



# NHD-0216K1Z-FL-YBW

## **Character Liquid Crystal Display Module**

NHD- Newhaven Display
0216- 2 Lines x 16 Characters

K1Z- Model

F- Transflective

L- Yellow/Green LED Backlight

Y- STN- Yellow/Green B- 6:00 Optimal View W- Wide Temperature

**RoHS Compliant** 

#### Newhaven Display International, Inc.

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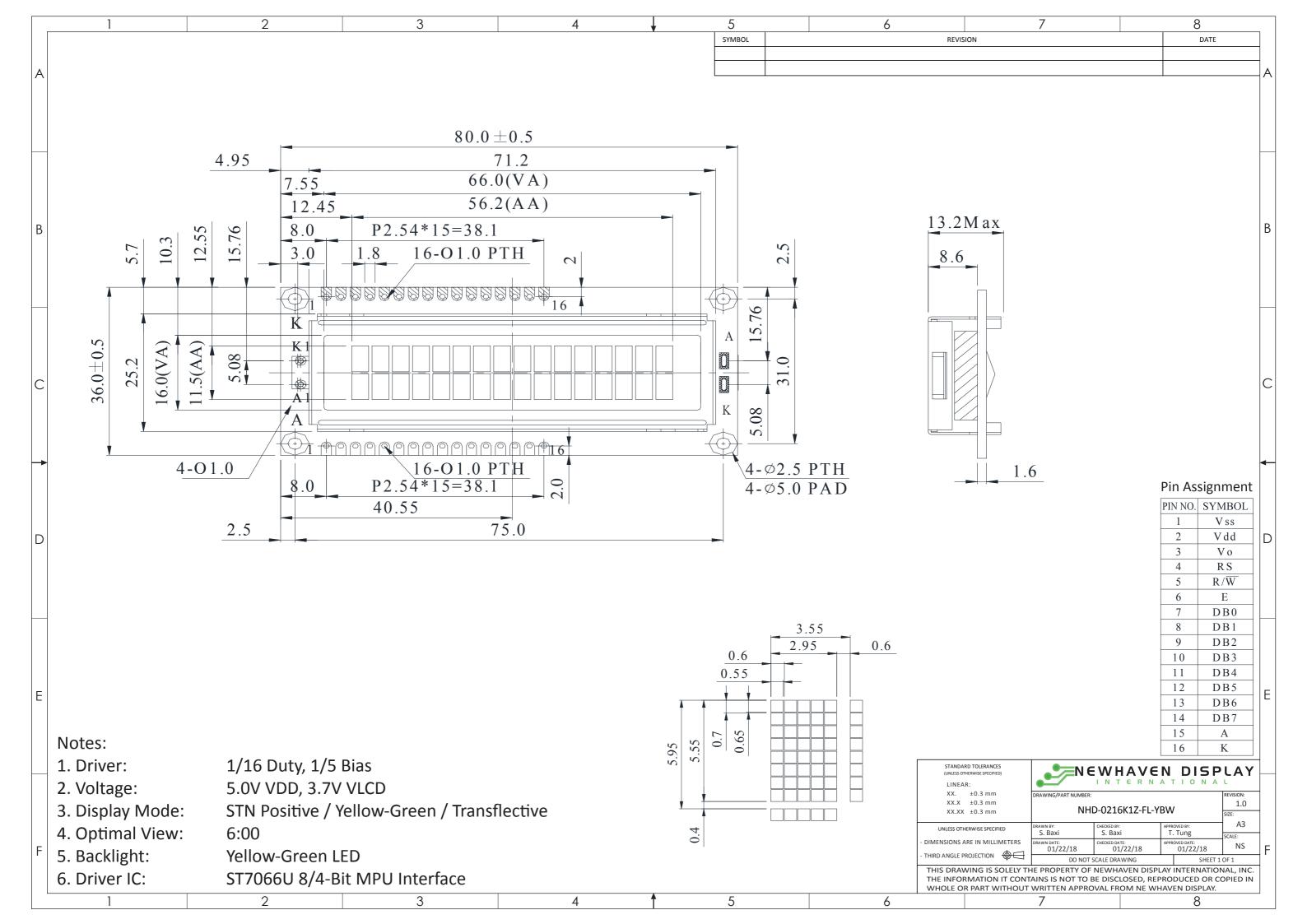
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**Document Revision History** 

