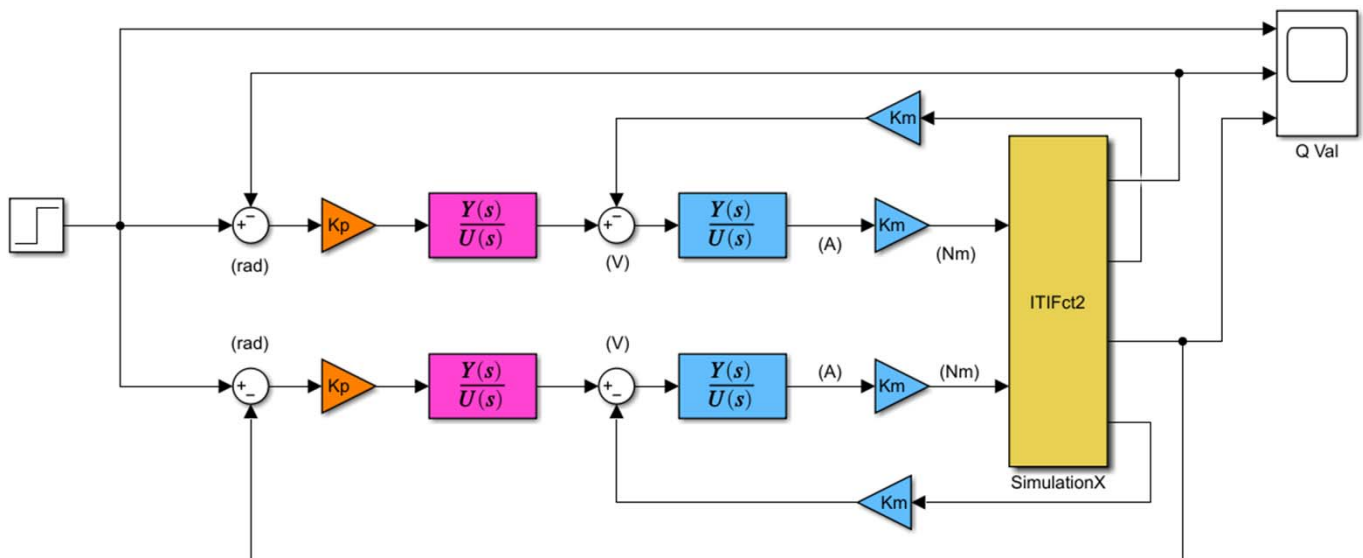


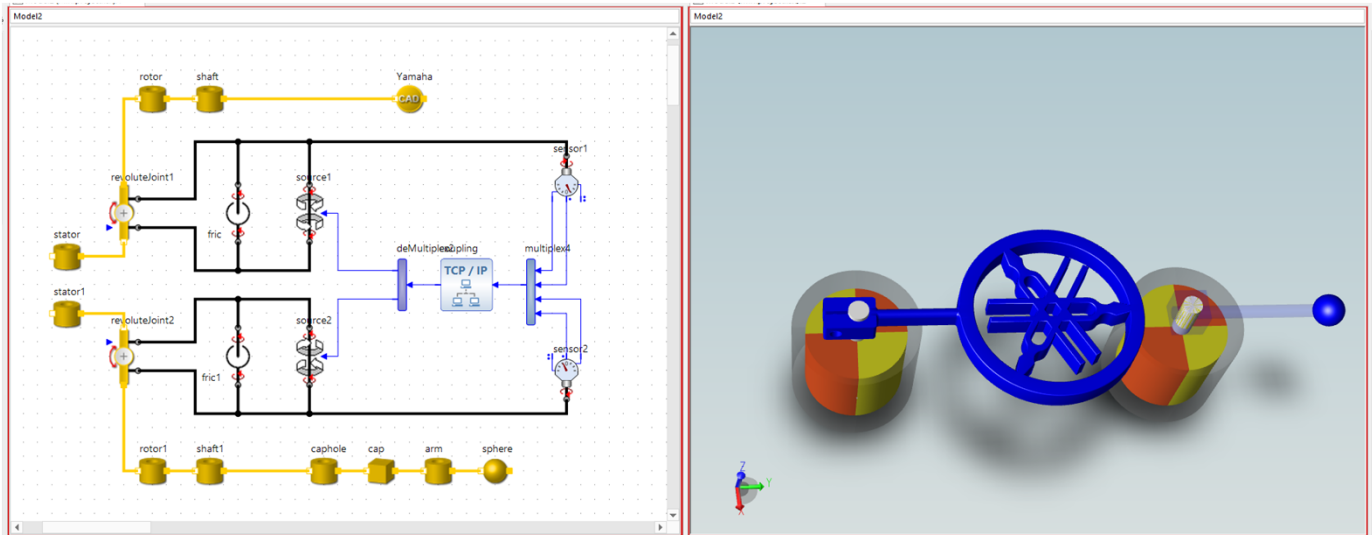
# Simulink



## Example System

- 2 identical systems
- Step response
- P-Controller (orange)
- Amplifier (pink)
- Electrical motor model (blue)

