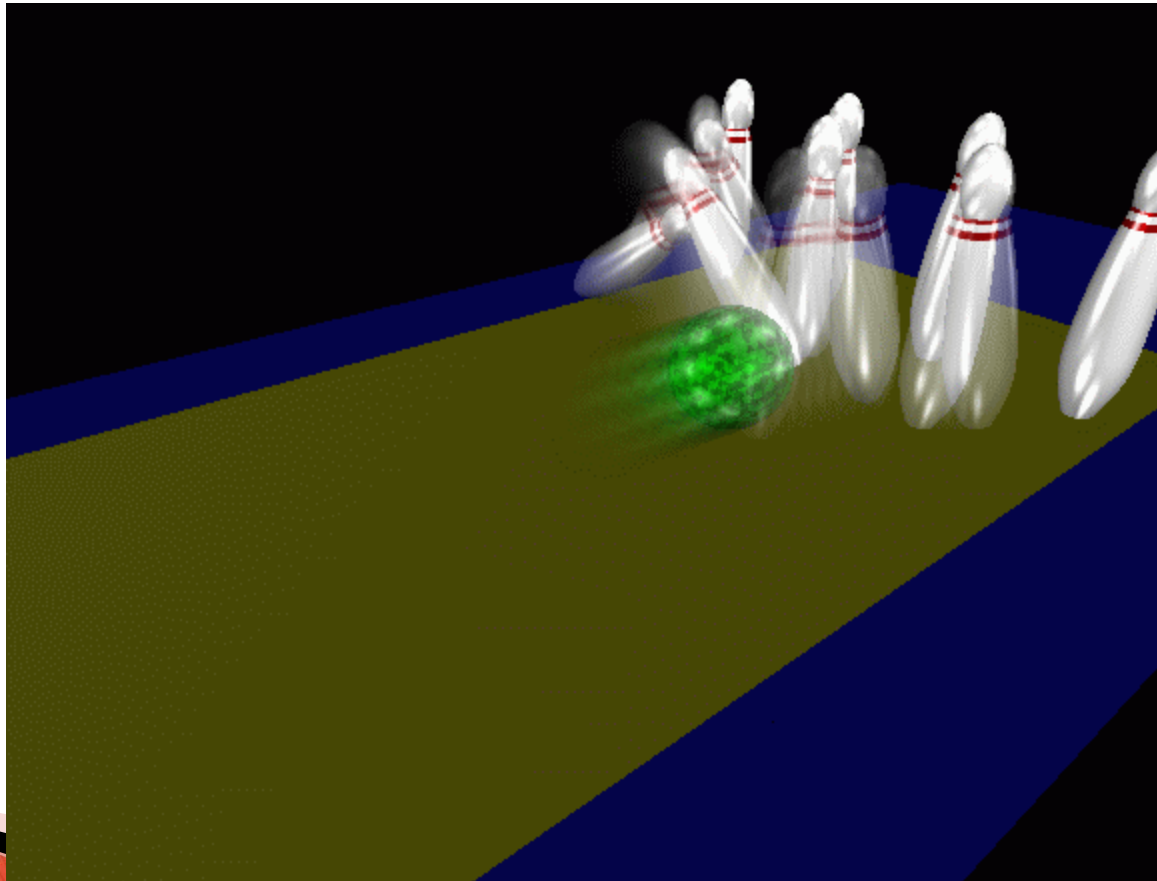


# Outline

- ▶ What is collision detection?
  - ▶ Collision Response
  - ▶ Classical Situation
  - ▶ Implementation
    - Approach
    - Implementation 1....2
    - Portal Engines and Object–Object Collisions
  - ▶ Questions
  - ▶ Resources
- 

# What is collision detection?

- ▶ The observation of intersection (close-to) of two or more object in (2D/3D) space



# Collision Response

- ▶ The programmed reaction for a collision
- ▶ Heavily dependant on
  - Desired natural reaction of the simulated objects, or
  - The desired effect



# Consider the following areas

- ▶ Video games
- ▶ Simulations/Training
- ▶ Robotics



# Classical Situations

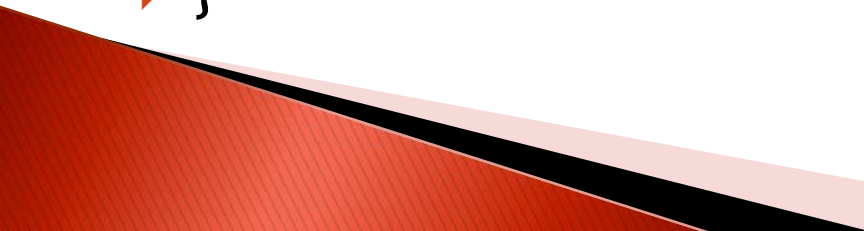
- ▶ Boundaries created by walls/floors
- ▶ Interaction between two or more objects in space
- ▶ Consider normal physical phenomena and the effects
  - Gravity
  - Elasticity
  - Limits
- ▶ General Areas
  - Polygonal Collision Detection
  - Curved Surfaces

