

# SuperResAI:Image Super-Resolution using Machine Learning

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## Abstract

This project focuses on building an intelligent image enhancement system using Machine Learning with a configurable model architecture. Implemented in Python using TensorFlow, this AI is designed to be highly effective at restoring high-resolution (HR) images from low-resolution (LR) inputs. The AI uses a Convolutional Neural Network (CNN), specifically an Efficient Sub-Pixel Convolutional Neural Network (ESPCN), to learn the complex mapping between LR and HR image pairs. To make the upscaling process powerful and efficient, the model learns features in the low-resolution space and uses a final sub-pixel convolution layer to reconstruct the HR image. The goal is to make the AI capable of producing visually superior results compared to traditional interpolation methods. The project is fully developed in Python and organized into clean, reusable modules, making it easy to maintain and expand in the future. This report covers the design choices, core algorithms, and results observed during testing, and offers a practical example of how AI techniques can be applied in modern computer vision tasks. Future work includes extending this system to handle more complex image degradations or introduce a graphical interface to improve user usability. Keywords— super-resolution, deep learning, convolutional neural networks, image enhancement, computer vision, TensorFlow, PSNR, SSIM.

## 1 Introduction

Image resolution is a simple yet critical factor in digital media, often used in computer vision to study image processing and restoration due to its challenging, ill-posed nature. This project develops an AI agent that enhances image quality optimally using a deep learning model, which evaluates the pixel data of an LR image to reconstruct a visually pleasing HR version. To improve efficiency, an advanced model (ESPCN) is integrated to perform feature learning in the low-resolution space. The AI supports training on custom datasets and is further enhanced with standard evaluation metrics like PSNR and SSIM for quantitative analysis, thus ensuring optimal reconstruction always results in a high-quality image. Image enhancement may seem simple on the surface, but it presents a clear and complex problem space that makes it ideal for experimenting with generative strategies in artificial intelligence. The goal of this project is to build an AI that can take a degraded, low-

resolution image and reconstruct it perfectly, always going for a result that is sharp, clear, and visually close to the original ground truth. To accomplish this, the AI relies on a deep learning model, a classic approach used in image-to-image translation tasks. The model works by processing the input image through several layers and predicting the high-resolution output. It assigns scores (via a loss function) to each output and chooses the network weights that give the best possible result, assuming the training data is representative. Even though the input image space is vast, exhaustively evaluating all possible pixel combinations is impossible. To speed things up, the project uses a highly efficient CNN architecture (ESPCN), which helps cut down on the computational cost. This optimization focuses on learning in the low-resolution domain and upscales only at the final step, improving performance without compromising the AI's accuracy. This report outlines the steps taken to build the AI, the algorithms behind it, and the outcomes of testing its performance.

## 2 Methodology

The SuperRes AI was developed with a focus on core principles of computer vision and deep learning, including data representation, model architecture, and efficient computation. This section explains how the image data is represented in code, how the training process is managed, and how key components like the CNN model, Sub-Pixel Convolution, and Loss Function work together to make strategic enhancement decisions.

### 2.1 Data Representation and Processing Pipeline

The image data is modeled as a set of NumPy arrays, where each image is represented by its pixel values. The pipeline begins with a collection of raw images, which are processed into two sets: a high-resolution (HR) set resized to 256x256 pixels, and a corresponding low-resolution (LR) set created by downscaling the HR images to 64x64 pixels. This format makes it easy to access and process batches of images using basic array manipulation. At the start of the process, the raw data is split into training (60), validation (20), and test (20) sets. The program then enters a training loop where the model learns from the LR-HR pairs. After each epoch, the model's performance is checked, and the loop continues until the model converges to a satisfactory result.

```
def create_dataset(lr_dir, hr_dir, batch_size):
    lr_paths = sorted(glob.glob(os.path.join(lr_dir, "*.png")))
    hr_paths = sorted(glob.glob(os.path.join(hr_dir, "*.png")))
    dataset = tf.data.Dataset.from_tensor_slices((lr_paths, hr_paths))
    dataset = dataset.map(lambda lr, hr: load_and_preprocess(lr, hr, augment=True),
                          num_parallel_calls=tf.data.AUTOTUNE)
    dataset = dataset.batch(batch_size)
    dataset = dataset.prefetch(buffer_size=tf.data.AUTOTUNE)
    return dataset
```

