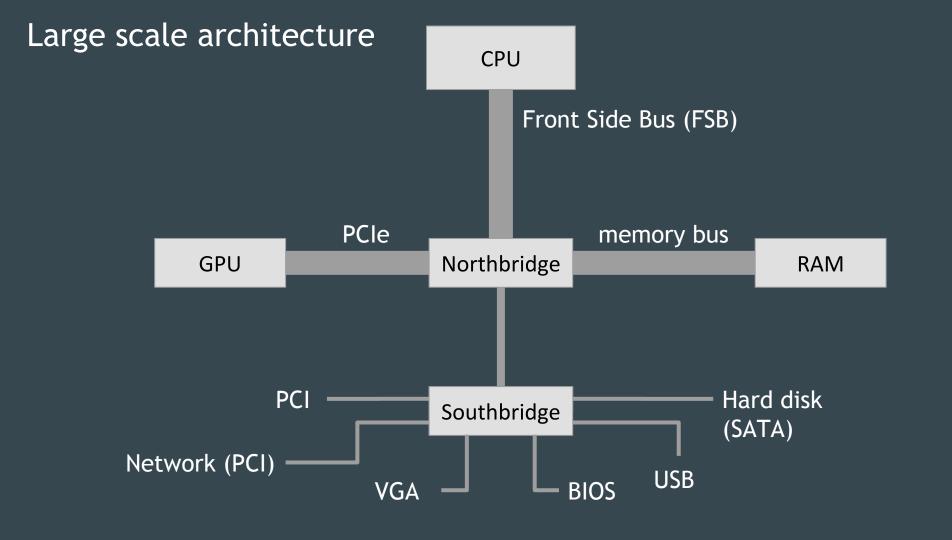
Astro 528 Week 4: Computer Architectures

Guest Lecture by Daniel Carrera



Large scale architecture: bus

 A "bus" is just a circuit to transfer data between components.

Ex:

USB Universal Serial Bus

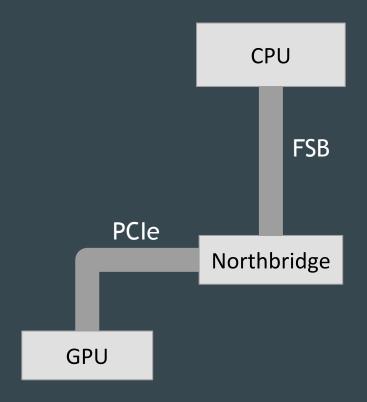
SATA Serial ATA

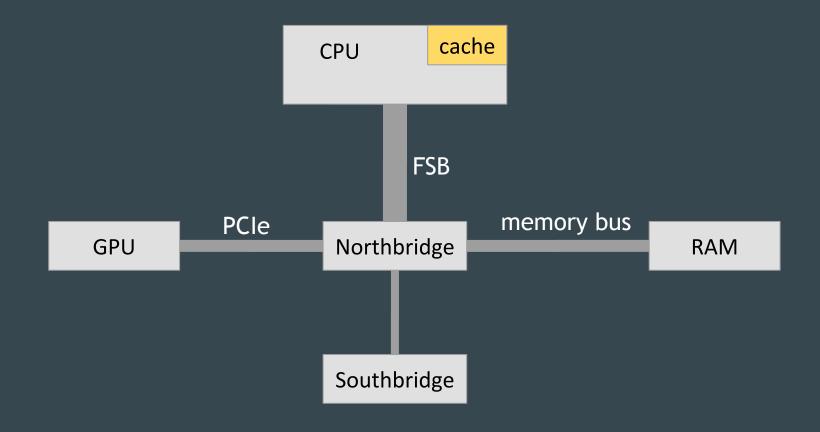
PCI Peripheral Component Interconnect

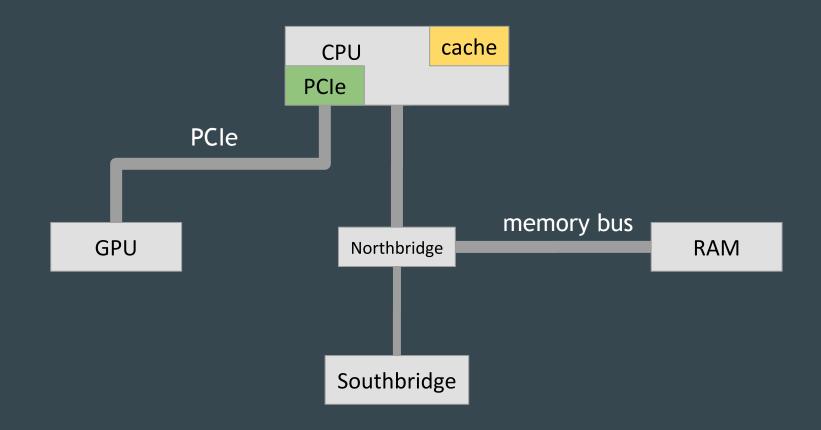
PCIe PCI-Express

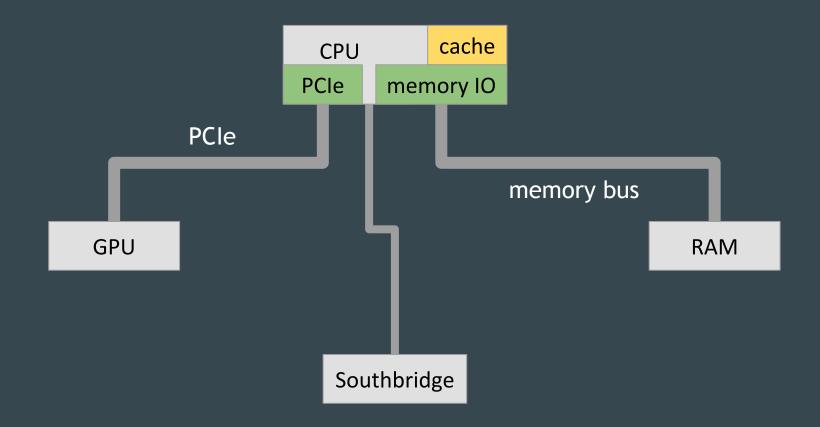
FSB Front Side Bus

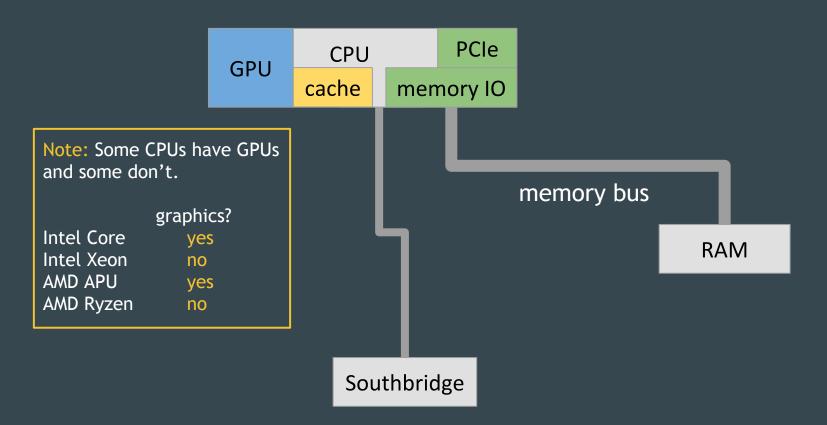
- All buses are much slower than the CPU.
- A lot of hardware and software design choices are entirely about avoiding the FSB.



