

lab 1 - part 1

Options...

Override Mass Properties... Recalculate

☒ Include hidden bodies/components
☐ Create Center of Mass feature
☐ Show weld bead mass

Report coordinate values relative to: -- default --

Mass properties of lab 1 - part 1
Configuration: Default
Coordinate system: -- default --

Density = 0.04 pounds per cubic inch

Mass = 2.34 pounds

Volume = 64.66 cubic inches

Surface area = 165.70 square inches

Center of mass: (inches)
X = 1.50
Y = 0.00
Z = -0.04

Principal axes of inertia and principal moments of inertia: (pounds * square inches)
Taken at the center of mass.
I_x = (0.00, 1.00, 0.00) P_x = 5.45
I_y = (0.00, 0.00, 1.00) P_y = 16.87
I_z = (1.00, 0.00, 0.00) P_z = 18.81

Moments of inertia: (pounds * square inches)
Taken at the center of mass and aligned with the output coordinate system. (Using positive tensor notation.)
I_{xx} = 18.81 I_{xy} = 0.00 I_{xz} = 0.00
I_{yx} = 0.00 I_{yy} = 5.45 I_{yz} = 0.00
I_{zx} = 0.00 I_{zy} = 0.00 I_{zz} = 16.87

Moments of inertia: (pounds * square inches)
Taken at the output coordinate system. (Using positive tensor notation.)
I_{xx} = 18.81 I_{xy} = 0.00 I_{xz} = -0.13
I_{yx} = 0.00 I_{yy} = 10.71 I_{yz} = 0.00
I_{zx} = -0.13 I_{zy} = 0.00 I_{zz} = 22.12

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lab 1 - part 1

Offset Entities Convert Entities Mirror Entities Extruded Boss/Base Extruded Cut Fillet Linear Pattern Mirror Draft Shell Reference Geometry Measure Mass Properties

Preparation

SOLIDWORKS Student Edition - Academic Use Only

Editing Part Simplified Interface IPS

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Mass Properties

lab 1 - part 2

Options...

Override Mass Properties... Recalculate

☒ Include hidden bodies/components
☐ Create Center of Mass feature
☐ Show weld bead mass

Report coordinate values relative to: -- default --

Mass properties of lab 1 - part 2
Configuration: Default
Coordinate system: -- default --

Density = 0.00 grams per cubic millimeter

Mass = 241.19 grams

Volume = 241189.43 cubic millimeters

Surface area = 46850.30 square millimeters

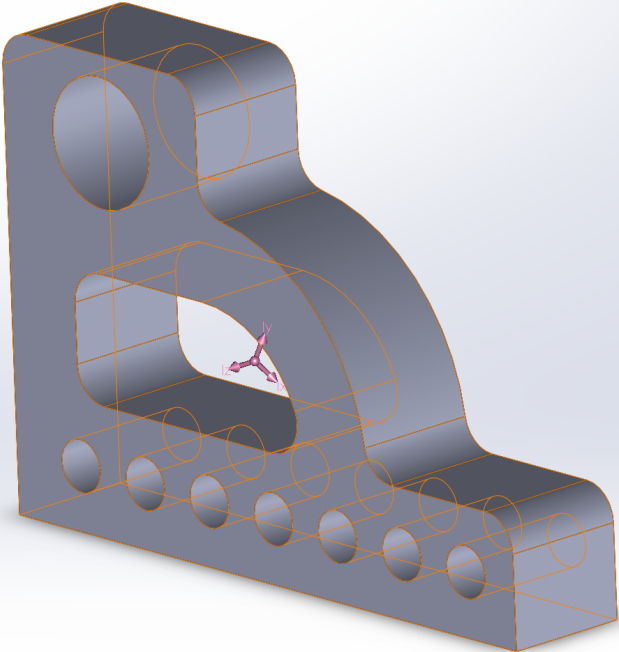
Center of mass: (millimeters)
X = 15.00
Y = 59.89
Z = 43.10

Principal axes of inertia and principal moments of inertia: (grams * square millimeters)
Taken at the center of mass.
I_x = (0.00, 0.89, -0.45) P_x = 194381.59
I_y = (0.00, 0.45, 0.89) P_y = 521093.52
I_z = (1.00, 0.00, 0.00) P_z = 679296.70

Moments of inertia: (grams * square millimeters)
Taken at the center of mass and aligned with the output coordinate system. (Using positive tensor notation.)
L_{xx} = 679296.70 L_{xy} = 0.00 L_{xz} = 0.00
L_{yx} = 0.00 L_{yy} = 260081.60 L_{yz} = -130952.22
L_{zx} = 0.00 L_{zy} = -130952.22 L_{zz} = 455393.51

Moments of inertia: (grams * square millimeters)
Taken at the output coordinate system. (Using positive tensor notation.)
I_{xx} = 1992491.08 I_{xy} = 216682.32 I_{xz} = 155925.33
I_{yx} = 216682.32 I_{yy} = 762364.22 I_{yz} = 491633.79
I_{zx} = 155925.33 I_{zy} = 491633.79 I_{zz} = 1374840.52

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The image shows a 3D model of a mechanical part, likely a bracket or support, with a coordinate system (X, Y, Z) centered at the mass center. The part has a complex shape with a large central cutout and several smaller circular features. The coordinate system is oriented such that the Z-axis points upwards, the Y-axis points to the right, and the X-axis points out of the page.

