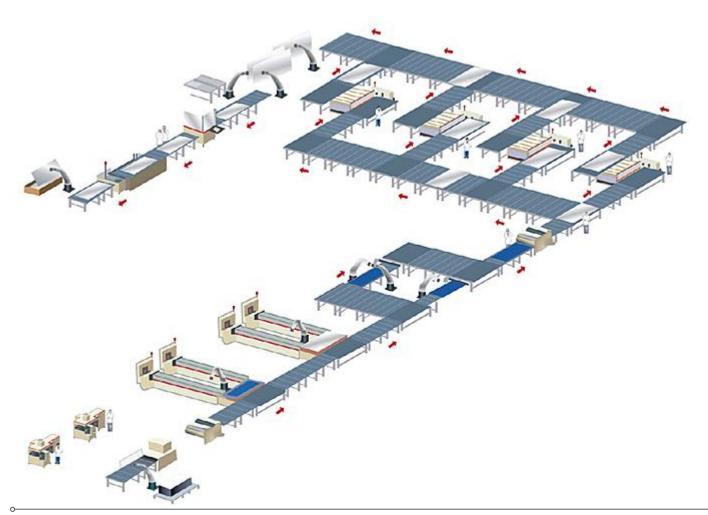
# **Applications of Data Analytics in Manufacturing**

Minh Nguyen, Dr.

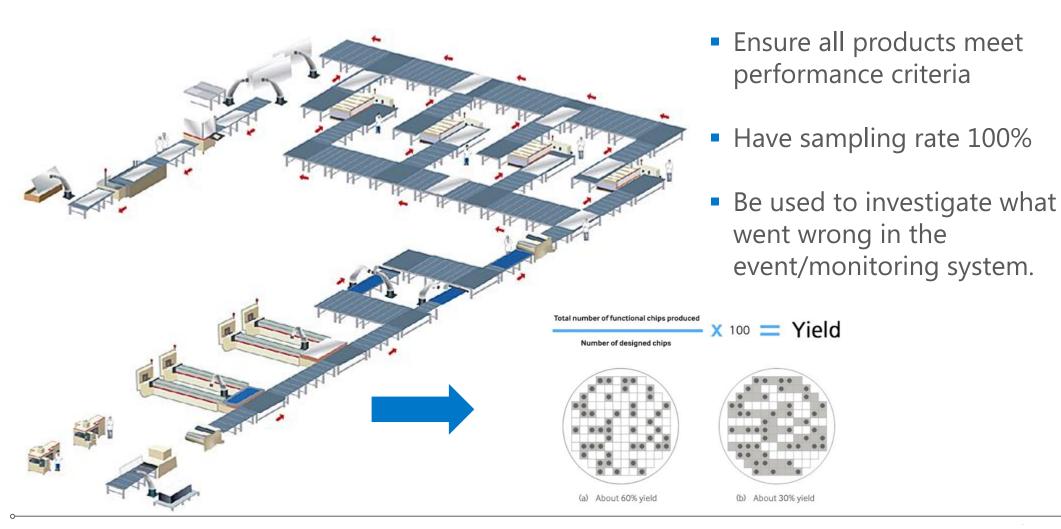
Micron Semiconductor Asia.

#### Overview of Production Line



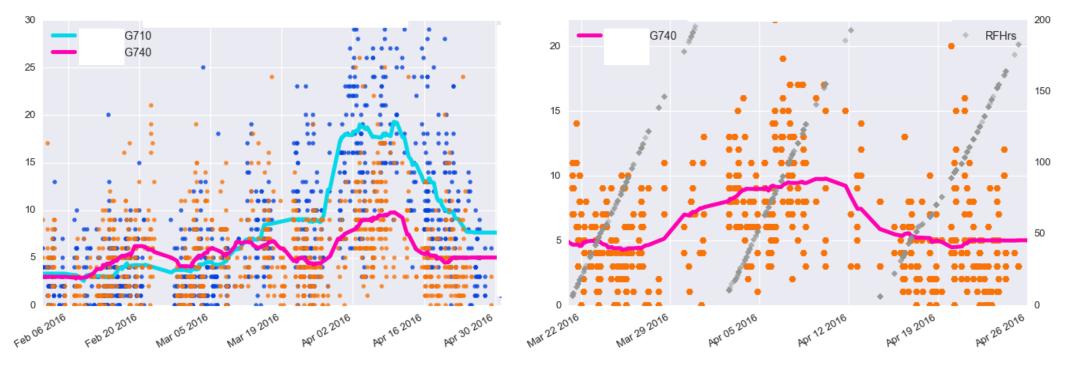
- Event system: recipe changes, tool maintenance activities (PM), human actions.
- Monitoring system: wafer ID, sensor signals, timing gates.
- Measurement system: deviation quality gates, yield output.