Revision	Date	Description	Changed by
0	10/5/07	Initial Release	-
1	10/9/09	User Guide Reformat	BE
2	10/23/09	Block Diagram Revision	BE
3	12/8/09	Pin description/backlight updated	BE
4	1/7/10	Optical updated	BE
5	1/6/11	Alternate controller information updated	AK
6	4/6/11	Mechanical drawing updated	AK
7	4/8/11	Electrical/Optical characteristics & Pin Description updated	AK
8	12/15/15	Electrical Characteristics updated, Timing characteristics	SB
		added	
9	1/22/18	Backlight Characteristics Updated	SB

#### **Functions and Features**

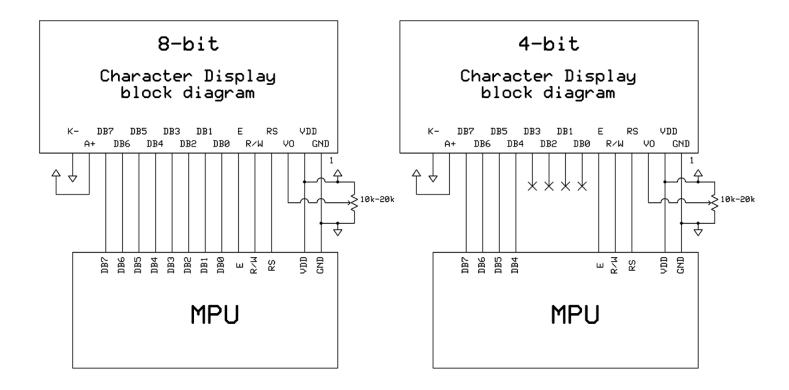
- 2 lines x 16 characters
- Built-in controller (ST7066U)
- +5.0V Power Supply
- 1/16 duty, 1/5 bias
- RoHS compliant



## **Pin Description and Wiring Diagram**

Pin No.	Symbol	<b>External Connection</b>	Function Description
1	$V_{SS}$	Power Supply	Ground
2	$V_{DD}$	Power Supply	Supply Voltage for logic (+5.0V)
3	$V_0$	Adj. Power Supply	Supply Voltage for contrast (approx. 1.3V)
4	RS	MPU	Register Select signal. RS=0: Command, RS=1: Data
5	R/W	MPU	Read/Write select signal, R/W=1: Read R/W: =0: Write
6	E	MPU	Operation Enable signal. Falling edge triggered.
7-10	DB0 – DB3	MPU	Four low order bi-directional three-state data bus lines. These
			four are not used during 4-bit operation.
11-14	DB4 – DB7	MPU	Four high order bi-directional three-state data bus lines.
15	LED+	Power Supply	Backlight Anode(+5.0V via on-board resistor)
16	LED-	Power Supply	Backlight Cathode (Ground)

**Recommended LCD connector:** 2.54mm pitch pins **Backlight connector:** --- **Mates with:** ---



#### **Electrical Characteristics**

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Operating Temperature Range	T <sub>OP</sub>	Absolute Max	-20	-	+70	°C
Storage Temperature Range	T <sub>ST</sub>	Absolute Max	-30	1	+80	°C
Supply Voltage	$V_{DD}$	-	4.5	5.0	5.5	V
Supply Current	I <sub>DD</sub>	$V_{DD} = 5.0V$	0.5	1.0	3.0	mA
Supply for LCD (contrast)	$V_{LCD}$	$T_{OP} = 25^{\circ}C$	3.5	3.7	3.9	V
"H" Level input	V <sub>IH</sub>	-	0.7 * V <sub>DD</sub>	-	$V_{DD}$	V
"L" Level input	$V_{IL}$	-	$V_{SS}$	-	0.6	V
"H" Level output	V <sub>OH</sub>	-	3.9	-	$V_{DD}$	V
"L" Level output	V <sub>OL</sub>	-	$V_{SS}$	-	0.4	V
Backlight Supply Voltage	$V_{LED}$	-	4.9	5.0	5.1	V
Backlight Supply Current	I <sub>LED</sub>	$V_{LED} = 5.0 \text{ V}$	65	130	160	mA