# Actual & Approx Inertia



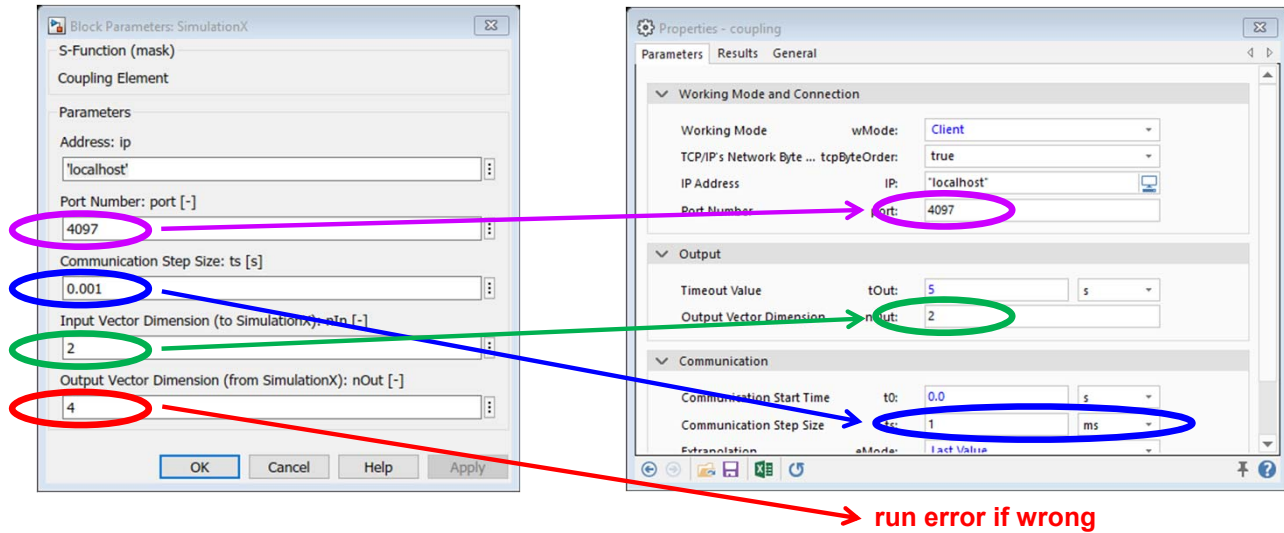
## Example System

- Yamaha pendulum
- Actual part from SolidWorks
- STL format
- Sphere mass
- Located at COM
- Arm transparent -> no dynamics
- Identical motor (rotor) dynamics

# Co-Simulation

## Simulink ITIFct2

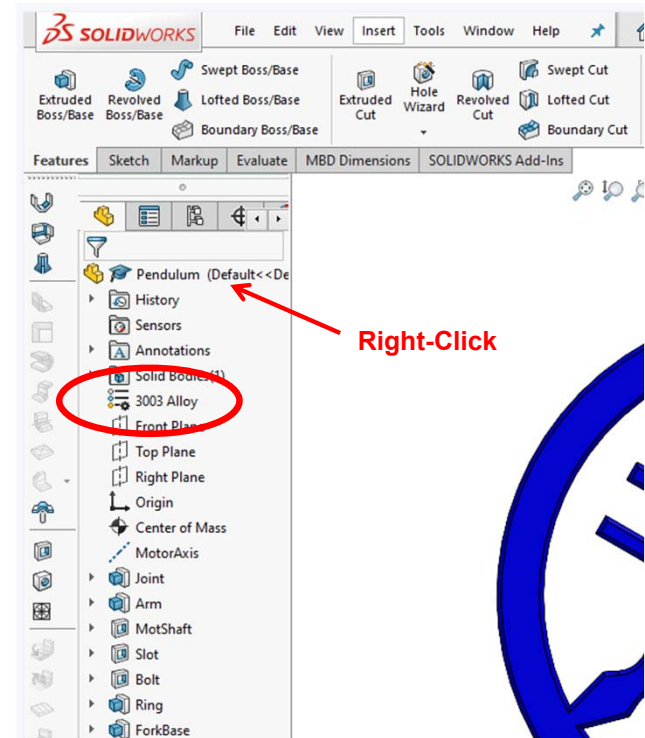
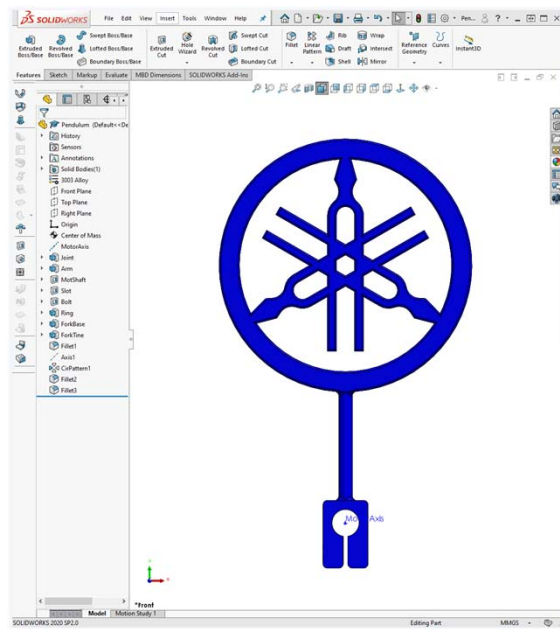
## SimulationX TCP/IP