## **Yield Modelling**



## **Yield Modelling**

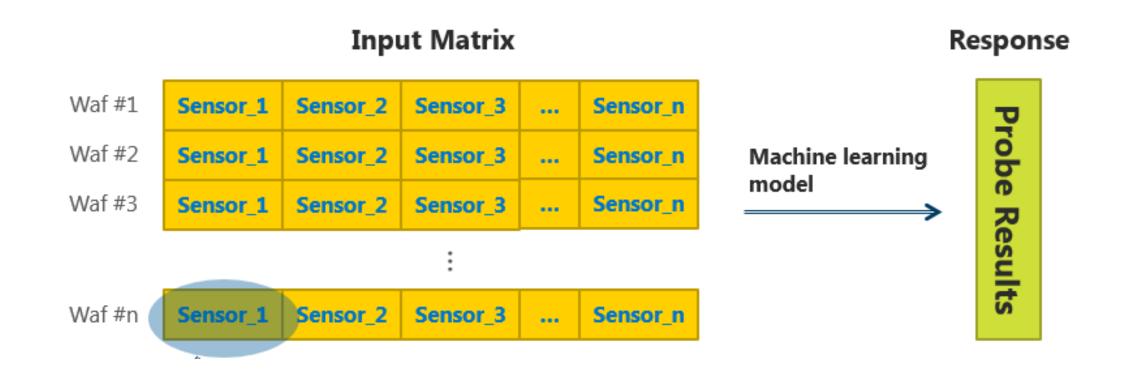
Investigate what went wrong with a bad tool



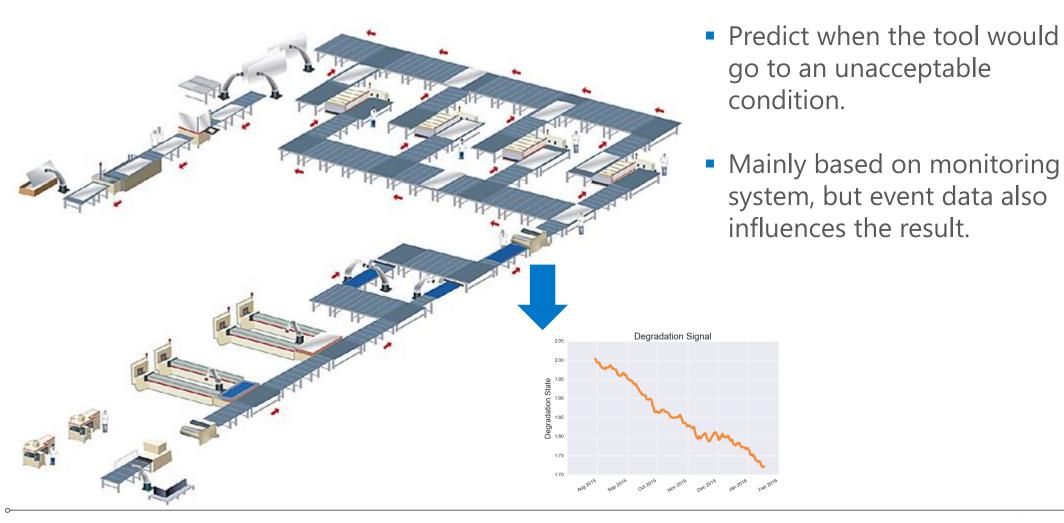
What are the root causes? How to improve yield?

**Answer from tool sensor signals** 

## **Yield Modelling**

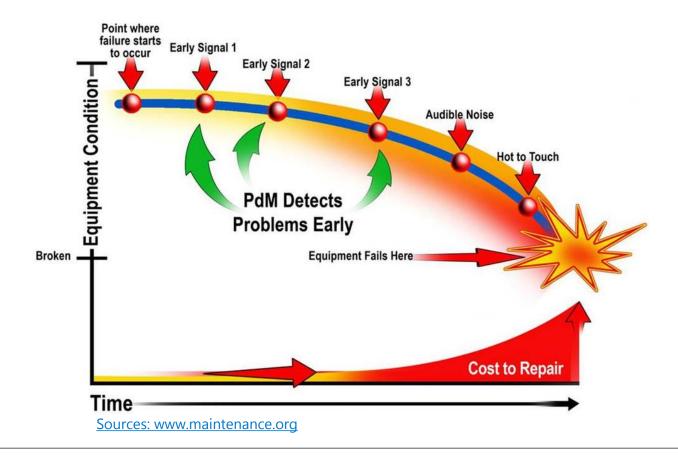


### **Predictive Maintenance**



#### **Predictive Maintenance**

Predict when a tool would go bad.



#### **Maintenance Model**

#### **Terminologies:**

#### <u>Degradation signal Y:</u>

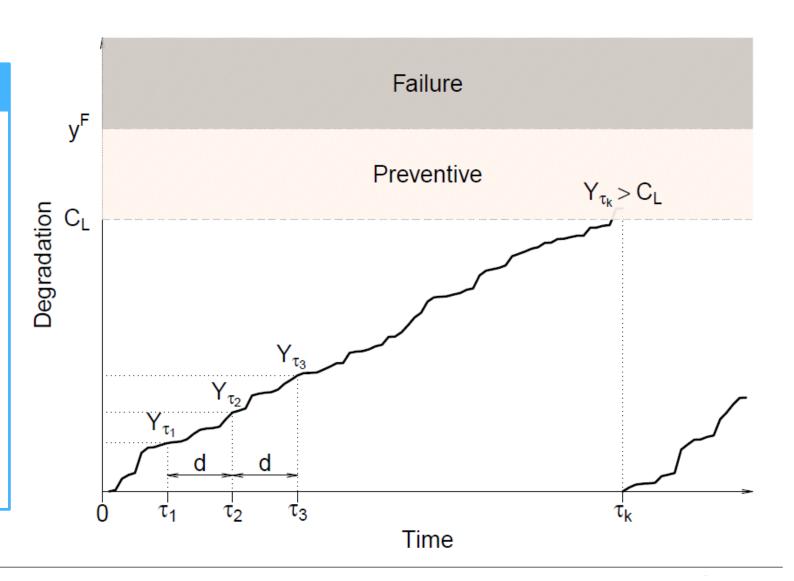
- Monotonically increasing or decreasing
- Recover after CM/PM