# \*Approach

- ▶ Start planning and creating its basic framework at the same time that we're developing a game's graphics pipeline
- ▶ Building a quick collision detection hack near the end of a development cycle will probably ruin the whole game because it'll be impossible to make it efficient.
- ▶ In a perfect game engine, collision detection should be precise, efficient, and very fast.
- ▶ These requirements mean that collision detection has to be tied closely to the scene geometry management pipeline.
- ▶ Brute force methods won't work — the amount of data that today's 3D games handle per frame can be mind-boggling. Gone are the times when you could check each polygon of an object against every other polygon in the scene.

# Implementation 1

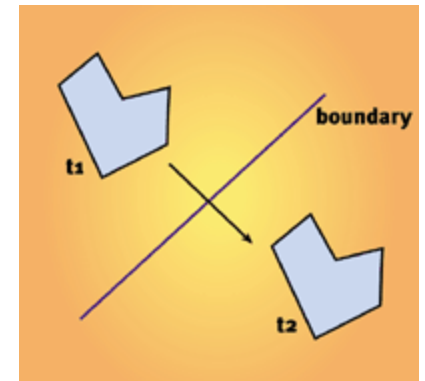
```
▶ while(1){  
    process_input();  
    update_objects();  
    render_world();  
}  
▶ update_objects(){  
    for (each_object)  
        save_old_position();  
        calc new_object_position  
        {based on velocity accel. etc.}  
        if (collide_with_other_objects())  
            new_object_position = old_position();  
            {or if destroyed object remove it etc.}  
▶ }
```





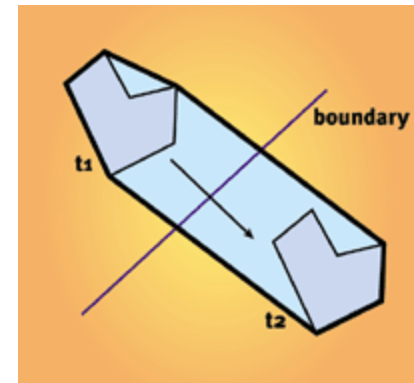
# Problems with Implementation 1

- ▶ No consideration for time in our equation
- ▶ If an object doesn't collide at time  $t_1$  or  $t_2$ , it may cross the boundary at time  $t$  where  $t_1 < t < t_2$
- ▶ This is especially true when we have large jumps between successive frames



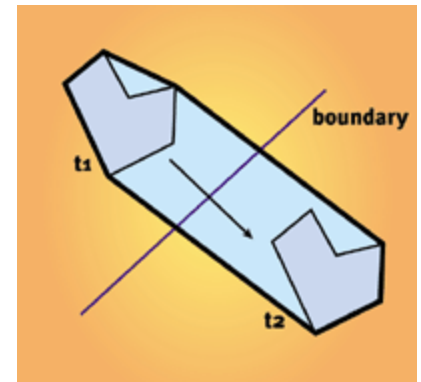
# Alternatively

- ▶ We could also create a solid out of the space that the original object occupies between time  $t_1$  and  $t_2$  and then test the resulting solid against the collision boundary
- ▶ This approach is very inefficient and will definitely slow down your game



# Implementation 2

- ▶ Subdivide the given time interval in half and test for intersection at the midpoint
- ▶ This approach will be faster than the previous method, but it's not guaranteed to catch all of the collisions

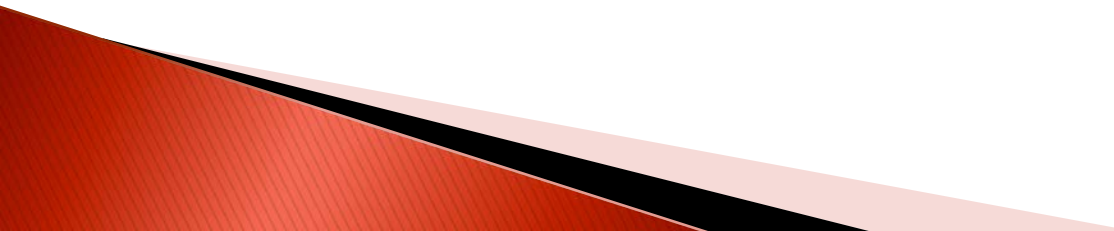


# Consider

- ▶ `collide_with_other_objects()` routine
- ▶ If we have a lot of objects in the scene, this routine can get very costly (using the previous methods)

