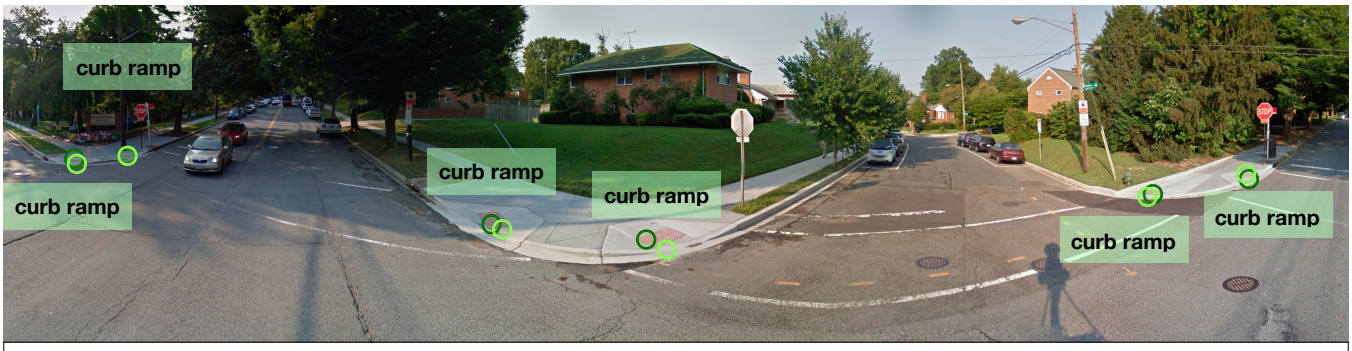
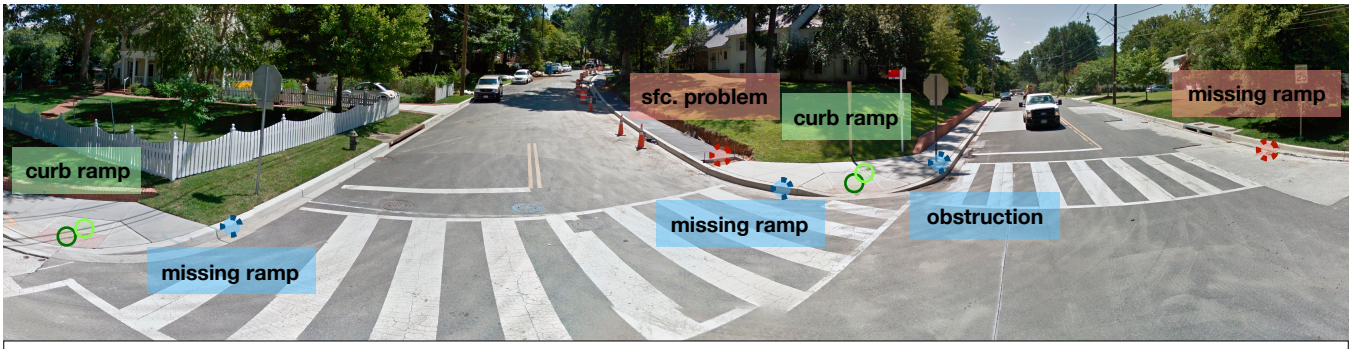


A scene with 100% accuracy. All 6 curb ramps were detected accurately.



A scene with mixed performance. Curb ramps were accurately detected, but the missing ramp at right was missed, as was the unusual surface problem (a hole in an under-construction sidewalk). Several false positives were predicted: two missing curb ramps at both ends of a sidewalk, and an obstruction at the base of a stop sign.

A scene with poor performance. The surface problem (a bump in the sidewalk) was detected a right, but the system produced a false positive label nearby. On the left side of the street, a long section of bumpy, damaged, and dirty sidewalk pavement was missed.