#### Failure Limit y<sup>F</sup>:

 Tool fails when degradation signal hits

#### Control Limit C<sub>L</sub>:

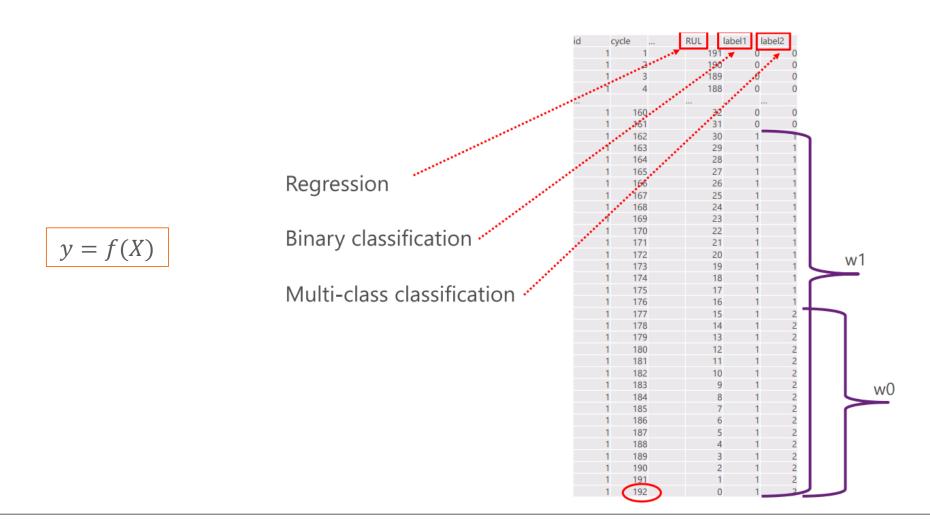
Perform PM when degradation signal hits



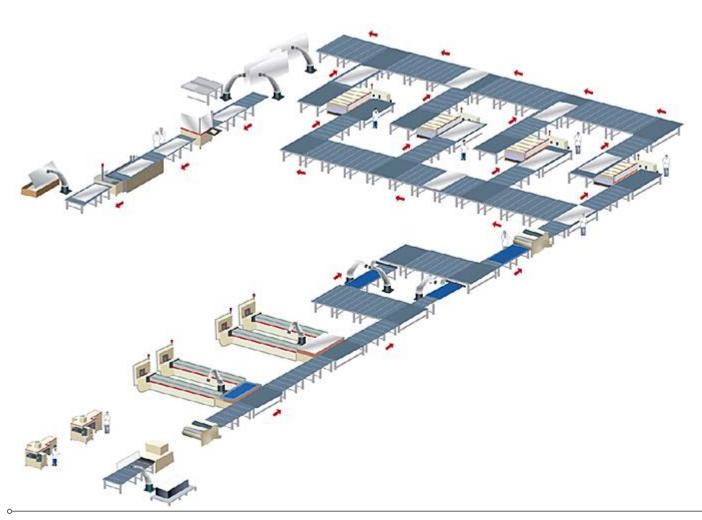
## **Real Scenario**



## **Problem Formulation**



#### Virtual Measurement



- Measurement is an expensive operation, some destructive.
   Consequently, its sampling rate is low.
- However, monitoring system has 100%, either sensor and scanning image.
- From

#### Virtual Measurement

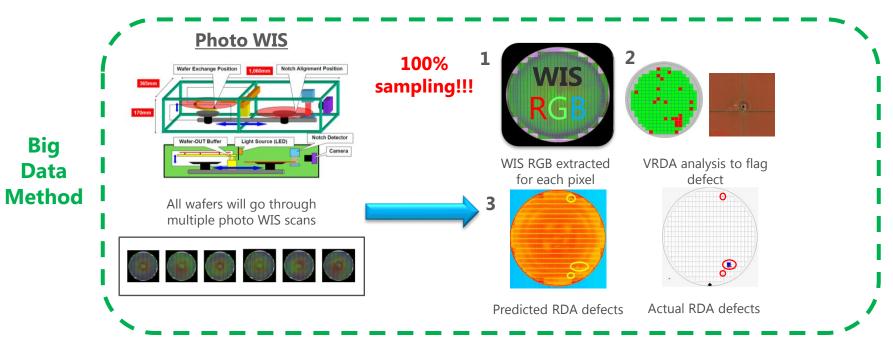
Motivation: Predict low-sampled measurement using 100% sampled images.

