

# Embedded MQTT Client in C++14

MQTT Client



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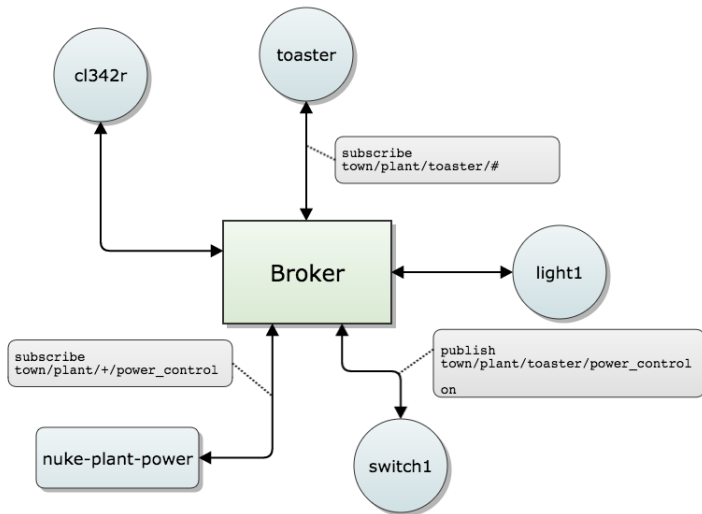
# Part I

## Introduction

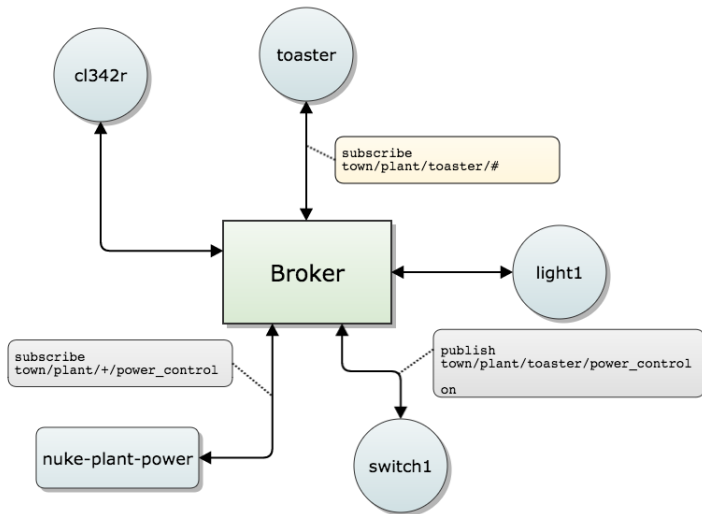
## Message Queue Telemetry Transport

- ▶ ISO Standard protocol
- ▶ Publisher/Subscriber model
- ▶ Considered light-weight
- ▶ Requires a reliable connection