## Display Results

- Drag & drop
- Minor differences in inertia

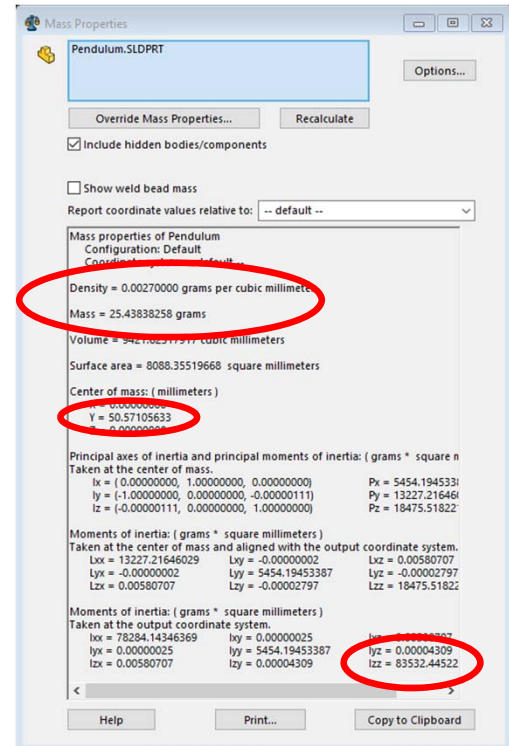
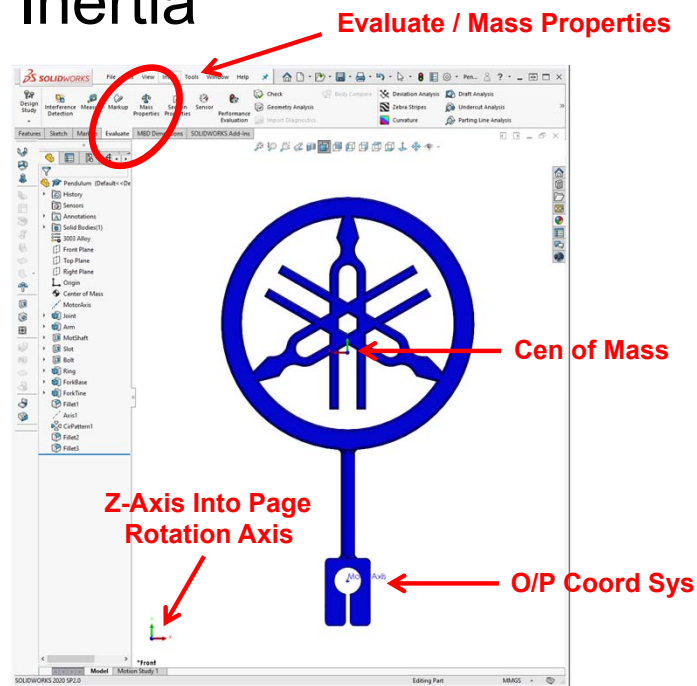
# Material