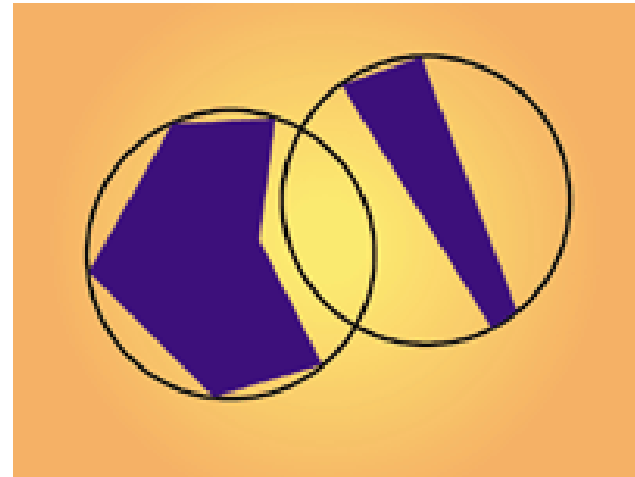


# Portal Engines and Object–Object Collisions

- ▶ Portal–based engines divide a scene or world into smaller convex polyhedral sections
  - ▶ Convex polyhedra are well–suited for the graphics pipeline because they eliminate overdraw
  - ▶ Determining whether an object’s polygons penetrate the world polygons can be computationally expensive
  - ▶ One of the most primitive ways of doing collision detection is to approximate each object or a part of the object with a sphere, and then check whether spheres intersect each other
  - ▶ This method is widely used even today because it’s computationally inexpensive
- 

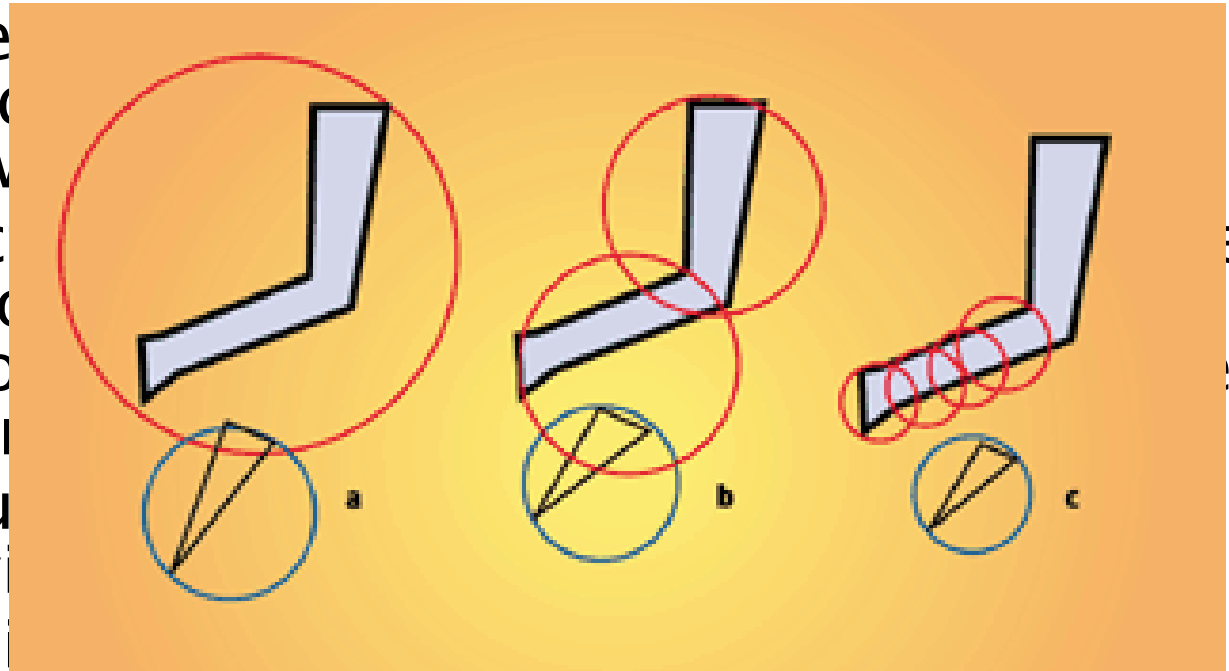
# Portal Engines and Object–Object Collisions

- ▶ We check whether the distance between the centers of two spheres is less than the sum of the two radii (which indicates that a collision has occurred)