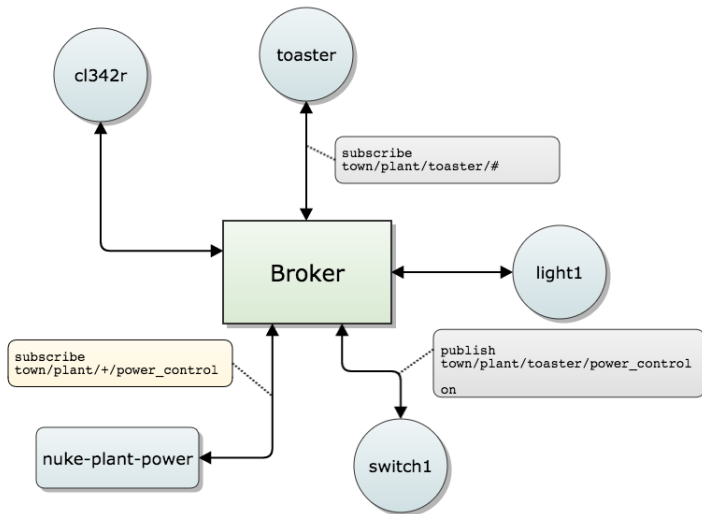
# MQTT



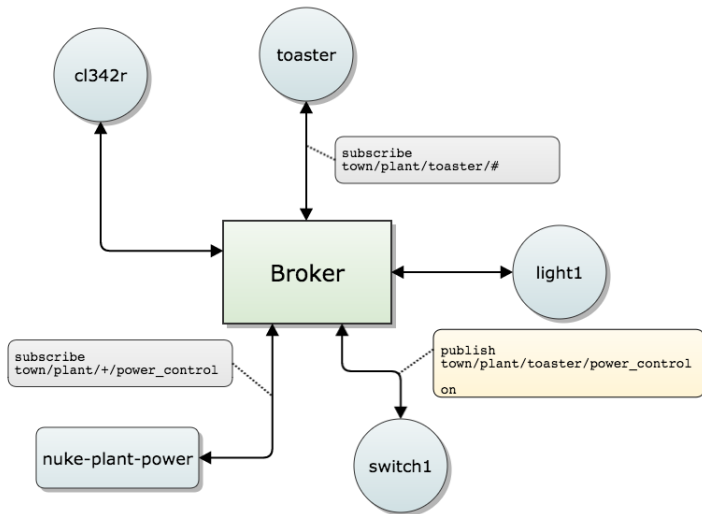
# MQTT



# MQTT

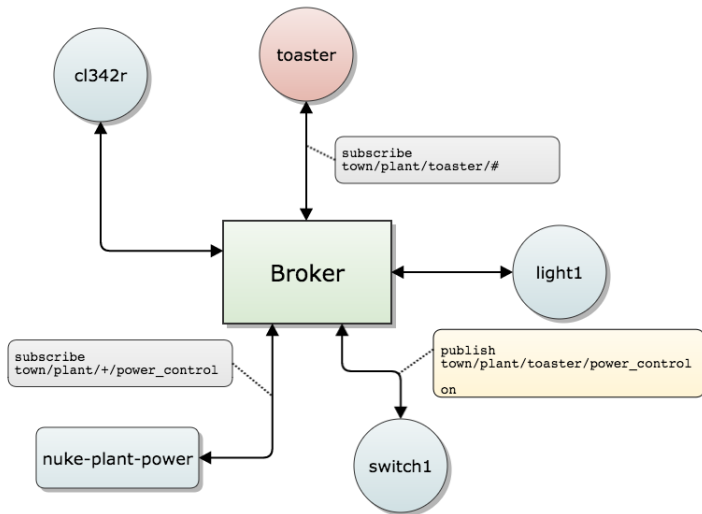


# MQTT

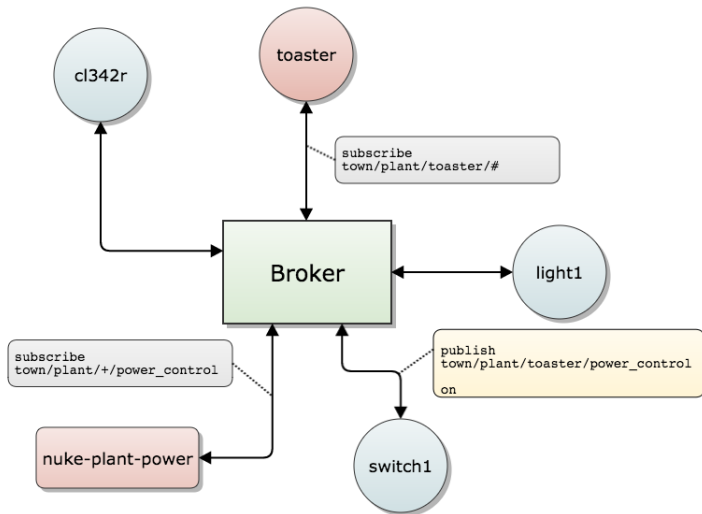




# MQTT



# MQTT



## The basic messages

- ▶ connect
- ▶ disconnect
- ▶ subscribe
- ▶ unsubscribe
- ▶ publish
- ▶ ping

## Three levels of QoS (Quality of Service)

- ▶ At most once delivery - QoS 0
- ▶ At least once delivery - QoS 1
- ▶ Exactly once delivery - QoS 2

# Where used?

MQTT is being used in large and small systems

- ▶ RabbitMQ to small devices
- ▶ Amazon IoT platform
- ▶ Lightbulbs, toasters, coffee makers... (IoT)
- ▶ medical equipment
- ▶ sensors
- ▶ phone applications

# Embedded?

What is embedded?

# C++ on Embedded?

Wut!



this is the code to set a vector to a constant size, initialized to zero.







**Michael Caisse**

@MichaelCaisse

Top 4 reasons you have (or have heard) for not using C++ in "embedded" targets -- Ready? Go!

RETWEETS

2

LIKE

1



10:36 PM - 3 May 2016



**Johnny T**

@FrogShadeGarden



Follow

[@MichaelCaisse](#) More complicated regulatory approval. Smaller developer pool. Bloated binaries. OK, that's all I recall right now.

10:46 PM - 3 May 2016



# #dontcrashmyrover



**clement cole**

@clement\_cole



 Follow

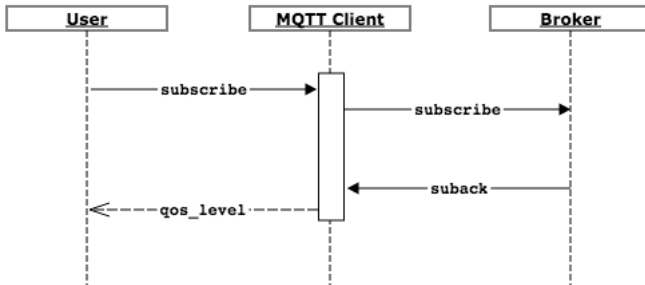
[@MichaelCaisse](#) CS programmers going wild by creating too many levels of abstractions ie templates and causing Mars Climate Observer to crash

6:36 PM - 11 May 2016

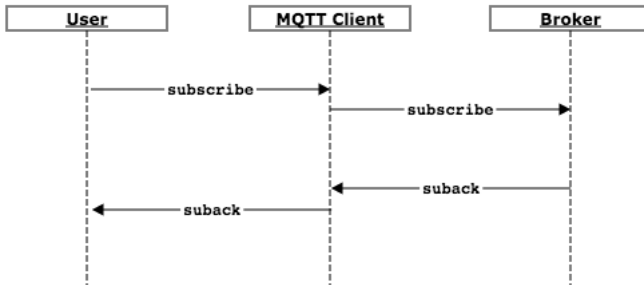


Don't do it!

