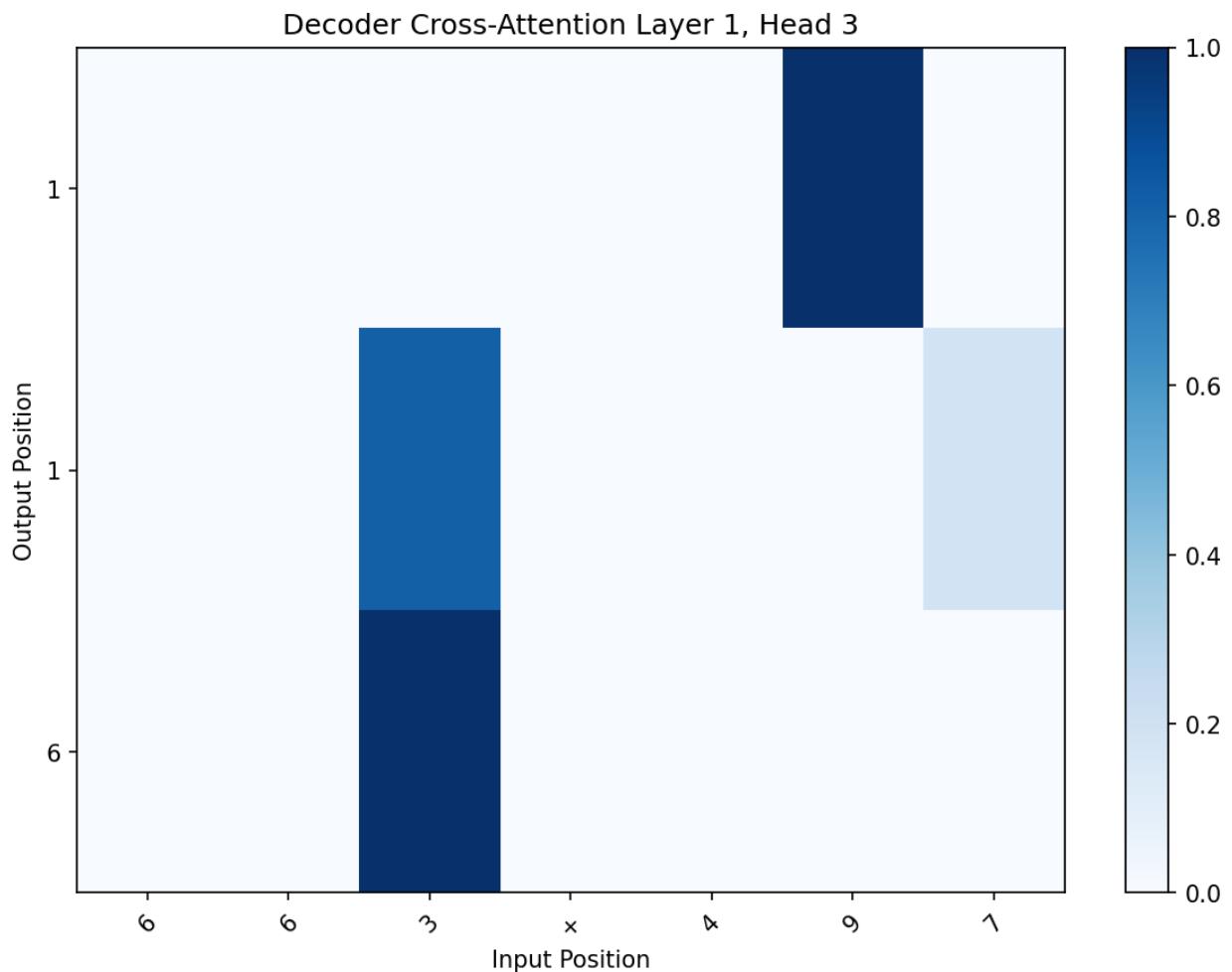