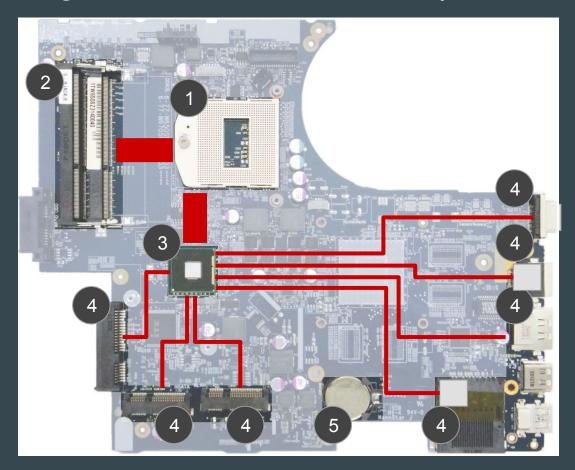








Large scale architecture: sample motherboard



- 1 CPU + northbridge
- 2 RAM
- 3 Southbridge
- 4 IO ports
- 5 CMOS battery

CPU architecture



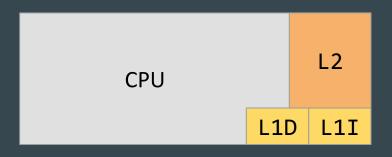
CPU architecture: cache levels



L1 Designed for speed at the expense of memory density.

L2 (the opposite)

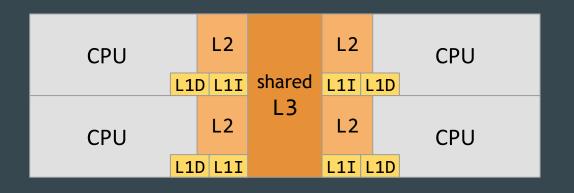
CPU architecture: cache levels



		Example (xeon E3-2030)
L1I	L1 instruction cache	32 kB
L1D	L1 data cache	32 kB
L2	instruction + data	256 kB

Evample (Veen EF 26E0)

CPU architecture: multi-core CPUs



L1I	per core
L1D	per core
L2	per core
L3	shared between cores
	- why is this important?

```
Example (Xeon E5-2650)

32 kB / core

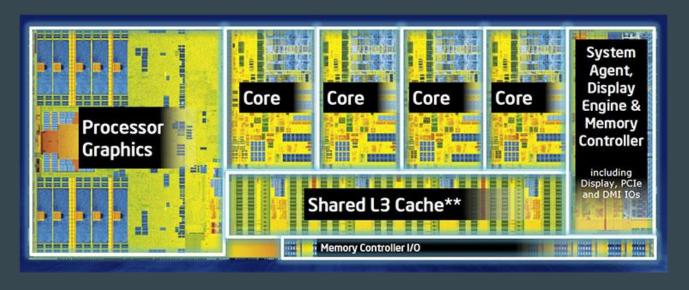
32 kB / core

256 kB / core

30 MB shared / 12 cores
```

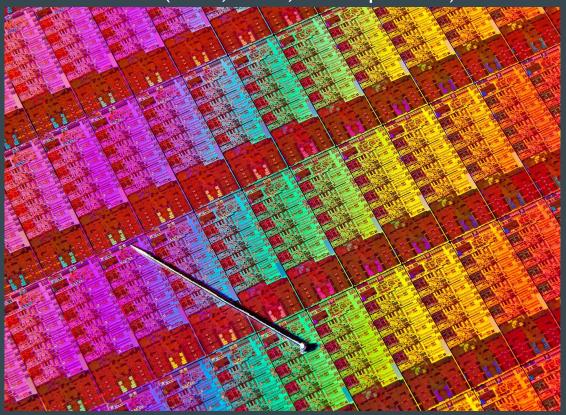
CPU architecture: examples

Haswell CPU (Intel, 2013, 22nm process)



CPU architecture: examples

Haswell wafer (Intel, 2013, 22nm process)



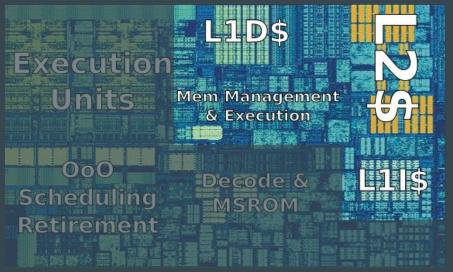
CPU architecture: examples

Skylake core (Intel, 2015, 14nm process)



CPU architecture: pre-fetching

Skylake core



The CPU pre-loads cache with data and instructions that it thinks is most likely to be needed soon.