## From SolidWorks

- Apply material to part
- Shows up in design tree

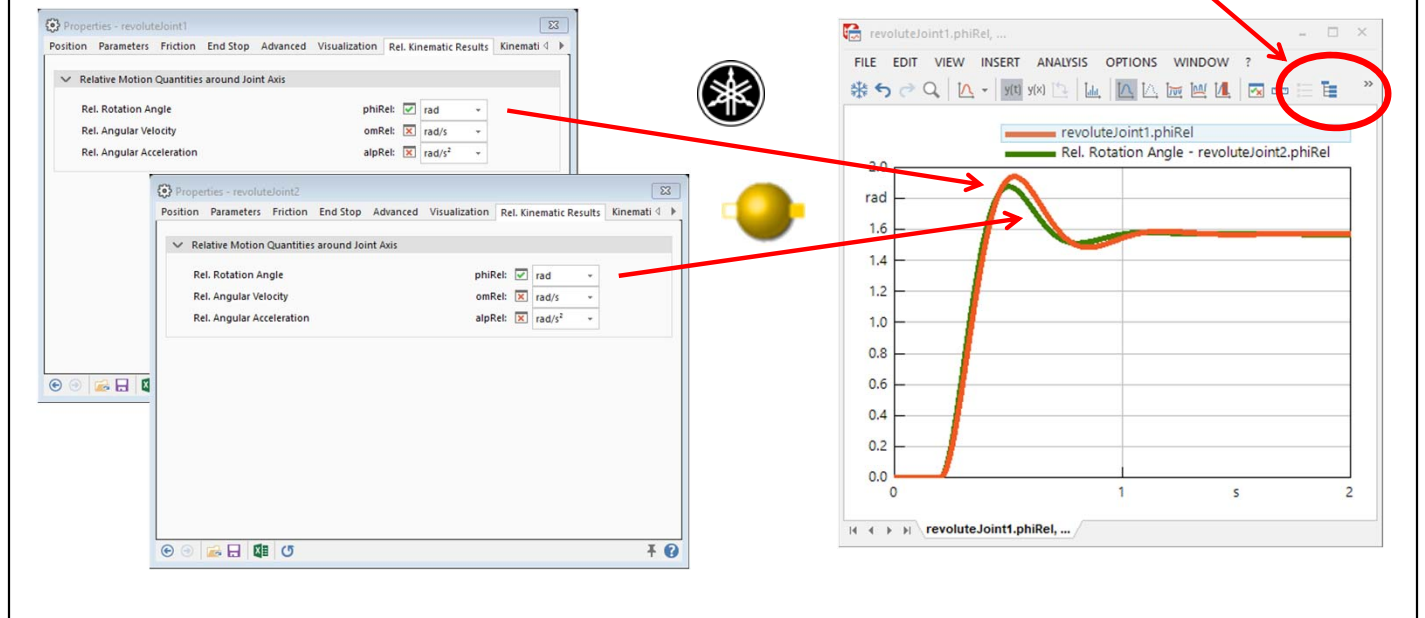
# Inertia



## Evaluate Tab

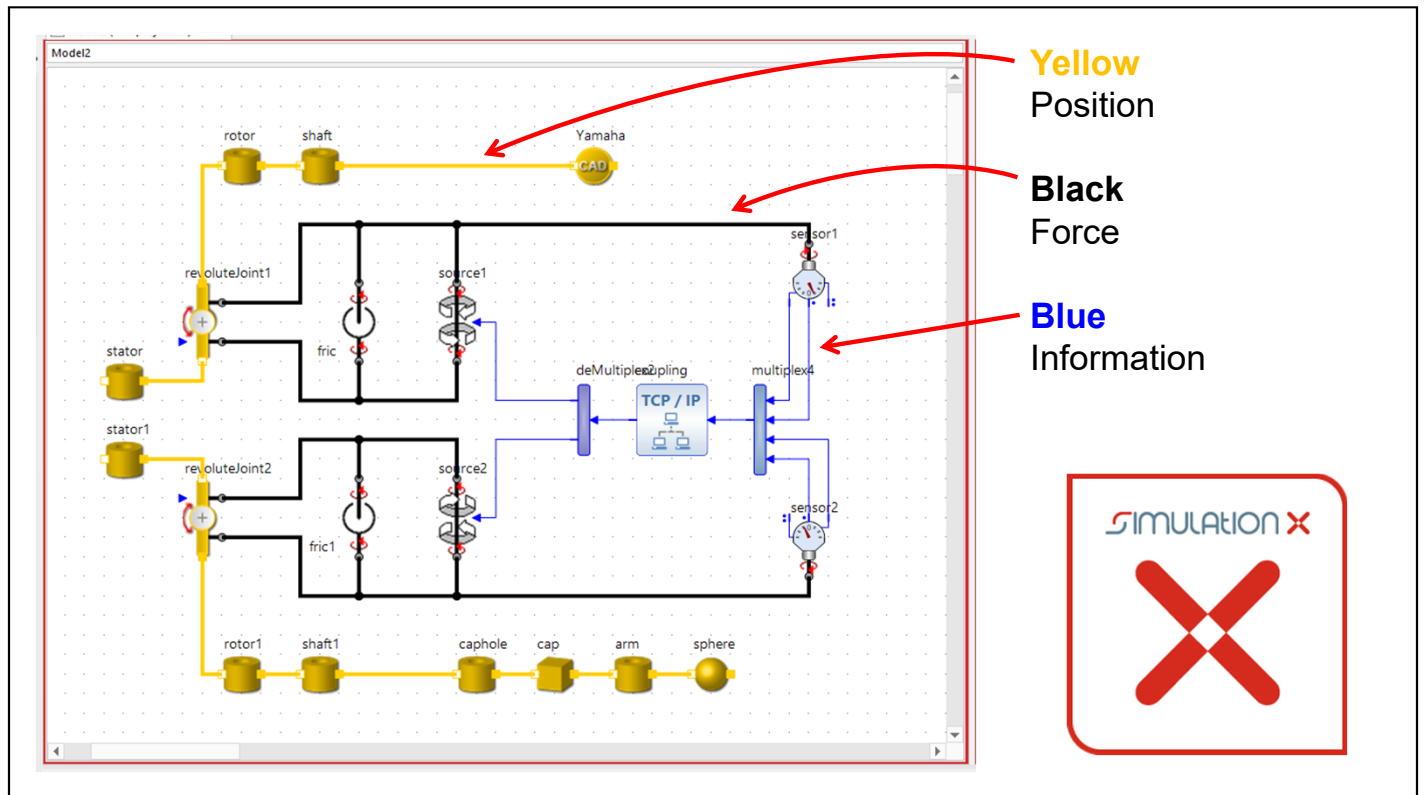
- Model Properties
- Material density
- Mass
- COM
- Inertia Tensors
- Choose co-ordinate centre wisely to get useful info