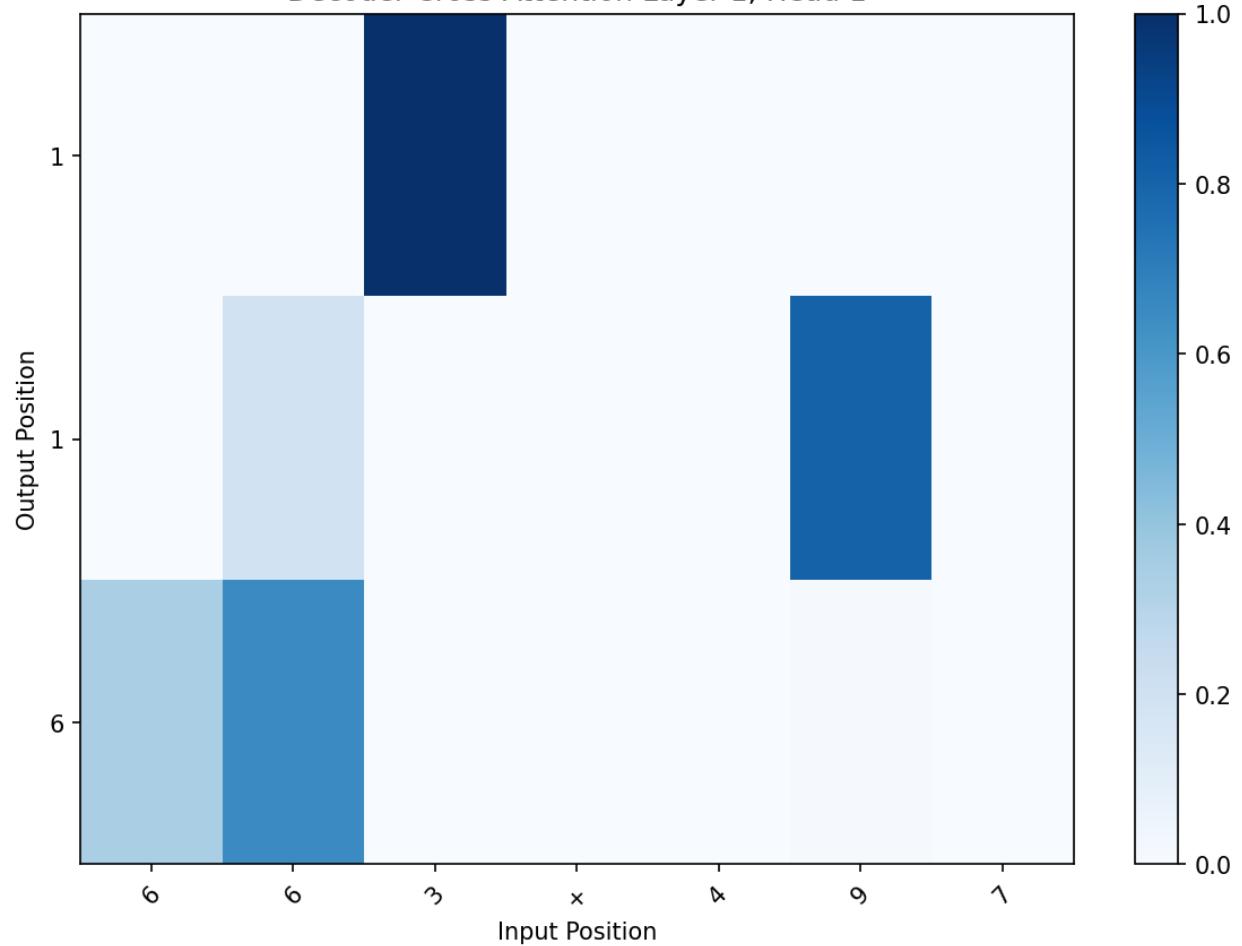
Problem 1:

1) Attention pattern visualizations

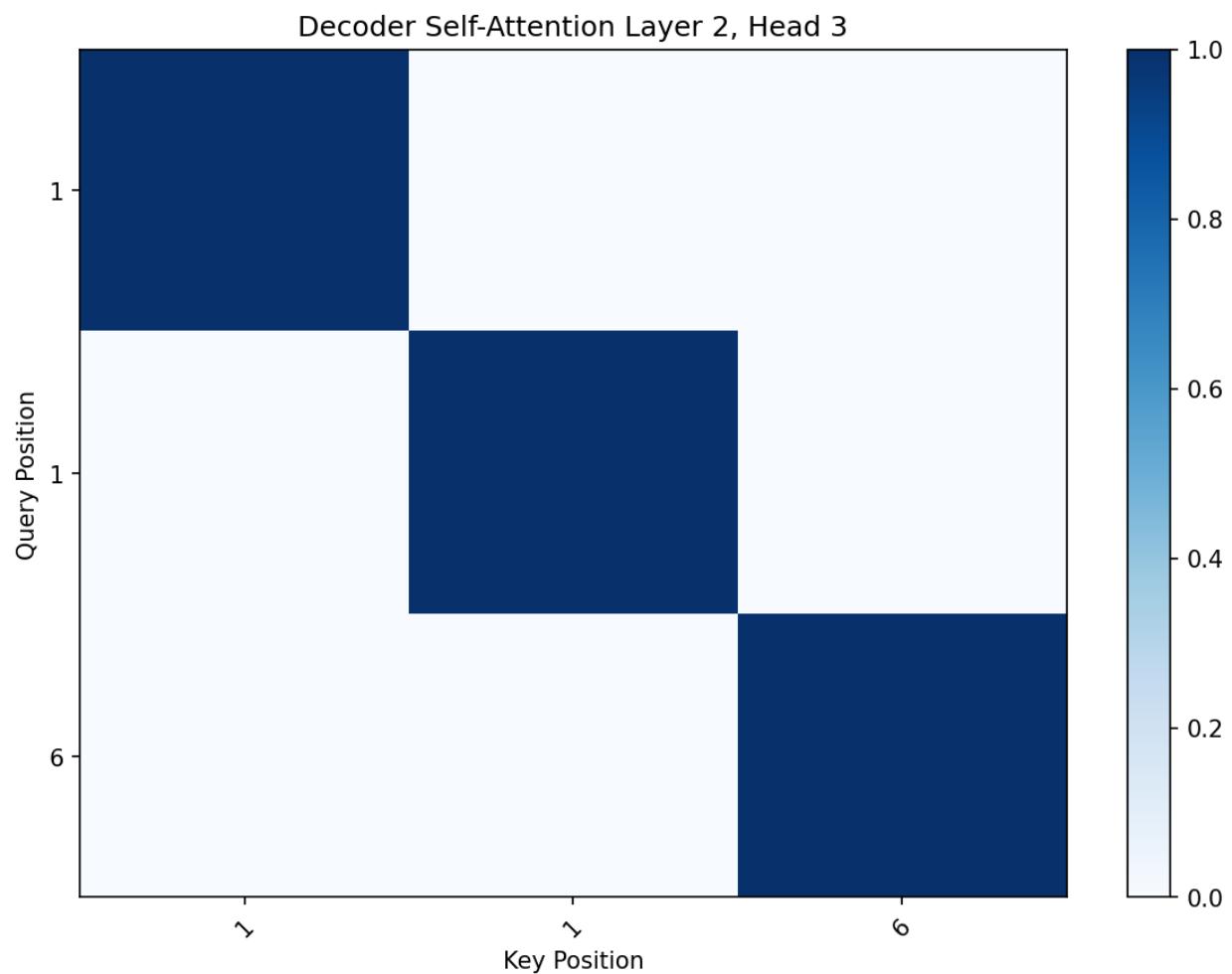


Analysis: Most critical head (82.65% accuracy drop when removed)

