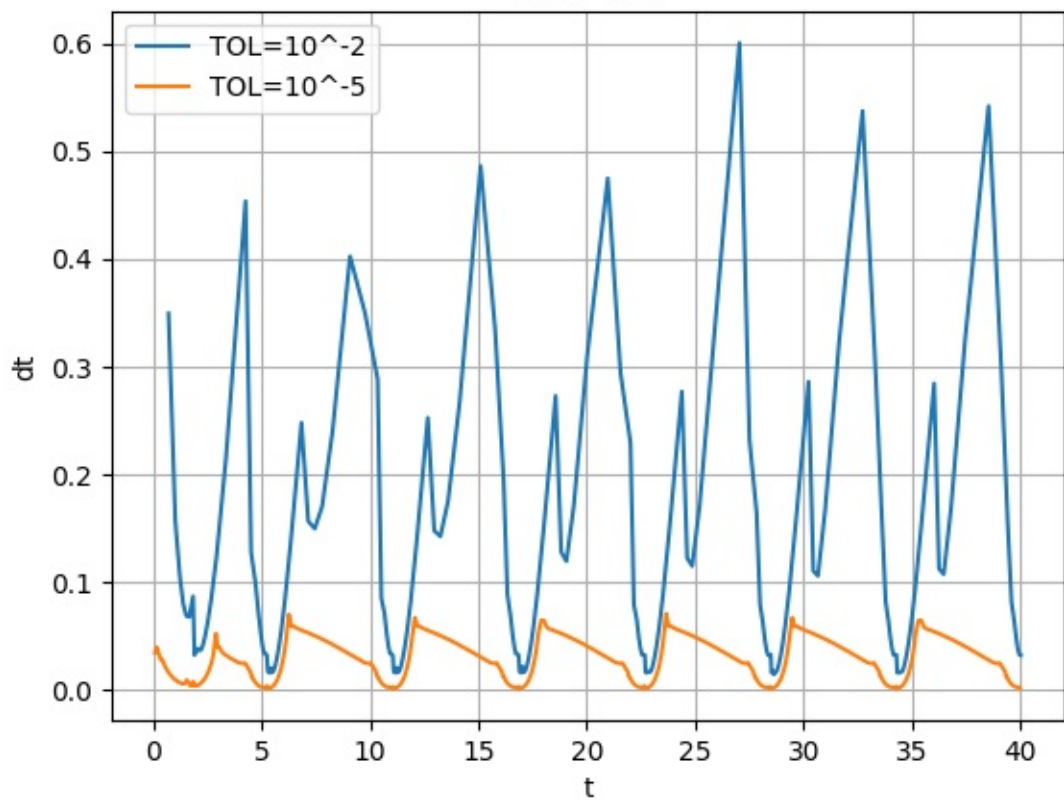
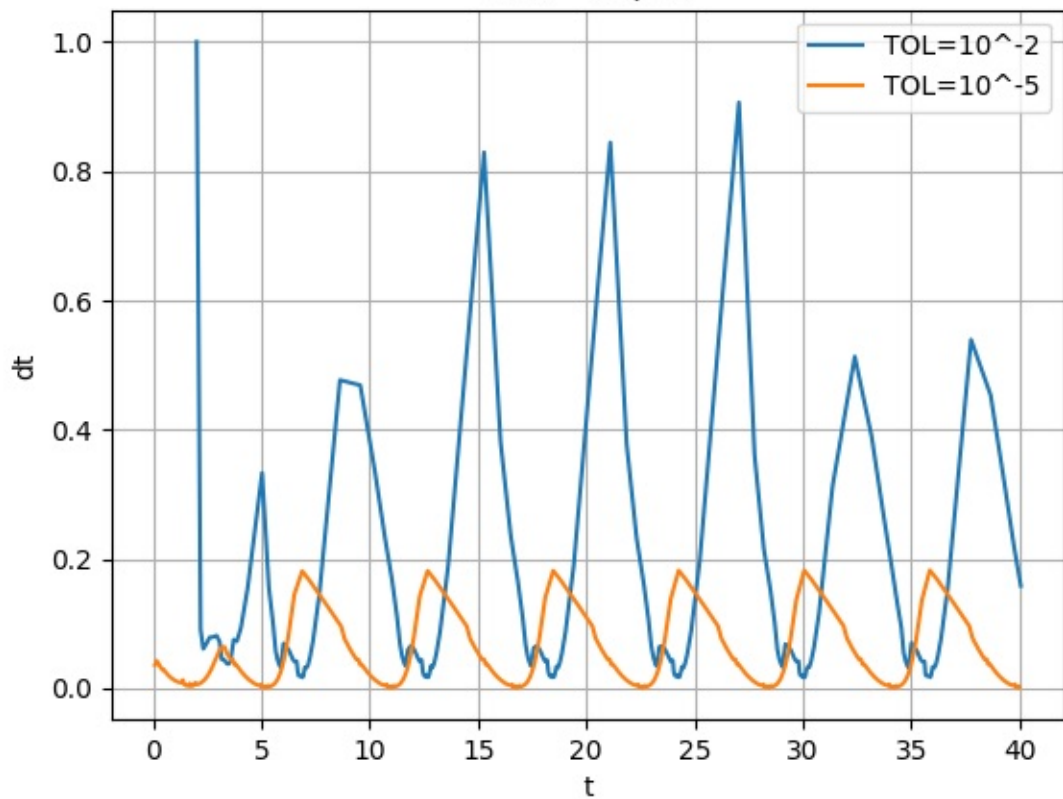