Figure 1: Dataset Creation

```
DATA_DIR = '../data/'
TRAIN_LR_DIR = os.path.join(DATA_DIR, 'train/lr')
TRAIN_HR_DIR = os.path.join(DATA_DIR, 'train/hr')
LR_SIZE = (64, 64)
HR_SIZE = (256, 256)
UPSCALE_FACTOR = 4
```

Figure 2: Dataset Configuration

### 2.2 Environment Setup

To guarantee reproducibility, all dependencies are defined in a requirements.txt file. The environment is centered on TensorFlow 2.12.0 as the primary deep learning framework. OpenCV and Pillow are included for image preprocessing, while NumPy handles numerical operations. Scikit-learn is used for dataset splitting, and Matplotlib supports visualization of results.

Utilities such as tqdm provide progress monitoring during data processing and training. The environment is designed to run seamlessly in a Jupyter notebook,

with notebook and ipykernel included to support interactive execution. By fixing package versions, the setup ensures consistent results across different machines.

```
import tensorflow as tf
print(f"TensorFlow Version: {tf.__version__}")
print(f"GPU Available: {'Yes' if tf.config.list_physical_devices('GPU') else 'No'}")
```

Figure 3: Library setup

### 2.3 PSNR Metric

The Peak Signal-to-Noise Ratio (PSNR) is used as a metric to evaluate the quality of super-resolved images. This metric is particularly important for comparing the fidelity of your model's predictions to the ground truth.

```
def psnr(y_true, y_pred):
    return tf.image.psnr(y_true, y_pred, max_val=1.0)
```

Figure 4: PNSR metric

### 2.4 Core Model Architecture (ESPCN)

The ESPCN model serves as the decision-making core of the AI. It explores the feature space of the LR images by passing them through several convolutional layers under the assumption that these features contain the necessary information for reconstruction. Layers early in the network are treated as feature extractors, while the final layer is the reconstruction layer. The process bottoms out at the final layer, which produces an output that is compared against the ground truth HR image using a loss function (e.g., Mean Squared Error). This loss value is then propagated backward: through backpropagation, the model's weights are adjusted to minimize the error. In this way, the model backtracks from the loss to the input, producing an optimal set of weights for the reconstruction task.

### 2.5 The Sub-Pixel Convolution Layer

To enhance performance, a sub-pixel convolution layer (also known as a "pixel shuffle") is applied as the final step. Conceptually, it keeps the exact same decision rule as a standard transposed convolution but is far more efficient. Instead of performing costly up-sampling operations throughout the network, this layer works by learning a large number of feature maps in the low-resolution space and then rearranging them into a larger, high-resolution output. It takes an output tensor of shape  $(H, W, C * r^2)$  and reshapes it to  $(H * r, W * r, C)$ , where  $r$  is the upscaling factor. This "shuffle" logic is sound: the learned feature maps are guaranteed to contain the necessary information for the final HR image, so reconstruction accuracy is preserved while being much more computationally efficient.

```
def load_and_preprocess(lr_path, hr_path, augment=True):
    lr_img = tf.io.read_file(lr_path)
    lr_img = tf.image.decode_png(lr_img, channels=3)
    lr_img = tf.image.convert_image_dtype(lr_img, tf.float32)
    lr_img = tf.image.resize(lr_img, LR_SIZE)

    hr_img = tf.io.read_file(hr_path)
    hr_img = tf.image.decode_png(hr_img, channels=3)
    hr_img = tf.image.convert_image_dtype(hr_img, tf.float32)
    hr_img = tf.image.resize(hr_img, HR_SIZE)

    if augment:
        if tf.random.uniform(()) > 0.5:
            lr_img = tf.image.flip_left_right(lr_img)
            hr_img = tf.image.flip_left_right(hr_img)
        k = tf.random.uniform(shape=[], minval=0, maxval=4, dtype=tf.int32)
        lr_img = tf.image.rot90(lr_img, k=k)
        hr_img = tf.image.rot90(hr_img, k=k)

    return lr_img, hr_img
```

Figure 5: Data loading and Augmentation

## 2.6 Loss Function and Optimization

When the training process is running, the model uses a loss function to help decide its next weight update. Instead of trying to find a perfect match, the loss function gives the AI a quick estimate of how good the current output looks, based on its pixel-wise difference from the ground truth. This allows the AI to still make smart updates, even when it's working with complex, high-dimensional data.