#### **Virtual Measurement**



Big

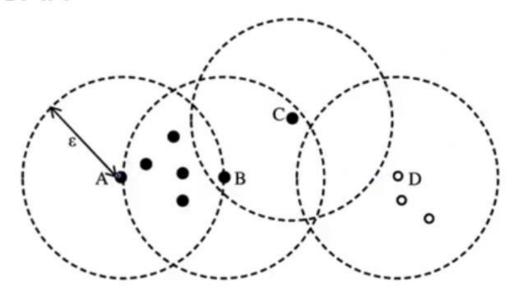




**100%** wafer sampling → Higher visibility to detect defective wafers

## **DBSCAN** Illustration - A density based method

#### **DBSCAN**



#### Parameters:

> Eps: Maximum radius( ε ) of neighborhood

➤ MinPts: Minimum Number of points within Eps-neighbor

# Modelling with Lasso and Random Forest

## Purposes of Data Modelling

#### Inference

- Explain the relationship among predictors and between predictors and responses.
- Tell data insights and trigger investigation

#### Prediction

 Estimate responses given predictor values in a set of unobserved samples.





#### **Data Structure**

Sample training data ~20k rows, 100 unique engine id

Sample testing data ~13k rows, 100 unique engine id

id		cycle	setting1	setting2	setting3	s1	52	s3		s19	s20	s21	RUL	label1	label2
	1	1	-0.0007	-0.0004	100	518.67	641.82	1589.7		100	39.06	23.419			
	1	2	0.0019	-0.0003	100	518.67	642.15	1591.82		100	39	23.4236			
	1	3	-0.0043	0.0003	100	518.67	642.35	1587.99		100	38.95	23.3442			
	1	191	0	-0.0004	100	518.67	643.34	1602.36		100	38.45	23.1295			
	1	192	0.0009	0	100	518.67	643.54	1601.41		100	38.48	22.9649			
	2	1	-0.0018	0.0006	100	518.67	641.89	1583.84		100	38.94	23.4585			
	2	2	0.0043	-0.0003	100	518.67	641.82	1587.05		100	39.06	23.4085			
	2	3	0.0018	0.0003	100	518.67	641.55	1588.32		100	39.11	23.425			
	2	286	-0.001	-0.0003	100	518.67	643.44	1603.63		100	38.33	23.0169			
	2	287	-0.0005	0.0006	100	518.67	643.85	1608.5		100	38.43	23.0848			
														1	
id		cycle	setting1	setting2	setting3	s1	52	s3		s19	s20	521			
	1	. 1	0.0023	0.0003	100	518.6	7 643.0	2 1585.2	9	100	38.86	23.3735			
	1	. 2	-0.0027	-0.0003	100	518.6	7 641.7	1 1588.4	5	100	39.02	23.3916			
	1	. 3	0.0003	0.0001	100	518.6	7 642.4	6 1586.9	1	100	39.08	23.4166			
	1	30	-0.0025	0.0004	100	518.6	7 642.7	9 1585.7	2	100	39.09	23.4069			
	1	31	-0.0006	0.0004	1 100	518.6	7 642.5	8 1581.2	2	100	38.81	23.3552			
	2	1	-0.0009	0.0004	1 100	518.6	7 642.6	6 1589.	3	100	39	23.3923			
	2	2	-0.0011	0.0002	2 100	518.6	7 642.5	1 1588.4	3	100	38.84	23.2902			
	2	3	0.0002	0.0003	3 100	518.6	7 642.5	8 1595.	5	100	39.02	23.4064			
	2	48	0.0011	-0.0001	100	518.6	7 642.6	4 1587.7	1	100	38.99	23.2918			
	2	49	0.0018	-0.0001	100	518.6	7 642.5	5 1586.5	9	100	38.81	23.2618			
	3	1	-0.0001	0.0001	100	518.6	7 642.0	3 1589.9	2	100	38.99	23.296			
	3	2	0.0039	-0.0003	3 100	518.6	7 642.2	3 1597.3	1	100	38.84	23.3191			
	3	3	0.0006	0.0003	3 100	518.6	7 642.9	8 1586.7	7	100	38.69	23.3774			
	3		0.0014	0.0002	2 100	518.6	7 643.2	4 1588.6	1	100	38.56	23.227			
	3	126	-0.0016	0.0004	1 100	518.6	7 642.8	8 1589.7	5	100	38,93	23,274			

## **Data Structure**

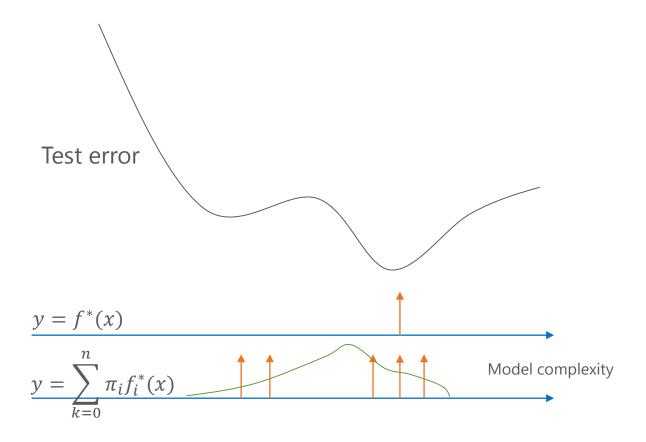


## 1. LASSO

## **Basic Model Assumptions**

$$y = f(X)$$

- Two approaches to estimate f
  - Underlying model style (\*)
  - Bayesian style