# Why another library?



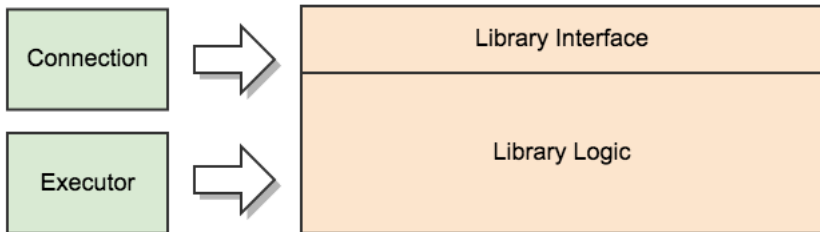
# Why another library?



# Why another library?

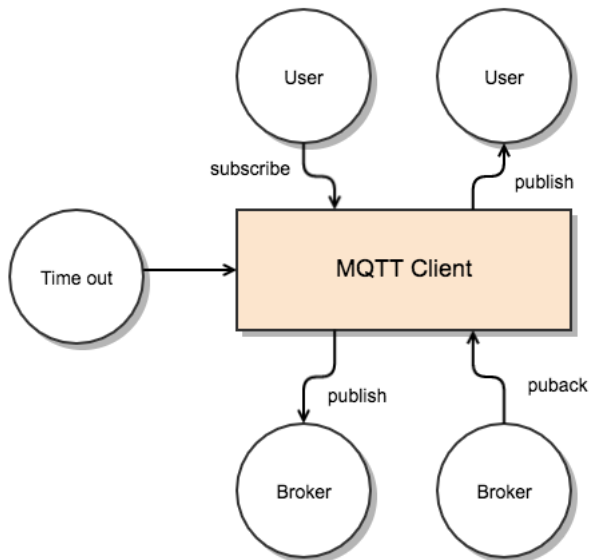
- ▶ Blocking
- ▶ Dependency injection
- ▶ Event notification
- ▶ Executor

# Injection





# Lots going on



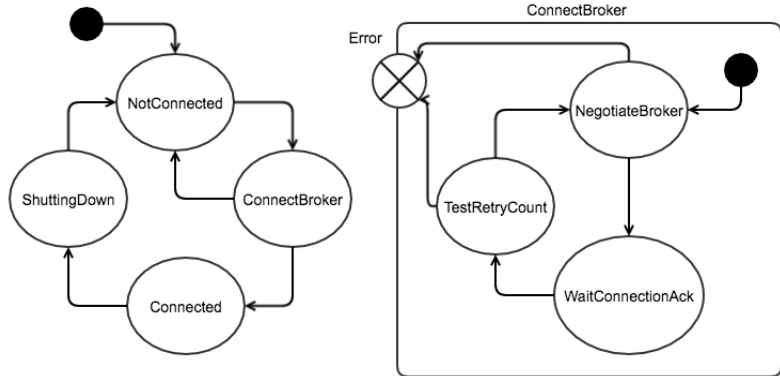
# Chain completion handlers

- ▶ Establish connection
- ▶ Negotiate with broker
- ▶ Subscribe

# Chain completion handlers?

No!

# Hierarchical Finite State-machine

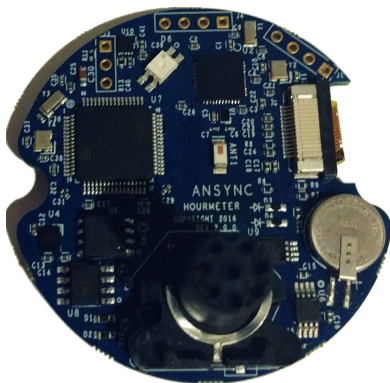


# Target Platform

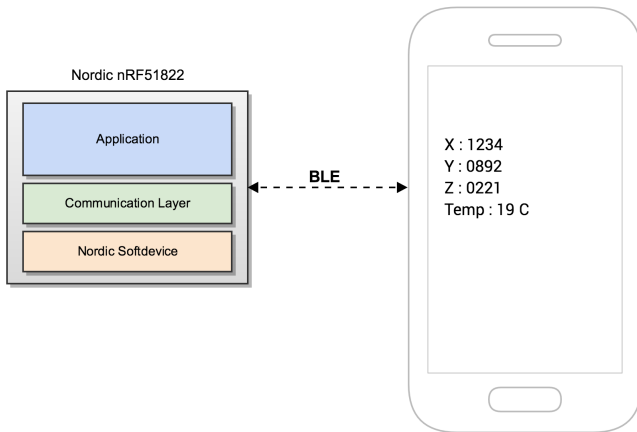
Thank you Ansync Labs!

- ▶ Nordic nRF51822
- ▶ 2.4GHz multiprotocol radio
- ▶ 32-bit ARM(R) Cortex(TM) M0
- ▶ 128KB embedded flash
- ▶ 32KB RAM

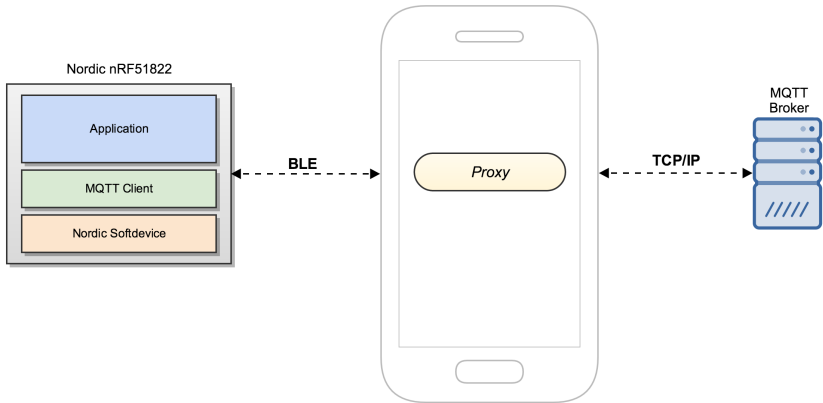
<http://ansync.com>



# The Original Test App



# The Goal



# The Sniped

- ▶ Agustin K-ballo Berge - wrote the Android App!
- ▶ Jeroen Habraken (VeXocide) - X3 contributions





## Part II

# Diving In

# Step 1

Get code to compile with C++.