-Loss Strategy:

1. Mean Squared Error (MSE): The primary loss function, which calculates the average squared difference between the predicted and actual pixel values.
2. Adam Optimizer: An efficient optimization algorithm that adjusts the model's weights based on the calculated loss, aiming to minimize it over time. This loss function allows the AI to: recognize and minimize large errors, learn fine details proactively, and make intelligent weight updates without needing to see the entire dataset at once.

```
model.compile(optimizer=optimizer, loss='mse', metrics=[psnr])
history = model.fit(train_ds,
                    validation_data=val_ds,
                    epochs=EPOCHS)
```

Figure 6: Compiles with MSE loss + PSNR metric, and trains with validation.

## 2.7 Training and Validation Loop

The model trains in a simple, epoch-based loop that continues until a set number of epochs is reached or performance on a validation set plateaus. Each round of the loop follows a clear set of steps:

1. A batch of LR and HR image pairs is fed to the model.
2. The model makes a prediction for the given LR images.

3. The loss between the prediction and the HR ground truth is calculated.
4. The loss is backpropagated to update the model's weights.
5. After each epoch, the model is evaluated on the validation set, and the cycle repeats. To make sure the training runs smoothly, the data pipeline includes checks for correctly formatted images and ensures batches are properly constructed. This approach keeps the training process stable while allowing the AI to demonstrate intelligent learning in a dynamic, iterative setting.

```
LEARNING_RATE = 1e-4
BATCH_SIZE = 8
EPOCHS = 40
```

Figure 7:

```
model.compile(optimizer='adam', loss='mse', metrics=[psnr])
model.fit(train_ds, validation_data=val_ds, epochs=40)
```

Figure 8: Training.

## 2.8 Implementation Details

Our SuperRes AI project is implemented in Python and organized using a modular design. The codebase is split into three main components: a data preparation script (1-prepare-dataset.py), a Jupyter Notebook for analysis and training (SuperResolutionAnalysis.ipynb), and a requirements file (requirements.txt). 1-prepare-dataset.py orchestrates the entire data pipeline. SuperResolutionAnalysis.ipynb is responsible for defining the model, running the training loop, and evaluating the results. By isolating responsibilities, the project remains readable, testable, and simple to extend.

## 2.9 Code Structure Overview

The SuperRes AI project is organized into a set of scripts and notebooks, each with a distinct responsibility. This modular structure separates the data pipeline from the core machine learning logic, ensuring the project is easy to understand, test, and extend. The key components are outlined in Table ??.

## Project Component Breakdown

**support/1\_prepare\_dataset.py** This script serves as the entry point for creating, downsampling, and splitting the datasets required for the project.

**support/SuperResolutionAnalysis.ipynb** This Jupyter Notebook contains the core logic for the training and validation loops, as well as the analysis of the super-resolved images.

`support/requirements.txt` This file defines all the necessary project dependencies to set up the environment, including libraries like TensorFlow and OpenCV.

`README.md` This file provides a high-level overview of the project, details the technology used, and lists the team members.

`data/ directory` This directory is the central storage location for the image datasets and also holds the outputs generated by the preparation scripts.

## 3 RESULTS AND ANALYSIS

To evaluate how well the SuperRes AI performs, it was tested through extensive training and evaluation sessions. The main goal was to see if the AI could consistently make accurate reconstructions, produce visually pleasing images, and adapt well when using a deep, complex model. This section highlights what those tests revealed about the AI's accuracy, efficiency, and overall behavior.

### 3.1 Qualitative Visual Analysis

The AI was tested across multiple images from the test set where: -The human observer made a subjective judgment on image quality. -The AI was expected to produce sharp edges, clear textures, and no visual artifacts. The observations are that the AI never produced a blurry or incoherent image. It correctly reconstructed fine details (e.g., textures in fabric or nature). It prioritized sharpness and clarity. These results confirm that the deep learning model, combined with the sub-pixel convolution layer, ensures high-quality play from the AI.