Ref: Chapter 5. Deep Learning. Ian Goodfellow, Yoshua Bengio and Aaron Courville

## **Linear Regression**

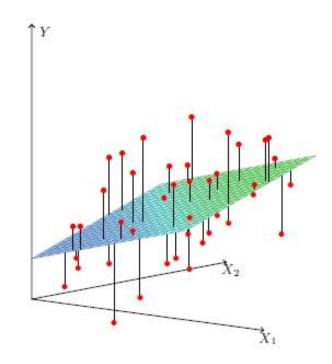
• Assumption:  $f(X) = B_0 + \sum_{j=1}^p X_j B_j$ 

#### To find B

$$J_B = (y - XB)^T (y - XB)$$

$$\frac{\partial J_B}{\partial B} = -2X^T(y - XB)$$

$$\hat{B} = (X^T X)^{-1} X^T y$$



## Ridge Regression

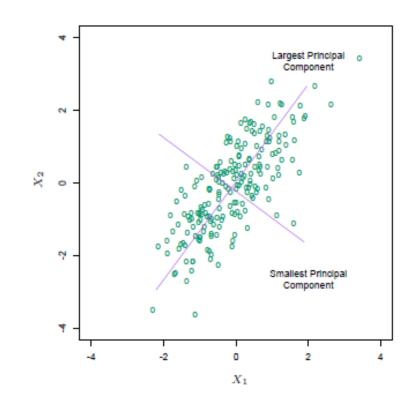
$$J_B = (y - XB)^T (y - XB) + \lambda B^T B$$
$$\hat{B} = (X^T X + \lambda I)^{-1} X^T y$$

With  $X = UDV^T$ 

$$\widehat{B} = V(D^2 + \lambda I)^{-1} D U^T y$$

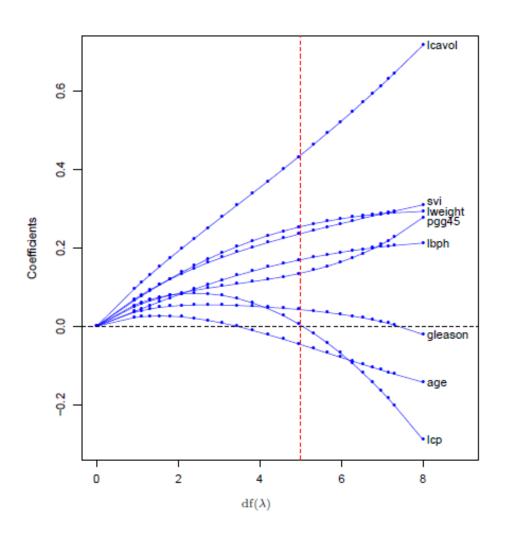
$$\hat{y} = X\hat{B} = \sum_{j=1}^{p} u_j \left(\frac{d_j^2}{d_j^2 + \lambda}\right) u_j^T y$$

 $u_j$  columns of U,  $d_j$  diagonal elements of D



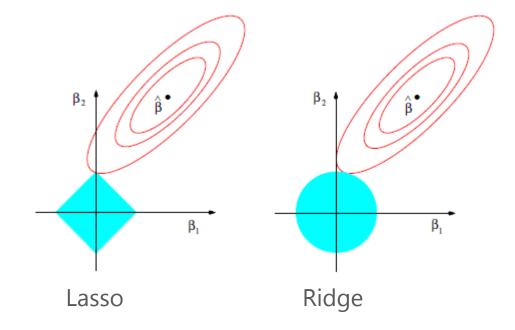
Ref: SVD Tutorial

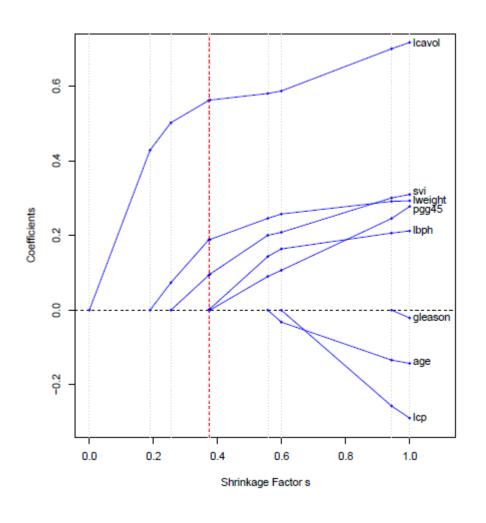
# Ridge Regression



## **Lasso Regression**

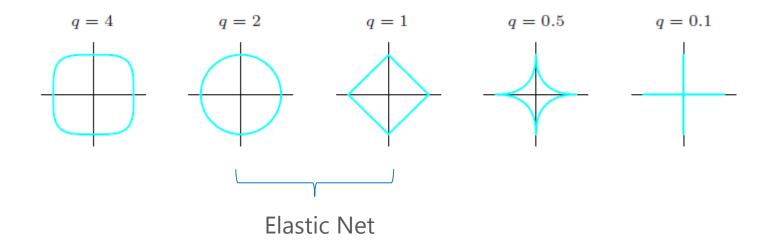
$$J_B = (y - XB)^T (y - XB) + \lambda \sum_{j=1}^p |B_j|$$





