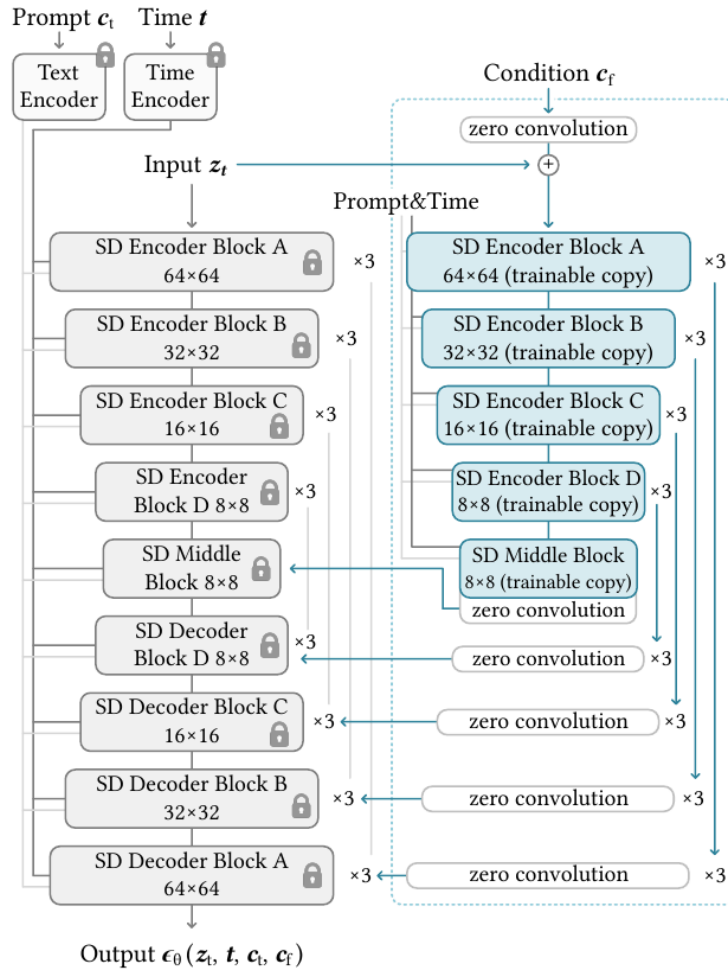


# Control Net for Image and Video Generation

- [1] ["Adding Conditional Control to Text-to-Image Diffusion Models"](#) (Zhang et al, ICCV 2023)
- [2] ["Control-A-Video: Controllable Text-to-Video Diffusion Models with Motion Prior and Reward Feedback Learning"](#) (Chen et al, 2023)

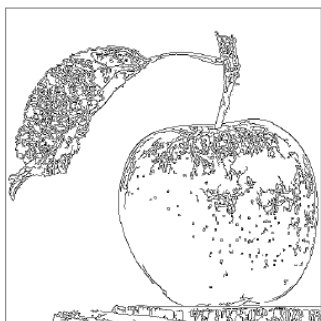
# Overall Architecture



(a) Stable Diffusion

(b) ControlNet

# Sudden Convergence Phenomenon



Test input



training step 100



step 1000



step 2000



step 6100



step 6133



step 8000



step 12000

The model does **NOT** gradually learn the control conditions but abruptly succeeds in following the input conditioning image; usually in less than 10K optimization steps.

# Classifier-Free Guidance

$$\epsilon_{\text{prd}} = \epsilon_{\text{uc}} + \beta_{\text{cfg}}(\epsilon_{\text{c}} - \epsilon_{\text{uc}})$$

where

- $\epsilon_{\text{prd}}$  — the model's final output
- $\beta_{\text{cfg}}$  — the weight of guidance
- $\epsilon_{\text{uc}} = \text{UnetWithoutControlNet}(\mathbf{z}_t, t, ""); \theta$  — unconditional output
- $\epsilon_{\text{c}} = \text{UnetWithControlNet}(\mathbf{z}_t, t, \mathbf{c}_t, \mathbf{c}_f; \theta, \phi)$  — conditional output
- $\mathbf{z}_t$  — noisy latent image
- $\mathbf{c}_t$  — text prompt
- $\mathbf{c}_f$  — condition image
- $\theta$  — pre-trained diffusion model's weights
- $\phi$  — control-net's weight