# Cleaning up

```
static int oled_write(uint8_t *bytes, int count) {  
    int tx = i2c_master_tx(OLED_I2C_ADDRESS, bytes, count);  
    if (tx < 1) return -1;  
    return tx;  
}
```

```
oled_write((uint8_t []){ 0x00, 0xAF }, 2);  
oled_write((uint8_t []){ 0x00, 0x8D, 0x14 }, 3);  
oled_write((uint8_t []){ 0x00, 0xA8, 0x0F }, 3);  
oled_write((uint8_t []){ 0x00, 0xDA, 0x02 }, 3);  
oled_write((uint8_t []){ 0x00, 0x81, 0xFF }, 3);  
oled_write((uint8_t []){ 0x00, 0x82, 0xFF }, 3);  
oled_write((uint8_t []){ 0x00, 0x83, 0xFF }, 3);
```

# Cleaning up

```
int oled_write(uint8_t const * bytes, int count)
{
    int tx = i2c_master_tx( OLED_I2C_ADDRESS
                           , const_cast<uint8_t*>(bytes)
                           , count);

    if (tx < 1) return -1;
    return tx;
}

int oled_write(std::initializer_list<uint8_t> bytes)
{
    return oled_write(bytes.begin(), bytes.size());
}

oled_write({ 0x00, 0xAF });
oled_write({ 0x00, 0x8D, 0x14 });
oled_write({ 0x00, 0xA8, 0x0F });
oled_write({ 0x00, 0xDA, 0x02 });
oled_write({ 0x00, 0x81, 0xFF });
oled_write({ 0x00, 0x82, 0xFF });
oled_write({ 0x00, 0x83, 0xFF });
```

Using: arm-none-eabi-g++ (GCC) 5.1.0

Condition	text	data	bss	total
C99	23576	136	2460	26172
C++14	25404	136	2440	27980

# Exceptions

Condition	text	data	bss	total
C99	23576	136	2460	26172
C++14	25404	136	2440	27980
C++14 - fno-rtti	25404	136	2440	27980
C++14 - fno-exceptions	20420	136	2440	22996

# Optimize flag Os

Condition	text	data	bss	total
C99 O3	23576	136	2460	26172
C++14 O3	25404	136	2440	27980
C++14 O3 - fno-exceptions	20420	136	2440	22996
C99 Os	18984	136	2456	21576
C++14 Os	21436	136	2440	24012
C++14 Os - fno-exceptions	16544	136	2440	19120

# Empty main

Condition	text	data	bss	total
C99 Os	720	96	0	816
C++14 Os - fno-exceptions	720	96	0	816



## Client to Server

```
struct connect
{
    mqtt::string client_id;
};

struct subscribe
{
    uint16_t packet_id;
    using topic_filter_t = std::tuple<mqtt::string, qos_t>;
    using filters_t = mqtt::vector<topic_filter_t>;
    filters_t filters;
};

struct unsubscribe
{
    uint16_t packet_id;
    mqtt::vector<mqtt::string> filters;
};

struct pingreq
{};

struct disconnect
{
    bool force;
};
```

# Types

```
namespace mqtt
{
    using string = std::string;

    template <typename ... T>
    using vector = std::vector<T...>;
}
```

# Types

```
namespace mqtt
{
    template < typename Char
              , typename Traits = std::char_traits<Char>>
    using basic_string = std::basic_string< Char, Traits
                                      , my_allocator<Char>>;

    using string = basic_string<char>;

    template <typename T>
    using vector = std::vector<T, my_allocator<T>>;
}
```

# Adding string

Change from adding/instantiating `std::string`

Condition	text	data	bss	total
delta	364	0	0	364

# mqtt::client

```
template < typename Connection
          , typename Executor
          , typename PublishHandler = mqtt_publish_handler_t >
class client
{
public:
    client( mqtt_string_t identifier
           , Connection & connection, Executor & task_executor);

private:
    detail::client_interface_wrapper< Connection
                                     , Executor
                                     > client_interface_;

    PublishHandler publish_handler_;
    mqtt_string_t mqtt_identifier_;

    detail::client_machine client_machine_;
};
```

# mqtt::client

```
template < typename Connection
          , typename Executor
          , typename PublishHandler = mqtt_publish_handler_t >
class client
{
public:
    client( mqtt_string_t identifier
           , Connection & connection, Executor & task_executor);

    void connect(configuration_t);
    void disconnect(bool force=false);

    void subscribe(topic_filter_t filter, handler);
    void subscribe(topic_filter_list_t filters, handler);

    void unsubscribe(topic_filter_t filter, handler);
    void unsubscribe(topic_filter_list_t filters, handler);

    template <typename F>
    void set_publish_handler(F && handler);

    void publish( topic_t topic, payload_t payload
                 , qos_t qos, bool retain, handler);

    template <typename T>
    void publish(T, handler);
```