## **Optical Characteristics**

	Ite	em	Symbol	Condition	Min.	Тур.	Max.	Unit
Ontinoal	Тор		φΥ+		-	20	-	0
Optimal Viewing	Bot	tom	φΥ-	C= > 2	-	40	-	0
	Left		θХ-	Cr ≥ 2	-	30	-	0
Angles	Righ	nt	θХ+		-	30	-	0
Contrast Rat	io		Cr	-	-	3	-	-
Despess		Rise	$T_R$	-	-	150	200	ms
Response Ti	ime	Fall	$T_{F}$	-	-	150	200	ms

#### **Controller Information**

Built-in ST7066U Controller.

Please download specification at <a href="http://www.newhavendisplay.com/app">http://www.newhavendisplay.com/app</a> notes/ST7066U.pdf

#### **DDRAM Address**

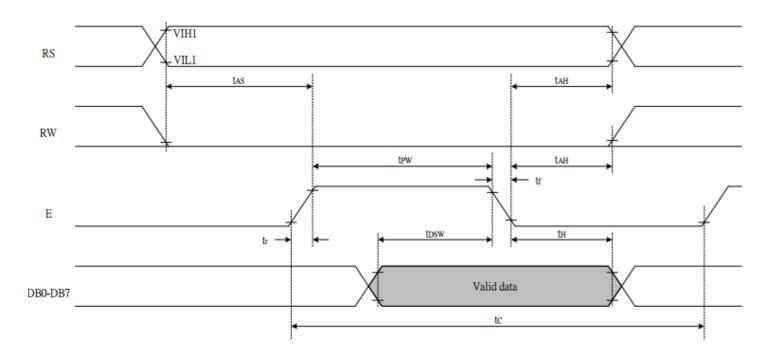
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
00	01	02	03	04	05	06	07	08	09	0A	OB	0C	0D	0E	0F
40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F

## **Table of Commands**

				Ins	tructi	ion co	ode					Execution
Instruction	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	Description	time (fosc= 270 KHZ
Clear Display	0	0	0	0	0	0	0	0	0	1	Write "20H" to DDRAM and set DDRAM address to "00H" from AC	1.52ms
Return Home	0	0	0	0	0	0	0	0	1	-	Set DDRAM Address to "00H" from AC and return cursor to its original position if shifted. The contents of DDRAM are not changed.	1.52ms
Entry mode Set	0	0	0	0	0	0	0	1	I/D	SH	Sets cursor move direction and specifies display shift. These parameters are performed during data write and read.	37μs
Display ON/ OFF control	0	0	0	0	0	0	1	D	С	В	D=1: Entire display on C=1: Cursor on B=1: Blinking cursor on	37µs
Cursor or Display shift	0	0	0	0	0	1	S/C	R/L	-	-	Sets cursor moving and display shift control bit, and the direction without changing DDRAM data.	37µs
Function set	0	0	0	0	1	DL	N	F	-	ı	DL: Interface data is 8/4 bits N: Number of lines is 2/1 F: Font size is 5x11/5x8	37µs
Set CGRAM Address	0	0	0	1	AC5	AC4	AC3	AC2	AC1	AC0	Set CGRAM address in address counter	37µs
Set DDRAM Address	0	0	1	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Set DDRAM address in address counter.	37µs
Read busy Flag and Address	0	1	BF	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Whether during internal operation or not can be known by reading BF. The contents of address counter can also be read.	0s
Write data To Address	1	0	D7	D6	D5	D4	D3	D2	D1	D0	Write data into internal RAM (DDRAM/CGRAM).	37µs
Read data From RAM	1	1	D7	D6	D5	D4	D3	D2	D1	D0	Read data from internal RAM (DDRAM/CGRAM).	37µs