# Results



## Display Results

- Drag & drop
- Minor differences in inertia



### Position

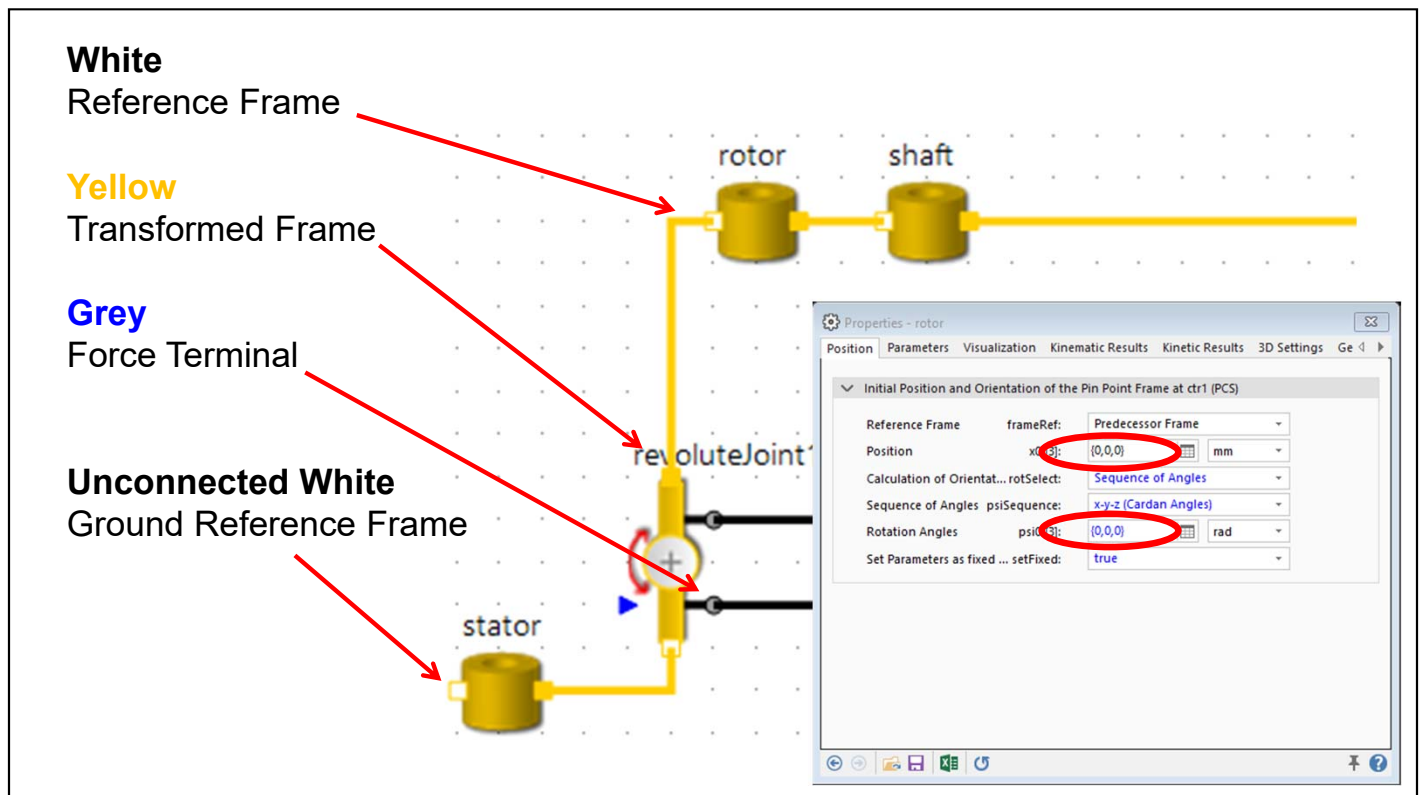
- Location of components
- Predecessor frame + motion / rotation
- Defines system inertia