# mqtt::client

```
template < typename Connection
          , typename Executor
          , typename PublishHandler = mqtt_publish_handler_t >
class client
{
public:
    client( mqtt_string_t identifier
           , Connection & connection, Executor & task_executor);

    void connect(configuration_t);
    void disconnect(bool force=false);

    void subscribe(topic_filter_t filter, handler);
    void subscribe(topic_filter_list_t filters, handler);

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    void unsubscribe(topic_filter_list_t filters, handler);

    template <typename F>
    void set_publish_handler(F && handler);

    void publish( topic_t topic, payload_t payload
                 , qos_t qos, bool retain, handler);

    template <typename T>
    void publish(T, handler);
```

# Construct a `mqtt::client`

```
template <typename Connection, typename Executor, typename PublishHandler>
client<Connection,Executor,PublishHandler>::
client( mqtt_string_t identifier
      , Connection & connection, Executor & task_executor)
    : client_interface_(connection, task_executor)
    , mqtt_identifier_(identifier)
{
    initialize_submachines(client_machine_, &client_interface_);
    client_machine_.start();
}
```



# Using boost::msm

```
struct client_machine_ : public machine_base<client_machine_>
{
};

using client_machine = boost::msm::back::state_machine<client_machine_>;
```

# Using boost : :msm

```
struct transition_table : TransitionTable<
//      Start      Event      Next      Action      Guard
//  +-----+-----+-----+-----+-----+
Row <  NotConnected , event::connect      , ConnectBroker , none      , none      >,
Row <  ConnectBroker , none      , Connected     , none      , none      >,
Row <  Connected     , event::publish_out , none      , send_packet , none      >,
Row <  Connected     , event::subscribe   , none      , send_packet , none      >,
Row <  Connected     , event::unsubscribe , none      , send_packet , none      >,
Row <  Connected     , event::connect     , none      , none      , none      >,
Row <  Connected     , event::disconnect  , ShuttingDown , none      , none      >,
Row <  ShuttingDown  , event::shutdown_timeout , NotConnected , none      , none      >
//  +-----+-----+-----+-----+-----+
>{};
```

# Using boost::msm

```
struct NotConnected : public State
{
    template <class Event, class FSM>
    void on_entry(Event const &, FSM & fsm)
    {
        fsm.client_->update_connection_status(DISCONNECTED);
    }
};

struct Connected : public State
{
    template< class Event, class FSM >
    void on_entry(Event const&, FSM& fsm)
    {
        fsm.client_->update_connection_status(CONNECTED);
    }

    template< class Event, class FSM >
    void on_exit(Event const&, FSM & fsm)
    {
        fsm.client_->update_connection_status(DISCONNECTING);
    }
};

struct ShuttingDown : public State
{
    // defer connect events until the next state
    using deferred_events = mpl::vector<event::connect>;
};
```

# Using boost::msm

```
struct NotConnected : public State
{
    template <class Event, class FSM>
    void on_entry(Event const &, FSM & fsm)
    {
        fsm.client_->update_connection_status(DISCONNECTED);
    }
};

struct Connected : public State
{
    template< class Event, class FSM >
    void on_entry(Event const&, FSM& fsm)
    {
        fsm.client_->update_connection_status(CONNECTED);
    }

    template< class Event, class FSM >
    void on_exit(Event const&, FSM & fsm)
    {
        fsm.client_->update_connection_status(DISCONNECTING);
    }
};

struct ShuttingDown : public State
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# Using boost::msm

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    {
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    }
};

struct Connected : public State
{
    template< class Event, class FSM >
    void on_entry(Event const&, FSM& fsm)
    {
        fsm.client_->update_connection_status(CONNECTED);
    }

    template< class Event, class FSM >
    void on_exit(Event const&, FSM & fsm)
    {
        fsm.client_->update_connection_status(DISCONNECTING);
    }
};

struct ShuttingDown : public State
{
    // defer connect events until the next state
    using deferred_events = mpl::vector<event::connect>;
};
```

# Using boost : :msm

```
struct transition_table : TransitionTable<
//      Start      Event      Next      Action      Guard
//  +-----+-----+-----+-----+-----+
Row <  NotConnected , event::connect      , ConnectBroker , none      , none      >,
Row <  ConnectBroker , none      , Connected     , none      , none      >,
Row <  Connected     , event::publish_out , none      , send_packet , none      >,
Row <  Connected     , event::subscribe   , none      , send_packet , none      >,
Row <  Connected     , event::unsubscribe , none      , send_packet , none      >,
Row <  Connected     , event::connect     , none      , none      , none      >,
Row <  Connected     , event::disconnect  , ShuttingDown , none      , none      >,
Row <  ShuttingDown  , event::shutdown_timeout , NotConnected , none      , none      >
//  +-----+-----+-----+-----+-----+
>{};
```

# Using boost::msm

```
struct send_packet
{
    template<class Fsm, class SourceState, class TargetState>
    void operator()( event::publish_out const& evt, Fsm& fsm
                    , SourceState&, TargetState& )
    {
        fsm.client_->send(evt.publish);
    }

    template<class Fsm, class SourceState, class TargetState>
    void operator()( event::subscribe const& evt, Fsm& fsm
                    , SourceState&, TargetState& )
    {
        fsm.client_->send(evt.subscribe);
    }

    template<class Fsm, class SourceState, class TargetState>
    void operator()( event::unsubscribe const& evt, Fsm& fsm
                    , SourceState&, TargetState& )
    {
        fsm.client_->send(evt.unsubscribe);
    }
};
```