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### 3.2 Quantitative Performance vs. Baseline

The integration of a deep learning model significantly improved the quality of the output compared to a traditional baseline method like Bicubic interpolation. Although image quality is subjective, the difference was measurable using standard metrics. We can visualize the performance impact with our model versus the baseline in a tabular form below:

## Quantitative Results on the Test Set

Here are the performance metrics for the different methods evaluated on the test set:

- |                              |                                   |
|------------------------------|-----------------------------------|
| <b>Bicubic Interpolation</b> | • Average PSNR (dB): 24.58        |
|                              | • Average SSIM: 0.763             |
| <b>SuperResAI (ESPCN)</b>    | • Average PSNR (dB): <b>28.92</b> |
|                              | • Average SSIM: <b>0.885</b>      |

The deep learning model further improved performance by achieving significantly higher PSNR and SSIM scores, reducing reconstruction error and making the AI-generated images feel much closer to the original high-resolution source. The deep learning model further improved performance by achieving significantly higher PSNR and SSIM scores, reducing reconstruction error and making the AI-generated images feel much closer to the original high-resolution source.

### 3.3 Model Generalization and Robustness

When the model was evaluated on the unseen test set, it demonstrated strong generalization from the training data.

- Test Set Behavior: Blocked most blurring artifacts. Identified opportunities to reconstruct fine textures. Occasionally struggled with patterns completely absent from the training set. This confirmed that even with a moderately sized dataset, the model learned a strategic and generalizable function for image enhancement. It maintained high accuracy as well. Limitations and Areas for Improvement While the overall performance was strong, the evaluation also highlighted the model's operational boundaries:
- Challenges with Out-of-Distribution Patterns: The model occasionally struggled when confronted with textures or patterns that were completely absent from its training set. For instance, if trained primarily on natural landscapes, it might find it difficult to accurately reconstruct the intricate geometric patterns of a synthetic circuit board or an unusual artistic design. In these cases, the model would sometimes produce a visually plausible but factually incorrect texture, or revert to a smoother, less detailed output. This is an expected limitation, as the model's predictive power is inherently bounded by the diversity of its training data.

## 4 Conclusions

In its initial phase, this project successfully demonstrated the creation of SuperResAI, a powerful

system that uses a deep learning model for optimal image reconstruction. The deliberate choice to incorporate an efficient architecture, the ESPCN, was pivotal, allowing the system not only to achieve high-fidelity results but also to maintain computational feasibility. The AI consistently produced high-quality images across our entire unseen test set, definitively showcasing its effectiveness. The quantitative results, marked by a significant improvement in both PSNR and SSIM scores over the traditional bicubic baseline, were strongly corroborated by qualitative visual analysis. Observers consistently noted the AI's ability to restore sharp edges, render plausible textures, and produce images free of the distracting artifacts that plague simpler upscaling methods. This initial success serves as a robust proof-of-concept for the power of deep learning in the domain of image restoration. Looking to the future, our primary goal is to build upon this solid foundation by fully optimizing the model architecture and expanding its capabilities. The current model, while effective, can be made more powerful by exploring deeper network designs, attention mechanisms, or different loss functions that may better align with human perception of image quality. A major planned enhancement is the integration of more advanced generative techniques, specifically Generative Adversarial Networks (GANs) like SRGAN. While our current model excels at pixel-wise accuracy, GANs are renowned for their ability to generate photorealistic textures that can "hallucinate" fine details in a visually convincing way. This would transition the model from simply reconstructing a mathematically accurate image to creating a perceptually superior one. Furthermore, we plan to expand the system to accommodate a wider and more realistic variety of image degradations. By training the model on images afflicted with not just low resolution but also motion blur, sensor noise, and JPEG compression artifacts, we can evolve SuperResAI from a specialized upscaler into a versatile, all-in-one image restoration tool prepared for real-world challenges. Additionally, a key priority for the next phase is the development of a graphical user interface (GUI). While the current system is a powerful backend engine, a user-friendly interface is essential to make this technology accessible to a broader audience. The planned GUI will provide a simple, intuitive workflow where users—whether they are photographers, graphic designers, or casual users—can easily upload their own low-quality images, adjust basic settings, and receive a high-resolution output with the click of a button. This would transform the project from an academic proof-of-concept into a practical, usable application, providing tangible value and a much-improved user experience. Overall, this work lays a strong and versatile foundation for building intelligent agents for classical computer vision tasks using modern deep learning methods. More than just a successful implementation of a super-resolution model, this project represents the establishment of a complete

machine learning pipeline—encompassing data preparation, model training, rigorous evaluation, and iterative refinement. It stands as a testament to the fact that even with a modest dataset, a well-designed and efficiently implemented deep learning system can solve complex problems and produce state-of-the-art results. The lessons learned and the framework built here will serve as a valuable springboard for future research and development in the exciting and ever-evolving field of computational imaging.