#### **G-Formula**

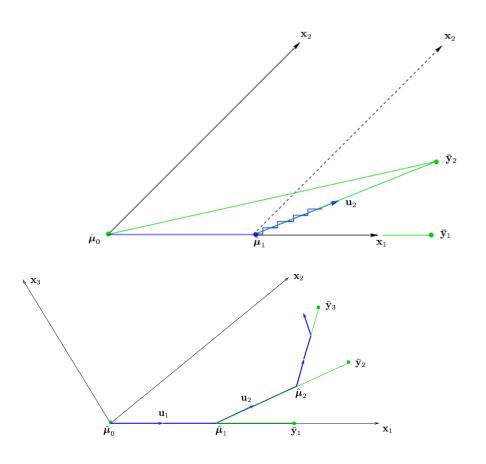
$$J_B = (y - XB)^T (y - XB) + \lambda \sum_{j=1}^p |B_j|^q$$



## Lasso Solution – Least Angle Regression (LAR)

#### Algorithm 3.2 Least Angle Regression.

- 1. Standardize the predictors to have mean zero and unit norm. Start with the residual  $\mathbf{r} = \mathbf{y} \bar{\mathbf{y}}, \, \beta_1, \beta_2, \dots, \beta_p = 0$ .
- 2. Find the predictor  $\mathbf{x}_i$  most correlated with  $\mathbf{r}$ .
- 3. Move  $\beta_j$  from 0 towards its least-squares coefficient  $\langle \mathbf{x}_j, \mathbf{r} \rangle$ , until some other competitor  $\mathbf{x}_k$  has as much correlation with the current residual as does  $\mathbf{x}_j$ .
- 4. Move  $\beta_j$  and  $\beta_k$  in the direction defined by their joint least squares coefficient of the current residual on  $(\mathbf{x}_j, \mathbf{x}_k)$ , until some other competitor  $\mathbf{x}_l$  has as much correlation with the current residual.
- 5. Continue in this way until all p predictors have been entered. After  $\min(N-1,p)$  steps, we arrive at the full least-squares solution.

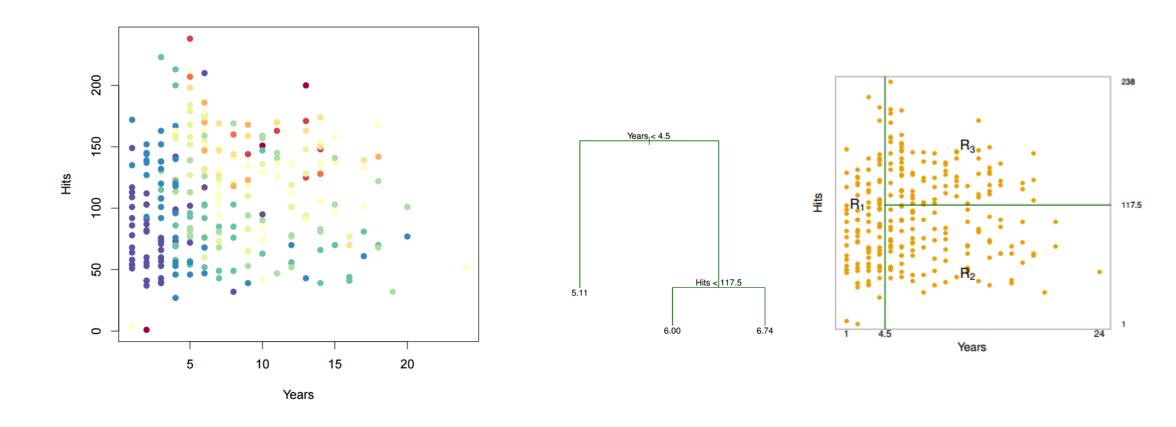


• Questions?

## 2. RANDOM FOREST

## **Decision Tree**

Salary is color-coded from low (blue, green) to high (yellow,red)



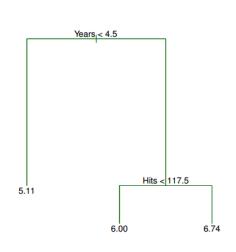
#### **Decision Tree**

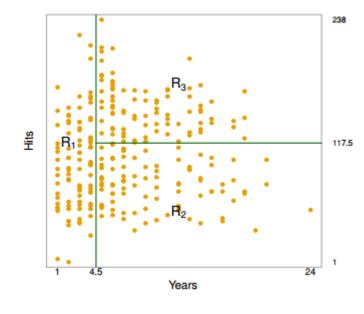
An approach that is known as recursive binary splitting