# Using boost::msm

```
struct client_machine_ : public machine_base<client_machine_>
{
    using submachines = Submachines<ConnectBroker>;
    using initial_state = NotConnected;
};

using client_machine = boost::msm::back::state_machine<client_machine_>;
```



# FSM Helpers

```
template <typename ...T>  
using TransitionTable = boost::mpl::vector<T...>;
```

```
template <typename ...T>  
using Submachines = meta::meta_list<T...>;
```

```
template <typename Derived>  
struct machine_base : public msm::front::state_machine_def<Derived>  
{  
    mqtt::detail::client_interface * client_ = nullptr;  
};
```

# FSM Helpers

```
template <typename ...T>  
using TransitionTable = boost::mpl::vector<T...>;
```

```
template <typename ...T>  
using Submachines = meta::meta_list<T...>;
```

```
template <typename Derived>  
struct machine_base : public msm::front::state_machine_def<Derived>  
{  
    mqttt::detail::client_interface * client_ = nullptr;  
};
```

# Type Erased Interface

```
struct client_interface
{
    virtual void send_to_broker(uint8_t const * data, uint16_t length) = 0;
    virtual void receive_from_broker(/*...*/) = 0;
    virtual void queue_task(/*...*/) = 0;
    virtual void update_connection_status(/*...*/) = 0;

    template <typename Packet>
    void send(Packet const & packet)
    {
        auto buffer = serialize(packet);
        send_to_broker(pointer(buffer), size(buffer));
    }
};
```

# Type Erased Interface

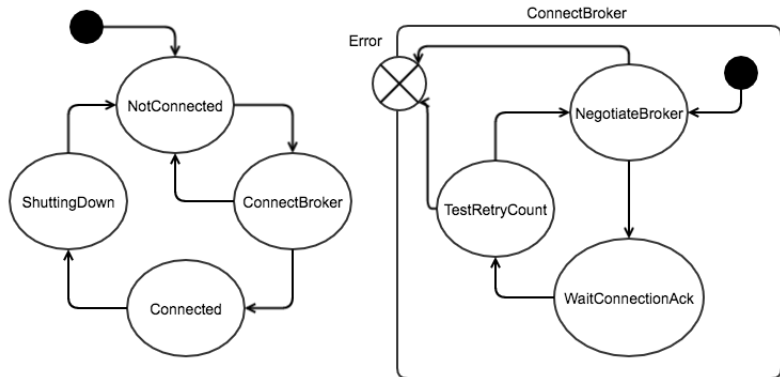
```
template <typename Connection, typename Executor>
struct client_interface_wrapper : client_interface
{
    client_interface_wrapper(Connection & broker, Executor & executor)
        : broker_(broker)
        , executor_(executor)
    {}

    virtual void send_to_broker( uint8_t const * data
                                , uint16_t length) override
    {
        broker_.send(data, length);
    }

private:
    Connection & broker_;
    Executor & executor_;
};
```

# Hierarchical Finite State-machine

## *Hierarchical* Finite State-machine



# Constructing `mqtt::client`

```
template <typename Connection, typename Executor, typename PublishHandler>
client<Connection,Executor,PublishHandler>::
client( mqtt_string_t identifier
      , Connection & connection, Executor & task_executor)
  : client_interface_(connection, task_executor)
  , mqtt_identifier_(identifier)
{
  initialize_submachines(client_machine_, &client_interface_);
  client_machine_.start();
}
```

# Initializing the Hierarchy

Technique lifted from `cierelabs::ladon`

```
template <typename Machine, typename Interface>
void initialize_submachines( Machine & machine
                           , Interface * interface )
{
    machine.client_ = interface;
    initialize_submachine_impl<Machine, Interface> impl(machine, interface);
    descend<Machine>::apply(&impl);
}
```

# Initializing the Hierarchy

```
template <typename MSMBackEnd, typename Interface>
struct initialize_submachine_impl
{
    initialize_submachine_impl(MSMBackEnd & machine, Interface * interface)
        : machine_(machine)
        , interface_(interface)
    {}

    template <typename SubMach>
    void operator() (SubMach const &)
    {
        SubMach* submachine = machine_. template get_state<SubMach*>();
        submachine->client_ = interface_;

        initialize_submachine_impl<SubMach, Interface> impl( *submachine
                                                             , interface_ );

        descend<SubMachine>::apply(&impl);
    }

    MSMBackEnd & machine_;
    Interface * interface_;
};
```



# Initializing the Hierarchy

```
template <typename Machine, typename Enable = void>
struct descend
{
    template<typename T>
    static void apply(T*) {}
};
```

```
template <typename Machine>
struct descend< Machine
              , std::enable_if_t<meta::size_v<typename Machine::submachines>
                              != 0> >
{
    template<typename T>
    static void apply(T* t)
    {
        meta::for_each<typename Machine::submachines>(*t);
    }
};
```