CPU architecture: pipelining

Even the simplest operations require at least 4 steps (fetch from cache, decode, execute, write back to cache). *Pipelining* keeps all the CPU components busy.

Without Pipelining

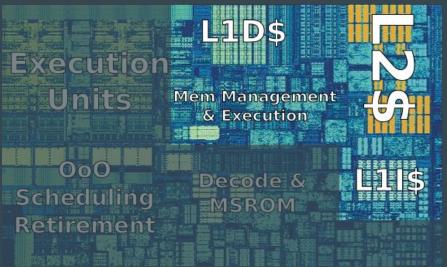
Fetch	А				В			
Decode		Α				В		
Execute			Α				В	
Write				Α				В

With Pipelining

Fetch	Α	В					
Decode		Α	В				
Execute			А	В			
Write				Α	В		

CPU architecture: branch prediction

Skylake core



When encountering a conditional:

```
statement 1
statement 2
if cond
statement 3
else
statement 4
```

The processor will guess which branch is most likely. It then fetches the data and *speculatively executes* the instruction (i.e. puts it in the pipeline).

CPU architecture: out of order execution

Skylake core



Pipelining requires knowledge of data dependencies, so it relies on Ooo.

Ooo = out of order execution

Processor executes instructions when data becomes available, rather than in their original order in the program.

Ex:

1.
$$a = b + c$$

2.
$$h = e + g$$

Lines 2 and 3 can be done in any order.

CPU architecture: cache misses

- AMD and Intel spend a lot of effort in trying to minimize cache misses.
- A cache miss is when the data you need is not in cache (esp. L1D).
- Both companies routinely achieve L1 cache hit rates of > 95%.

CPU architecture: the cost of a cache miss

Zen architecture (AMD, 2017, 14 nm process)

	Latency		
L1D	~1.0ns		
L2	~5.3ns		
L3	~21.6ns		
RAM	~84.0ns		

Assuming a 95% L1 hit rate,

Q: What fraction of the time is spent in cache misses if...

- the other 5% is in L2?
- the other 5% is in L3?
- the other 5% is in RAM?

(ignore execution time and bandwidth)

CPU architecture: the cost of a cache miss

Zen architecture (AMD, 2017, 14 nm process)

	Latency	Answer
L1D	~1.0ns	
L2	~5.3ns	22%
L3	~21.6ns	53%
RAM	~84.0ns	82%

Assuming a 95% L1 hit rate,

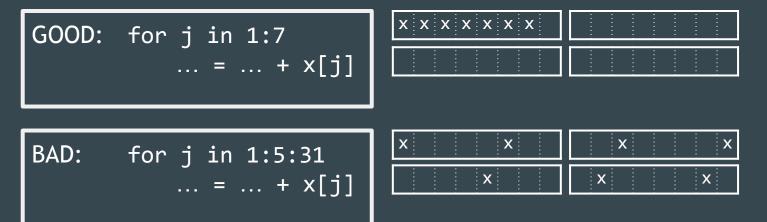
Q: What fraction of the time is spent in cache misses if...

- the other 5% is in L2?
- the other 5% is in L3?
- the other 5% is in RAM?

(ignore execution time and bandwidth)

Software design: cache lines

- Data moves across cache in units of 64 bytes (usually), or 8 x Float64.
 This is called a cache line.
- Design your code to access data sequentially inside a cache line to minimize cache misses.



Software design: cache lines

Xeon E5-2650 L1D 32 kB / core

L1D 32 kB / core L2 256 kB / core L3 30 MB shared

Exercise 3 from last Thursday (matrix multiply: A * b)

N	Storage	column_inner	row_inner	Ratio
64	33 kB	4.564 μs	4.146 μs	1.1
128	129 kB	22.037 μs	14.847 μs	1.5
256	514 kB	114.570 μs	57.350 μs	2.0
512	2 MB	448.123 μs	229.487 μs	2.0
1024	8 MB	1.8 ms	885.461 μs	2.0
2048	32 MB	35.9 ms	3.8 ms	9.4

Q: Why does the ratio suddenly jump at the last line? (speculate)

Q: Why is Julia's implementation faster than row_inner? (speculate)