# Portal Engines and Object-Object Collisions

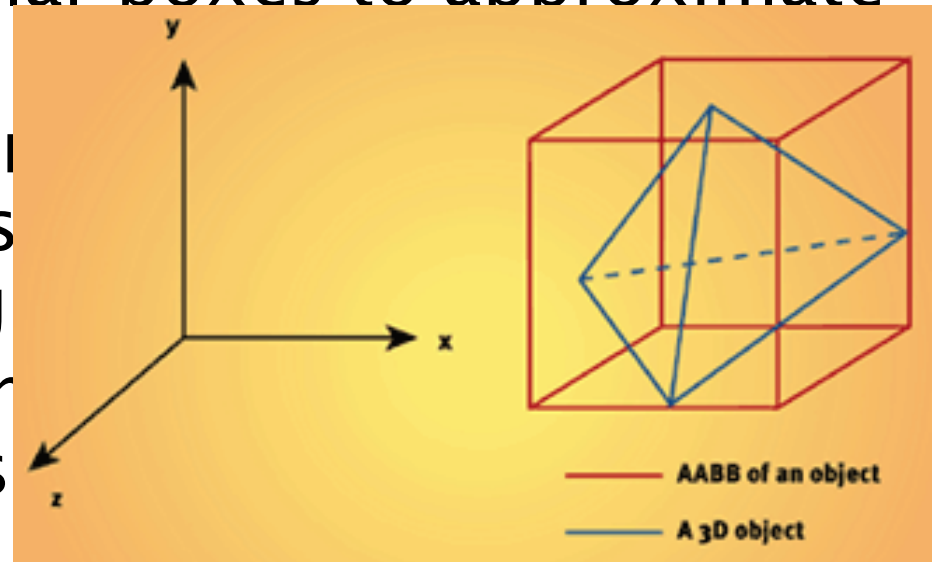
- ▶ But what if we use this imprecise method as simply a first step.
- ▶ We represent the object as a sphere, and check if it intersects with the portal.
- ▶ If we detect an intersection, we refine the precision by representing the object as a set of spheres, and check if any of them intersects with the portal.
- ▶ We continue this process until we are satisfied with the precision.
- ▶ This basic method is what we'll try to perfect to suit our needs.





# Portal Engines and Object-Object Collisions

- ▶ Using spheres to approximate objects is computationally inexpensive, but because most geometry in games is square, we should try to use rectangular boxes to approximate objects
- ▶ Developers have long used axis-aligned bounding boxes (AABBs) and this recursive subdivision is used in various ray-tracing algorithms
- ▶ In practice, these methods are implemented as octrees and axis-aligned bounding boxes (AABBs)





# Implementation Guidelines

- ▶ “Simple” algorithm for interaction (pools)?
  - Consider
    - Position of the objects
    - Force
    - Mass
    - Acceleration
    - Momentum
    - Velocity

# Collision Detection

- ▶ A huge area of study for design of graphics simulations and games
- ▶ Further area of study
  - Building AABB trees
  - Detecting Collisions Using Hierarchy Trees
  - Collision Techniques Based on BSP Trees
  - Curved Objects and Collision Detection

Questions?

# Collision Detection Further Reading

- ▶ H. Samet. *Spatial Data Structures: Quadtree, Octrees and Other Hierarchical Methods*. Addison Wesley, 1989.
- ▶ • For more information about AABBs take a look at J. Arvo and D. Kirk. “A survey of ray tracing acceleration techniques,” *An Introduction to Ray Tracing*. Academic Press, 1989.
- ▶ • For a transformation speedup, check out James Arvo’s paper in Andrew S. Glassner, ed. *Graphics Gems*. Academic Press, 1990.
- ▶ • S. Gottschalk, M. Lin, and D. Manocha. “OBBTree: A hierarchical Structure for rapid interference detection,” Proc. Siggraph 96. ACM Press, 1996. has contributed a great deal to the discussion of OBBs in terms of accuracy and speed of execution.
- ▶ • S. Gottschalk. *Separating Axis Theorem*, TR96-024, UNC Chapel Hill, 1990.
- ▶ • N. Greene. “Detecting intersection of a rectangular solid and a convex polyhedron,” Graphics Gems IV. Academic Press, 1994. introduces several techniques that speed up the overlap computation of a box and a convex polyhedron.

# Resources

- ▶ [http://www.gamasutra.com/view/feature/131598/advanced\\_collision\\_detection\\_.php](http://www.gamasutra.com/view/feature/131598/advanced_collision_detection_.php)
- ▶ [http://en.wikipedia.org/wiki/Collision\\_detection](http://en.wikipedia.org/wiki/Collision_detection)
- ▶ **Collision Maths**
  - <http://www.edenwaith.com/products/pige/tutorials/collision.php>