# Initializing the Hierarchy

```
template <typename Machine, typename Enable = void>
struct descend
{
    template<typename T>
    static void apply(T*) {}
};
```

```
template <typename Machine>
struct descend< Machine
              , std::enable_if_t<meta::size_v<typename Machine::submachines>
                              != 0> >
{
    template<typename T>
    static void apply(T* t)
    {
        meta::for_each<typename Machine::submachines>(*t);
    }
};
```

# Wut! Another TMP Library?

```
template <typename ... T>  
struct meta_list {};
```

# size

```
template <typename List>
struct size
{};
```

```
template <typename ... T>
struct size<meta_list<T...>>
{
    static const std::size_t value = sizeof...(T);
};
```

```
template< class T >
constexpr std::size_t size_v = size<T>::value;
```

# size

```
template <typename List>
struct size
{};
```

```
template <typename ... T>
struct size<meta_list<T...>>
{
    static const std::size_t value = sizeof...(T);
};
```

```
template< class T >
constexpr std::size_t size_v = size<T>::value;
```

# for\_each

```
namespace detail
{
    struct do_nothing
    {
        template <typename ... Args>
        do_nothing(Args && ...) {}
    };

    template <typename ...T, typename Func>
    Func for_each(meta_list<T...> &&, Func && f)
    {
        do_nothing((f(T{}), 0)...);
        return f;
    }
}

template <typename List, typename Func>
Func for_each(Func && f)
{
    return detail::for_each(List{}, std::forward<Func>(f));
}
```

# for\_each

```
namespace detail
{
    struct do_nothing
    {
        template <typename ... Args>
        do_nothing(Args && ...) {}
    };

    template <typename ...T, typename Func>
    Func for_each(meta_list<T...> &&, Func && f)
    {
        do_nothing((f(T{}), 0)...);
        return f;
    }
}

template <typename List, typename Func>
Func for_each(Func && f)
{
    return detail::for_each(List{}, std::forward<Func>(f));
}
```

# Cost of `initialize_submachines`

Condition	text	data	bss	total
Just the parent	0	0	0	0
With submachine	28	0	0	28



# Cost of `initialize_submachines`

Why the complexity??

# Easy for user!

```
struct client_machine_ : public machine_base<client_machine_>
{
    using submachines = Submachines<ConnectBroker>;
    using initial_state = NotConnected;
};

using client_machine = boost::msm::back::state_machine<client_machine_>;
```

# Types

```
enum class qos_t : uint8_t
{
    QOS0      = 0x00,
    QOS1      = 0x01,
    QOS2      = 0x02,
    FAILURE   = 0x80,
};
```

## Bidirectional

```
struct publish
{
    bool dup = false;
    uint8_t qos = 0x00;
    bool retain = false;
    mqtt::string topic_name;
    uint16_t packet_id;
    mqtt::vector<uint8_t> payload;
};
```

```
struct puback
{
    uint16_t packet_id;
};
```

# Types

```
enum class qos_t : uint8_t
{
    QOS0      = 0x00,
    QOS1      = 0x01,
    QOS2      = 0x02,
    FAILURE   = 0x80,
};
```

## Bidirectional

```
struct publish
{
    bool dup = false;
    uint8_t qos = 0x00;
    bool retain = false;
    mqtt::string topic_name;
    uint16_t packet_id;
    mqtt::vector<uint8_t> payload;
};
```

```
struct puback
{
    uint16_t packet_id;
};
```

## Server to Client

```
struct connack
{
    bool session_present;
    uint8_t response_code;
};

struct suback
{
    uint16_t packet_id;
    using qos_obtained_t = mqtt::vector<qos_t>;
    qos_obtained_t qos_obtained;
};

struct unsuback
{
    uint16_t packet_id;
};

struct pingresp
{};
```

Incomming control messages:

```
struct control_packet
: public x3::variant< puback
                    , connack
                    , suback
                    , unsuback
                    , pingresp >
{
    using base_type::base_type;
    using base_type::operator=;
};
```

# Adapted Types

```
BOOST_FUSION_ADAPT_STRUCT(  
    ciere labs::mqtt::packet::puback,  
    (uint16_t, packet_id)  
)  
  
BOOST_FUSION_ADAPT_STRUCT(  
    ciere labs::mqtt::packet::connack,  
    (bool, session_present)  
    (uint8_t, response_code)  
)  
  
BOOST_FUSION_ADAPT_STRUCT(  
    ciere labs::mqtt::packet::suback,  
    (uint16_t, packet_id)  
    (ciere labs::mqtt::packet::suback::qos_obtained_t, qos_obtained)  
)  
  
BOOST_FUSION_ADAPT_STRUCT(  
    ciere labs::mqtt::packet::unsuback,  
    (uint16_t, packet_id)  
)  
  
BOOST_FUSION_ADAPT_STRUCT(  
    ciere labs::mqtt::packet::publish,  
    (mqtt::string, topic_name)  
    (uint16_t, packet_id)  
    (mqtt::vector<uint8_t>, payload)  
)
```

# Parse it!

```
bool keepPacketizing = true;
while(keepPacketizing)
{
    switch(parsePhase_)
    {
        case ParsePhase::HEADER_BYTE:
            keepPacketizing = readHeader();
            break;
        case ParsePhase::LENGTH:
            keepPacketizing = readLength();
            break;
        case ParsePhase::BODY:
            keepPacketizing = readBody();
            break;
    }
}
```