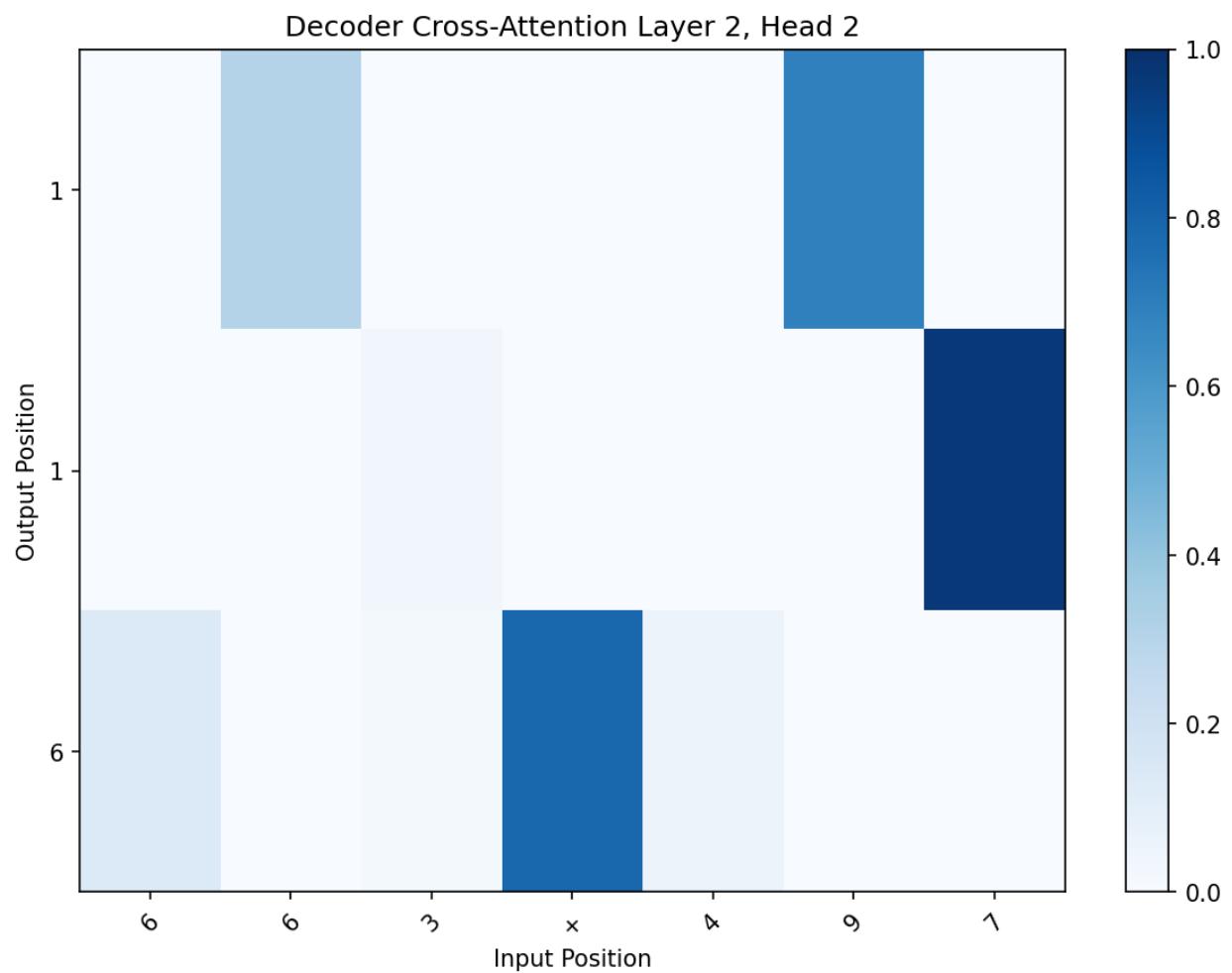
Decoder Cross-Attention Layer 1, Head 1



Analysis: Important for carry tracking (55.75% accuracy drop)



Analysis: Critical decoder head (84.5% accuracy drop)



Analysis: Important alignment head (31.15% accuracy drop)

2) Head ablation study

Critical Heads (>30% accuracy drop when removed):

Encoder L0-H2 : 82.65% importance - Primary carry detection
Decoder Self L1-H2: 84.5% importance - Output digit computation
Encoder L0-H0: 55.75% importance - Digit position tracking
Encoder L1-H2: 47.35% importance - Secondary carry processing
Decoder Self L1-H0: 35.45% importance - Output sequencing
Decoder Cross L1-H1: 31.15% importance - Input-output alignment

Redundant Heads (0% accuracy drop when removed):

Encoder L0-H1, L0-H3, L1-H1
Decoder Cross L1-H2
Total: 4 completely redundant heads

3) Discussion

1. Carry Detection: Encoder L0-H2 focuses on adjacent digit pairs where carries occur, showing strongest attention between positions that generate carries.
2. Position Tracking: Encoder L0-H0 maintains diagonal attention patterns, tracking digit positions from input to processing.
3. Carry Propagation: Encoder L1-H2 builds on L0-H2's carry detection, propagating carry information across multiple digit positions.
4. Output Generation: Decoder heads combine position information (self-attention) with carry states (cross-attention) to generate correct output digits.