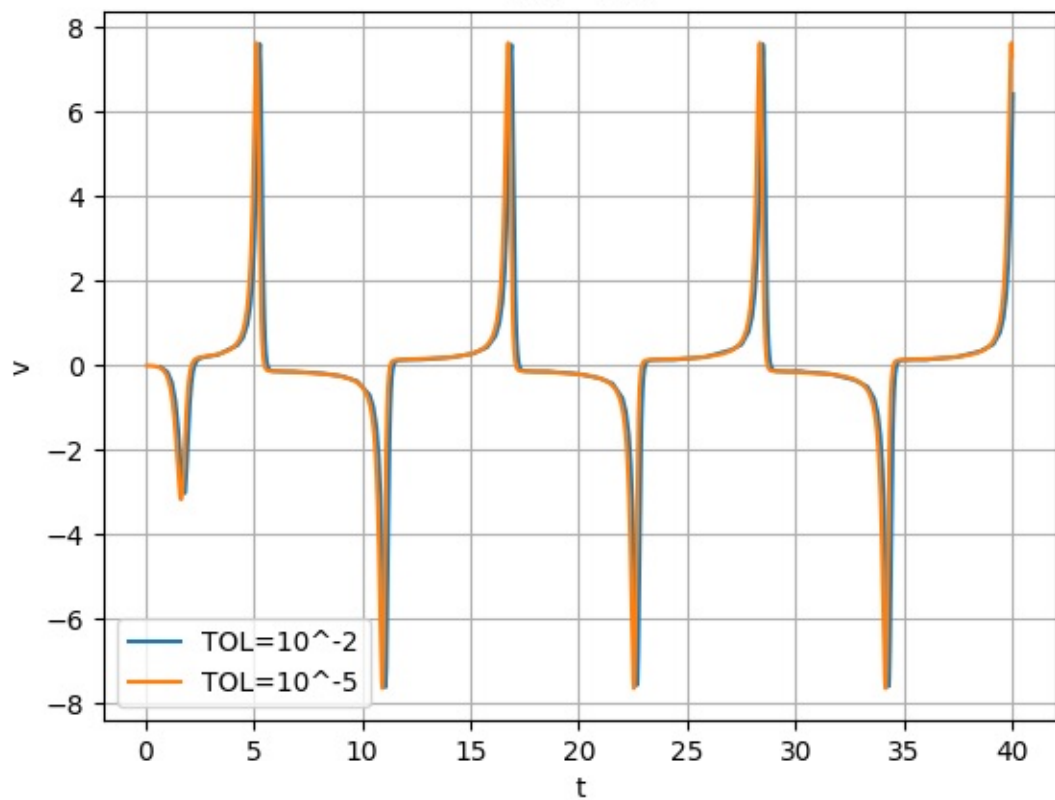
dt(t) - rk2



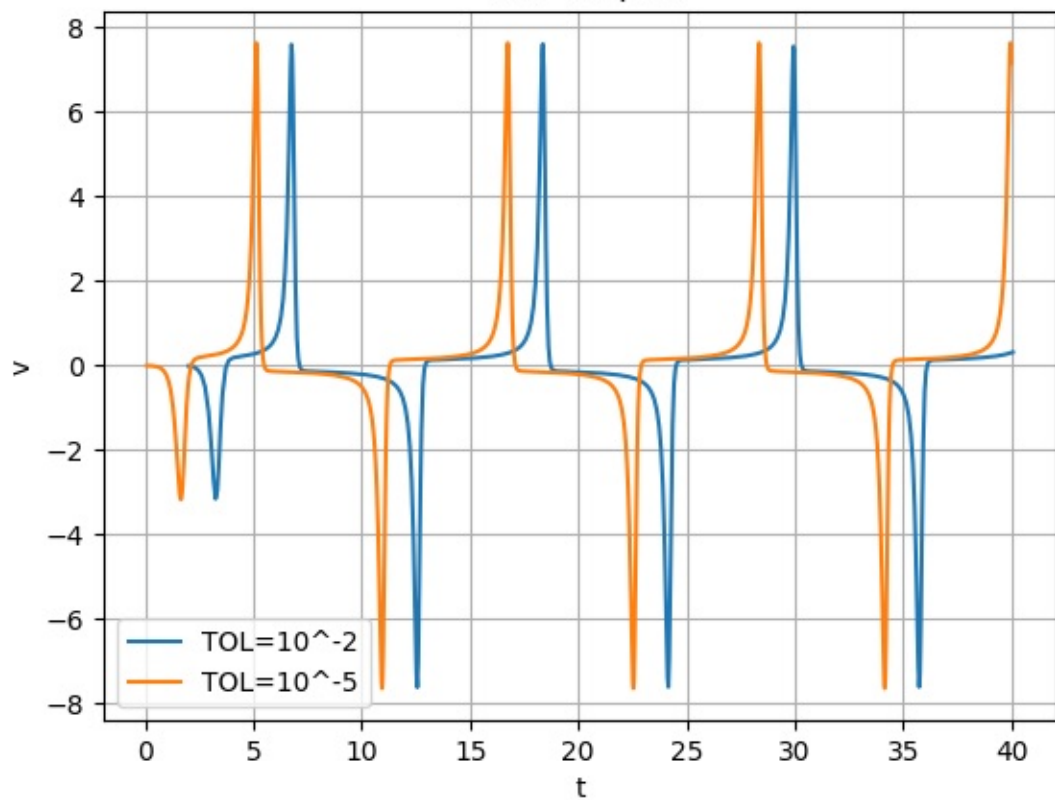