# Classifier-Free Guidance Resolution Weighting



(a) Input Canny map



(b) W/o CFG

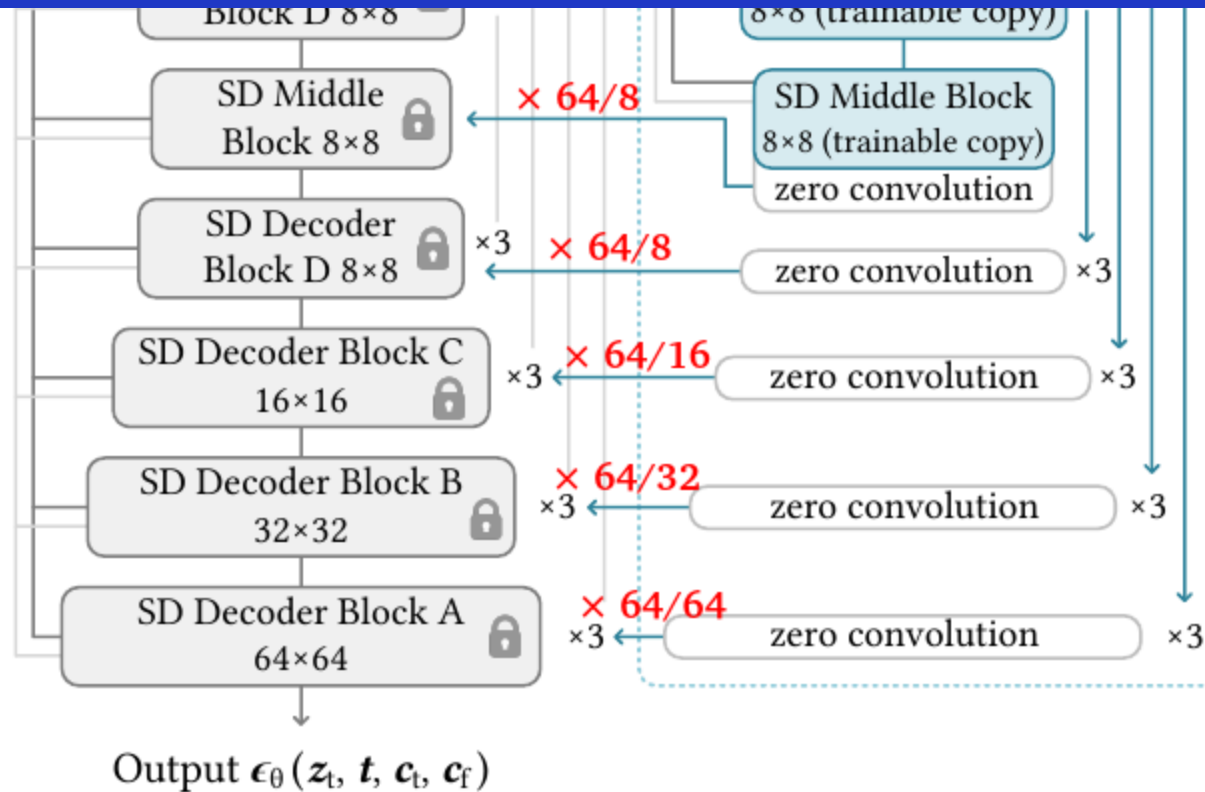


(c) W/o CFG-RW



(d) Full (w/o prompt)

# Classifier-Free Guidance Resolution Weighting



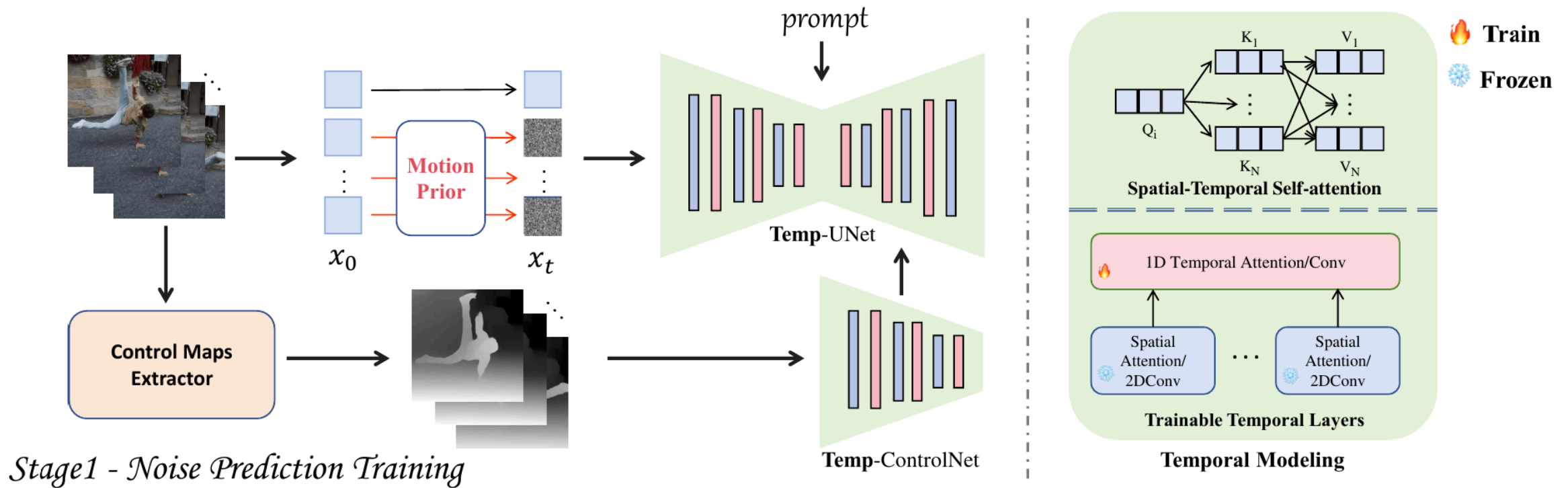
(a) Stable Diffusion

(b) ControlNet

By multiplying a weight  $w_i$  to each connection between Stable Diffusion and ControlNet according to the resolution of each block  $w_i = 64/h_i$ , where  $h_i$  is the size of  $i$ th block, *e.g.*,  $h_1 = 8, h_2 = 16, \dots, h_{13} = 64$ , we can achieve the better generation result.



# ControlNet for VideoGeneration



"Control-A-Video: Controllable Text-to-Video Diffusion Models with Motion Prior and Reward Feedback Learning" (Chen et al, 2023)