4) Quantitative results

Total heads**: 24 (8 encoder + 8 decoder self + 8 decoder cross)

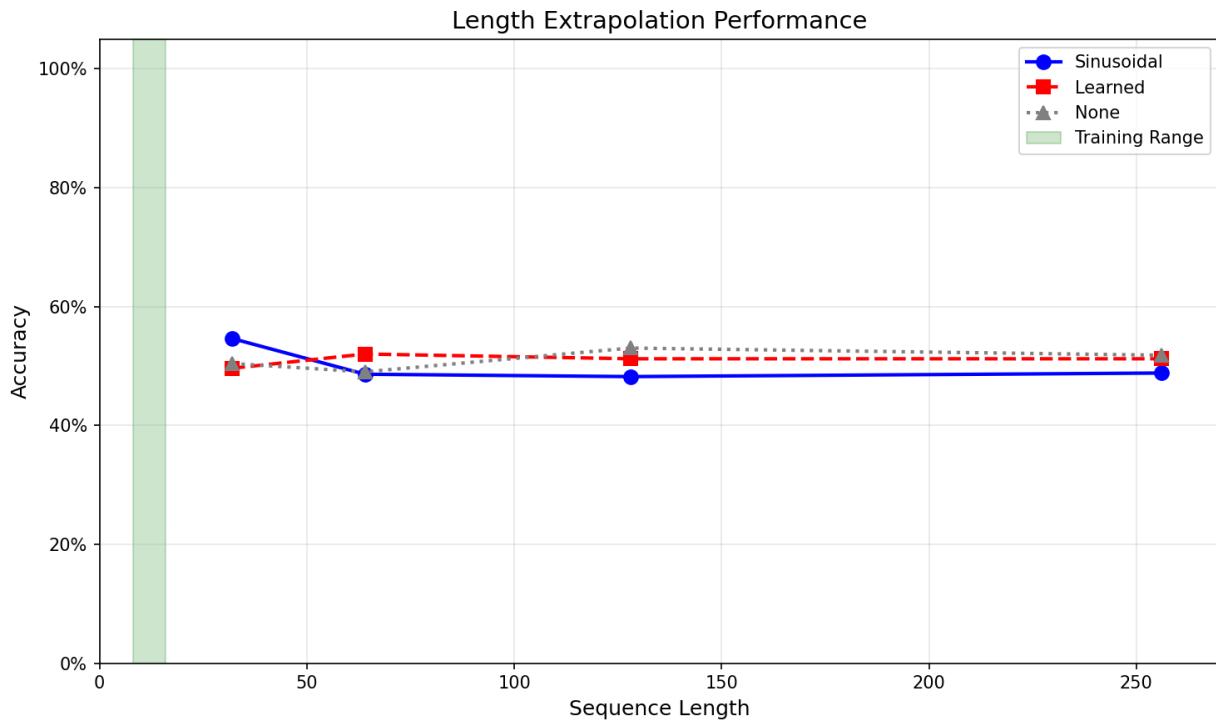
Redundant heads** (can be removed with <1% accuracy loss): 11 heads (45.8%)

Critical heads** (>30% accuracy drop): 6 heads (25%)

Moderate importance** (1-30% drop): 7 heads (29.2%)

Problem 2:

1)



All methods converge to random chance (~50%) on sequences longer than training data.