dt(t) - trapez



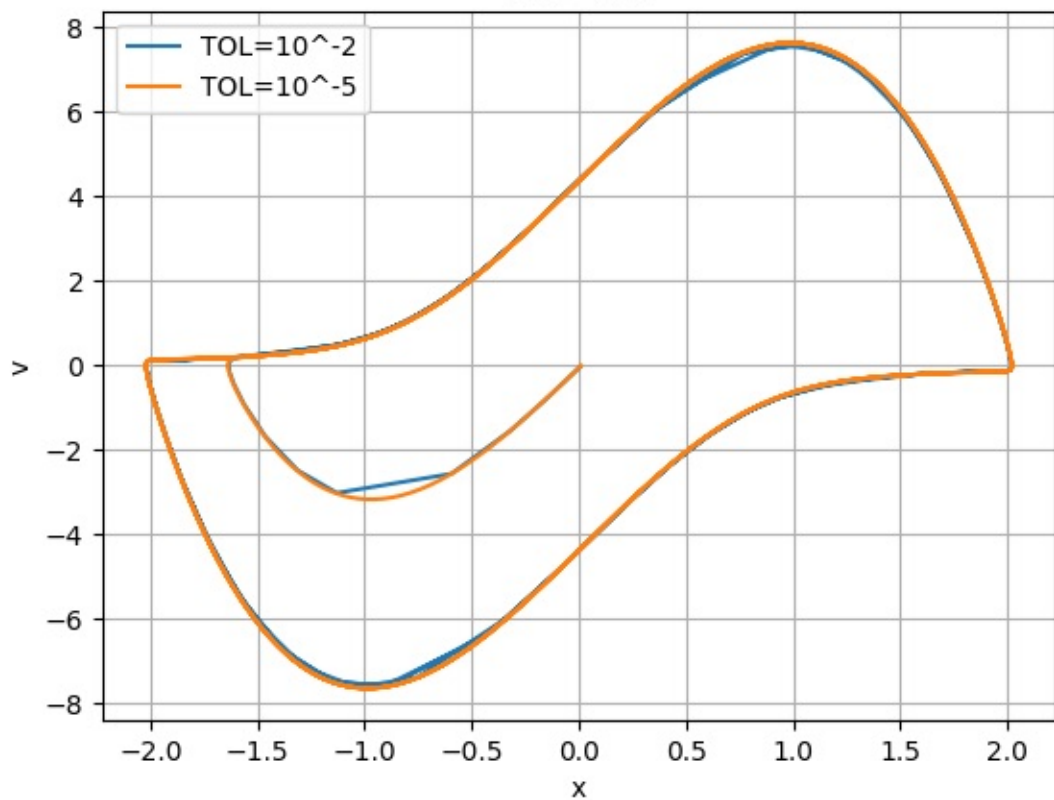
$v(t) - \text{rk2}$



