

Singularwertzerlegung

$$Y = (y_0, y_1, y_2, \dots) \in \mathbb{R}^{n, \text{Hilfswert}} \text{ defin. Daten}$$

$$YY^T = Q \Lambda Q^T \quad Q = (q_0, q_1, q_2, \dots)$$

\uparrow
ges. Basis

gesucht: Basis $V = (v_0, v_1, \dots)$ V ist orthogonal, $\|v_i\| = 1$

$$v_i^T Y Y^T v_i = v_i^T X^T X v_i = (X v_i)^T X v_i = \|X v_i\|^2 \quad v_i^T v_j = 0 \quad i \neq j$$

$$\underset{\|v_i\|=1}{\arg \max} \|X v_i\| \quad \boxed{\sigma_i v_i = X v_i} \quad \|v_i\|=1 \quad \sigma_i \geq 0$$

$$\begin{aligned} \sigma_i v_i^T \sigma_j v_j &= (X v_i)^T (X v_j) = v_i^T X^T X v_j \\ &= v_i^T Y Y^T v_j = \underbrace{v_i^T Q \Lambda Q^T}_{= d_i^T \Lambda d_j} v_j \Rightarrow d_{i,j} = e_{i,j} \\ &\Rightarrow e_i^T \Lambda e_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \end{aligned}$$

$$\|\sigma_i v_i\|^2 = \sigma_i v_i^T v_i \sigma_i = \lambda_i \Rightarrow \sigma_i^2 = \lambda_i \Rightarrow \sigma_i = \sqrt{\lambda_i}$$

$$\underset{\|v_i\|=1}{\arg \max} \|v_i^T X\| \quad \text{rang}(X)=r < n$$

$$\boxed{|U| | \Sigma | |V| = |X| |V|}$$

$$\boxed{|U| | \Sigma | |V^T| = |X| |V^T|}$$

linke
Singularvekt.

rechte
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reduzierte
SVD

$$V \in \mathbb{R}^{n \times n}$$

$$|\Sigma| = (\sigma_0, \sigma_1, \dots, \sigma_{r-1}, 0, \dots)$$

Singularwertzerlegung

U, V orthogonal

Σ diagonal $\sigma_i \geq 0$

Singularwerte

$$\begin{array}{ccc} \oplus & \xrightarrow{X} & \oplus \\ \downarrow v^T & \xrightarrow{\Sigma} & \downarrow v \\ \oplus & \xrightarrow{V} & \oplus \end{array}$$

Anwendungen der SVD

$$X = U \Sigma V^T$$

$$\Sigma = \begin{pmatrix} \sigma_0 & & \\ & \ddots & \\ & & \sigma_r & 0 & 0 & \dots & 0 \end{pmatrix} \quad \sigma_0 \geq \sigma_1 \geq \dots \geq \sigma_r = \sigma_{r+1} = \dots = 0$$

$$\Sigma^+ = \begin{pmatrix} \frac{1}{\sigma_0} & & \\ & \ddots & \\ & & \frac{1}{\sigma_{r-1}} & 0 & \dots & 0 \end{pmatrix}$$

$$X^+ = V \Sigma^+ U^T \quad \text{Pseudo inverse}$$

$$XX^+ = U \Sigma \underbrace{V^T}_{\Sigma^+} V \Sigma^+ U^T = U \Sigma \Sigma^+ U^T = U \begin{pmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & 0 & 0 & \dots & 0 \end{pmatrix} U^T$$

$$\Rightarrow X \in \mathbb{R}^{4 \times 4}, \text{rang}(X) = 4 \rightarrow X^+ = X^{-1}$$

LGS

$$Ax \approx b \quad x = A^+ b \text{ ist immer ok!}$$

1. $Ax = b$ hat genau eine Lösung $\rightarrow x = A^+ b$ ist die ges. Lsg.
2. $Ax = b$ hat keine Lösung \rightarrow minimiere $\|Ax - b\|$
3. $Ax = b$ hat viele Lösungen $\rightarrow \arg \min_{Ax=b} \|x\|$

$$\begin{aligned} \|Ax - b\| &= \|U \Sigma V^T x - b\| \\ &= \|U^T (U \Sigma V^T x - b)\| = \|\Sigma V^T x - U^T b\| \quad x' = V^T x \\ &= \|\Sigma x' - U^T b\| \quad b' = U^T b \end{aligned}$$

$$\begin{aligned} \|\Sigma x' - U^T b\|^2 &= \sum_{i=0}^{r-1} (\sigma_i x'_i - b'_i)^2 + \sum_{i=r}^{n-1} (-b'_i)^2 \quad \sigma_i x'_i = b'_i \\ x'_i &= \frac{b'_i}{\sigma_i} \quad x'_i \neq 0 \rightarrow x'_i = 0 \\ V^T x = x' &= \Sigma^+ b' = \Sigma^+ U^T b \end{aligned}$$

$$\rightarrow x = V \Sigma^+ U^T b = A^+ b$$

Homogene LGS

$$Ax = 0 \quad \text{für} \quad x \neq 0 \quad Ax = 0 \rightarrow f(x) = 0$$

$$\underset{\|x\|=1}{\arg \min} \|Ax\|$$

$$x' = V^T x$$

$$\underset{\|x\|=1}{\arg \min} \|U\Sigma V^T x\| = \underset{\|x\|=1}{\arg \min} \|\Sigma V^T x\| = \underset{\|x\|=1}{\arg \min} \|\Sigma x'\|$$

$$= \left((\sigma_0 x'_0)^2 + (\sigma_1 x'_1)^2 + \dots \right)^{\frac{1}{2}}$$

$$\sigma_0 \geq \sigma_1 \geq \dots \geq \sigma_{n-1} \Rightarrow x'_0 = \dots = x'_{n-2} = 0, \quad x'_{n-1} = 1$$

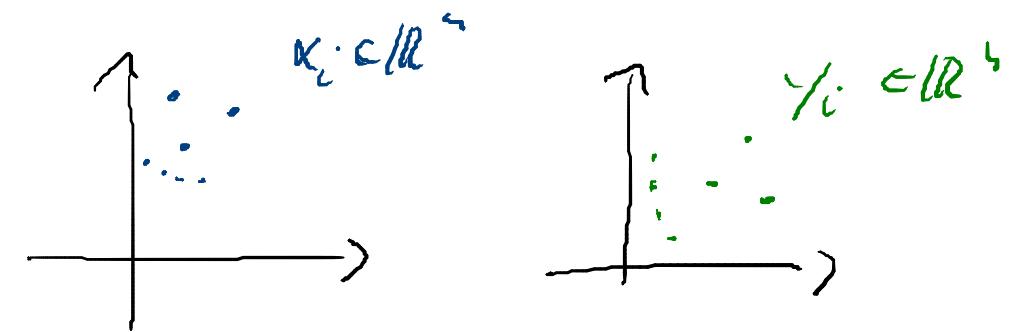
$$x' = e_{n-1}$$

$$x = Vx' = Ve_{n-1}$$

\Rightarrow die letzte Spalte von V

\rightarrow der rechte Singularvekt. zum linken Singularwert.

Orthogonale Prozessoren Problem



$$x = (x_0, x_1, \dots)$$

$$y = (y_0, y_1, \dots)$$

$$T x_i \approx y_i \quad \sum_i \|T x_i - y_i\|^2 \rightarrow \min$$

$$xy^\top = U \Sigma V^\top$$

$$\det(xy^\top) \geq 0 \quad \text{ges. Rotation ist } UV^\top$$

ausreichen

$$U(\begin{smallmatrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{smallmatrix}) V'$$