Top-down,

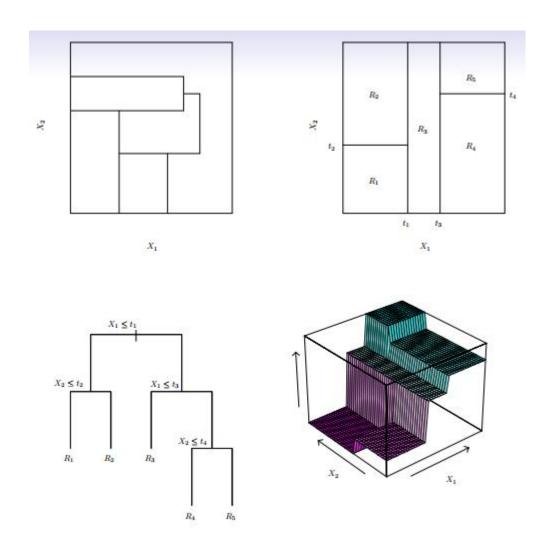
#### Greedy

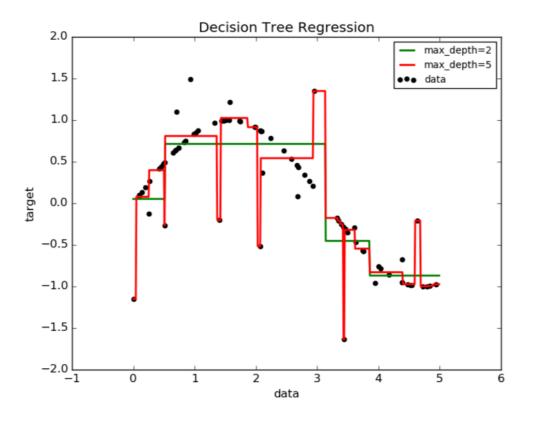
Predict the response for a given test observation <u>using the mean</u> of the training observations in the region





## **Tree Complexity and Overfitting**





## **Tree Pruning**

- Motivation: Simple tree is too biased.
   Complex tree is overfitting.
- Naïve solution: grow the tree only so long as the decrease in the RSS due to each split exceeds some (high) threshold.
  - Result in smaller trees, but is too short-sighted:

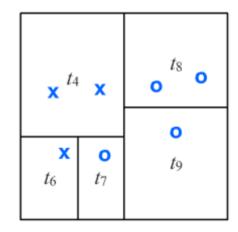
     a seemingly worthless split early on in the tree
     might be followed by a very good split

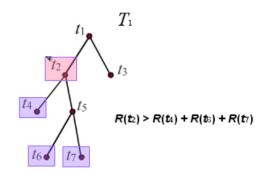
#### XOR

P	$\overline{Q}$	$P \ xor \ Q$
1	1	0
1	0	1
0	1	1
0	0	0

## **Tree Pruning**

- Motivation: Simple tree is too biased.
   Complex tree is overfitting.
- Better solution: grow a large tree, then merge back nodes to obtain a smaller tree of the right size <u>link</u>





$$0.25 > 0 + 0 + 0$$

## Cost complexity pruning (or Weakest link pruning)

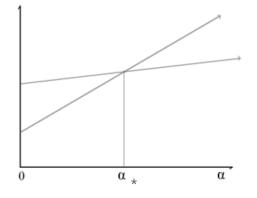
- Define  $T_t$  a branch rooted at a node t, and and  $\tilde{T}_t$  is its set of terminal nodes.
- Let  $\alpha$  be a regularization parameter.

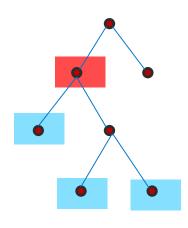
$$R_{\alpha}(t) = R(t) + \alpha * 1$$

$$R_{\alpha}(T_t) = \sum_{t' \text{ in } \tilde{T}_t} R(t') + \alpha * |\tilde{T}_t|$$

$$R(t) = R(T_t)$$

$$\alpha_* = \frac{R(t) - R(T_t)}{\left|\tilde{T}_t\right| - 1}$$





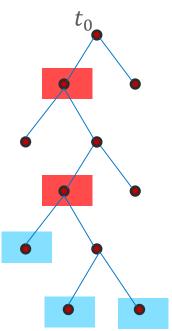
## Cost complexity pruning (or Weakest link pruning)

- 1. Construct a large tree  $T_0$ .
- 2. Find a node t that minimizes the function  $g(t) = \frac{R(t) R(T_t)}{|\tilde{T}_t| 1}$ . Let  $\alpha_1 = g(t)$  and remove all sub-nodes under t to produce  $T_1$ .
- 3. Repeat step 2 to find two sequences

$$\alpha_1 < \alpha_2 < \alpha_3 < \cdots < \alpha_{|T|}$$

$$T_1 > T_2 < T_3 > \dots > t_0$$

Note: R(t) can be stored.