### Force

- Mechanical models
- Not a physical object that you can pick up and hold

### Information

- Signals
- Just like Simulink



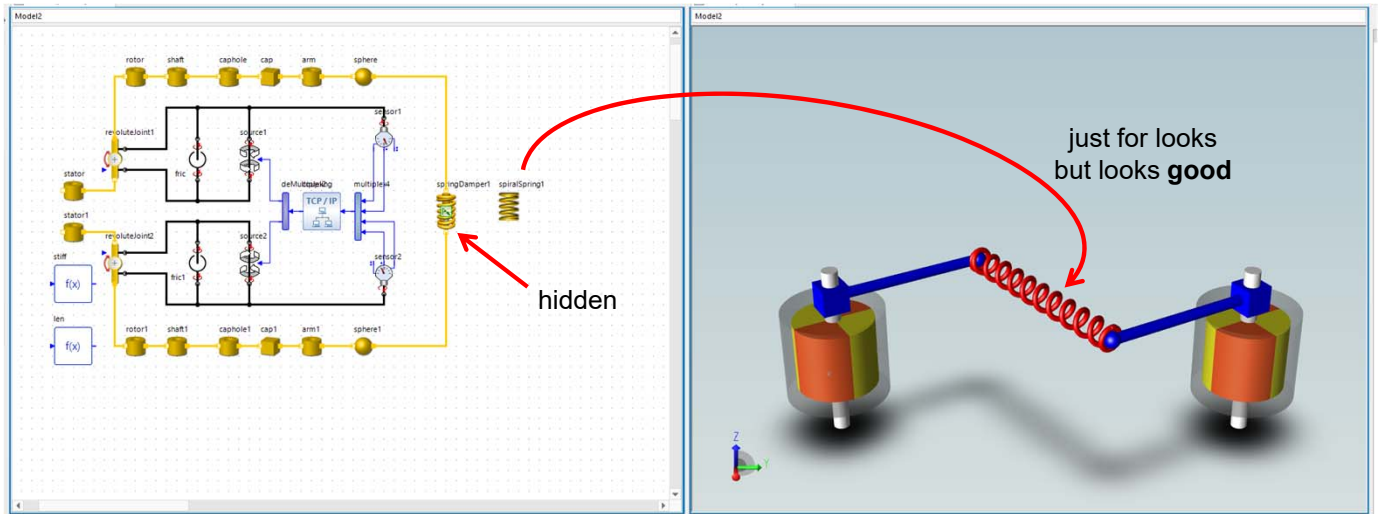
### Rigid Bodies

- Reference frame aligns with Transformed frame of previous element
- Position & Rotation Angles Transform frame



# Flexible Members & Animation Bodies

White  
Reference Frame



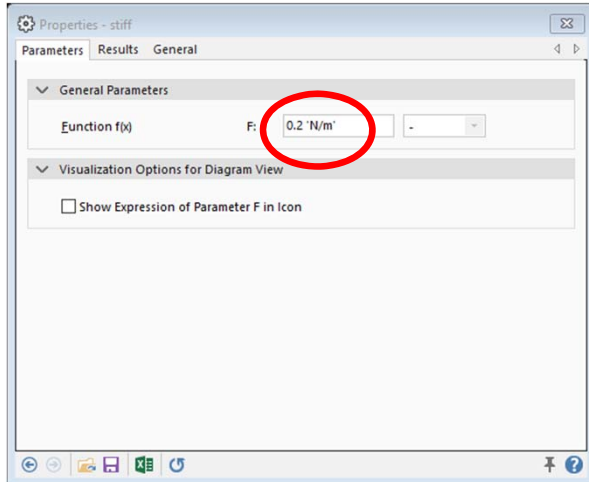
## Force Elements

- No fixed length
- 2 Reference Frames (White)
- Reaction force
- Closed kinematic chains

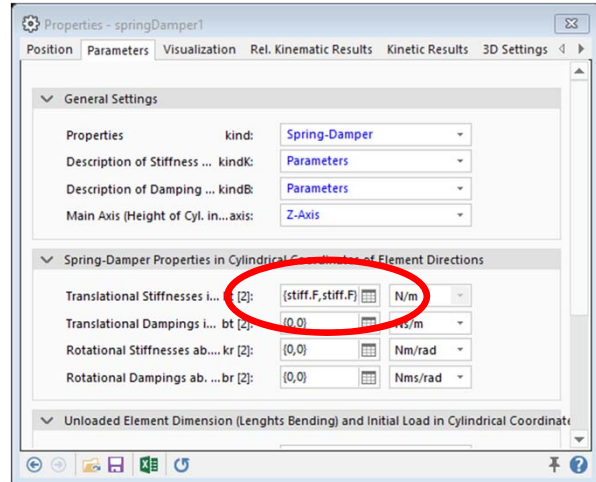
## Animation Bodies

- No dynamic effect
- Visual representation only
- No explicit connection (yellow) to model
- Physical spring hidden