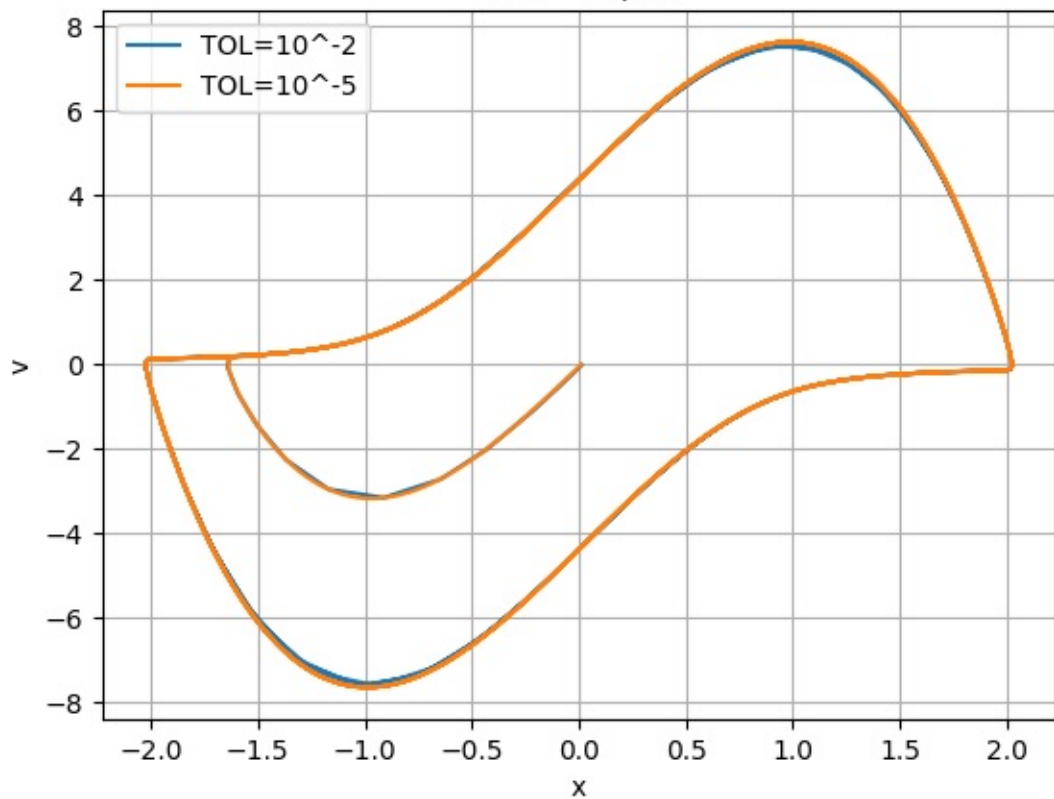
$v(t)$ - trapez



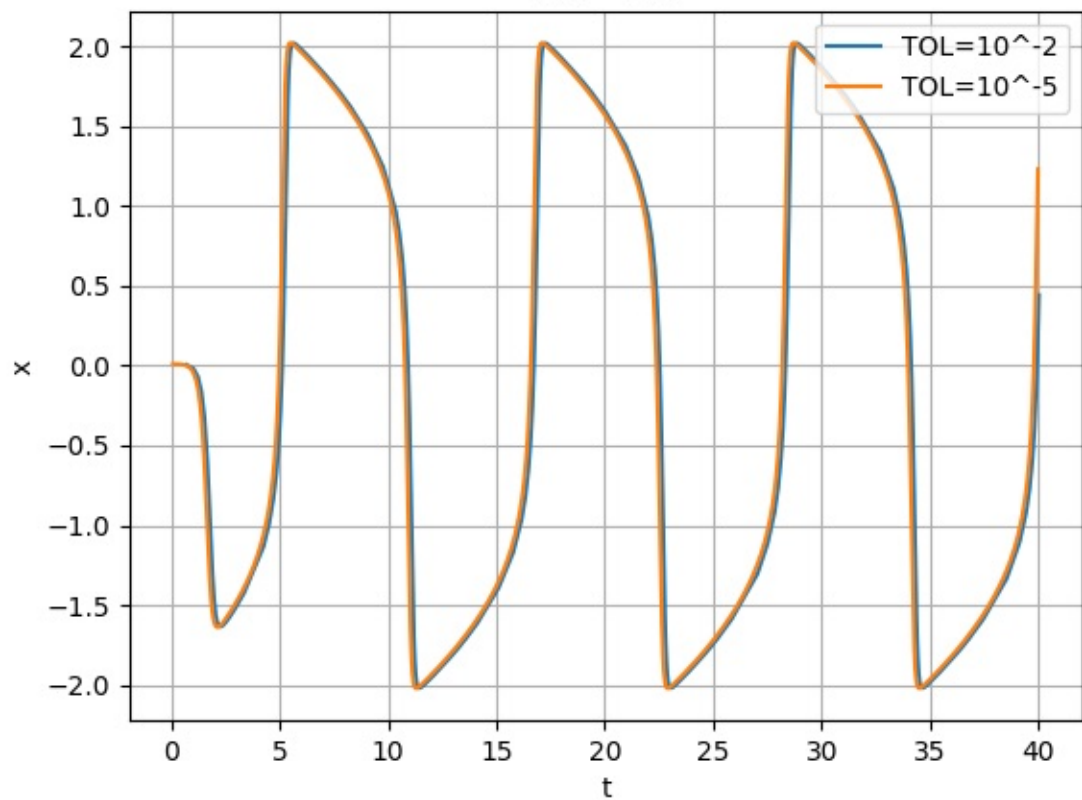
$v(x) - \text{rk2}$



$v(x)$ - trapez



$x(t)$ - rk2



$x(t)$ - trapez

