

Root finding

(1) Bisection method :-

$$f(a)f(b) < 0$$

$$\therefore \text{approximate root } x_1 = \frac{a+b}{2}$$

$$\therefore \text{if } (f(x_1)f(b) < 0) \quad , \quad x_2 = \frac{x_1+b}{2}$$

$$\therefore \text{if } (f(x_1)f(a) > 0) \quad , \quad x_2 = \frac{a+x_1}{2}$$

(2) False position method

$$\text{approximate root, } x_1 = \frac{af(b) - f(a)b}{f(b) - f(a)}$$

$$\text{if } [f(x_1)f(b) < 0] \quad x_2 = \frac{x_1f(b) - bf(x_1)}{f(b) - f(x_1)}$$

$$\therefore \text{if } [f(a)f(x_1) < 0] \quad x_2 = \frac{af(x_1) - x_1f(a)}{f(x_1) - f(a)}$$

(3) Newton Raphson

$$\therefore \text{approximate root } x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

(n)

b=n not given

Numerical Integration

$$h = \frac{b-a}{n}$$

① Trapezoid rule (n any)

$$\int_a^b f(x) dx = \frac{h}{2} (y_0 + 2(y_1 + y_2 + y_3 + \dots + y_{n-1}) + y_n)$$
$$= \int_a^b y dx$$

② Simpson's $\frac{1}{3}$ rule = $\frac{h}{3} (y_0 + 4(y_1 + y_3 + \dots + y_{n-1}) + 2(y_2 + y_4 + \dots + y_{n-2}) + y_n)$
(n even)

③ Simpson's $\frac{3}{8}$ rule = $\frac{3h}{8} (y_0 + 3(y_1 + y_2 + y_4 + y_5 + \dots + y_{n-1} + y_{n-2}) + 2(y_3 + y_6 + \dots + y_{n-3}) + y_n)$
(n is divisible by 3)

ODE

① Euler's method:-

$$\frac{dy}{dx} = f(x) = f(x, y)$$

$$\therefore f(x_0) = y_0 \text{ (given)}$$

same for both

$$\therefore y(x_n) = y_n = y_{n-1} + h f(x_{n-1}, y_{n-1})$$

$$\therefore x_n = x_0 + nh$$

$$\therefore h = x_n - x_{n-1} \text{ or given}$$

② Runge-kutta method:-

$$y(x_n) = y_n = y_{n-1} + \frac{1}{2} (k_1 + k_2)$$

$$\therefore k_1 = h f(x_{n-1}, y_{n-1})$$

$$\therefore k_2 = h f(x_{n-1} + h, y_{n-1} + k_1)$$

$$\therefore x_n = x_0 + nh$$

$$\Delta y_0 = y_2 - y_1$$

Interpolation

$$u = \frac{x - x_0}{h}$$

Newton forward formula

$$y(x) = y_0 + \Delta y_0 u + \frac{\Delta^2 y_0}{2!} u(u-1) + \frac{\Delta^3 y_0}{3!} u(u-1)(u-2) + \frac{\Delta^4 y_0}{4!} u(u-1)(u-2)(u-3) + \dots$$

first derivatives,

$$y'(x) = \frac{1}{h} \left(\Delta y_0 + (2u-1) \Delta^2 y_0 + \frac{3u^2 - 6u + 2}{3!} \Delta^3 y_0 + \frac{4u^3 - 18u^2 + 22u - 6}{4!} \Delta^4 y_0 + \dots \right)$$

2nd derivatives

$$y''(x) = \frac{1}{h^2} \left(\Delta^2 y_0 + (u-1) \Delta^3 y_0 + \frac{6u^2 - 18u + 11}{12} \Delta^4 y_0 + \dots \right)$$

3rd derivatives

$$y'''(x) = \frac{1}{h^3} \left(\Delta^3 y_0 + \frac{2u-3}{2} \Delta^4 y_0 + \dots \right)$$

(* given)

Newton backward formula

$$y(x) = y_n + \Delta y_n u + \frac{\Delta^2 y_n}{2!} u(u+1) + \frac{\Delta^3 y_n}{3!} u(u+1)(u+2) + \frac{\Delta^4 y_n}{4!} u(u+1)(u+2)(u+3) + \dots$$

$$\therefore u = \frac{x - x_n}{h}$$

Lagrange formula:

$$f(x) = y(x) = \frac{(x-x_1)(x-x_2)(x-x_3)}{(x_0-x_1)(x_0-x_2)(x_0-x_3)} + \frac{(x-x_0)(x-x_2)(x-x_3)}{(x_1-x_0)(x_1-x_2)(x_2-x_3)} + \frac{(x-x_0)(x-x_1)(x-x_3)}{(x_2-x_0)(x_2-x_1)(x_2-x_3)} + \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_3-x_0)(x_3-x_1)(x_3-x_2)}$$

x given
on
not given =

$$\begin{aligned} a_1x + b_1y + c_1z &= d_1 \\ a_2x + b_2y + c_2z &= d_2 \\ a_3x + b_3y + c_3z &= d_3 \end{aligned}$$

$$\left| \begin{array}{l} |a_1| > |b_1| + |c_1| \\ |b_2| > |a_2| + |c_2| \\ |c_3| > |a_3| + |b_3| \end{array} \right| \left| \begin{array}{l} x = g_1(y, z) \\ y = g_1(x, z) \\ z = g_1(x, y) \end{array} \right|$$

working rule

Gauss-Jacobi:-

$$\begin{aligned} x_i &= g_i(y_{i-1}, z_{i-1}) \\ y_i &= g_i(x_{i-1}, z_{i-1}) \\ z_i &= g_i(x_{i-1}, y_{i-1}) \end{aligned}$$

Gauss seidal:-

$$\begin{aligned} x_i &= g_i(y_{i-1}, z_{i-1}) \\ y_i &= g_i(x_i, z_{i-1}) \\ z_i &= g_i(x_i, y_i) \end{aligned}$$

Gaussian elimination method

convert the argument matrix into row echelon form

$$\left[\begin{array}{ccc|c} 1 & A & B & C \\ 0 & 1 & D & E \\ 0 & 0 & 1 & F \end{array} \right]$$

now operations only =

(x, y, z) = ?

∴ then

$$\begin{aligned} x + yA + zB &= C \\ y + zD &= E \\ z &= F \end{aligned}$$

Gauss Jordan Elimination

now echelon form

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & A \\ 0 & 1 & 0 & B \\ 0 & 0 & 1 & C \end{array} \right]$$

$$\begin{aligned} \therefore x &= A \\ \therefore y &= B \\ \therefore z &= C \end{aligned}$$