## Function Properties



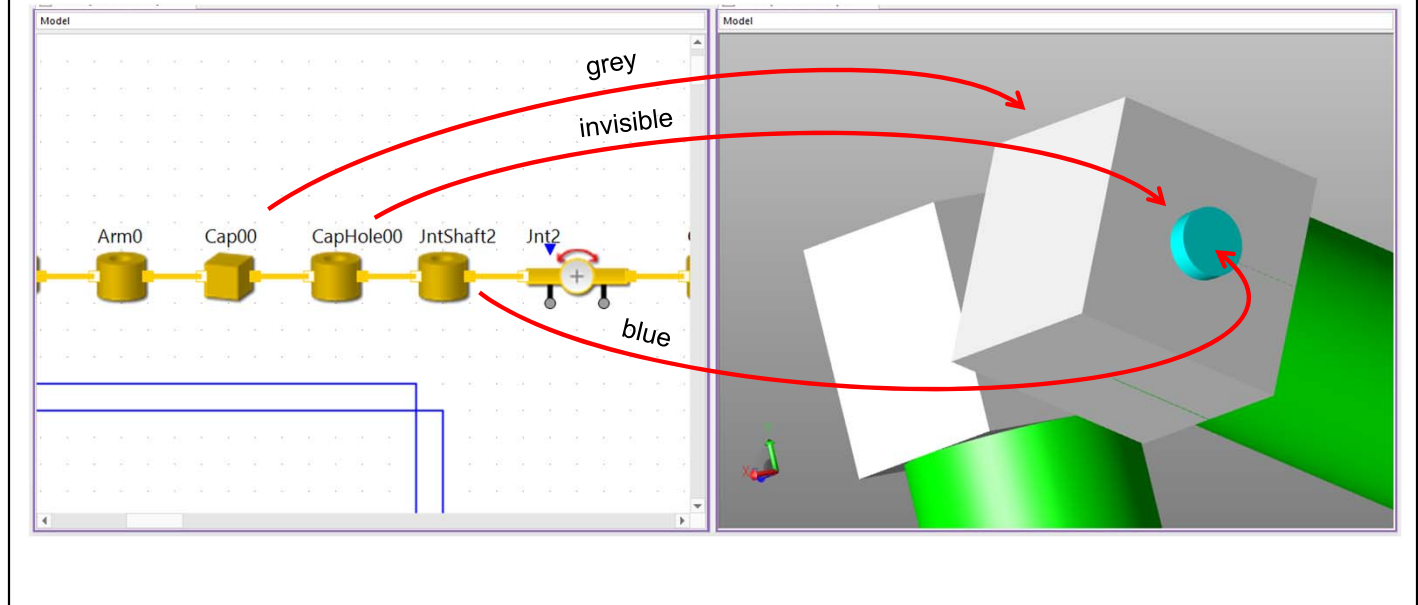
## Body Properties



### Useful When

- Parameter used in multiple places
- Design parameter

# Holes

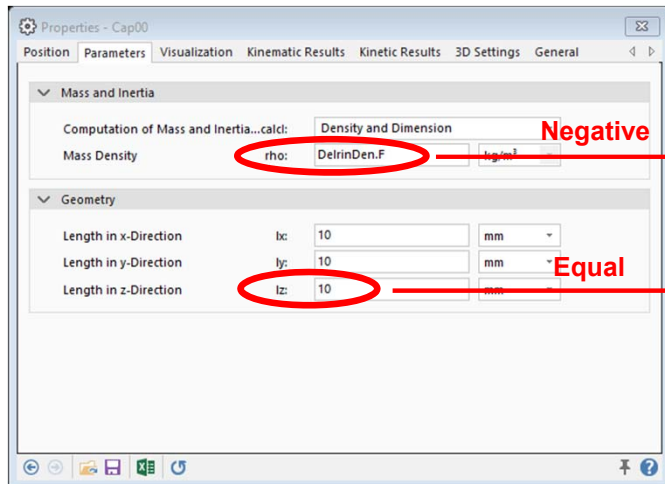


## Hole

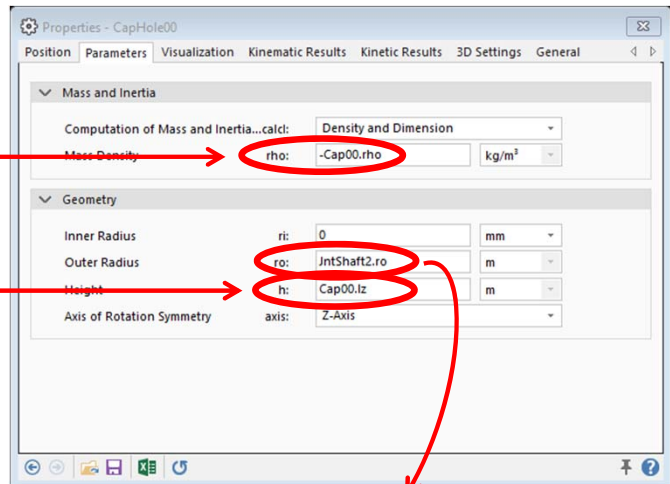
- Remove inertia from system
- Shaft not same material as Cap

# Holes

## Cap



## Hole

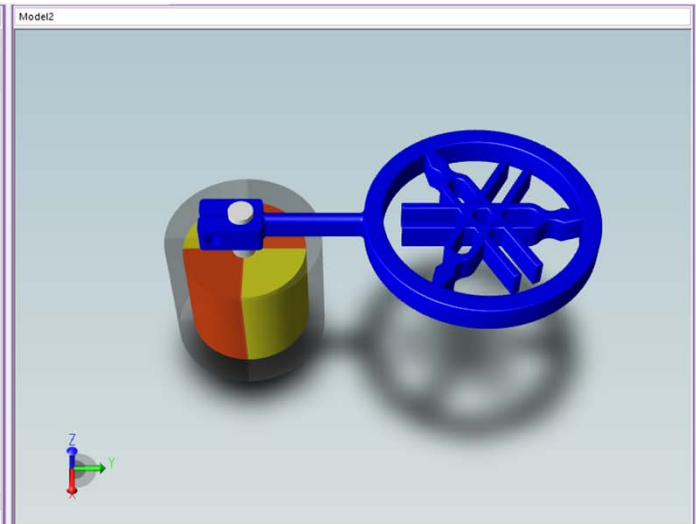
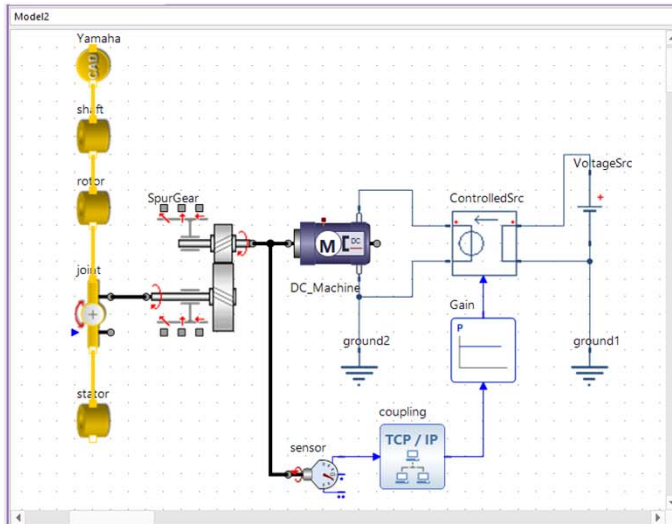
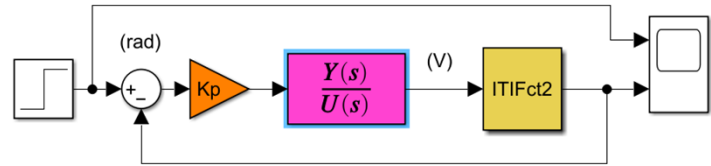


