

CNN

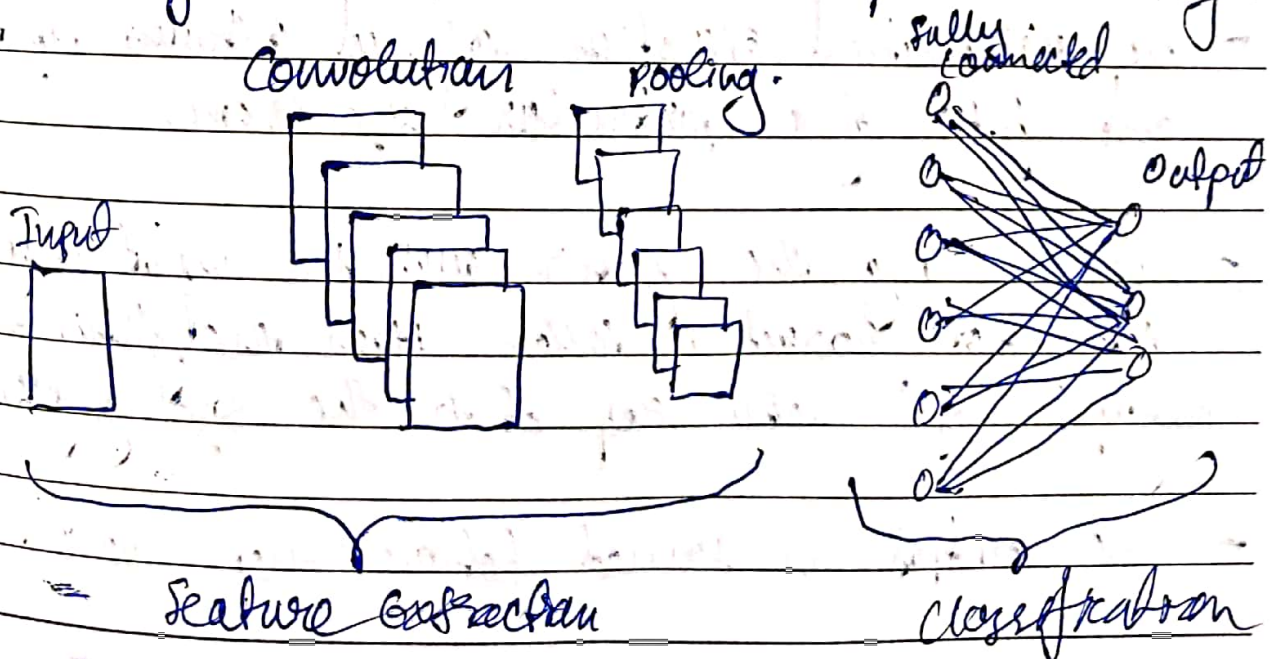
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- It is a class of Deep Neural networks that recognize and classify particular features from images and are widely used for analyzing visual images.

Architecture

2 Main Parts to a CNN Architecture.

- 1) Feature Extraction - A convolutional tool that separates and identifies various features of image for analysis.
- 2) A fully connected layer that utilizes the output from the convolution process and predict the class of the image based on the features extracted in previous stages.



Convolution Layers

Mainly 3 layers that make up the CNN.

- 1) Convolutional layer
- 2) Pooling layer
- 3) Fully connected layer

these 3 layers stacked the CNN arch is formed.

Along with these 3, there are 2 important parameters.

- 1) Dropout layer
- 2) Activation function

1) Convolutional Layer

- It is first layer used to extract various features from the input images.
- the mathematical operation performed between input layer and filter of a particular size $m \times n$.
- By sliding the filter over the input image, the dot product is taken with the filter and the input image with respect to the size of filter (conv).
- the output is termed feature map which

gives info about image such as the corners and edges.

2) Pooling Layer :

- This layer decrease the size of the convolved feature map to reduce the computational cost.

- It is performed by decreasing the connection between layers and independently operates on each feature map, depending on the method used.

Max pooling : Largest element is taken from feature map.

Average : calculated the avg of the elements in predefined size image section.

Sum pooling : The total sum of the element in the predefined section is computed in it.

3) Fully Connected Layer

- It consist of the weight and biases along with neurons.

- Used to connect the neurons between 2 different layers.

- These layers are usually placed before the output layer and form last few layers of CNN architecture.

- The input image from previous layers are flattened and fed to FC layer.

- The flattened vector undergoes few more FC layers where the mathematical function operations usually take place.

- In this stage classification process begins to take place.

4) Dropout :

- When features are connected in FC layer it can cause overfitting in training dataset.

- Dropout layer helps where in a few neurons are dropped from the neural network during training process which results in reduced size of the model.

- On passing 0.3, 30% of the nodes are dropped out randomly from the neural network.

5) Activation functions :-

- Used to learn and approximate any kind of continuous and complex relationship between variables of the network.
- It decides which info of the model should fire in the forward direction and which ones should not at the end of the network.

VGGNet Architecture ⑨

- Visual Geometry Group, is a standard deep CNN architecture with multiple layers. ~~Three~~ ^{deep}
- The "deep" refers to the no. of layers.
eg: VGG-16 or VGG-19.
consisting of 16 or 19 convolutional layers.
- Developed to increase the depth of such CNN to increase the model performance.
- The architecture is on the basis of ground-breaking object recognition models.
- Also surpasses baselines of many tasks and datasets beyond ImageNet.

- Most popular image recognition architecture

VGG16 :-

- This model supports 16 layers.
- It has top-5 accuracy in ImageNet over 92.7%.
- It replaces that the large kernel-sized filters with several 3x3 kernel sized filters one after another; it makes significant improvement over AlexNet.
- It ~~can~~ support 16 layers and can classify images into 1000 object categories, includes, keyboard, animals, pencil, mouse etc.
- The model has input size of 224-by-224.

VGG16 Architecture :-

- It is an extensive network and has a total of around 138 million parameters.
- Its simplicity is what makes the network more appealing.
- Few convolution layers and pooling layers.

Very deep convolutional layers

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reduces the height and the width.

- Around 64 filters are available that can be double to about 128 and then 256 filters. In last layer, we use 512 filters.

Embedding layer

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- It represent words in an array, not in form of dim 1 but continuous vectors.
- can represent any word in few dimension, mostly based on the number of unique words in our text.

steps to convert raw data to embedding

* Load text data in array.

* Process the data

* Tokenize and pad convert text to sequence and using the tokenizer and pad them with keras.preprocessing and pad sequence methods.

* Initialize a model with Embedding layer of dimension (max-words, representation dimension, input-size)

- max-words: It is the no. of unique words in your data.
- representation dimension: It is the no. of dimensions in which you want to represent.
- input-size - size of your padded sequence (maxlen).