

INTERPOLATION

Horner's Rule: Instead of evaluating $P(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$ [3n flops]
Eval $P(x) = a_0 + x(a_1 + x(a_2 + \dots + x(a_n)))$ [2n flops]

Polynomial Interpolation: Given $S = \{(t_i, y_i)\}_{i=1}^m$, find unique $P_{m-1}(t) = C_1 + C_2t + \dots + C_{m-1}t^{m-1}$ that interpolates S

Solving
$$\begin{cases} C_1 + C_2t_1 + C_3t_1^2 + \dots + C_mt_1^{m-1} = y_1 \\ C_1 + C_2t_2 + C_3t_2^2 + \dots + C_mt_2^{m-1} = y_2 \\ C_1 + C_2t_3 + C_3t_3^2 + \dots + C_mt_3^{m-1} = y_3 \end{cases}$$

is the same as
(Vandermonde matrix)

$$\begin{bmatrix} 1 & t_1 & t_1^2 & \dots & t_1^{m-1} \\ 1 & t_2 & t_2^2 & \dots & t_2^{m-1} \\ 1 & t_3 & t_3^2 & \dots & t_3^{m-1} \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \\ C_3 \\ \vdots \\ C_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$\uparrow \quad \vee \qquad \qquad \uparrow \quad C \qquad \qquad \uparrow \quad y$

Using IEEE double precision gets C_s to about 4 digits of accuracy.
- difficult to be accurate.

Another approach.

$P_{m-1}(t) = C_1 \cdot 1 + C_2 \cdot t + C_3 \cdot t^2 + \dots + C_m \cdot t^{m-1}$ is expressed using monomial basis $\{1, t, t^2, \dots, t^{m-1}\}$

Suppose $\{b_i(t)\}_{i=1}^m$ is a basis for \mathbb{P}_{m-1}

$$\begin{bmatrix} b_1(t_1) & b_2(t_1) & \dots & b_m(t_1) \\ b_1(t_2) & b_2(t_2) & \dots & b_m(t_2) \\ \vdots & \vdots & \ddots & \vdots \\ b_1(t_m) & b_2(t_m) & \dots & b_m(t_m) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

$$B \alpha = y$$

Choose $B = I$ (identity matrix), then $\alpha = \gamma$ **LAGRANGE BASIS**

construct basis s.t. $b_i(t_j) = \begin{cases} 1 & \text{when } i=j \\ 0 & \text{when } i \neq j \end{cases}$

We want $b_i(t_2) = 0 \rightarrow$ includes $(t-t_2)$
 $b_i(t_m) = 0 \rightarrow$ includes $(t-t_m)$

so far $b_i(t_1) = (t-t_2)(t-t_3)\dots(t-t_m)$

we want $b_i(t_1) = 1$ so scale by $\frac{1}{(t_1-t_2)(t_1-t_3)\dots(t_1-t_m)}$

$$\text{so } b_i(t) = \frac{(t-t_2)(t-t_3)\dots(t-t_m)}{(t_1-t_2)(t_1-t_3)\dots(t_1-t_m)}$$

$$b_R(t) = \prod_{\substack{j=1 \\ j \neq R}}^m \frac{(t-t_j)}{(t_R-t_j)}$$

$$\underline{I} \alpha = \gamma$$

$$\alpha = \gamma$$

Choose $B =$ Lower triangular **Newton Basis**

ERROR

$$f(t) - P_{m-1}(t) = \frac{1}{m!} \cdot f^{(m)}(c_t) \cdot w_m(t)$$

- c_t some point in (t_1, t_m) that depends on t

$$- w_m(t) = (t-t_1)(t-t_2)\dots(t-t_m) = \prod_{i=1}^m (t-t_i)$$

$$\max_{t \in [t_1, t_m]} |f(t) - P_{m-1}(t)| \leq \frac{1}{m!} \max_{t \in [t_1, t_m]} |f^{(m)}(t)| \max_{t \in [t_1, t_m]} |w_m(t)|$$

$\max_i |w_m(t)|$ is messy for $m > 4$, but we can show $\max_{t \in [t_1, t_m]} |w_m(t)| \leq \frac{h^m (m-1)!}{4}$

$$- h = \max_i |t_{i+1} - t_i|$$

PIECEWISE POLYNOMIAL INTERPOLATION

NONLINEAR EQUATIONS

Intermediate Value Theorem (IVT)

Bisection Method

given continuous $f(x)$, L, R s.t. $f(L) \cdot f(R) < 0$, $L < R$

while $\frac{1}{2}(R-L) > \text{ABSTOL}$:

$$m = L + (R-L)/2$$

if $\text{sign}(f(L)) == \text{sign}(f(m))$:

$$L = m$$

else:

$$R = m$$

$$x^* = L + (R-L)/2$$

After n intervals, error is $e_n = |m_n - x^*| \leq \frac{1}{2^n} |R - L|$

Fixed Point Iteration : find p^* s.t. $g(p^*) = p^*$ where $g(x) = x - f(x)$

compute $x_0 = 0$

then $x_{i+1} = g(x_i)$

until $|x_{i+1} - x_i| < 5 \times 10^{-7}$

$g \in C[a, b]$, $\forall x \in [a, b]$, $g(x) \in [a, b] \Rightarrow g(x)$ has fixed point in $[a, b]$

$g'(x)$ exists on (a, b) $\wedge |g'(x)| \leq k < 1 \forall x \in (a, b) \Rightarrow$ fixed point is unique

Newton's Method

$\begin{cases} x_0 = \text{given initial guess} \\ x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \end{cases}$

Fixed point iteration with $g(x) = x - \frac{f(x)}{f'(x)}$

Secant Method

$\begin{cases} x_{i+1} = x_i - \frac{f(x_i)(x_i - x_{i-1})}{f(x_i) - f(x_{i-1})} \\ \text{where } x_0, x_1 \text{ is given} \end{cases}$

Rate Of Convergence : $\lim_{x_i \rightarrow x^*} \frac{e_{i+1}}{(e_i)^r} = C \neq 0$

Bisection: $e_{i+1} = \frac{1}{2} e_i \rightarrow \lim_{x_i \rightarrow x^*} \frac{e_{i+1}}{e_i} = \frac{1}{2}$ and $r=1$

$r=1$ means linear convergence

$r>1$ means super linear convergence

Newton: $e_{i+1} = \left| \frac{f''(\theta)}{2f'(x_i)} \right| e_i^2 \rightarrow \lim_{x_i \rightarrow x^*} \frac{e_{i+1}}{e_i^2} = \left| \frac{f''(\theta)}{2f'(x_i)} \right| = \text{Constant}$

$r=2$ quadratic convergence

if $f'(x^*) = 0$, x^* is a multiple root and convergence is linear

Secant: $\lim_{x_i \rightarrow x^*} \frac{e_{i+1}}{e_i e_{i-1}} = \lim_{x_i \rightarrow x^*} \frac{e_{i+1}}{e_i^r} = C \neq 0$ for $r = \frac{1+\sqrt{5}}{2} = 1.618$