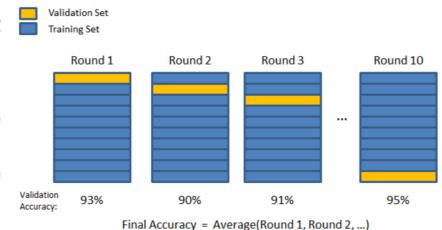
## Single Decision Tree

#### Algorithm 8.1 Building a Regression Tree

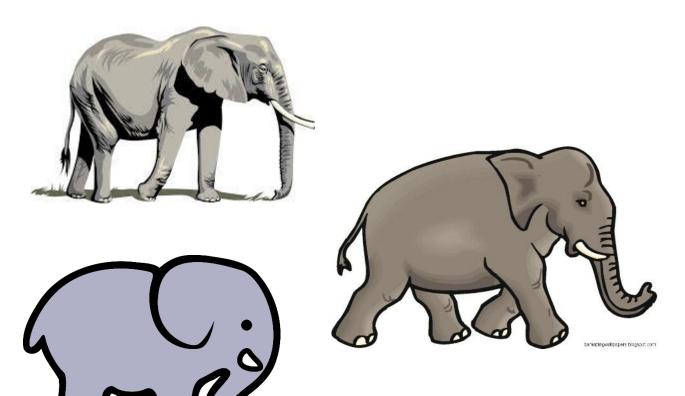
- Use recursive binary splitting to grow a large tree on the training data, stopping only when each terminal node has fewer than some minimum number of observations.
- Apply cost complexity pruning to the large tree in order to obtain a sequence of best subtrees, as a function of α.
- 3. Use K-fold cross-validation to choose  $\alpha$ . That is, divide the training observations into K folds. For each  $k = 1, \ldots, K$ :
  - (a) Repeat Steps 1 and 2 on all but the kth fold of the training data.
  - (b) Evaluate the mean squared prediction error on the data in the left-out kth fold, as a function of  $\alpha$ .

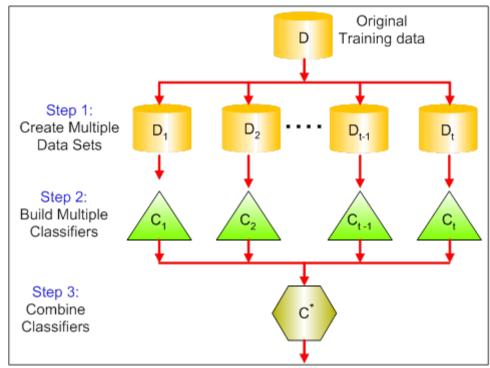
Average the results for each value of  $\alpha$ , and pick  $\alpha$  to minimize the average error.

4. Return the subtree from Step 2 that corresponds to the chosen value of  $\alpha$ .



# **Bagging**



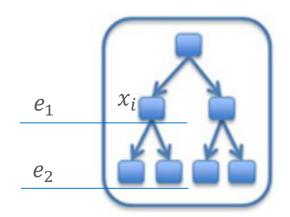


## **Bagging – Prediction**

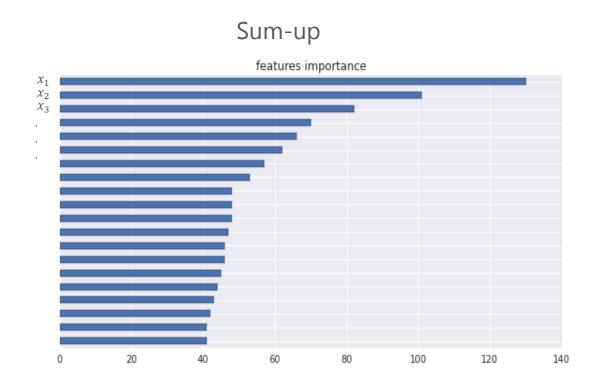
 Averaging predictions from multiple trees, each is constructed on one part of a training data set. Famous method: Bootstrap (sampling with replacement).

# **Bagging – Variable Importance**

#### At each tree

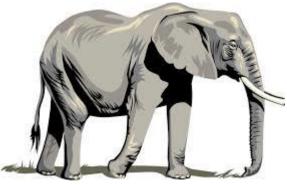


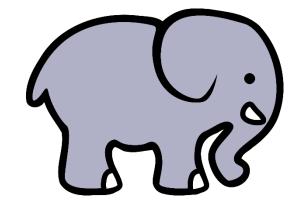
Importance of  $x_i$ =  $e_1 - e_2$ 



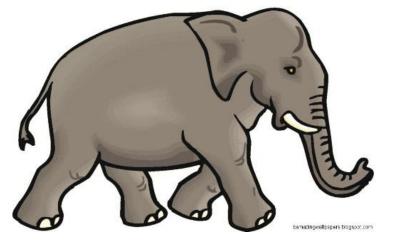
## **Random Forest**









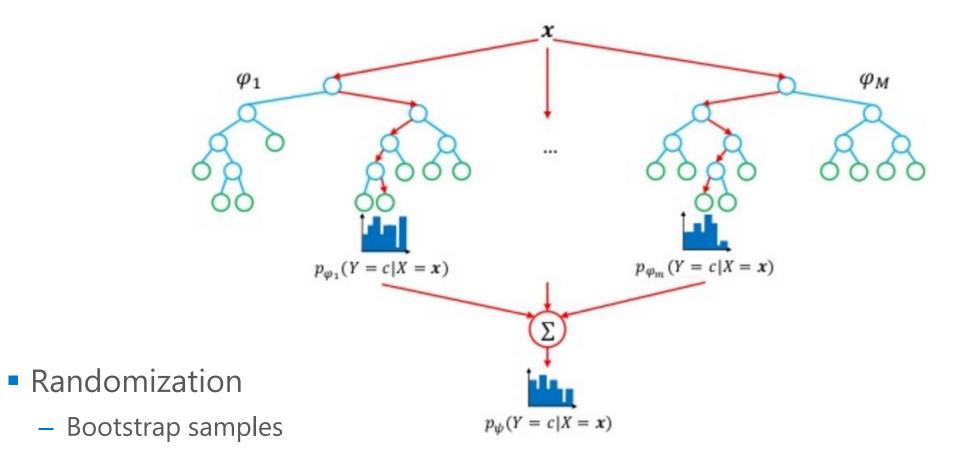






### Random Forest

Variable selection for each tree



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