Mass Properties

lab 1 - part 3

Options...

Override Mass Properties... Recalculate

☒ Include hidden bodies/components

☐ Create Center of Mass feature

☐ Show weld bead mass

Report coordinate values relative to: -- default --

Mass properties of lab 1 - part 3
Configuration: Default
Coordinate system: -- default --

Density = 0.00 grams per cubic millimeter

Mass = 15374.17 grams

Volume = 15374170.18 cubic millimeters

Surface area = 623882.73 square millimeters

Center of mass: (millimeters)

| | | |
|----------|------------|-----------|
| X = 0.00 | Y = 160.53 | Z = -0.30 |
|----------|------------|-----------|

Principal axes of inertia and principal moments of inertia: (grams * square millimeters)
Taken at the center of mass.

| | |
|----------------------------|-------------------|
| lx = (0.00, 1.00, -0.01) | Px = 181853165.62 |
| ly = (0.00, 0.01, 1.00) | Py = 304529952.90 |
| lz = (1.00, 0.00, 0.00) | Pz = 400563583.97 |

Moments of inertia: (grams * square millimeters)
Taken at the center of mass and aligned with the output coordinate system. (Using positive tensor notation.)

| | | |
|--------------------|--------------------|--------------------|
| Lxx = 400563583.97 | Lxy = 0.00 | Lxz = 0.00 |
| Lyx = 0.00 | Lyy = 181864538.45 | Lyx = -1181123.64 |
| Lzx = 0.00 | Lzy = -1181123.64 | Lzz = 304518580.07 |

Moments of inertia: (grams * square millimeters)
Taken at the output coordinate system. (Using positive tensor notation.)

| | | |
|--------------------|--------------------|--------------------|
| lxx = 796740525.74 | lxy = 0.00 | lxz = 0.00 |
| lyx = 0.00 | lyy = 181865967.64 | lyz = -1933593.75 |
| lzx = 0.00 | lzy = -1933593.75 | lzz = 700694092.64 |

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lab 1 - part 3

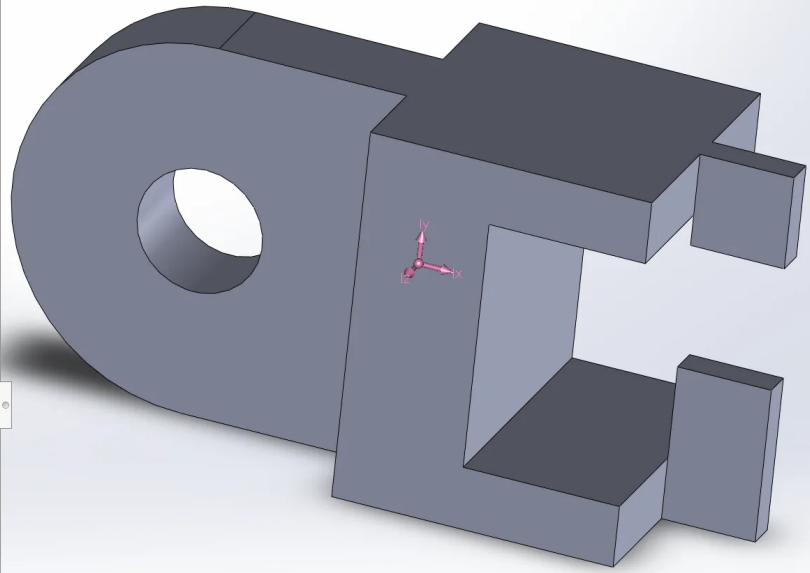
Search files and models

Sketch Line Corner Rectangle Circle Polygon Centerpoint Arc Spline Smart Dimension Add Relation Sketch Fillet Trim Entities Linear Sketch Pattern Offset Entities Convert Entities Mirror Entities Extruded Boss/Base Extruded Cut Fillet Linear Pattern Mirror Draft Shell Reference Geometry Measure Mass Properties

Basic Modeling Tools SOLIDWORKS CAM SOLIDWORKS CAM TBM Simulation Analysis Preparation

lab 1 - part 3

- Solid Bodies(1)
- Equations
- Material <not specified>
- Front Plane
- Top Plane
- Right Plane
- Origin
- Boss-Extrude1
- Sketch1
- Mirror1
- Cut-Extrude2
- Sketch2



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