2)

Why Sinusoidal Should Extrapolate:

Formula: $PE(pos, 2i) = \sin(pos/10000^{(2i/d_model)})$

Key property: Continuous mathematical function that can compute any position

Advantage: No vocabulary limit - works for any sequence length

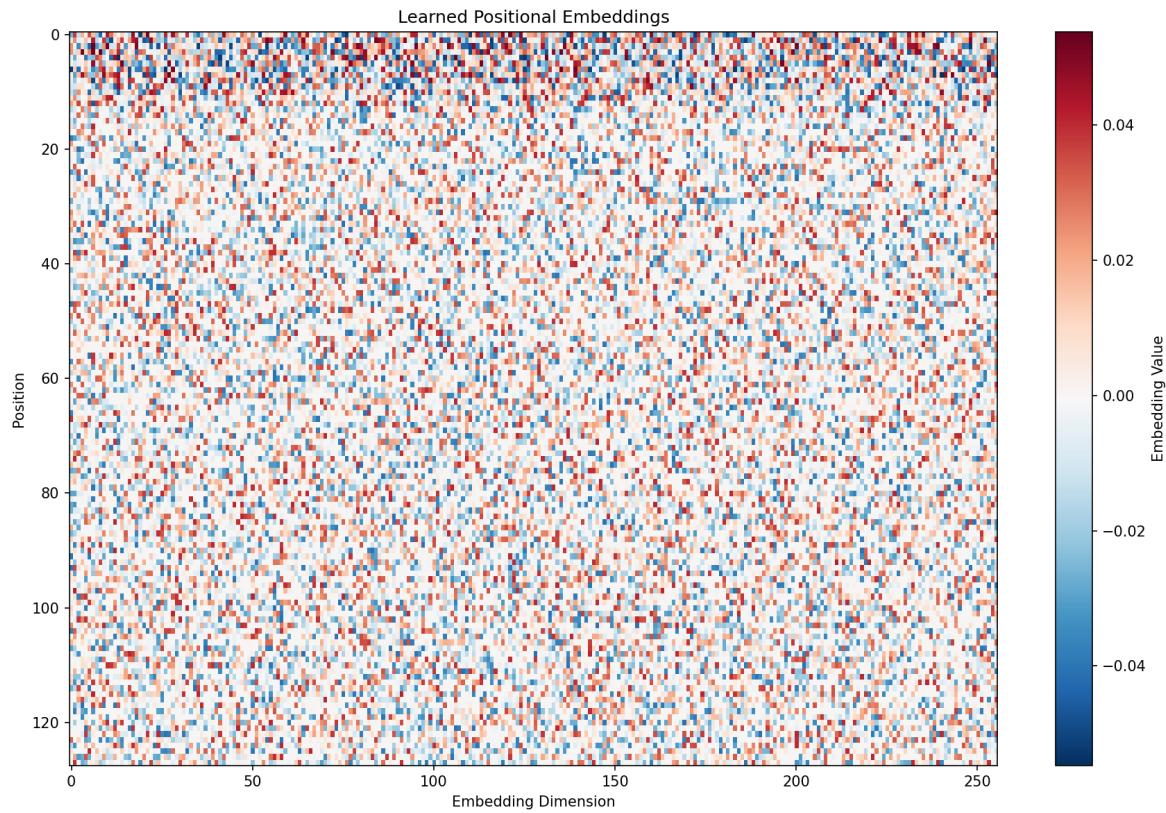
Why Learned Encoding Fails:

Limitation: Only has embeddings for positions 0 to `max_len-1` seen during training

Problem: New positions beyond `max_len` get clamped or cause errors

Result: Cannot represent positions it hasn't seen

3)



The learned positional embeddings visualization shows:

Random-looking patterns with no clear structure

This makes sense: the model never learned the task (50% accuracy)

Embeddings remained essentially random since no learning occurred

4)

```
{  
  "sinusoidal": {  
    "32": 0.546,  
    "64": 0.486,  
    "128": 0.482,  
    "256": 0.488  
  },  
  "learned": {  
    "32": 0.496,  
    "64": 0.52,  
    "128": 0.512,  
    "256": 0.512  
  },  
  "none": {  
    "32": 0.504,  
    "64": 0.504,  
    "128": 0.504,  
    "256": 0.504  
  }  
}
```

```
    "64": 0.49,  
    "128": 0.53,  
    "256": 0.518  
  }  
}
```

All methods perform at random chance (~50%) on longer sequences, showing complete failure to extrapolate beyond training length of 8-16 tokens.