# Parse it!

```
bool MQTTPacketizer::readHeader()  
{  
    if(!data_.empty())  
    {  
        currentHeader_ = data_.front();  
        data_.pop_front();  
        parsePhase_ = ParsePhase::LENGTH;  
        return true;  
    }  
  
    return false;  
}
```

# Parse it!

```
void MQTTPacketizer::formPacket ()
{
    switch (currentHeader_ & 0xf0)
    {
        case MQTTPacketType::PUBLISH:
            receivePacket (makePublishPacket ());
            break;

        case MQTTPacketType::CONNACK:
            receivePacket (makeConnackPacket ());
            break;

        case MQTTPacketType::PUBACK:
            receivePacket (makePubackPacket ());
            break;

        case MQTTPacketType::SUBACK:
            receivePacket (makeSubackPacket ());
            break;
    }
}
```

# Parse it!

```
packet::suback MQTTPacketizer::makeSubackPacket()
{
    packet::suback packet;
    packet.packetID = getUint16();

    int responseCount = currentLength_ - 2;
    for(int i=0; i<responseCount; ++i)
    {
        packet.qosObtained.push_back(
            static_cast<packet::suback::Code>(getUint8())
        );
    }

    return packet;
}
```

# boost::spirit ??

```
auto const control_packet_def =  
    omit[byte_(0x40)] >> puback  
  | omit[byte_(0x10)] >> publish  
  | omit[byte_(0x20)] >> connack  
  | omit[byte_(0x90)] >> suback  
  | omit[byte_(0xb0)] >> unsuback  
  | omit[byte_(0xc0)] >> attr(packet::pingresp{})  
;
```

# boost::spirit ??

```
auto const qos_def =  
    omit[byte_(0x00)] >> attr(packet::qos_t::QOS0)  
  | omit[byte_(0x01)] >> attr(packet::qos_t::QOS1)  
  | omit[byte_(0x02)] >> attr(packet::qos_t::QOS2)  
  | omit[byte_(0x80)] >> attr(packet::qos_t::FAILURE)  
  ;
```

```
auto const suback_def =  
    skip_encoded_length  
  >> big_word  
  >> *qos  
  ;
```

# boost::spirit ??

```
auto const qos_def =  
    omit[byte_(0x00)] >> attr(packet::qos_t::QOS0)  
  | omit[byte_(0x01)] >> attr(packet::qos_t::QOS1)  
  | omit[byte_(0x02)] >> attr(packet::qos_t::QOS2)  
  | omit[byte_(0x80)] >> attr(packet::qos_t::FAILURE)  
  ;
```

```
auto const suback_def =  
    skip_encoded_length  
  >> big_word  
  >> *qos  
  ;
```

# boost::spirit ??

```
auto const puback_def =  
    skip_encoded_length  
    >> big_word  
    ;  
  
auto const connack_def =  
    skip_encoded_length  
    >> ( omit[byte_(0x01)] >> attr(true)  
        | attr(false) )  
    >> byte_  
    ;  
  
auto const unsubst_def =  
    skip_encoded_length  
    >> big_word  
    ;  
  
auto const publish_def =  
    skip_encoded_length  
    >> big_word  
    ;
```

Grammar (composed parsers) and usage:

Just over 3KB !



# Templates are not evil

Don't try and be smarter than your compiler

# struct to bytes

```
template <typename T>
auto serialize(T && packet)
{
    auto variable_length = get_variable_length(packet);
    // packet size : variable length + control header + encoded length size
    uint16_t packet_size = variable_length + 1 +
                           (int) (variable_length/128) + 1;

    auto packet_data = get_packet_buffer(packet_size);
    serialize_impl( packet
                   , std::back_inserter(packet_data)
                   , variable_length);

    return packet_data;
}
```

# struct to bytes

```
template <typename Iterator>
Iterator serialize_impl( packet::subscribe const & subscribe
                        , Iterator iter
                        , int variable_length)
{
    // control header
    *iter++ = 0x82;

    encode_length(variable_length, iter);
    encode(subscribe.packet_id, iter);

    for(auto & topic : subscribe.filters)
    {
        encode(std::get<0>(topic), iter);
        *iter++ = static_cast<uint8_t>(std::get<1>(topic));
    }
    return iter;
}
```

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    serialize_impl( packet
                   , std::back_inserter(packet_data)
                   , variable_length);

    return packet_data;
}

constexpr uint16_t get_variable_length(packet::pingreq const &)
{
    return 0;
}

template <typename Iterator>
Iterator serialize_impl(packet::pingreq const &, Iterator iter, int)
{
    copy({0xc0, 0x00}, iter);
    return iter;
}
```

# struct to bytes

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    // packet size : variable length + control header + encoded length size
    uint16_t packet_size = variable_length + 1 +
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    serialize_impl( packet
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## Part III

# Conclusion

# A few thoughts

- ▶ Templates are not evil
- ▶ Know what you are doing with templates
- ▶ Determine your level of “*embedded*”
- ▶ Use `std` containers to start
- ▶ Don't out-think the compiler!



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# A few thoughts

- ▶ Templates are not evil
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- ▶ Determine your level of “*embedded*”
- ▶ Use `std` containers to start
- ▶ Don't out-think the compiler!

# What is left?

- ▶ Decide on memory/container strategy
- ▶ Extension points
- ▶ Documentation
- ▶ Case studies
- ▶ Testing

A Name!

# Name?

Macchiato

`maqiatto`



# Where do I find it?

`https://github.com/cierelabs/maqiatto`





# Part IV

## Bonus