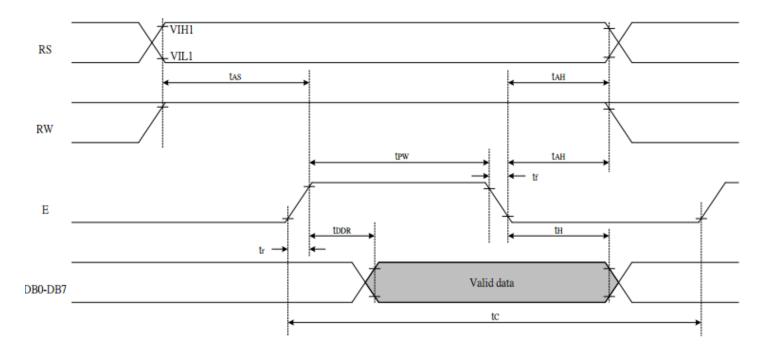
# **Timing Characteristics**

## Writing data from MPU to ST7066U



	Write Mode (Writing data from MPU to ST7066U)									
T <sub>C</sub>	Enable Cycle Time	Pin E	1200	•	•	ns				
T <sub>PW</sub>	Enable Pulse Width	Pin E	140	,		ns				
$T_R, T_F$	Enable Rise/Fall Time	Pin E	-		25	ns				
T <sub>AS</sub>	Address Setup Time	Pins: RS,RW,E	0			ns				
T <sub>AH</sub>	Address Hold Time	Pins: RS,RW,E	10	•	•	ns				
T <sub>DSW</sub>	Data Setup Time	Pins: DB0 - DB7	40	ı	•	ns				
T <sub>H</sub>	Data Hold Time	Pins: DB0 - DB7	10	•	•	ns				

## Reading data from ST7066U to MPU



	Read Mode (Reading Data from ST7066U to MPU)										
T <sub>C</sub>	Enable Cycle Time	Pin E	1200	-	-	ns					
T <sub>PW</sub>	Enable Pulse Width	Pin E	140	•	•	ns					
$T_R, T_F$	Enable Rise/Fall Time	Pin E	•	-	25	ns					
T <sub>AS</sub>	Address Setup Time	Pins: RS,RW,E	0	-	-	ns					
T <sub>AH</sub>	Address Hold Time	Pins: RS,RW,E	10	-	-	ns					
T <sub>DDR</sub>	Data Setup Time	Pins: DB0 - DB7	-	-	100	ns					
T <sub>H</sub>	Data Hold Time	Pins: DB0 - DB7	10	-	-	ns					

## **Built-in Font Table**

<u>67-64</u>	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
0000	CG RAM (1)															
0001	(2)															
0010	(3)															
0011	(4)															
0100	(5)															
0101	(6)															
0110	7)															
0111	(8)															
1000	(1)															
1001	(2)															
1010	(3)															
1011	(4)															
1100	(5)															
1101	(6)															
1110	(7)															
1111	(8)															

