```
1 #include (iostream)
 2 #include <cstring>
 3 #include <cstdlib>
 4 using namespace std;
 6 class DaryHeap {
 7 private:
 8 int d;
 9 int heapSize;
10 int size;
      int *array;
11
      int childNum;
12
13 public:
       DaryHeap(int length, int childNum) {
14
           heapSize = 0;
15
           childNum = d;
                                                Brytruetor
16
           size = 10;
17
           array = new int[length + 1];
18
          for (int i = 0; i < length + 1; i++)
19
               array[i] = -1;
20
          int j = 0;
21
          while (array[j] != -1)
22
               j++:
23
         this->array = array;
24
          this->d = childNum;
25
26
27
       bool isEmpty() {
28
          return heapSize == 0;
29
                                         check whether is empty
30
31
       bool isFull() {
32
33
           return heapSize == size;
34
 35
 36
 37
        void insert(int k) {
                                                  insert function
  38
            if (isFull()) {
               cout << "Queue is full" << endl;
  40
```

```
array[heapSize] = k;
    41
    42
               heapSize++;
               swim(heapSize - 1);
    43
   44
   45
   46
          int delMax() {
   47
              if (isEmpty()) {
   48
                  cout << "Queue is empty" << endl;</pre>
   49
  50
                  return 0;
  51
  52
             int key = array[0];
  53
             array[0] = array[heapSize - 1];
  54
             heapSize--:
                                                     delete maximum function
  55
             Sink();
 56
             return key;
 57
 58
 59
        void swim(int index) {
 60
            int parentIndex = findparent(index);
            while (parent_index >= 0 && index > 0) {
 61
                if (heap[index] > heap[parent_index]) {
62
63
                    int temp = heap[index]:
                    heap[index] = heap[parent_index];
64
65
                    heap[parent_index] = temp;
66
                    index = parent index:
67
                    parent_index = findparent(index);
68
               } else
69
                    break;
70
71
72
73
74
       int findparent(int i) {
75
           return (i - 1) / childNum;
76
                                                  calculation
77
78
       int kthChild(int i, int k) {
79
           return childNnum * i + k;
80
```

```
81
         void Sink(int hole) {
  82
             int child;
  83
             int tmp = array[hole];
  84
             for (kthChild(hole, 1) < heapSize; hole = child) {</pre>
  85
                 if (array[child] < tmp)</pre>
  86
                    array[hole] = array[child];
  87
                 else
  88
                     break:
 89
 90
            array[hole] = tmp;
 91
 92
 93
 94
        void printHeap() {
 95
            for (int i = 0; i < heapSize; i++)
 96
                cout << array[i] << " ";
 97
        }
 98
 99
        void doubleArray() {
100
101
102
103
      void heap() {
104
            for (int index = findparent(heapSize - 1); index >= 0; index
105
                Sink(index);
106
107
108
109 };
110
111 int main() {
        DaryHeap the:
112
                                         main function
        the. insert();
113
114
        the. delMax():
 115 the. swim();
 116
        the. Sink():
 117
         the. printHeap();
  118
         return 0;
  119 }
```