Same radius as shaft

## Hole

- Remove inertia from system
- Shaft not same material as Cap

# Gear Sets



## Spur Gear

- Power Transmission (1D) / Transmission Elements
- Reverses direction
- Specify losses

## DC Machine

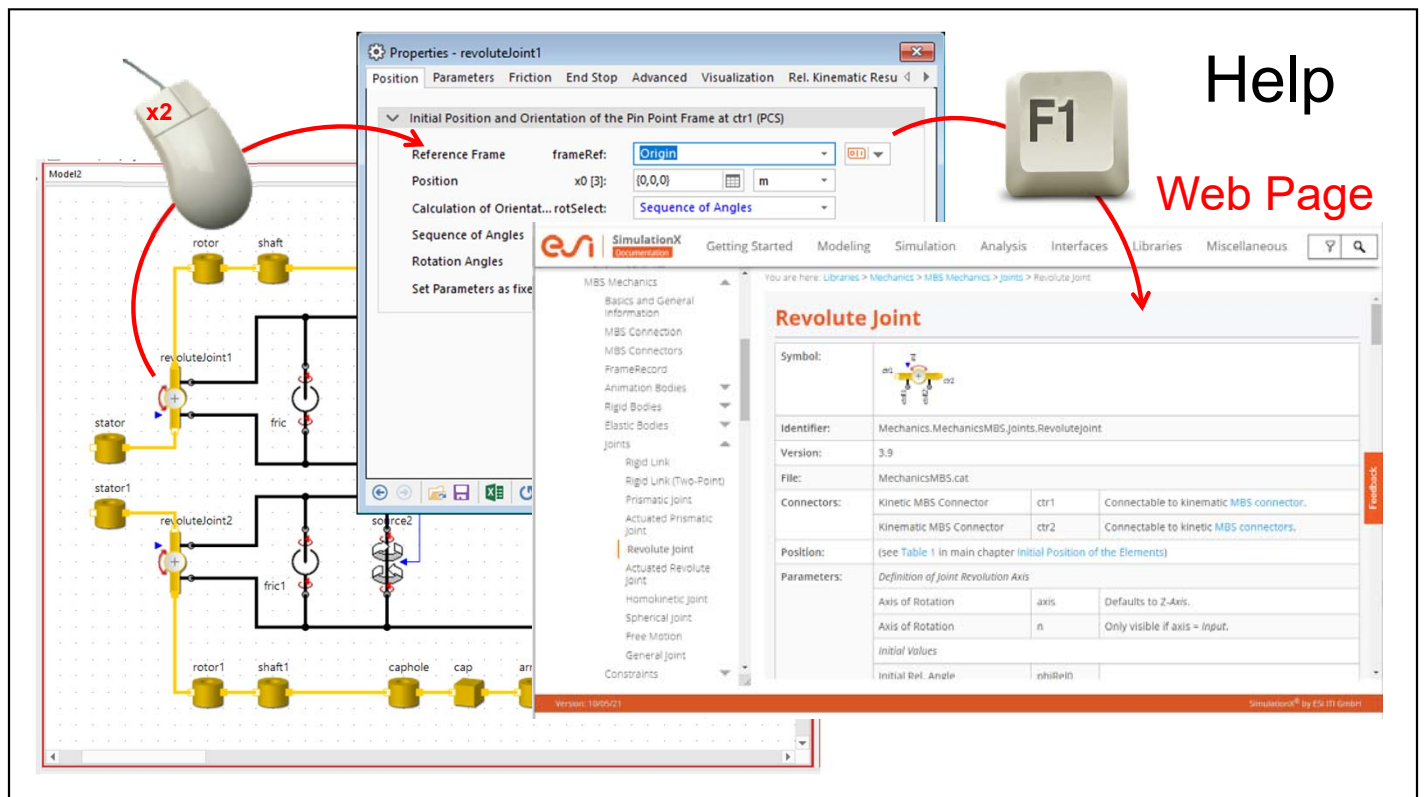
- Electro-Mechanics / Electric Machines / DC Machine
- Ground 1 terminal to avoid singularity

## Controlled Voltage Source

- Electrical and Electronics / Analog / Basic Elements / Linear VCVS
- Electrical and Electronics / Analog / Sources / Voltage Source
- Ground 1 terminal to avoid singularity

## Gain

- Signal Blocks / Linear Signal Blocks / Proportional Gain (P Gain)
- VCVS scales input by Voltage Source value (12 V)
- Divide by 12V to compensate



## Getting Help

- Double-click what you are interested in
- Press F1
- Web-Page appears
- Other topics on left
- Search bar above