#### **Example Initialization Program**

```
8-bit Initialization:
void command(char i)
     P1 = i;
                                 //put data on output Port
                                 //D/I=LOW : send instruction
     DI = 0;
                                 //R/W=LOW : Write
     R_W = 0;
     E = 1;
     Delay(1);
                                 //enable pulse width >= 300ns
     E = 0;
                                 //Clock enable: falling edge
void write(char i)
     P1 = i;
                                 //put data on output Port
     D_I = 1;
                                  //D/I=HIGH: send data
     R_W = 0;
                                 //R/W=LOW : Write
     E = 1;
     Delay(1);
                                 //enable pulse width >= 300ns
     E = 0;
                                 //Clock enable: falling edge
void init()
{
     E = 0;
     Delay(100);
                                 //Wait >40 msec after power is applied
     command(0x30);
                                 //command 0x30 = Wake up
                      //must wait 5ms, busy flag not available
//command 0x30 = Wake up #2
//must wait 160us, busy flag not available
//command 0x30 = Wake up #3
//must wait 160us, busy flag not available
//Function set: 8-bit/2-line
//Set cursor
//Display ON: Cursor ON
     Delay(30);
                                 //must wait 5ms, busy flag not available
     command(0x30);
     Delay(10);
     command(0x30);
     Delay(10);
     command(0x38);
     command(0x10);
                                 //Display ON; Cursor ON
     command(0x0c);
     command(0x06);
                                 //Entry mode set
```

```
4-bit Initialization:
void command(char i)
     P1 = i;
                              //put data on output Port
                              //D/I=LOW : send instruction
     DI = 0;
                              //R/W=LOW : Write
     R_W = 0;
                              //Send lower 4 bits
    Nybble();
     i = i << 4;
                              //Shift over by 4 bits
     P1 = i;
                              //put data on output Port
     Nybble();
                              //Send upper 4 bits
void write(char i)
     P1 = i;
                              //put data on output Port
    D_I = 1;
                              //D/I=HIGH : send data
    R_W = 0;
                             //R/W=LOW : Write
    Nybble();
                             //Clock lower 4 bits
     i = i << 4;
                              //Shift over by 4 bits
    P1 = i;
                              //put data on output Port
    Nybble();
                              //Clock upper 4 bits
/**********************
void Nybble()
     E = 1;
    Delay(1);
                             //enable pulse width >= 300ns
    E = 0;
                              //Clock enable: falling edge
void init()
{
     P1 = 0;
     P3 = 0;
     Delay(100);
                              //Wait >40 msec after power is applied
     P1 = 0x30;
                              //put 0x30 on the output port
     Delay(30);
                              //must wait 5ms, busy flag not available
     Nybble();
                              //command 0x30 = Wake up
     Delay(10);
                              //must wait 160us, busy flag not available
                              //command 0x30 = Wake up #2
     Nybble();
                              //must wait 160us, busy flag not available
     Delay(10);
                              //command 0x30 = Wake up #3
     Nybble();
                              //can check busy flag now instead of delay
     Delay(10);
     P1 = 0x20;
                             //put 0x20 on the output port
    Nybble();
                             //Function set: 4-bit interface
     command(0x28);
                             //Function set: 4-bit/2-line
     command(0x10);
                              //Set cursor
     command(0x0F);
                              //Display ON; Blinking cursor
     command(0x06);
                              //Entry Mode set
            *************
```

## **Quality Information**

Test Item	Content of Test	Test Condition	Note
High Temperature storage	Endurance test applying the high storage temperature for a long time.	+80°C , 48hrs	2
Low Temperature storage	Endurance test applying the low storage temperature for a long time.	-30°C , 48hrs	1,2
High Temperature Operation	Endurance test applying the electric stress (voltage & current) and the high thermal stress for a long time.	+70°C 48hrs	2
Low Temperature Operation	Endurance test applying the electric stress (voltage & current) and the low thermal stress for a long time.	-20°C , 48hrs	1,2
High Temperature / Humidity Operation	Endurance test applying the electric stress (voltage & current) and the high thermal with high humidity stress for a long time.	+40°C, 90% RH, 48hrs	1,2
Thermal Shock resistance	Endurance test applying the electric stress (voltage & current) during a cycle of low and high thermal stress.	0°C,30min -> 25°C,5min -> 50°C,30min = 1 cycle 10 cycles	
Vibration test	Endurance test applying vibration to simulate transportation and use.	10-55Hz , 15mm amplitude. 60 sec in each of 3 directions X,Y,Z For 15 minutes	3
Static electricity test	Endurance test applying electric static discharge.	VS=800V, RS=1.5k $\Omega$ , CS=100pF One time	

Note 1: No condensation to be observed.

Note 2: Conducted after 4 hours of storage at 25°C, 0%RH.

**Note 3:** Test performed on product itself, not inside a container.

#### **Precautions for using LCDs/LCMs**

See Precautions at <a href="https://www.newhavendisplay.com/specs/precautions.pdf">www.newhavendisplay.com/specs/precautions.pdf</a>

#### **Warranty Information and Terms & Conditions**

http://www.newhavendisplay.com/index.php?main\_page=terms